

# Low Cost Remote Sensing for Precision Farming using UAVs

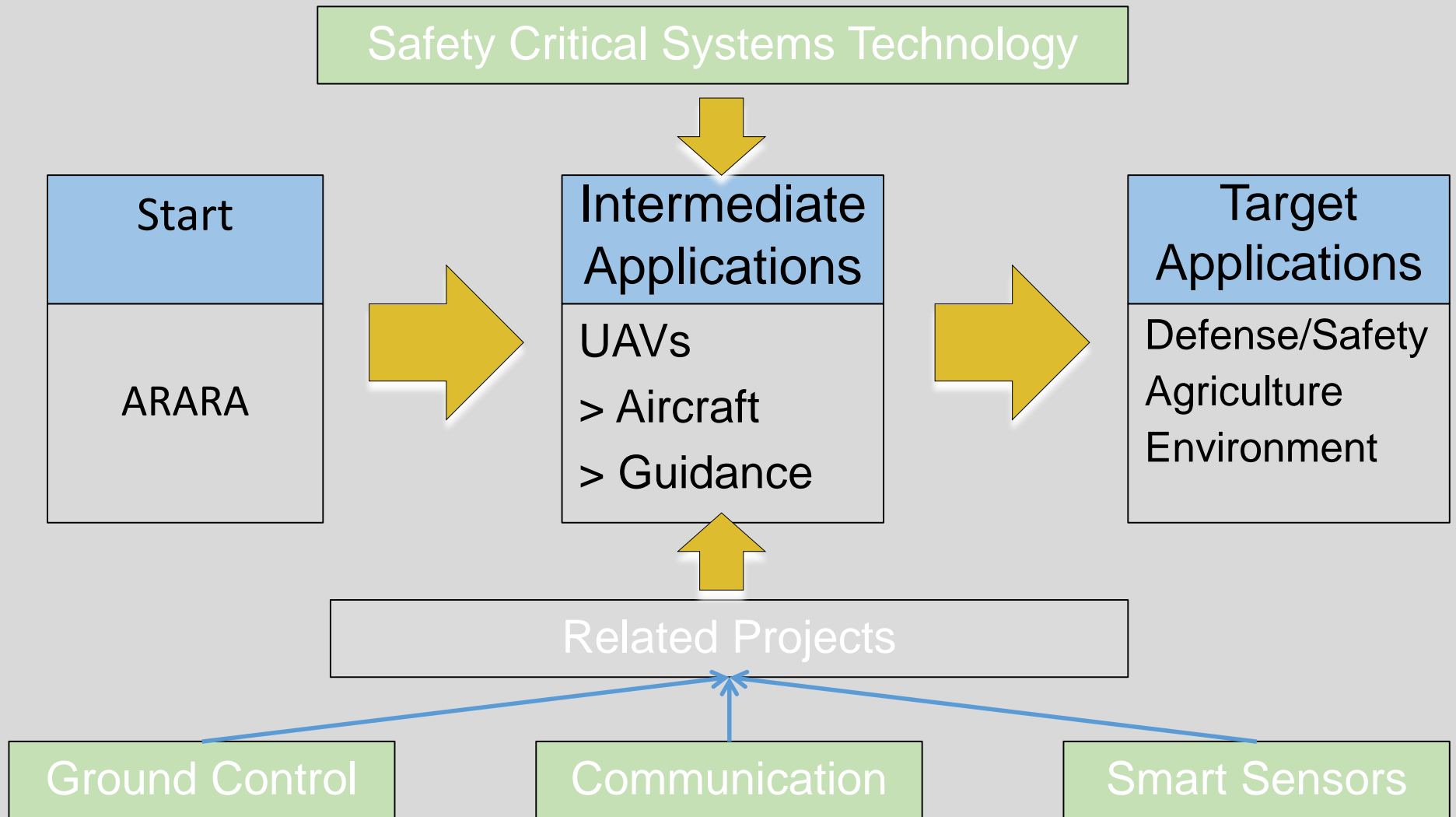
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# Summary

- Research on UAS in the ICMC-USP
  - The ARARA Project
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  - INCT-SEC
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    - AP1
    - AP2
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  - SARVant
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  - The Payload – MOSA
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# Research on UAS in the ICMC-USP



# The ARARA Project

- ARARA stands for Autonomous and Radio Assisted Reconnaissance Aircraft
- The ARARA project started in 1997 aiming at the use of unmanned aircraft for crop monitoring and the surveillance of areas under environmental stress



# The ARARA Project

- Phase 1 – Radio controlled aircraft (model airplanes). Geo-referenced images using on-board GPS. Flights under eyesight range (finished in 2000)
- Phase 2 – Custom designed aircraft. Complete on-board instrumentation. Ground control station. Instrument flights, beyond eyesight range. (finished in 2003)
- Phase 3 – Auto pilot, moving ground control station. (finished in 2006)
- Phase 4 – New hardware and software architectures, on-board image processing, new data link technology, larger autonomy

# ARARA / ARARA NG

- Operating data
  - Engine ~~40~~ **55**cc, ~~2~~ **4**T, 5HP, AVGAS
  - Max weight : ~~20~~**16**Kg
  - Payload: ~~3~~**4**Kg
  - Flight endurance: ~~4~~ **8**h
  - Cruise speed : ~~100~~ **200**km/h
  - Stall speed : ~~40~~ **60** km/h
  - Autonomous or remote controlled aircraft
  - Emergency parachute
  - Electric generator/engine starter
  - Moving ground control station
  - Autonomous takeoff (on a car) **and landing (on skis)**



# INCT-Sec Tiriba

- **Electric propulsion**
- **Max takeoff weight: 4kg**
- **Payload: 800 g**
- **Autonomy: 45 min**
- **Cruiser speed: 100km/h**
- **Stoll speed: 40km/h**
- **Autonomous or remote controlled flight**
- **Landing – automatic parachute landing, manual belly landing**
- **Takeoff – automatic hand launch**



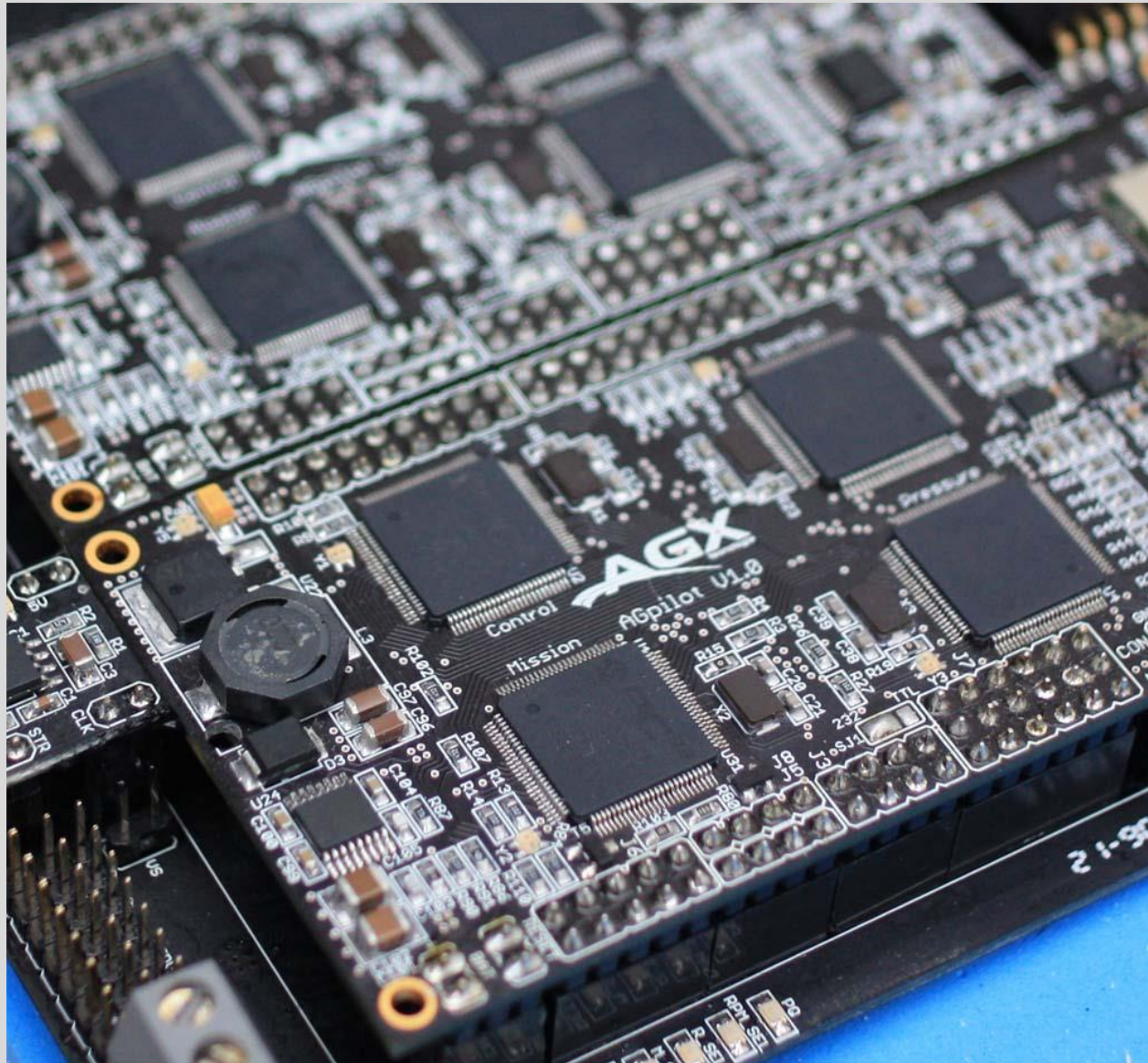
# INCT-Sec Autopilot





# INCT-Sec Autopilot 3way redundant - SarVANT

Tree way  
redundancy



Open Source

# GISA & Ararinha



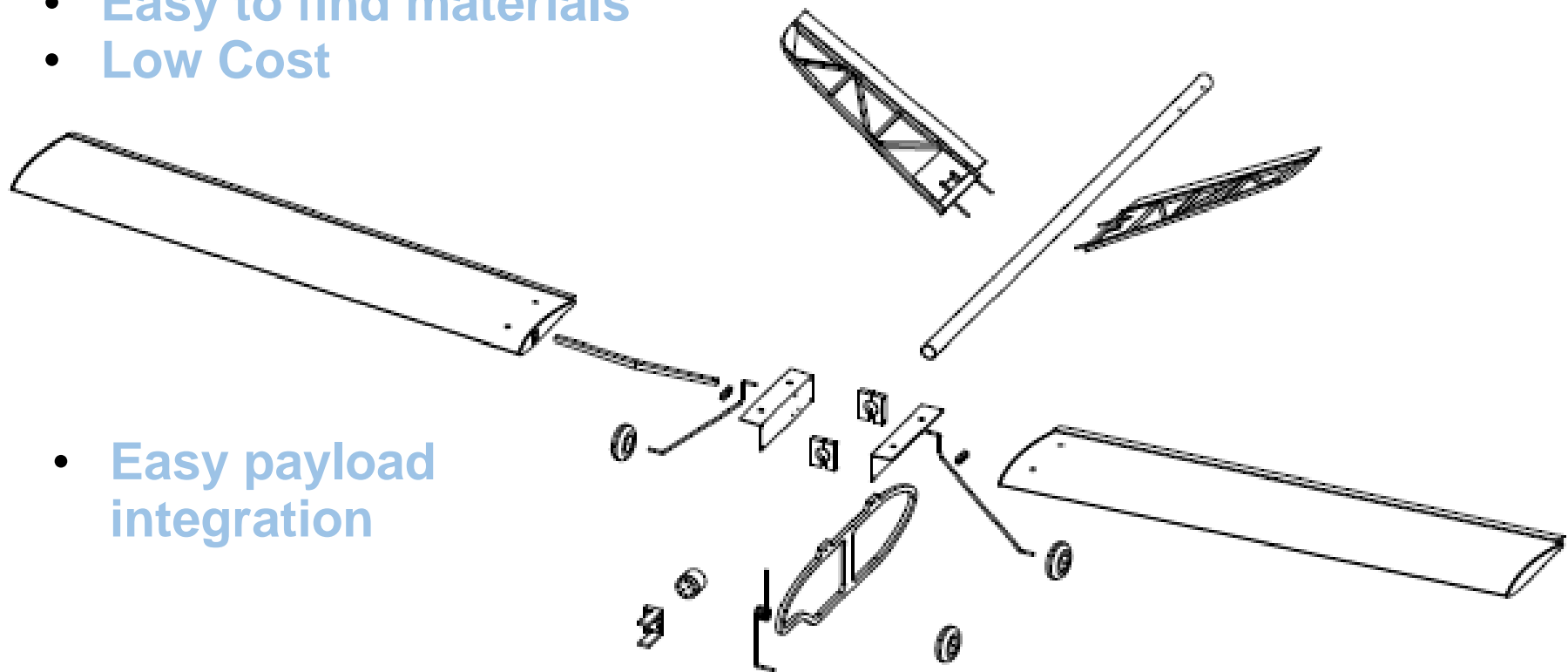
# Ararinha

Open aircraft design developed at GISA - Interest Group on Unmanned Aerial Systems and Applications

Goal – share knowledge on unmanned aircraft and applications among students, industrial partners and hobbyists


# Ararinha

- Easy building
- Easy to find materials
- Low Cost

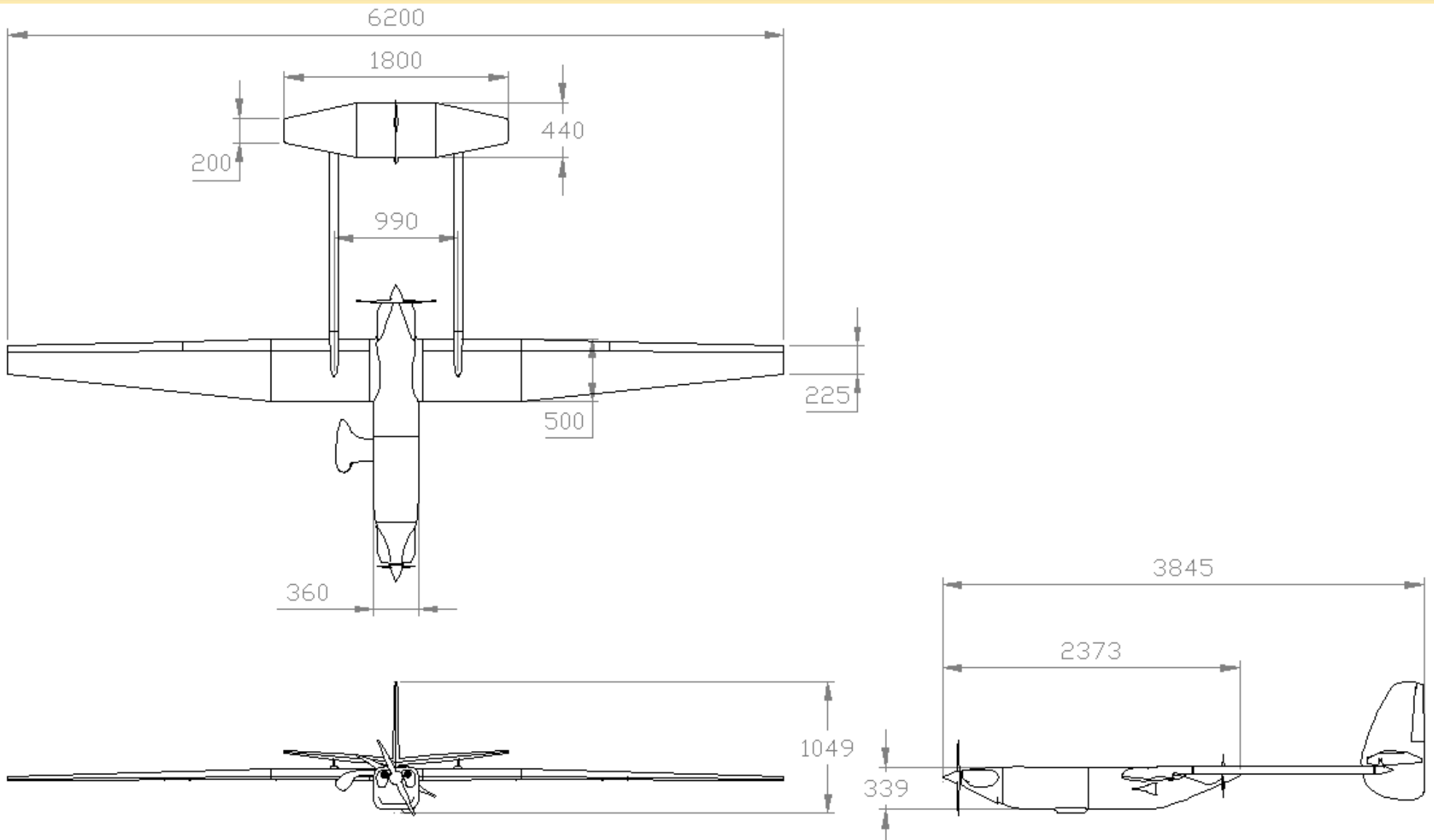


- Easy payload integration

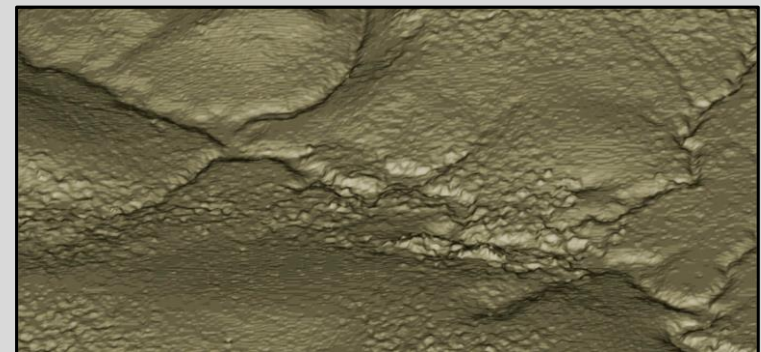
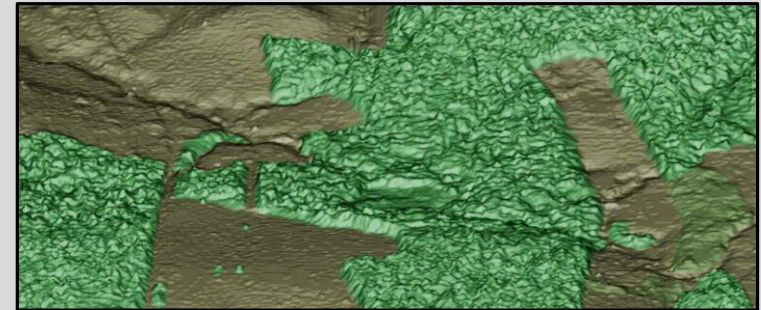
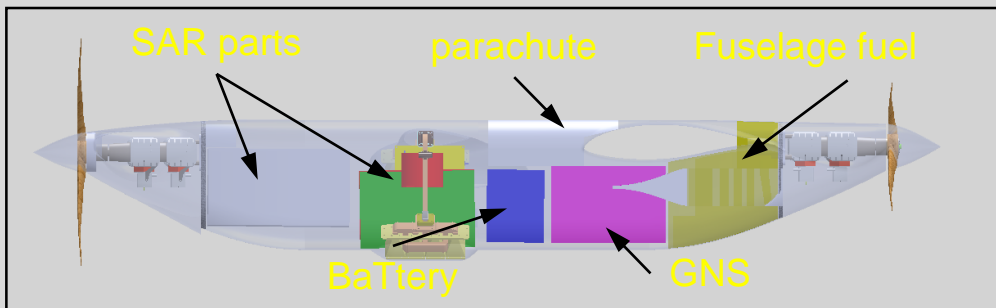
# Orbisat-Aeroálcool SARVant

- 
- Wing load: 47 Kg/m<sup>2</sup>
  - Dry Weight: 35 Kg
  - Maximum takeoff weight: 120 Kg
  - Payload: 45 Kg
  - Propulsion: 2 DLE-222 - 21.5Hp's each
  - Stol speed (flaps on, ISA): 72 Km/h
  - Cruise speed(8000 ft; ISA+10): 200 Km/h
  - Autonomy: 20+ Hours
  - Cruise range: 4000+ Km
  - Rate of climb: 2000 Pés/min
  - Takeoff and landing distance: 250 m

# SARVant – Main Dimensions



# SarVANT Payload Integration



# Tiriba MIL

- Electric propulsion
- Max takeoff weight: 7kg
- Payload: 800 g
- Autonomy: 90 min
- Cruiser speed: 70/100 km/h
- Stoll speed: 40/55 km/h



- Autonomous or remote controlled flight
- Landing – automatic parachute landing,  
manual belly landing
- Takeoff – automatic hand launch



# Tiriba MIL



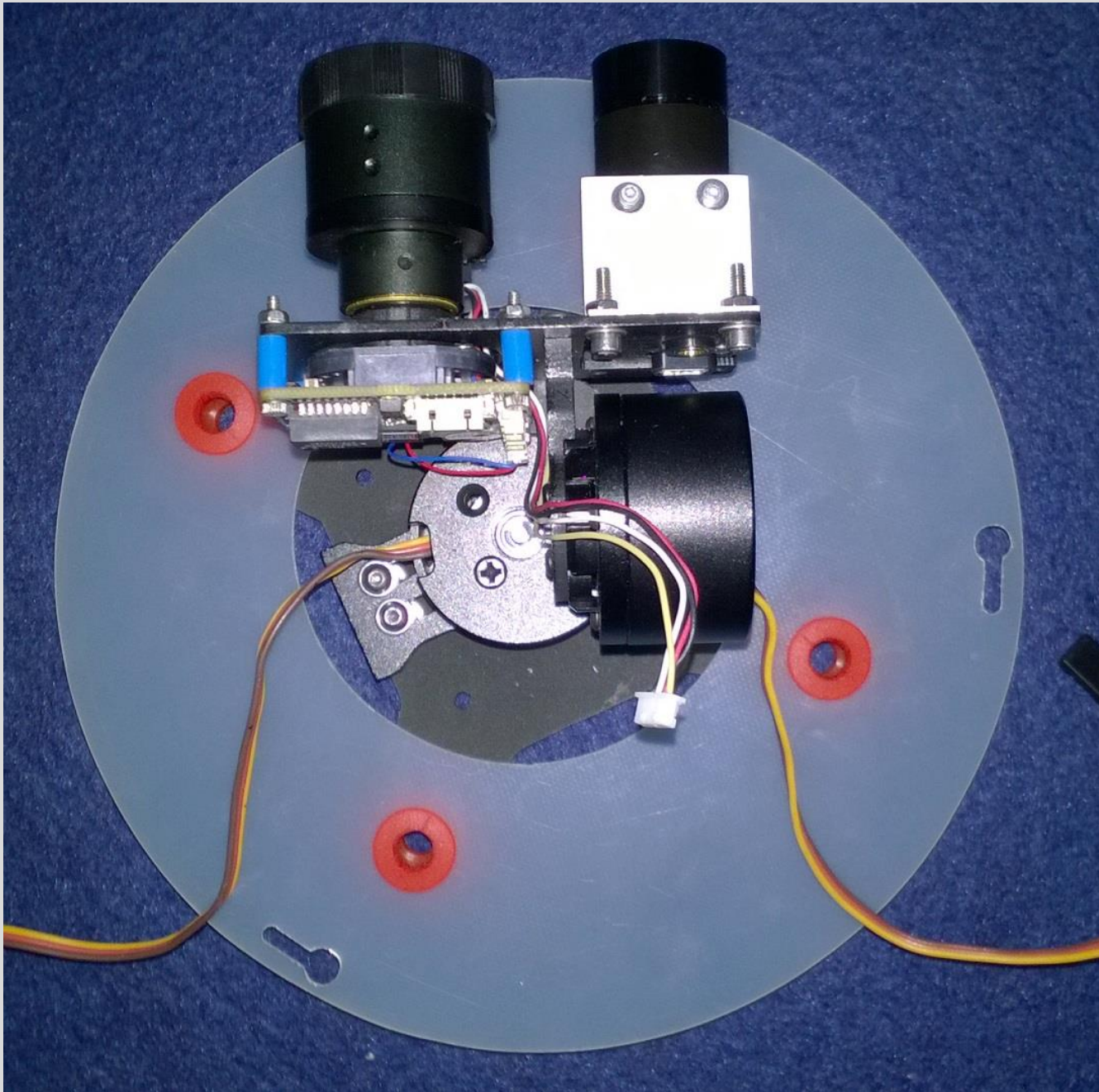
# Tiriba MIL



# Tiriba MIL



# Tiriba MIL



# Tiriba MIL



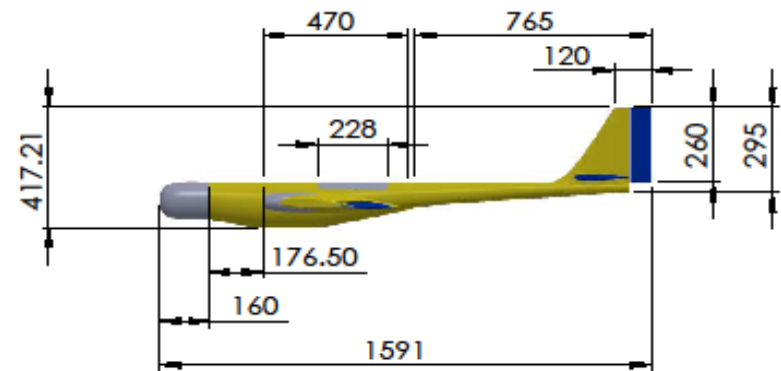
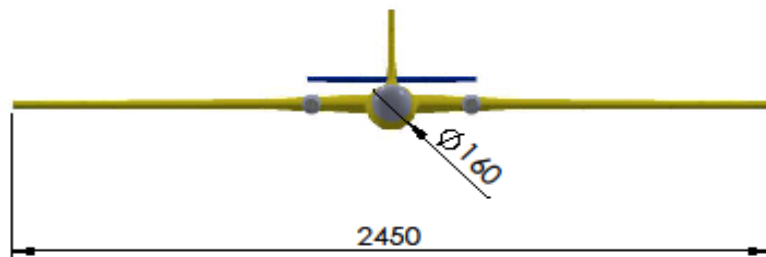
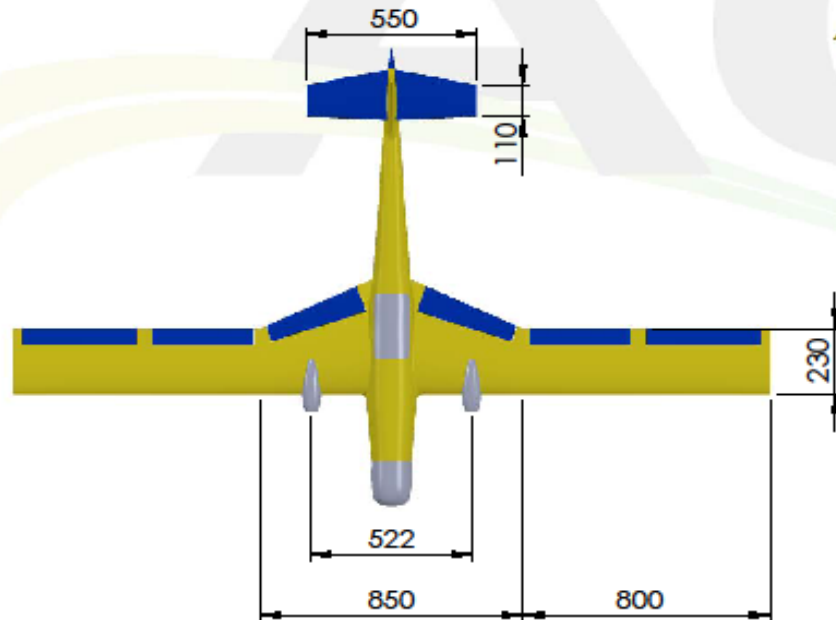
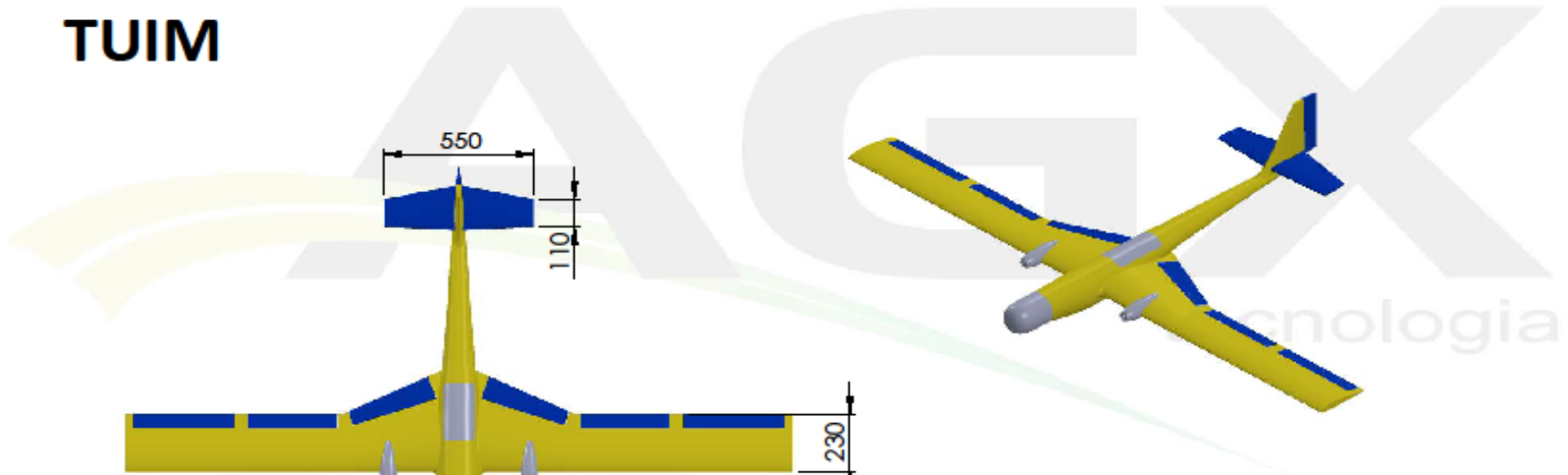
# Tuim/Agilis

- MTOW: 7/9 Kg
- *Payload*: 1,5/1.8 Kg
- Cruiser: 100Km/h
- Autonomy:
  - 1h @ 80Km/h
  - 2.5h @ 100Km/h
- Propulsion:
  - Twin engine, electric powered
  - Gas – 35cc
- Takeoff/Landing: VTOL
- Emergency parachute



# Tuim/Agilis

TUIM



un.: mm

# Applications Agriculture Management





# Applications Agriculture Management

## Precision Agriculture

### 1. Data gathering

Remote sensing

Local sensing

### 2. Data analysis

Problem identification

Opportunities identification for better crop yields

### 3. Action

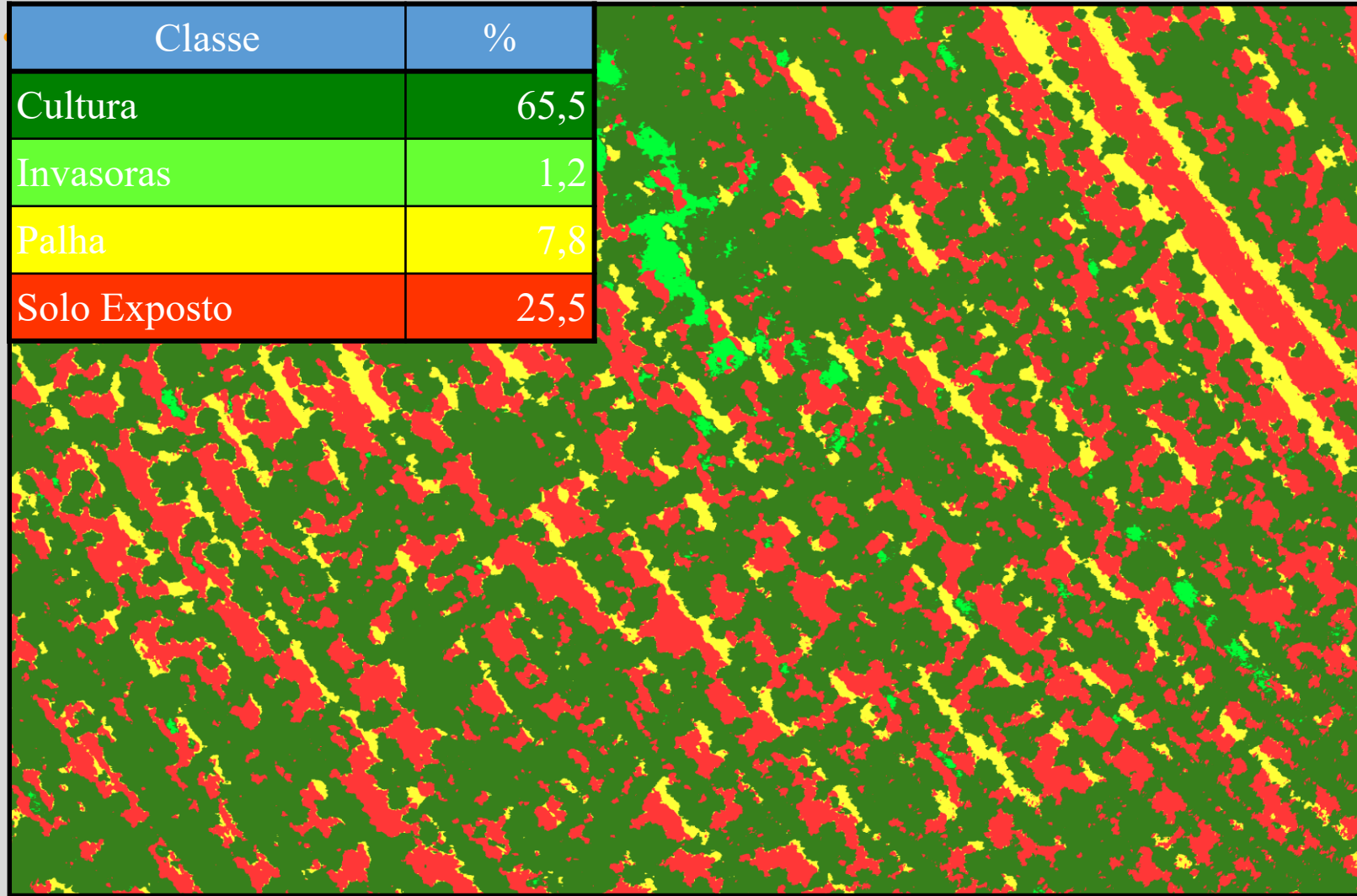
Raw data -> Thematic maps -> Actuation maps

Temporal resolution is important

Problem correction / opportunities exploration

Current season / future seasons

# Applications Agriculture Management



Soil,  
Straw,  
Weed  
and Crop  
Mapping

# Applications Agriculture Management

Faults  
Mapping



# Applications Agriculture Management

Faults  
Mapping

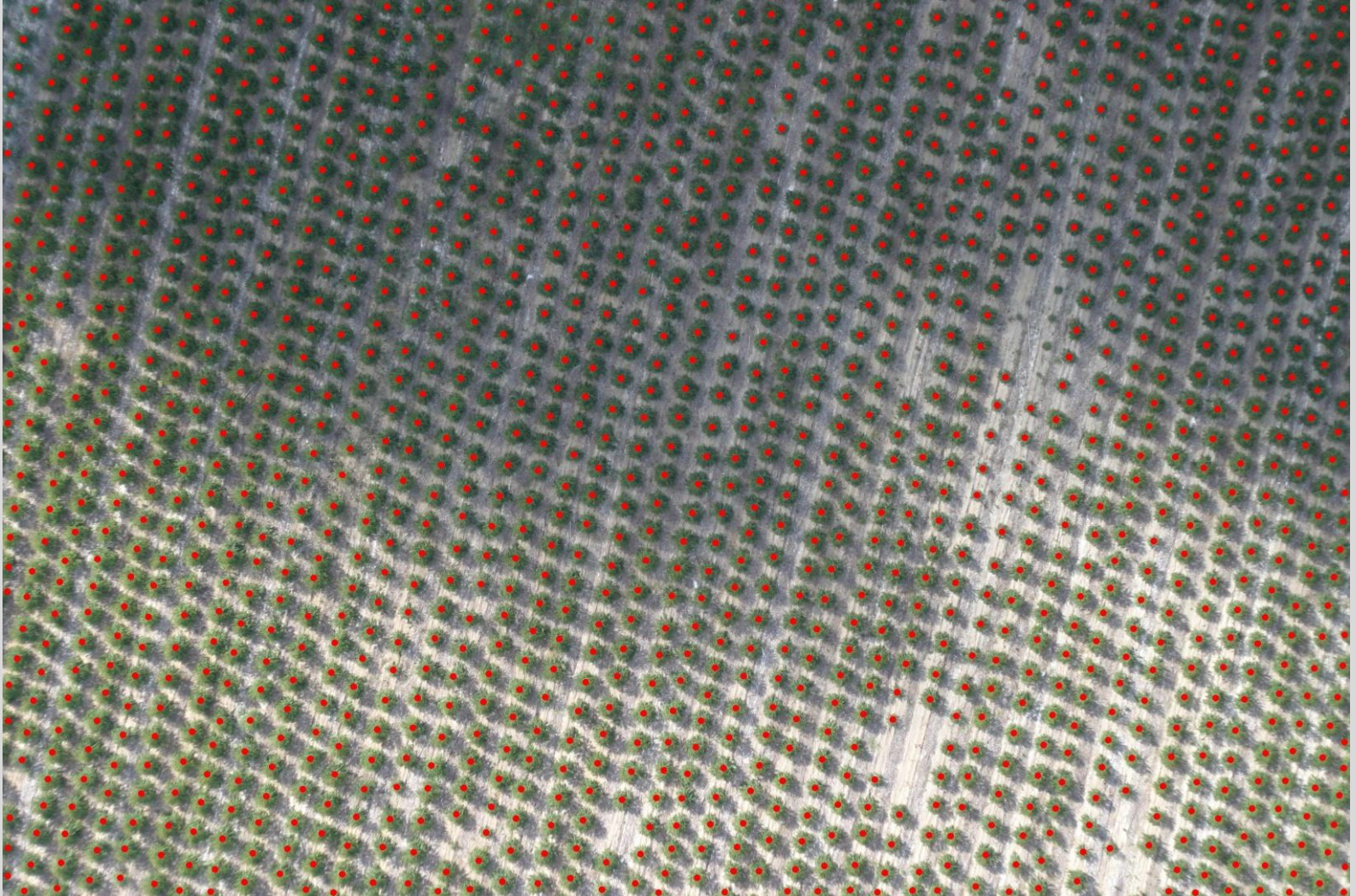


# Applications Agriculture Management



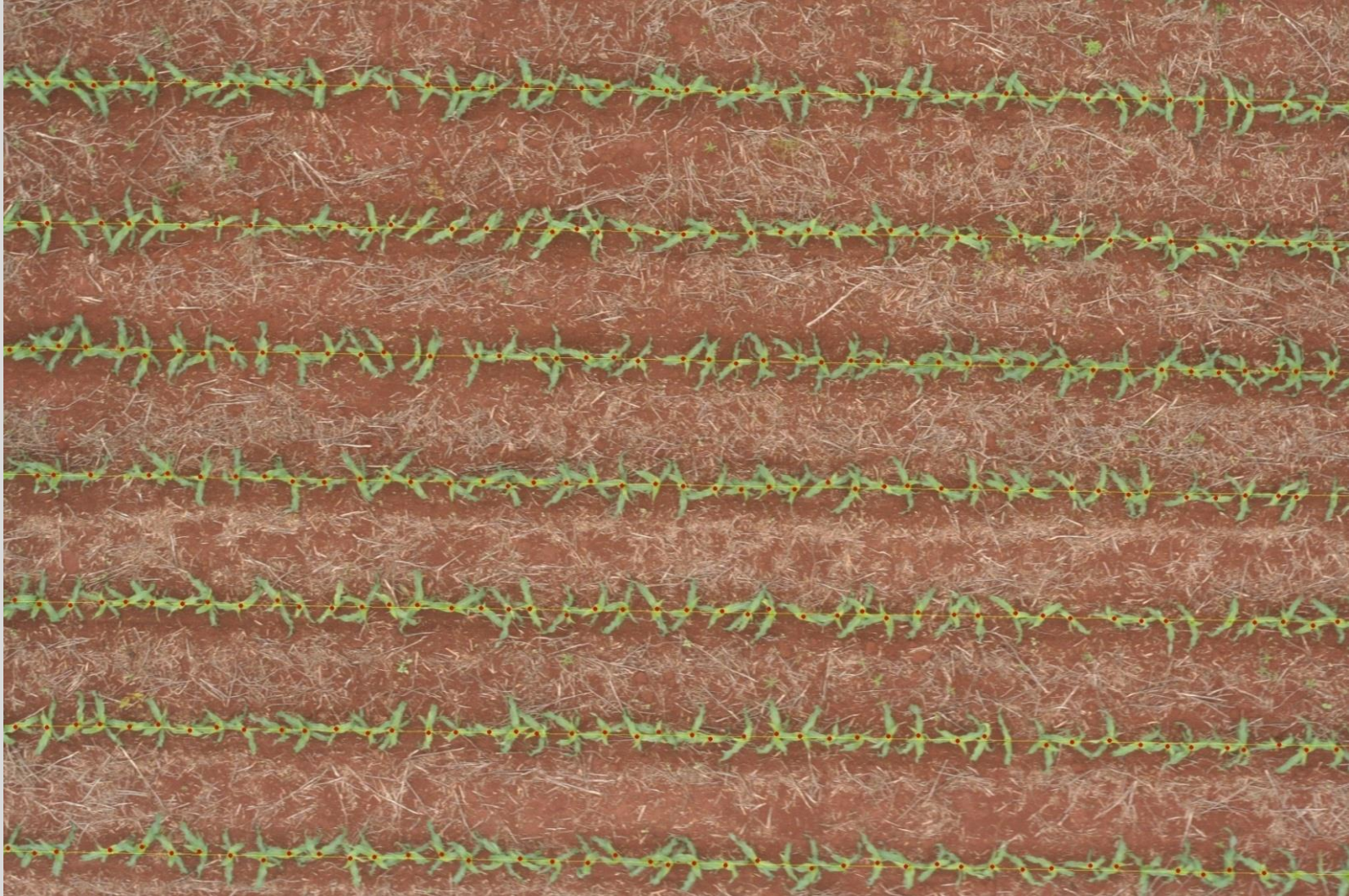
# Applications Agriculture Management

Tree  
Counting



# Applications Agriculture Management

Seeding  
Quality  
Evaluation

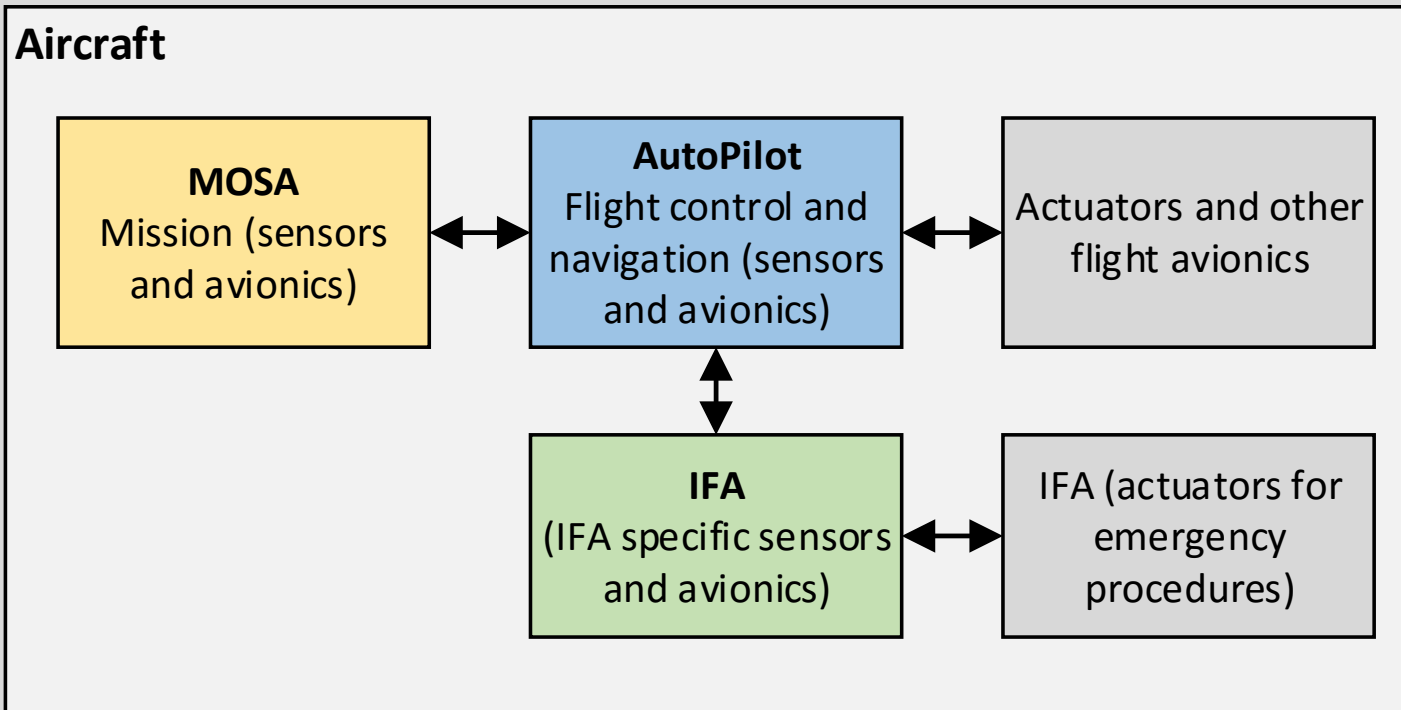


# UAS Components

- Ground segment
  - Ground Monitoring and Control Station
  - Ground Payload Control Station
- Aerial segment
  - Aircraft
  - Control avionics
  - Payload
- Communications
  - Air-Air
  - Air-Ground



# Improved System Organization



## MOSA:

- Mission accomplishment

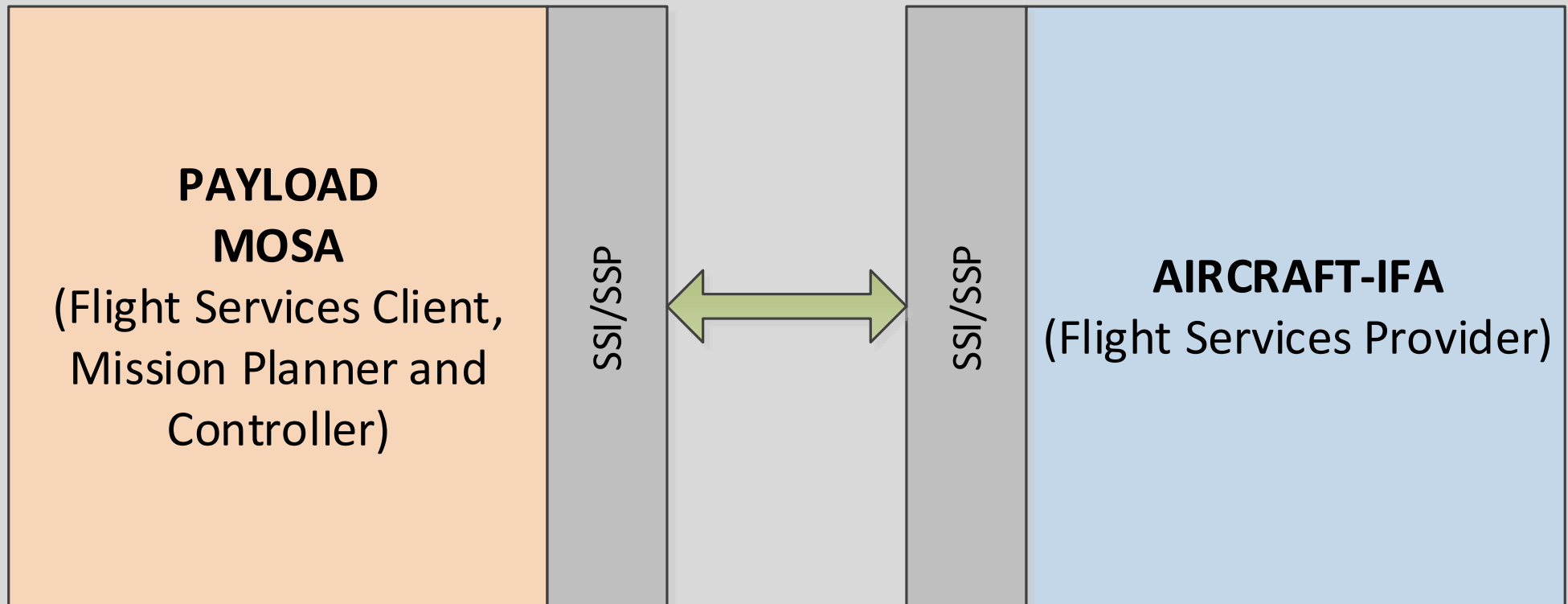
## AutoPilot:

- Flight control
- Basic navigation
- Flight services
- Communication services
- Position services

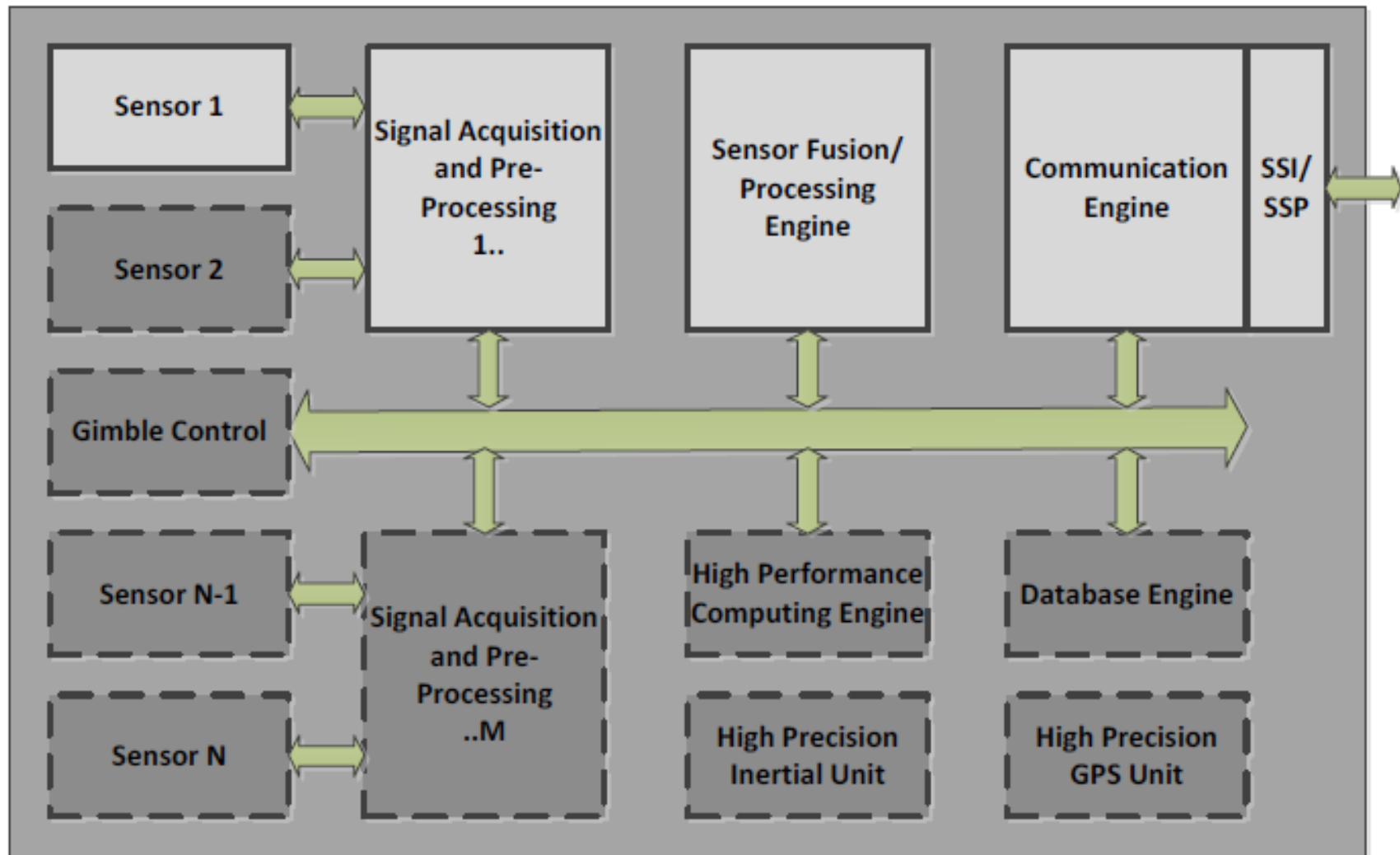
## IFA:

- Ensure Safety
- May provide safety-related information

# Separating the Mission Mission Oriented Sensor Array

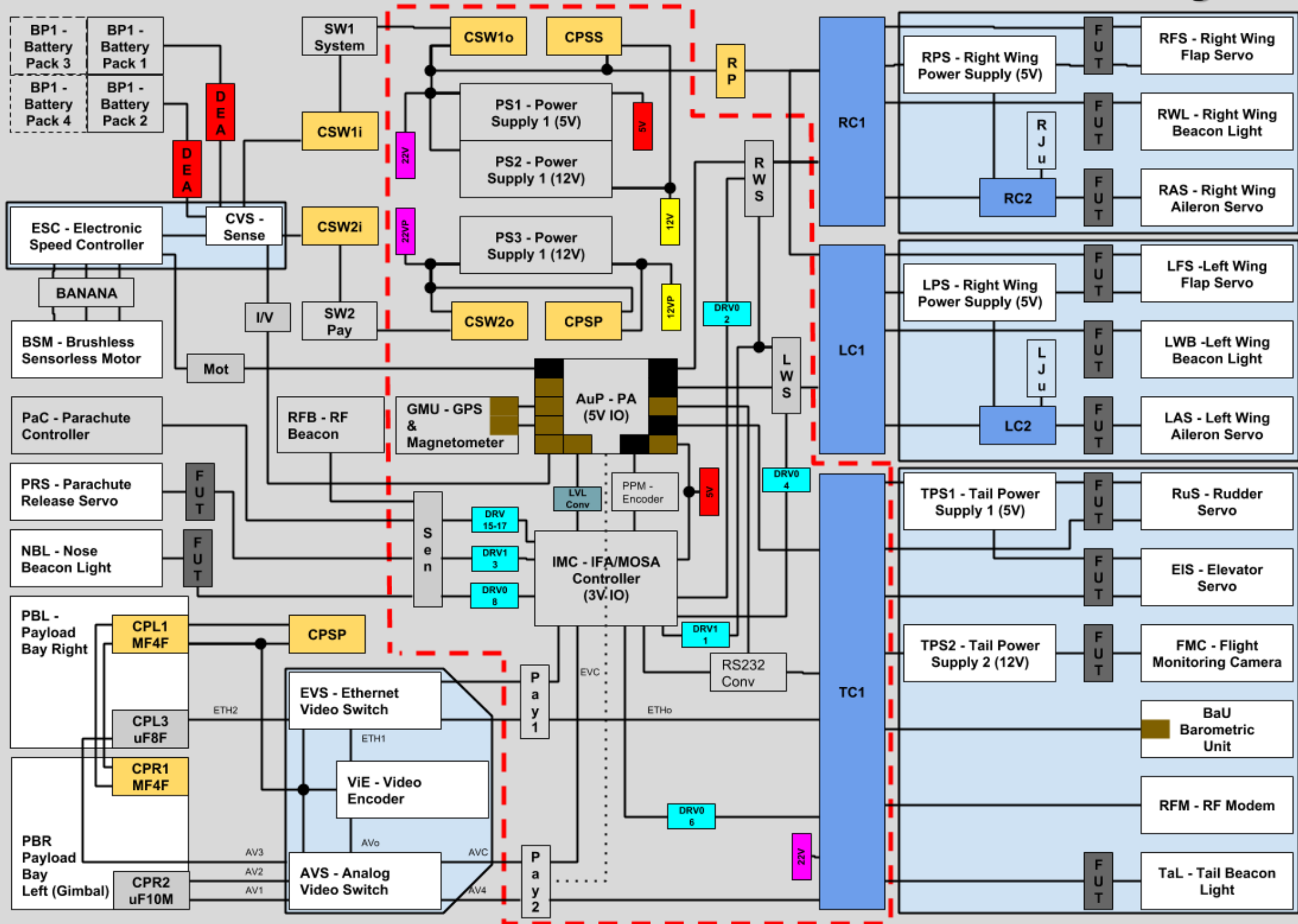


# Functional Architecture of a MOSA System



Options

# Tiriba MIL – Block Diagram



# Success Metrics

- Safety point of view – no catastrophic faults (no loss of human lives or costly installations)
- Mission point of view – full mission accomplishment
- Commercial point of view - Adequate Cost-Benefit ratio

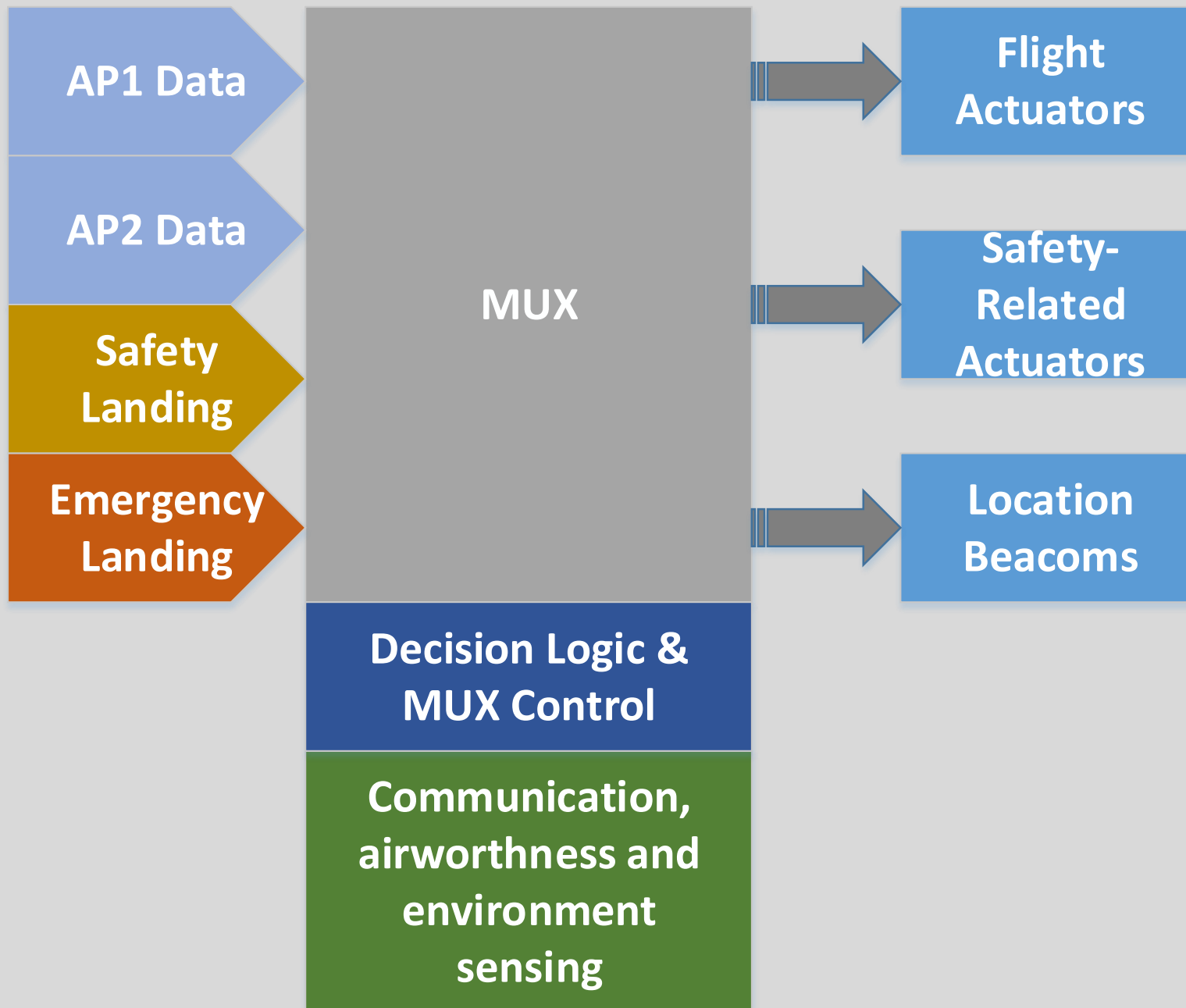
# Failure Rates

- Catastrophic failures – lead to losses of human lives or hull loss
- Rates:
  - Commercial aviation –  $10^{-6}$  per flight hour
  - Light Civil aviation –  $10^{-4}$  per flight hour
  - Medium to big UAVs -  $10^{-2}$  to  $10^{-3}$
  - Medium to big UAVs -  $10^{-1}$  to  $10^{-2}$
- In fact, small UAVs only last for few tens of hours...

# Cost Benefit

- Light civil aviation charges around R\$700 per flight hour, including pilot, equipament, insurance, fuel, maintenance, depreciation, etc.
- A small UAV that lasts for 20 hours must cost less than:
  - $R\$20 \times 700$  (cost of 20 flight hours in a light aircraft) –  $R\$20 \times 100$  (operator cost) = R\$12.000
  - To present the same cost/benefit ratio of the manned aircraft...
- Solution
  - increase UAV robustness
  - decrease price
  - Increase automation

# In the Rexcue - IFA<sup>2</sup>S System





# Low Cost, Professional Small UAVs

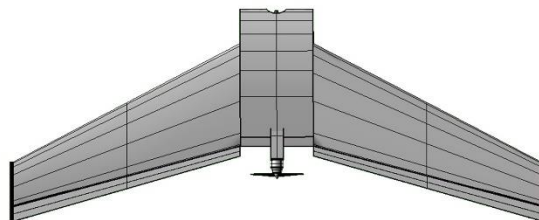
	Carcará 1	Ararinha Gas	Agilis Gas
Availability	Since 2006 (Brazilian Navy)	Since 2013 (Improved from a open project)	2016 (VTOL capability, single or dual engine)
Wingspan	1,6m	1,9m	2,45m
Powerplant	Gas, Ethanol, Methanol, Electric	Ethanol (option: Gas, Methanol, Electric)	Gas (option: Electric)
Endurance	50min	75 min	150min
Takeoff (Automatic)	Hand launching or catapult	Hand launching or tricycle	Hand launching, or VTOL
Landing (Automatic)	Deep Stall	Tricycle, parachute, belly, floats or deep stall	Parachute, skis or VTOL
MTOW	1,5Kg	3,5Kg	9Kg
Payload	250gr	750gr	1800gr
Cruiser speed	45 Km/h	70 Km/h	90 Km/h
Structure materials	Foam, carbon fiber	Aluminum, foam, wood	Carbon/glass fiber

# Carcará 1



## CARCARÁ RPV

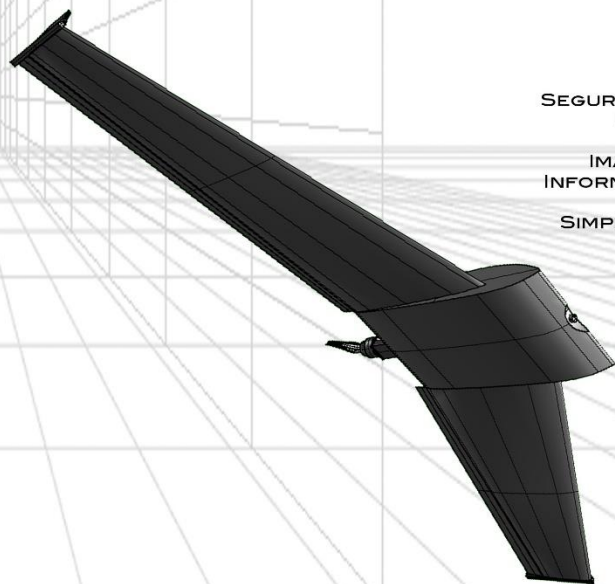
O SISTEMA AÉREO CARCARÁ RPV REPRESENTA UMA SOLUÇÃO DE BAIXO CUSTO PARA MISSÕES DE RECONHECIMENTO TÁTICO EM TEMPO REAL. ESSE ROBUSTO SISTEMA ESTÁ ATUALMENTE EM OPERAÇÃO NA MARINHA DO BRASIL ONDE EQUIPA O PRIMEIRO PELOTÃO DE VEÍCULOS AÉREOS NÃO TRIPULADOS DAS FORÇAS ARMADAS BRASILEIRAS, PELVANT.



### CARACTERÍSTICAS DO SISTEMA

BAIXA ASSINATURA ACÚSTICA  
SEGURO PARA OPERAR SOBRE ÁREA URBANA  
NECESSITA DE APENAS UM OPERADOR  
RÁPIDA MONTAGEM E DESMONTAGEM  
IMAGENS TRANSMITIDAS EM TEMPO REAL  
INFORMAÇÕES ATUALIZADAS DE TELEMETRIA

SIMPLICIDADE PORTABILIDADE E ROBUSTEZ



Since 2006  
(Brazilian Navy)

1,6m

Gas, Ethanol,  
Methanol, Electric

50min

Hand launching or  
catapult

Deep Stall

1,5Kg

250gr

45 Km/h

Foam, carbon fiber



# Carcará 1



# Ararinha Pro



## Ararinha Gas

Since 2013  
(Improved from a  
open project)

1,9m

Ethanol (option:  
Gas, Methanol,  
Electric)

75 min

Hand launching or  
tricycle

Tricycle, parachute,  
belly, floats or  
deep stall

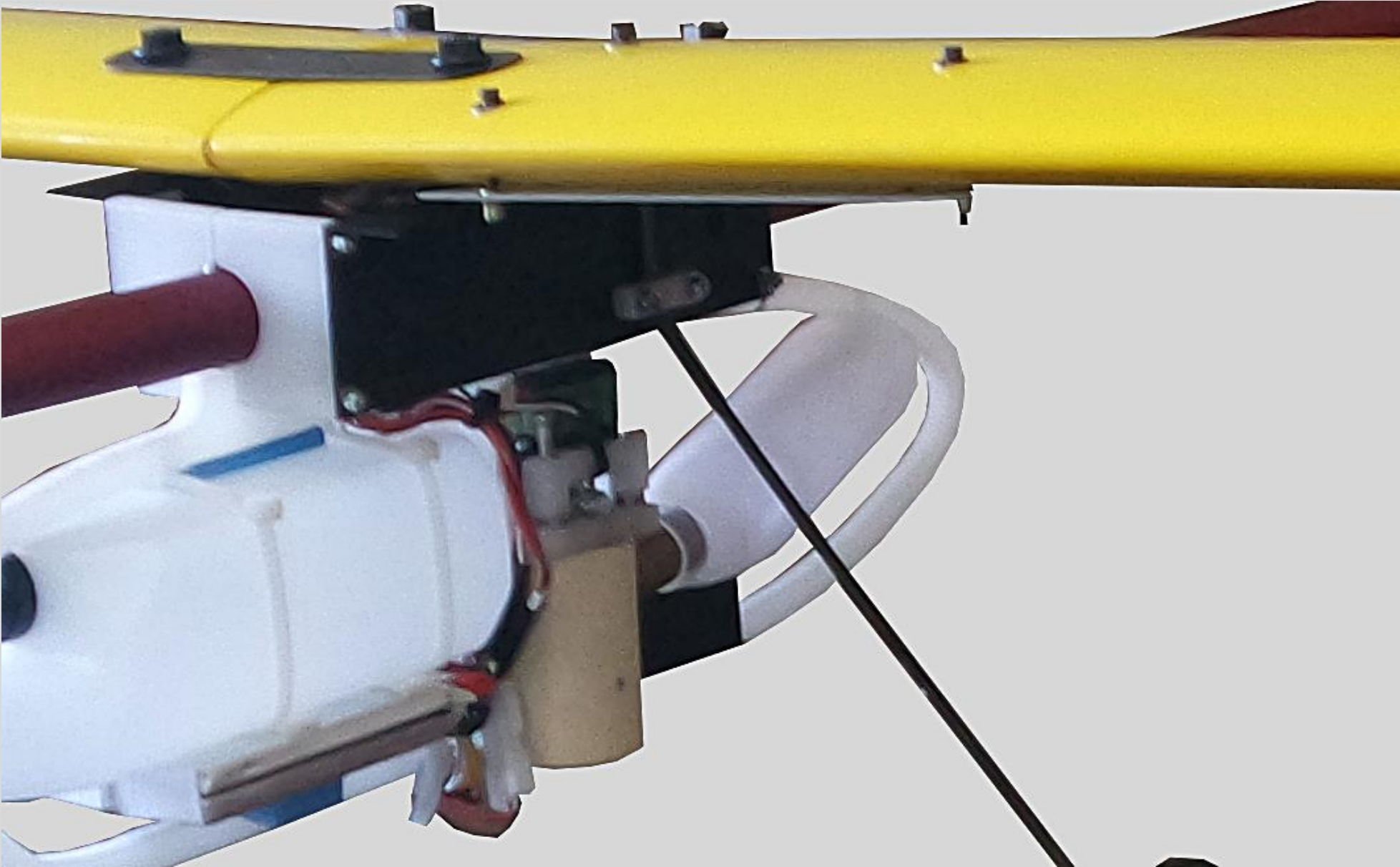
3,5Kg

750gr

70 Km/h

Aluminum, foam,  
wood

# Dispenser



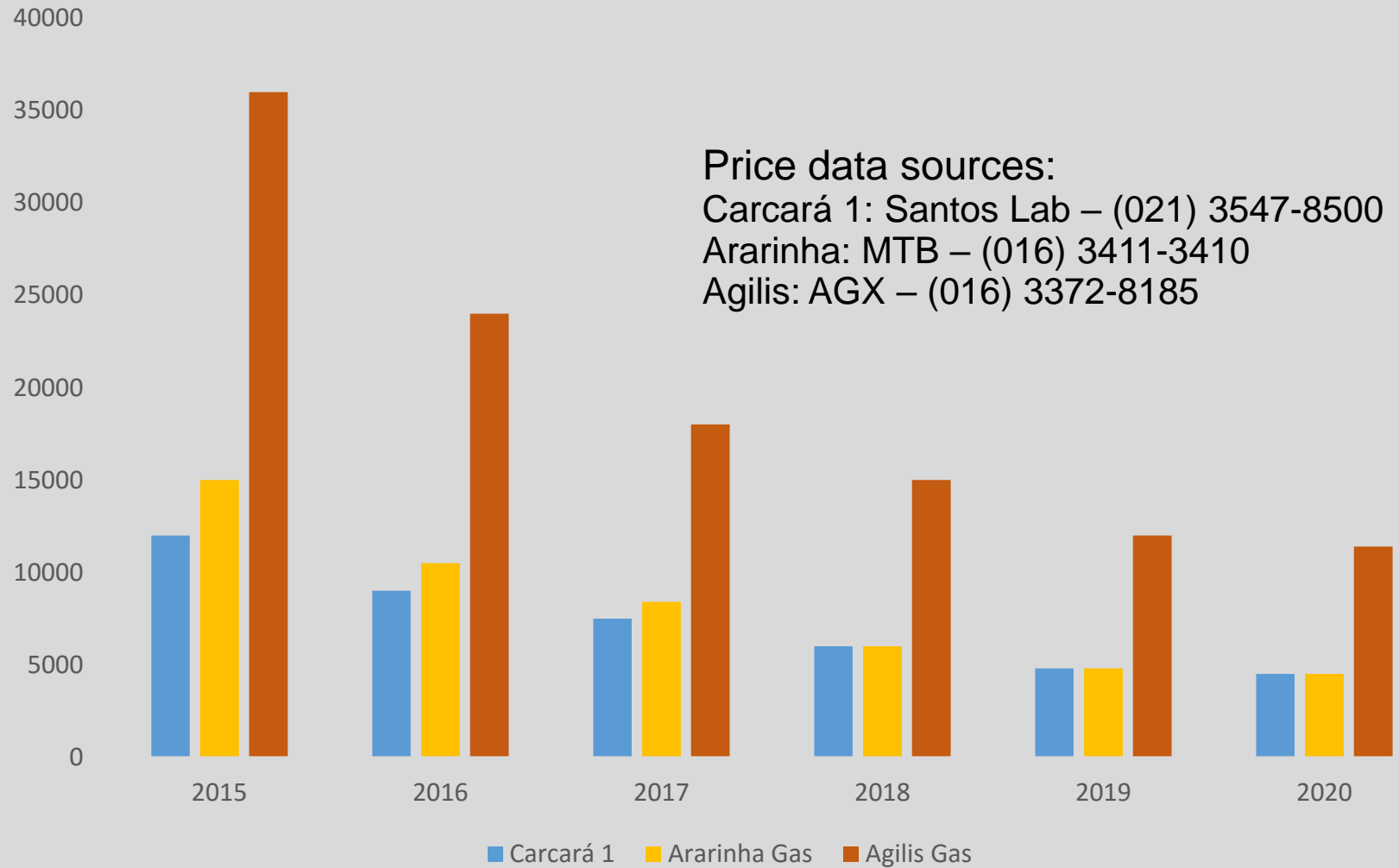
# Low Cost, Low Weight Sensors

Sensor Type	Spectrum	Spatial resolution	Weight	Price – US\$
Photographic Camera Small	Visible - RGB	21 Mpixels	250gr	400
Photographic Camera Small	Visible - RGB	29 Mpixels	350gr	600
Photographic Camera Medium Size	Visible - RGB	36 Mpixel	550gr	2000
Photographic Camera Full Frame - Big	Visible - RGB	51 Mpixel	1050gr	3700
Video camera	RGB	4Mpixel	20gr	200
Multispectral camera	R, G, NIR	3Mpixel	200gr	?
Thermal vídeo camera	8000 – 12000 um	0,25Mpixel	35gr	3000
Multispectral camera	4 to 12 bands	0,1Mpixel	500-1200gr	?

# The Good News

## Small UAVs Price Evolution in Brasil (R\$)

Minimal System Price (w/ 21Mpixel RGB Sensor)



# Final Remarks

- **Main expertise in UAV technology**
  - Aircraft design
  - Aircraft manufacturing
  - Development of electronic control systems (hardware and software)
  - UAV field operation experience
- **Focus on**
  - Intelligent flight (IFA) controlled by intelligent sensors (MOSA)
  - Quality assurance and certification
  - Commercial applications, mainly in agriculture and environment monitoring
  - Favorable cost/benefit ratio



Thank you!