

MAC5921 – Deep Learning

Aula 12 – 03/10/2023

Transformers

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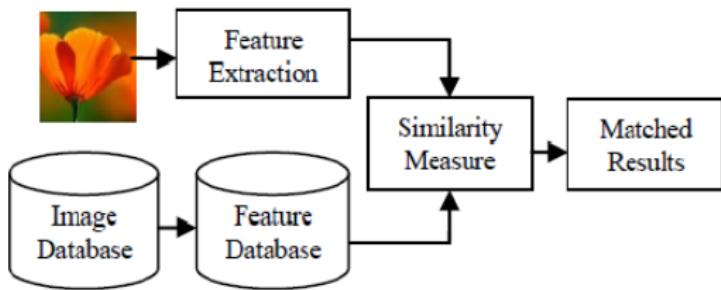
1. **Redes neurais convencionais** (*fully connected*)
2. **Redes neurais convolucionais** (CNN)
3. **Redes neurais recorrentes** (RNN)

Transformers – usa mecanismos de attention

Como funcionam buscas de objetos complexos?

- Imagens
- Documentos
- Vídeos
- Áudio
- etc

Exemplo: Busca de imagens em um banco de dados



Métricas de similaridade (dados multidimensionais)

https://en.wikipedia.org/wiki/Similarity_measure

Indexação multidimensional

Christian Böhm, Stefan Berchtold, and Daniel A. Keim. 2001.

**Searching in high-dimensional spaces: Index structures
for improving the performance of multimedia databases.**

ACM Comput. Surv. 33, 3 (September 2001), 322–373.

<https://doi.org/10.1145/502807.502809>

Similaridade coseno – fim da digressão

Comumente usado para comparar dois vetores de *features*

The cosine of two non-zero vectors can be derived by using the [Euclidean dot product](#) formula:

$$\mathbf{A} \cdot \mathbf{B} = \|\mathbf{A}\| \|\mathbf{B}\| \cos \theta$$

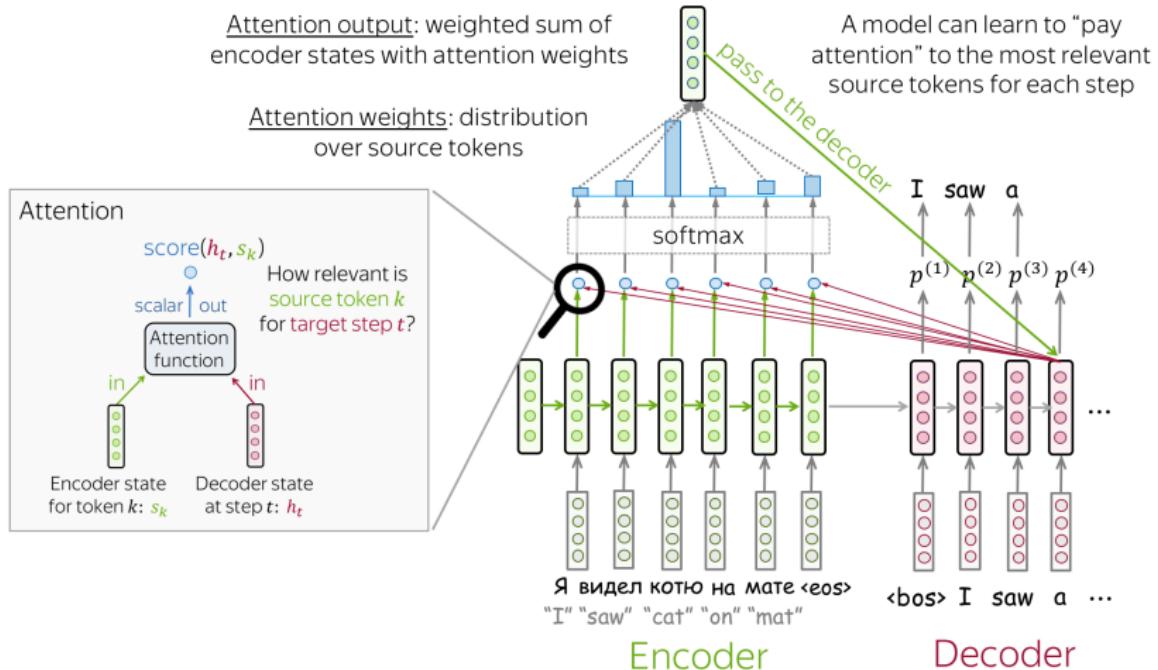
Given two n -dimensional [vectors](#) of attributes, \mathbf{A} and \mathbf{B} , the cosine similarity, $\cos(\theta)$, is represented using a [dot product](#) and [magnitude](#) as

$$\text{cosine similarity} = S_C(A, B) := \cos(\theta) = \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\| \|\mathbf{B}\|} = \frac{\sum_{i=1}^n A_i B_i}{\sqrt{\sum_{i=1}^n A_i^2 \cdot \sum_{i=1}^n B_i^2}},$$

where A_i and B_i are the i th [components](#) of vectors \mathbf{A} and \mathbf{B} , respectively.

Fonte: Wikipedia

Attention em redes recorrentes para tarefas seq2seq



https://lena-voita.github.io/nlp_course/seq2seq_and_attention.html

Estados do encoder: s_k

Estados do decoder: $h_t = f(h_{t-1}, \hat{y}_{t-1}, c_t)$

Saída do decoder: $\hat{y}_t = g(\hat{y}_{t-1}, h_t, c_t)$

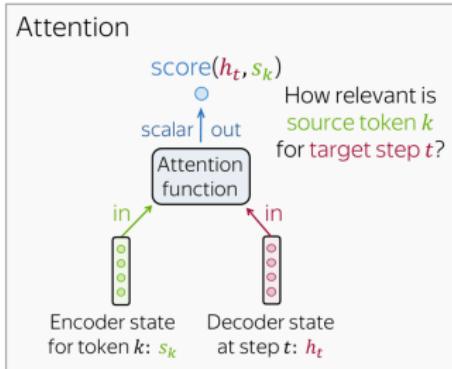
Vetor de contexto:

$$c_t = \sum_{k=1}^T \alpha_{tk} s_k$$

Escore de alinhamento e pesos:

$$e_{tk} = a(h_{t-1}, s_k) \quad \alpha_{tk} = \frac{\exp(e_{tk})}{\sum_{j=1}^T \exp(e_{tj})}$$

Exemplos de função de alinhamento



Dot-product

$$h_t^T \times s_k$$

$$\text{score}(h_t, s_k) = h_t^T s_k$$

Bilinear

$$h_t^T \times [W] \times s_k$$

$$\text{score}(h_t, s_k) = h_t^T W s_k$$

Multi-Layer Perceptron

$$w_2^T \times \tanh([W_1 \times h_t] s_k)$$

$$\text{score}(h_t, s_k) = w_2^T \cdot \tanh(W_1[h_t, s_k])$$

https://lena-voita.github.io/nlp_course/seq2seq_and_attention.html

Attention seria uma convolução com kernel igual ao tamanho da sequência de entrada??

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O kernel de convolução, após o treinamento, tem pesos fixos. Assim, independentemente do passo t na decodificação, sempre olharia os estados do *encoder* da mesma forma

O *attention* calcula dinamicamente o peso a ser dado para cada um dos estados do *encoder*

Ponto fraco das RNNs do tipo encoder-decoder

Recorrência – impossibilita paralelização

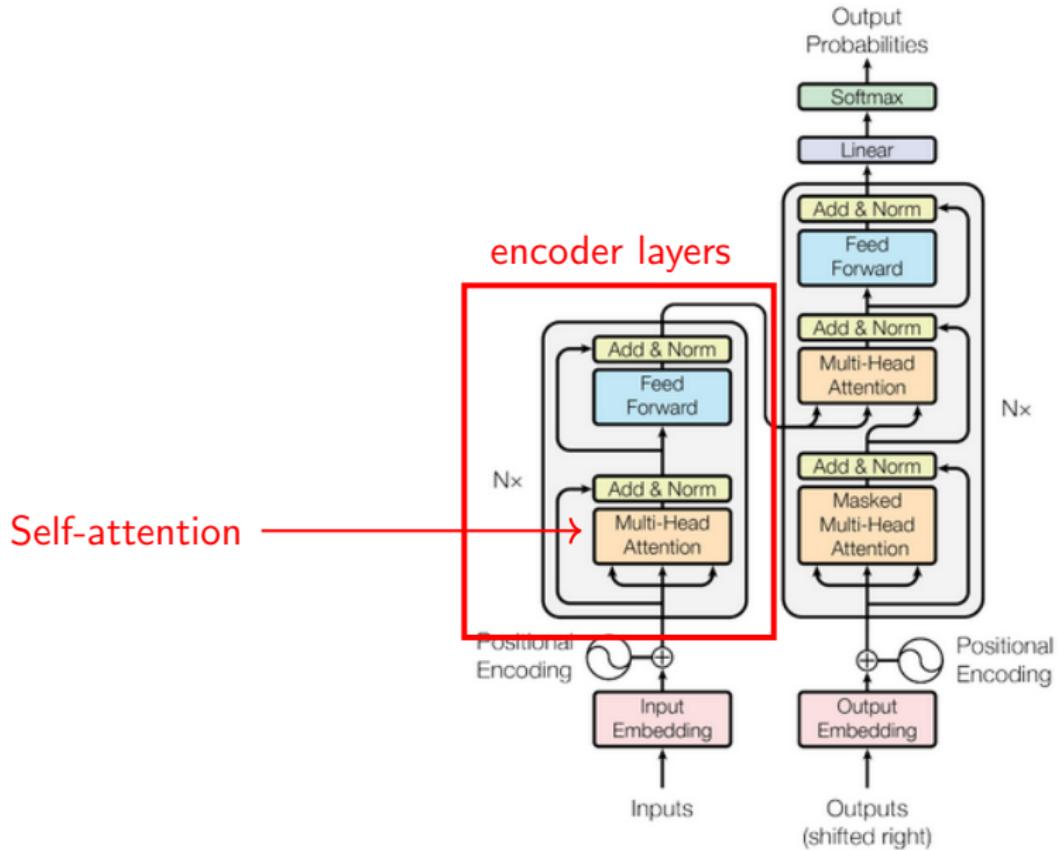
Transformers (2017)

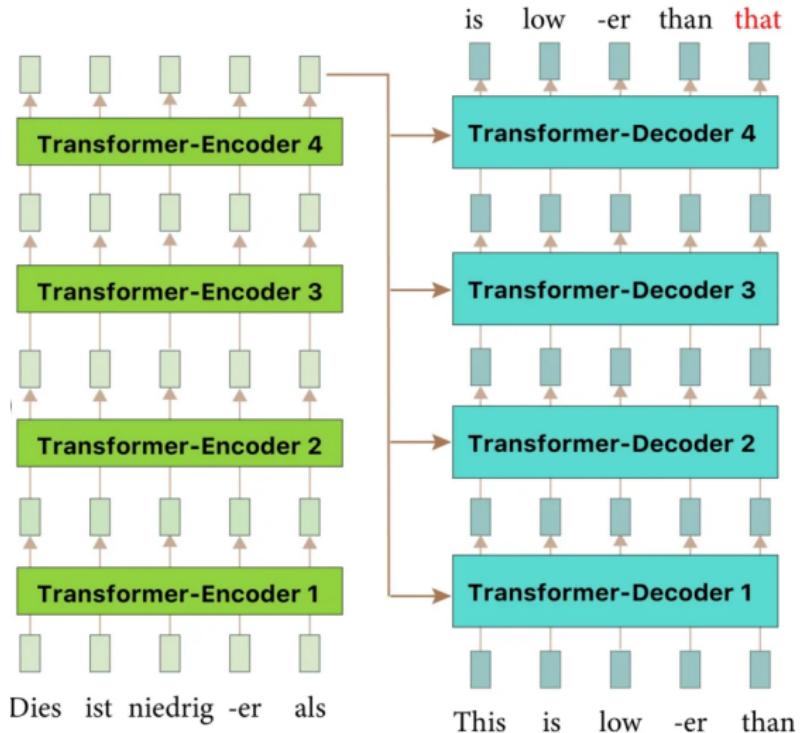
Attention Is All You Need

Ashish **Vaswani**, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones
Aidan N. Gomez, Łukasz Kaiser, Illia Polosukhin

<https://arxiv.org/abs/1706.03762>

– elimina recorrência + introduz self-attention





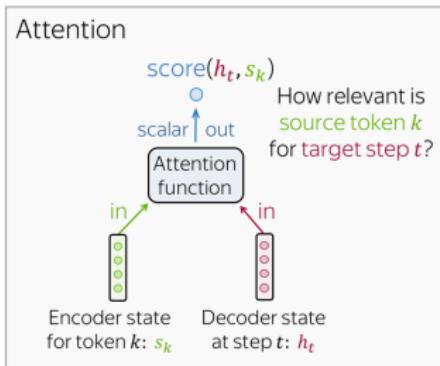
<https://cvml-expertguide.net/terms/dl/seq2seq-translation/transformer/> (adaptado)

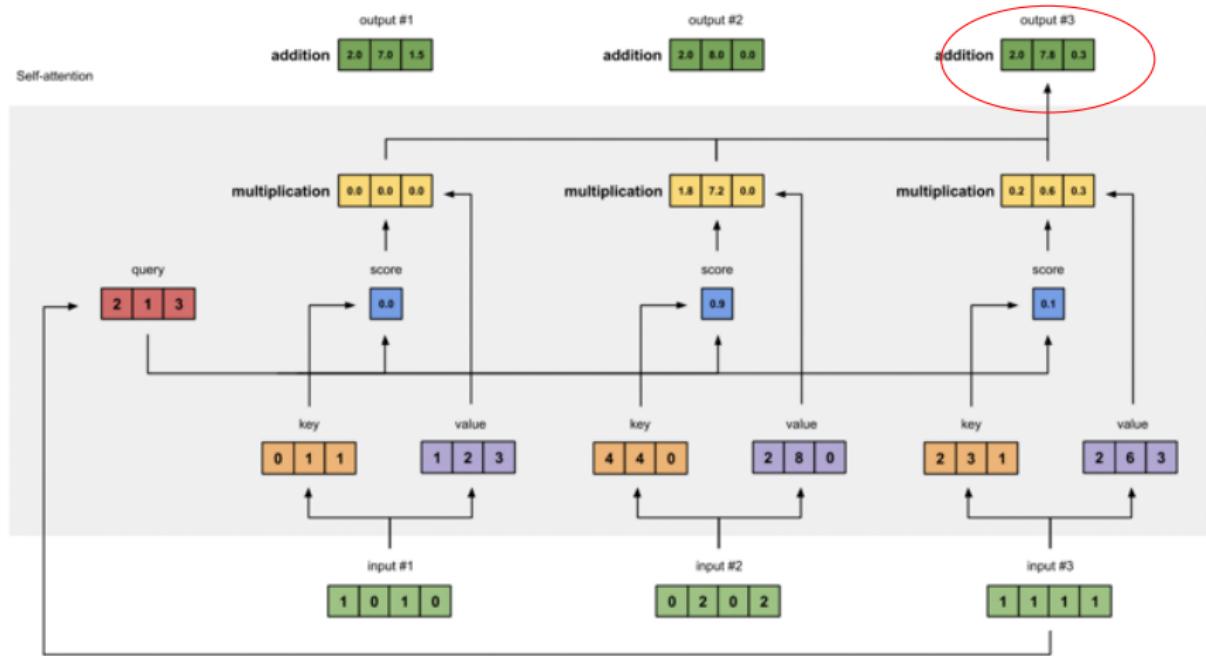
Self-attention

Calculada entre uma camada e outra no encoder (ou no decoder)
Relaciona um elemento a outros elementos na própria sequência

$$\text{Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$

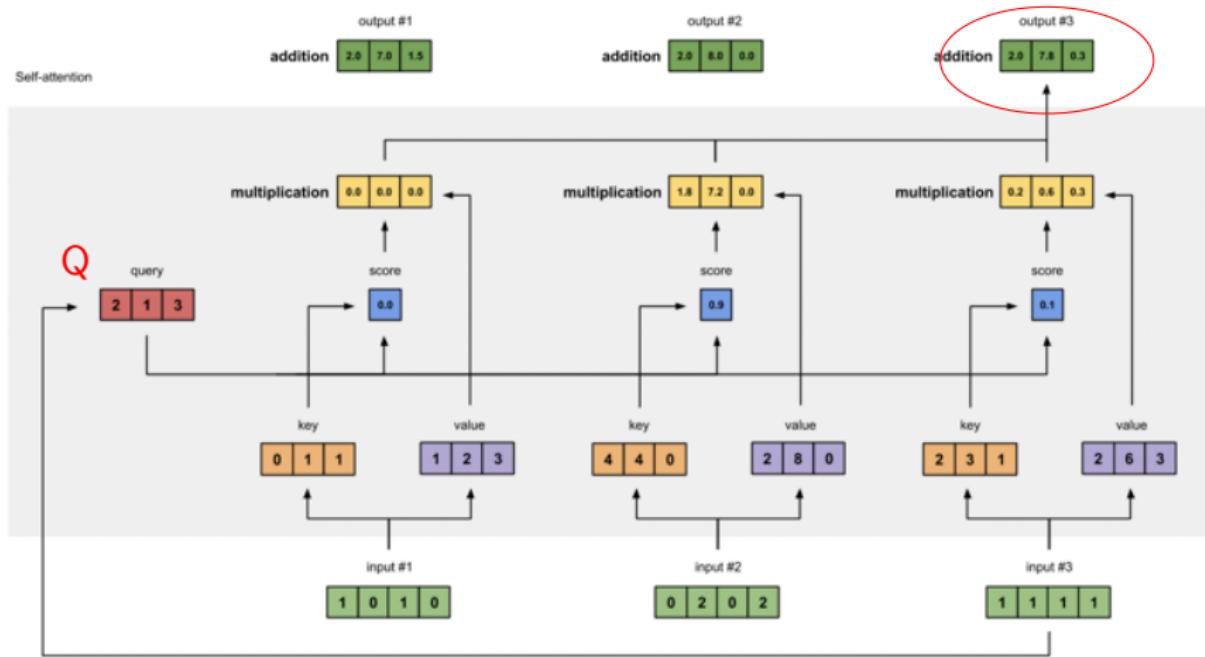
Q : query
 K : key
 V : value





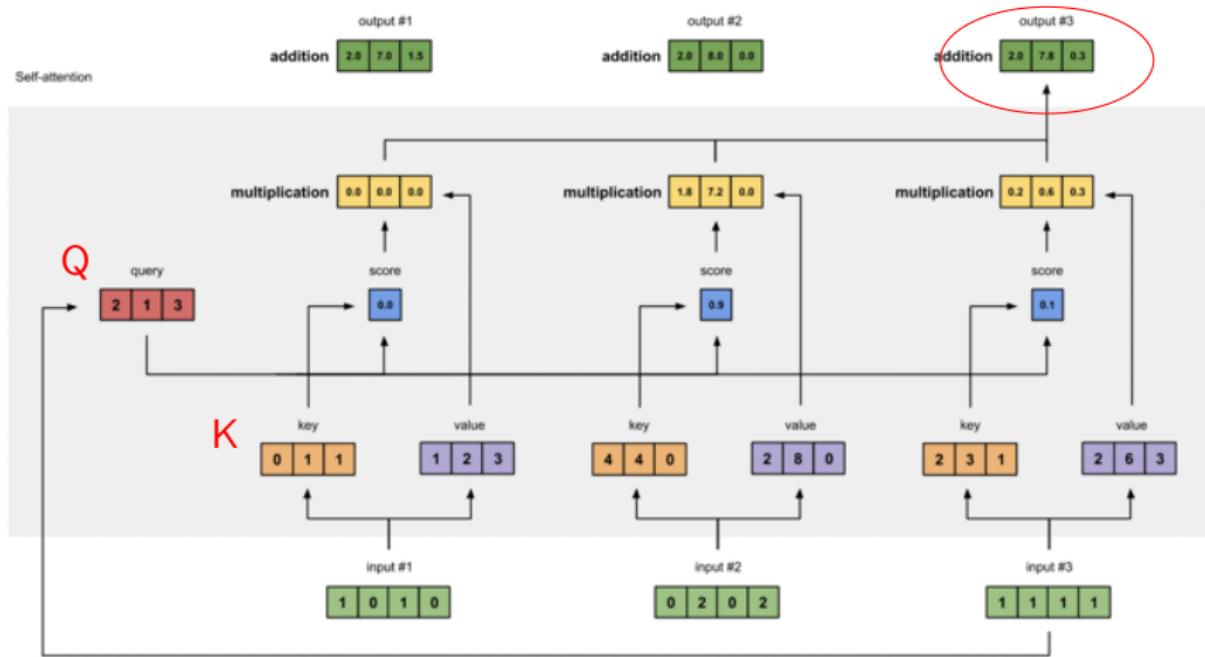
<https://towardsdatascience.com/illustrated-self-attention-2d627e33b20a>

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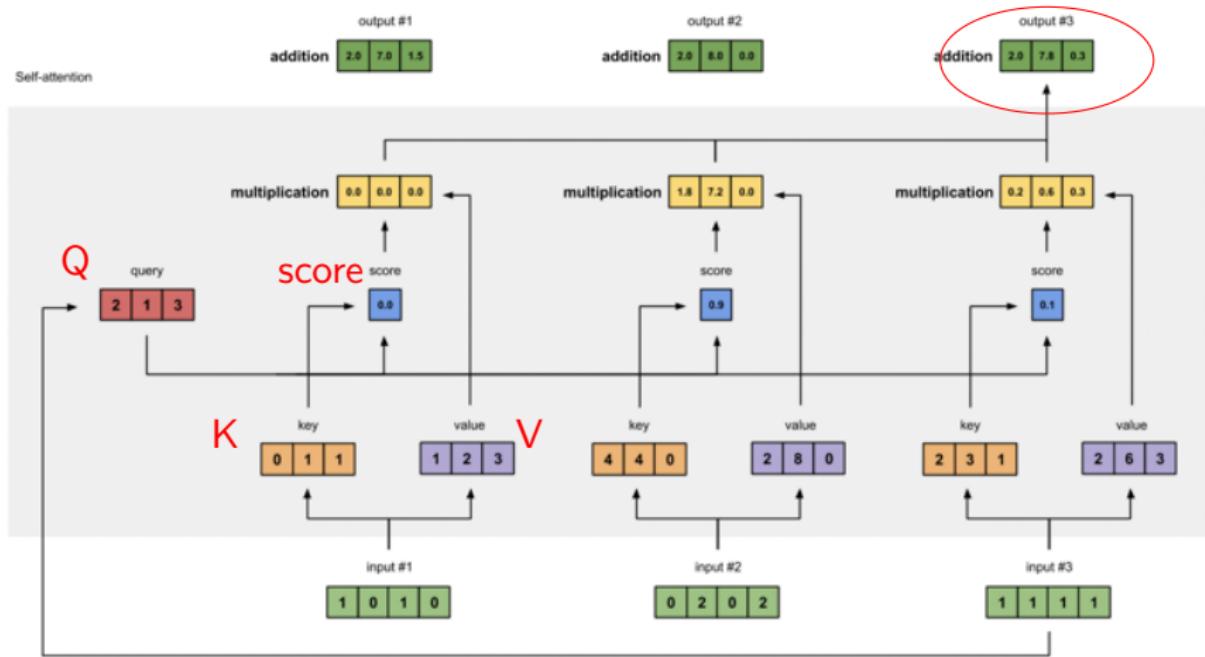
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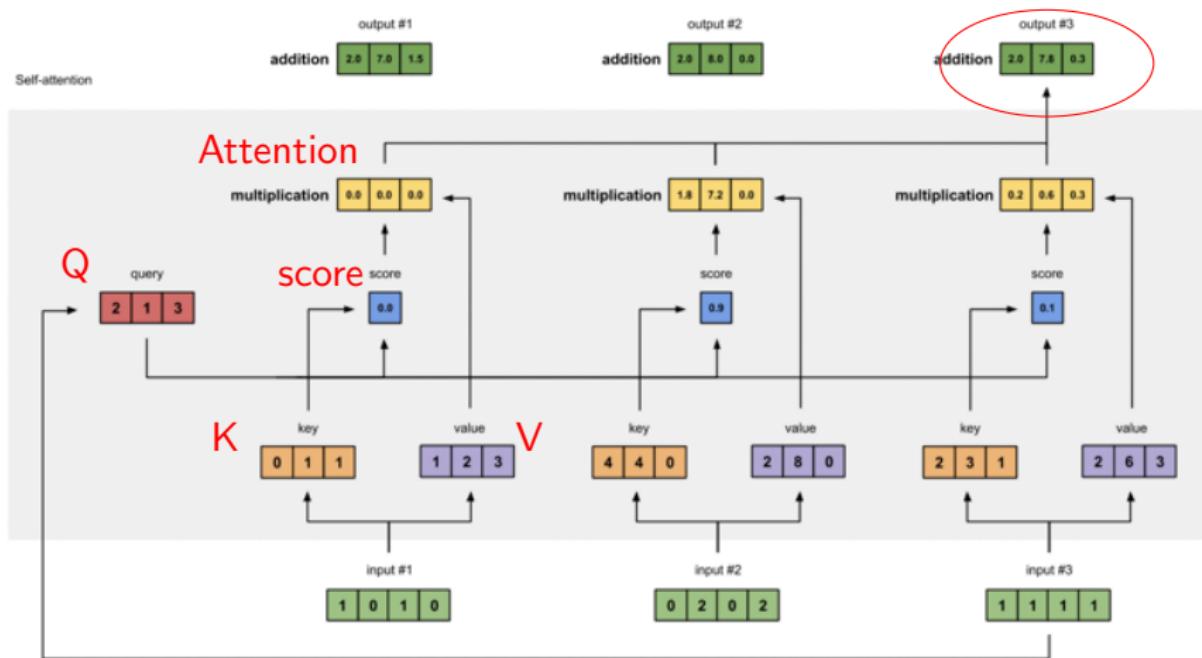
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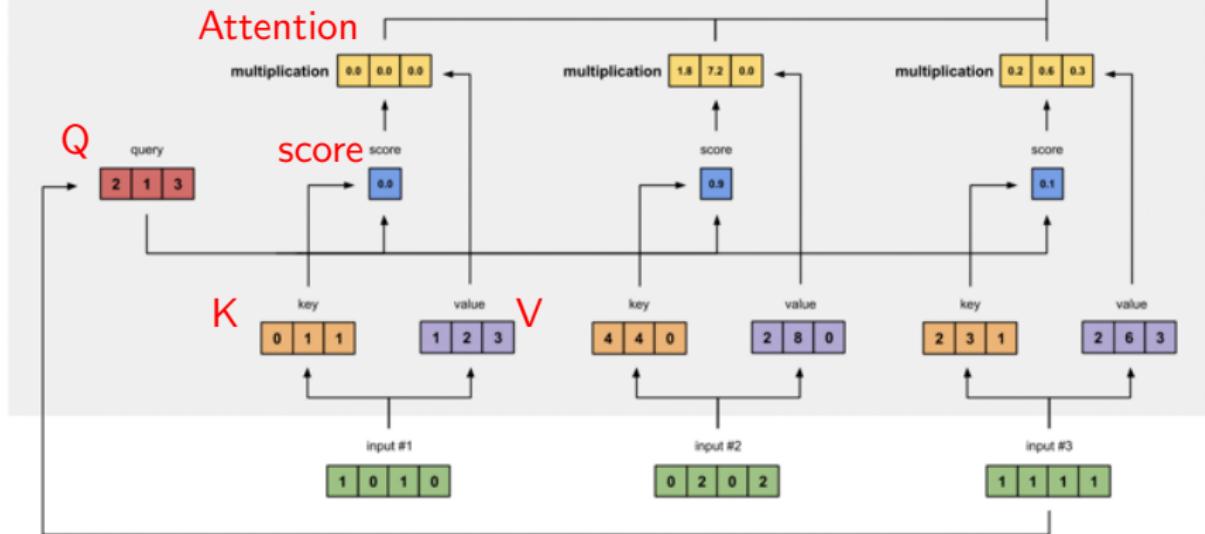
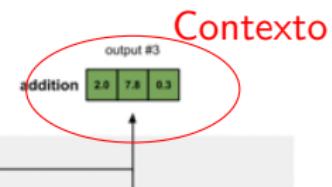
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Each vector receives three representations (“roles”)

$$[W_Q] \times [] = []$$

Query: vector **from** which
the attention is looking

“Hey there, do you have this information?”

$$[W_K] \times [] = []$$

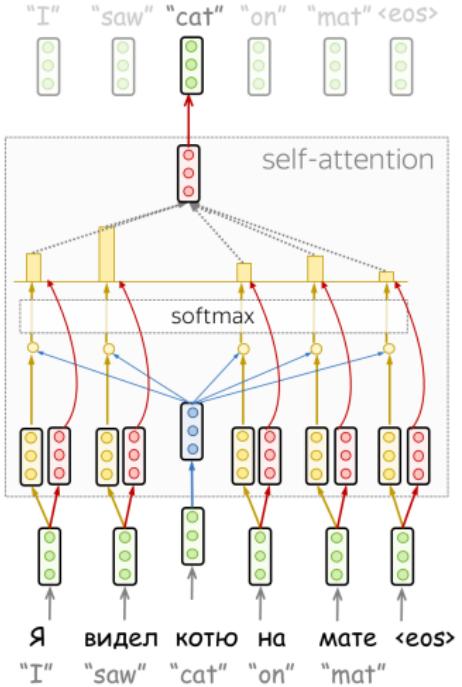
Key: vector **at** which the query
looks to compute weights

“Hi, I have this information – give me a large weight!”

$$[W_V] \times [] = []$$

Value: their weighted sum is
attention output

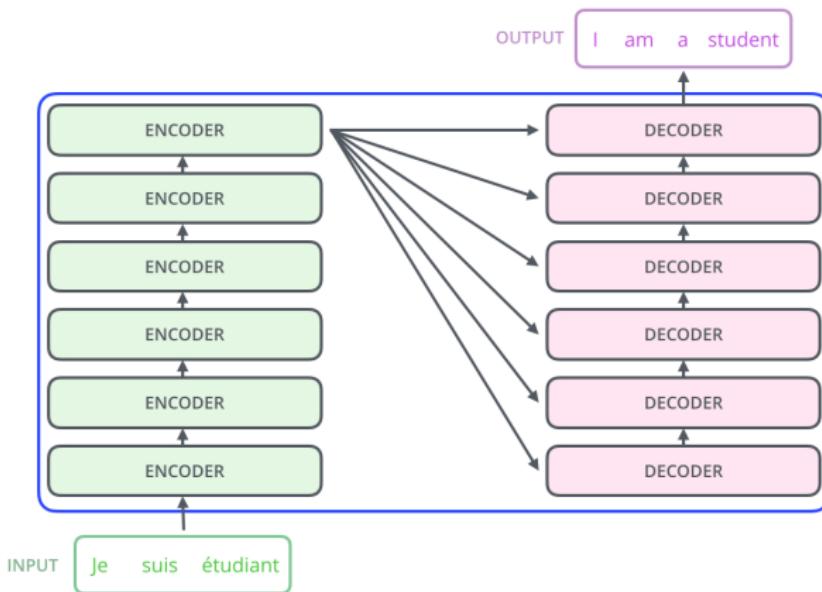
“Here’s the information I have!”



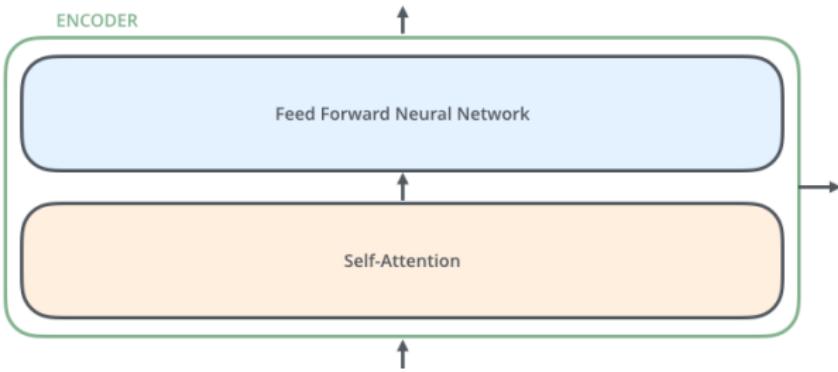
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Vários detalhes em

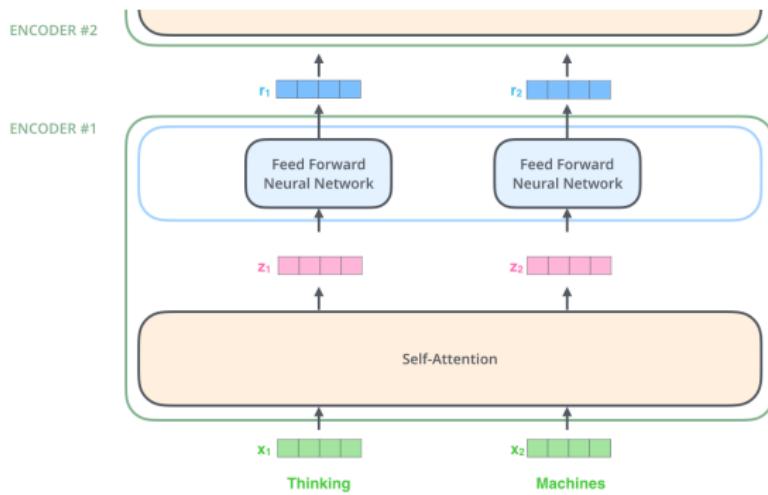
<https://jalammar.github.io/illustrated-transformer/>



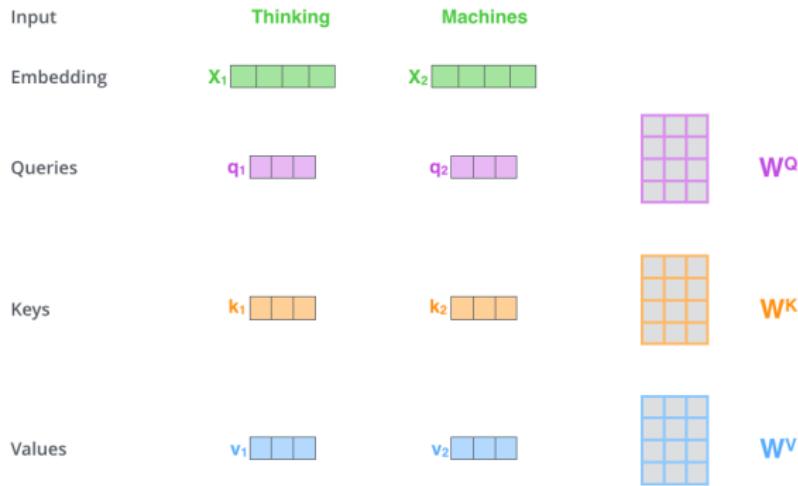
Visão geral de uma camada do encoder



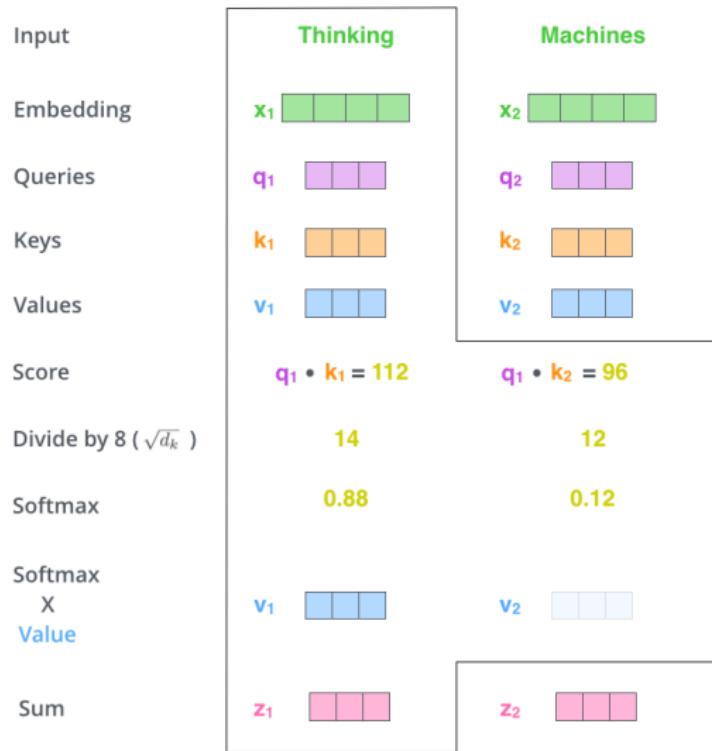
Visão mais detalhada de uma camada do encoder



Geração dos elementos (Q , K , V) usados no cálculo do attention



Context – saída da camada

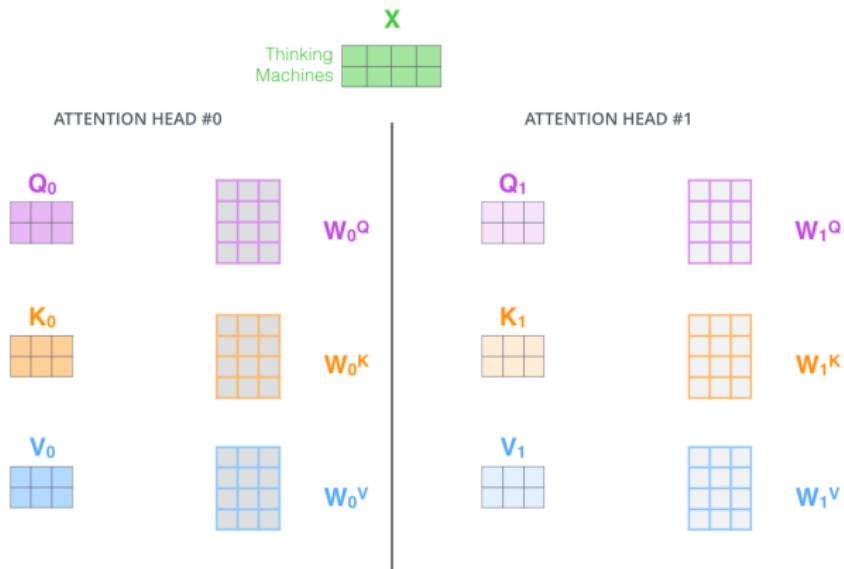


$$\text{Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$

Attention é calculada para todos os elementos da sequência em paralelo

$$\text{softmax} \left(\frac{\begin{matrix} \text{Q} & \times & \text{K}^T \\ \begin{matrix} \text{---} \end{matrix} & \quad & \begin{matrix} \text{---} \end{matrix} \end{matrix}}{\sqrt{d_k}} \right) \text{V}$$
$$= \begin{matrix} \text{Z} \\ \begin{matrix} \text{---} \end{matrix} \end{matrix}$$

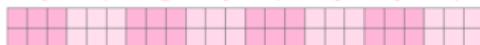
Podemos ter **Multi-head attention**
(análogo a múltiplos filtros na CNN)



Multi-head attention é calculada em paralelo

1) Concatenate all the attention heads

$Z_0 \quad Z_1 \quad Z_2 \quad Z_3 \quad Z_4 \quad Z_5 \quad Z_6 \quad Z_7$



2) Multiply with a weight matrix W^o that was trained jointly with the model

\times



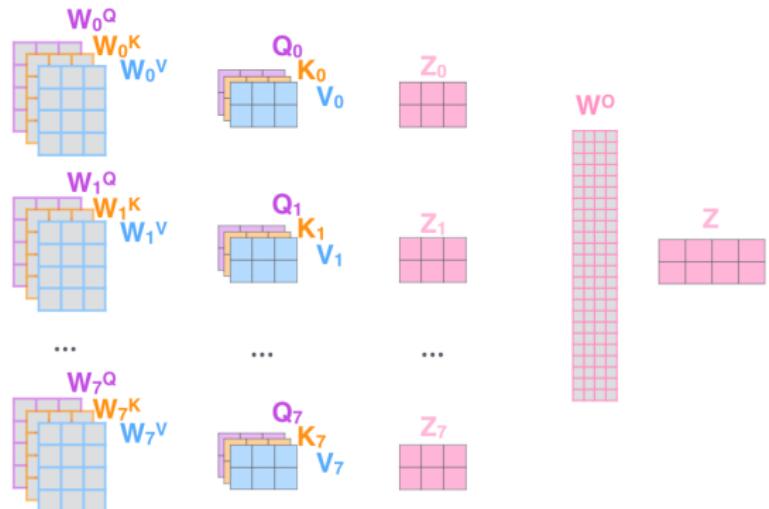
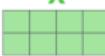
3) The result would be the Z matrix that captures information from all the attention heads. We can send this forward to the FFNN

$$= \begin{matrix} Z \\ \hline \end{matrix}$$

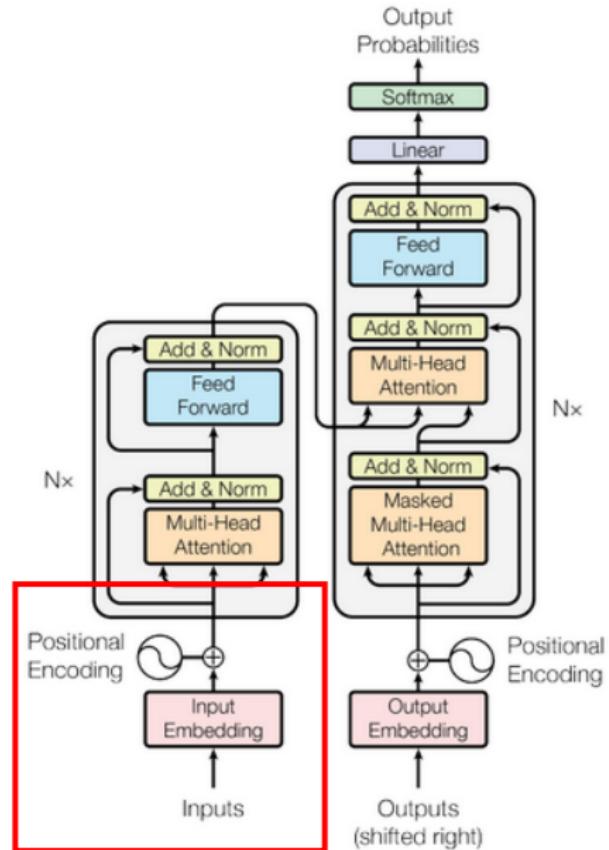
Visão geral com alguns detalhes

- 1) This is our input sentence*
- 2) We embed each word*
- 3) Split into 8 heads. We multiply X or R with weight matrices
- 4) Calculate attention using the resulting $Q/K/V$ matrices
- 5) Concatenate the resulting Z matrices, then multiply with weight matrix W^o to produce the output of the layer

Thinking Machines
 X



* In all encoders other than #0, we don't need embedding. We start directly with the output of the encoder right below this one



Positional encoding

Tokens and embedding