

# MATLAB

## An Introduction

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2015 BRAZIL STUDY ABROAD PROGRAM

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# Why Matlab?

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**Friendly environment**

**Simple programming language**

**Lots of tools**

**Can be applied in several areas of knowledge**

# First steps

## Interface

The image displays the MATLAB R2014a software interface. The main window shows the 'HOME' tab with various toolbars and a 'Command Window' displaying a prompt. A 'Current Folder' browser is visible on the left. Overlaid on this is the 'MATLAB' help browser, showing the 'Contents' pane with categories like 'Getting Started', 'User Guide', and 'Functions'. The main help content area displays 'Functions: By Category' and 'Alphabetical List', along with a 'What's New' section for 'MATLAB Release Notes'.

The 'Editor' window shows a script named 'EnergyForecastAnalysis.m' with the following code:

```
1 %% Energy Forecasting
2 % This demo showcases visualization and analysis (heavy statistics) for
3 % forecasting energy usage based on historical data. We have access to
4 % hour-by-hour utility usage for the month of January, including
5 % information on the day of the week and the Heating Degree Days (defined
6 % as 65 minus Average Temperature) of each day. Using this information, we
7 % will come up with an algorithm for forecasting future energy usage based
8 % on parameters such as day-type, forecasted temperature, and time of day.
9
10 % Copyright 2007 The MathWorks, Inc.
11
12 %% Load Data
13 % Load data from excel worksheet
14
15 close all;
16
17 fileName = 'January.xls';
18 energyData = xlsread(fileName, 'Liability', 'D2:AAS2');
19 DayType = xlsread(fileName, 'Weather', 'B2:BS2');
20 HDD = xlsread(fileName, 'Weather', 'C2:CS2'); %Heating Degree Days
21
22 numDays = size(energyData,1);
23 numHours = size(energyData,2);
24
25 allDays = {'Monday', 'Tuesday', 'Wednesday', 'Thursday', ...
26           'Friday', 'Saturday', 'Sunday'};
27
28 % Forecast for
29 dayOfWeek = 'Monday';
30 timeOfDay = 15 ; % 3PM
31
```

The 'Figure' window, titled 'Figure 1: Flotation kinetics', displays a plot of Flotation Time  $\tau$  [min] on the x-axis (ranging from 1.5 to 5) versus an unlabeled y-axis (ranging from 0.35 to 0.4). The plot shows experimental data points (red squares) and several fitted curves: Classical Model (blue), Klimpel Model (green), Kelsall Model (red), Modified Kelsall (cyan), Gamma Model (magenta), and Fully Mixed Model (yellow).

# First steps

---

## Programming language

```
>> a = 1+1
```

```
>> b = [1, 1, 2, 3, 5, 8, 13, 21]
```

```
>> x = a+b
```

```
x =
```

```
3, 3, 4, 5, 7, 10, 15, 23
```

# First steps

---

## Matlab's tools

- Vectors and matrices
- Plotting and graphics
- Symbolic calculus
- Differential equations
- Transforms
- Model fitting
- Simulink
- A lot of other tools...

# Hands on!

---

Try calculating those math operations:

$$5 \left( \frac{3}{4} \right) + \frac{9}{5} = 5.55$$

$$4^3 \left( \frac{3}{4} - \frac{9}{2 * 3} \right) = -48$$

# Hands on!

---

Find the volume of a beer can (consider the can as a cylinder):

The volume of a beer can be calculated by:

$$V = \pi r^2 h$$

$$r = 3 \text{ cm}$$

$$h = 12.5 \text{ cm}$$

# Hands on!

---

```
>> r = 3;
```

```
>> h = 12.5;
```

```
>> V = pi*3^2*12.5
```

```
V =
```

```
353.4292
```



# Other operators

---

Natural logarithm

```
>> log(a);
```

Base ten log

```
>> log10(a);
```

Exponential:

```
>> exp(a);
```

Trigonometric functions

```
>> cos(pi);
```

```
>> sin(pi);
```

```
>> tan(pi);
```

```
>> acos(pi);
```

```
>> asin(pi);
```

```
>> atan(pi);
```

Complex numbers

```
>> y = 5i;
```

```
>> z = 1+3*i;
```

```
>> w = 3j;
```

# Script file

---

Using script files, it's possible to save the work for later use or for recording data

It's very useful when there is a long sequence of operations

Let's create a script file:

- File -> New -> Script
- Or click on the New file icon on the toolbar at the top of the screen

# Script file

---

**Type in the script file:**

```
% Example 1: Using script file  
x = [1,2,3,4];  
y = exp(x)
```

Save the file as *example1.m*

# Script file

---

**At the command window, type:**

`>> example1`

# Vector and Matrices

---

When you work with data, you need to handle them sometimes.

Vectors are one-dimensional arrays.

```
>> a = [1, 2, 3]
```

```
a =
```

```
1 2 3
```

```
>> a = [1; 2; 3]
```

```
a =
```

```
1
```

```
2
```

```
3
```

```
>> a'
```

```
=
```

```
1 2 3
```

# Vector and Matrices

---

Matlab allows you to append vectors together to create new ones.

Let **u** and **v** be two column vectors *m* and *n* respectively.

What happens if I type:

```
>> w = [u; v]
```

# Vector and Matrices

---

```
>> w = [u; v];  
>> size(w)  
ans =  
    m+n
```

The same works for row vectors as well

# Vector and Matrices

---

It is possible to create uniformly spaced vector using colons:

```
>> t = [0:10]
```

```
t =
```

```
0  1  2  3  4  5  6  7  8  9 10
```



# Vector and Matrices

---

You can also change the step size of the vector using the syntax:

```
>> t = [0:2:10]
```

```
t =
```

```
0    2    4    6    8   10
```

# Hands on!

---

Using a script file, try to create a time vector **t** from 0 to 10 using 1 as step size. Then, create a vector **y = 1-exp(-t)**.

After that, create an vector **t2** from 0 to 10 using 0.1 as step size and a vector **y2 = 1-exp(-t2)**.

# Hands on!

---

First, the vector **t**:

```
>> t = [0:10];
```

Then, the vector **y**:

```
>> y = 1-exp(-t);
```

The vector **t2** and **y2**:

```
>> t2 = [0:0.1:10]; y = 1-exp(-t2);
```

# Hands on! (Plus)

---

Using the command *plot*, try to plot **txy** and **t2xy2** in the same figure.

## Tips:

The syntax for plot is plot(**a**,**b**).

**a** and **b** must be the same length.

You can plot more than one couple using the syntax (**a,b,c,d**).

# Extracting information of the vectors

---

There are several commands to get information from vectors.

Some examples are:

```
>> f = [1 4 -6 3 7 9 -2 6 3 -7...  
4 9 19];
```

```
>> length(f)
```

```
ans =  
  
13
```

```
>> max(f)
```

```
ans =  
  
19
```

```
>> min(f)
```

```
ans =  
  
-7
```

# Extracting information of the vectors

---

First of all, we need the dot product of the vector **v**.

Let's define **v = [4 6 9]**.

The array product of **v** is given by:

```
>> v.*v  
ans =  
16    36    81
```

# Extracting information of the vectors

---

Then, we need to sum the dot product of the vector **v**:

```
>> a = sum(v.*v)
```

```
a =
```

```
133
```

The magnitude of **v** is the square root of a.

```
>> mag = sqrt(a)
```

```
mag =
```

```
11.5325
```

# Operation with matrices

---

A matrix is a two-dimensional array of numbers. To create a matrix in Matlab, we enter each row as a sequence of comma (or space), and then use semicolons to mark the end of each row.

For example:

```
>> A = [1, 4; 5 2]
```

```
A =
```

```
1 4
```

```
5 2
```

```
>> 2*A
```

```
ans =
```

```
2 8
```

```
10 4
```



# Operation with matrices

---

If two matrices have the same size, we can add or subtract them:

```
>> B = [1 3; -1 -4];
```

```
>> A+B
```

```
ans =
```

```
2    7
```

```
4   -2
```

# Operation with matrices

---

We can also compute the transpose of a matrix. The transpose operation switch the rows and columns in a matrix.

```
>> A'
```

```
ans =
```

```
1 5
```

```
4 2
```

# Operation with matrices

---

If the matrix contains complex elements, the transpose will compute the conjugates:

```
>> C = [1+i, 4-i; 5+2i, 3-3i]
```

```
C =
```

```
1+1i  4-i
```

```
5+2i  3-3i
```

```
>> C'
```

```
ans =
```

```
1-1i  5-2i
```

```
4+i   3+3i
```

# Operation with matrices

---

If you want to compute the transpose of a matrix with complex elements without computing the conjugate, you use (.'):

```
>> C'
```

```
ans =
```

```
1+1i    5+2i
```

```
4-i     3-3i
```

# Operation with matrices

---

The array multiplication works with matrix as well. It is important to recognize that this is not matrix multiplication.

```
>> A = [1, 4; 5 2]; B = [1 3; -1 -4];
```

```
>> A.*B
```

```
ans =
```

```
1 12
```

```
-5 -8
```

# Matrix multiplication

---

Let's consider two matrices:

```
>> C = [2, 1; 1, 2]; D = [3, 4; 5, 6];
```

The multiplication between them will be:

```
>> C*D
```

```
ans =
```

```
11    14
```

```
13    16
```

# Special matrix types

---

The identify matrix is a square matrix that has ones along the diagonal and zeros elsewhere. To create a n-order identify matrix, type:

```
>> eye(n);
```

```
>> eye(2)
```

```
ans =
```

```
1    0
```

```
0    1
```

# Special matrix types

---

**To create a matrix of zeros, type:**

```
>> zeros(n)      % n-order matrix of zeros
```

```
>> zeros(m,n)   % mxn matrix of zeros
```

**To create a matrix of ones, type *ones(n)* or *ones(m,n)*.**



# Referencing matrix elements

---

Individuals elements and columns in a matrix can be referenced using Matlab. Consider the matrix:

```
>> A = [1 2 3; 4 5 6; 7 8 9]
```

```
A =
```

```
1 2 3
```

```
4 5 6
```

```
7 8 9
```

# Referencing matrix elements

---

We can pick out the element at row position **m** and column position **n** by typing  $A(m,n)$ .

**For example:**

```
>> A(2,3)
```

```
ans =
```

```
6
```

# Referencing matrix elements

---

To reference all elements in the *ith* column, we write  $A(:,i)$ .

```
>> A(:,2)
```

```
ans =
```

```
2
```

```
5
```

```
8
```

# Referencing matrix elements

---

To pick out the elements in the *ith* through *jth* column, we type  $A(:,i:j)$ .

```
>> A(:,2:3)
```

```
ans =
```

```
2   3
```

```
5   6
```

```
8   9
```

# Referencing matrix elements

---

We can pick out pieces or sub matrices as well.

```
>> A(2:3,1:2)
```

```
ans =
```

```
4 5
```

```
7 8
```

# Referencing matrix elements

---

We can change the value of matrix elements using these references as well.

```
>> A(1,1) = -8
```

```
ans =
```

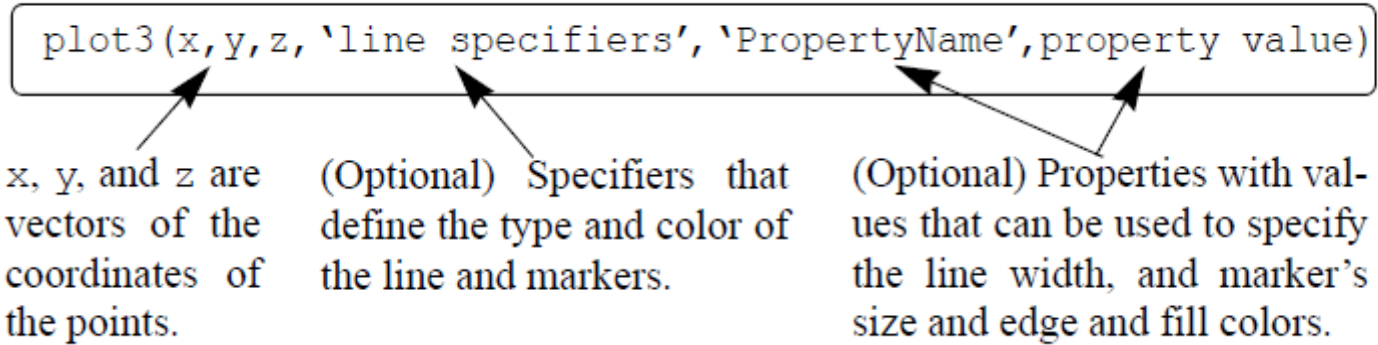
```
-8    2    3
```

```
4    5    6
```

```
7    8    9
```

# Three-Dimensional Plots

---



# Hands on!

---

example, if the coordinates  $x$ ,  $y$ , and  $z$  are given as a function of the parameter

$t$  by:

$$x = \sqrt{t} * \sin(2*t)$$

$$y = \sqrt{t} * \cos(2*t)$$

$$z = 0.5*t$$

$$\text{For } 0 \leq t \leq 6*\pi$$

Using the command `plot3`, try to plot `tx(x,y,z)` in the same figure.



# Hands on!

---

```
t=0:0.1:6*pi;  
x=sqrt(t).*sin(2*t);  
y=sqrt(t).*cos(2*t);  
z=0.5*t;  
plot3(x,y,z,'k','linewidth',1)  
grid on  
xlabel('x'); ylabel('y'); zlabel('z')
```

# Determinants and Linear Systems

---

To calculate the determinant of a matrix A in Matlab, simply write `det(A)`.

**For example:**

```
>> A = [1 3; 4 5]; det(A)  
ans =  
-7
```

# Determinants and Linear Systems

---

Consider the following set of equations:

$$5x+2y-9z=44$$

$$-9x-2y+2z=11$$

$$6x+7y+3z=44$$

To find a solution to a system of equations like this, we can use two steps.

# Determinants and Linear Systems

---

First, we find the determinant of the coefficient matrix A:

$$A = \begin{pmatrix} 5 & 2 & -9 \\ -9 & -3 & 2 \\ 6 & 7 & 3 \end{pmatrix}$$

```
>> A = [5 2 -9; -9 -3 2; 6 7 3]; det(A)
```

```
ans =
```

```
368
```

When the determinant is nonzero, a solution exists. This solution is the column vector:

$$X = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

# Determinants and Linear Systems

---

Matlab allows us to generate the solution readily using left division. First we need create a column of the numbers on right-hand side of the system. We find:

```
>> b = [44; 11; 5];  
>> A\b  
ans =  
[-5.1250 7.6902 -6.0272]'
```

# Determinants and Linear Systems

---

Another way to solve linear system problems is check the rank of the system. Let's consider the linear system of equations with **m** equations and **n** unknowns:

$$\mathbf{Ax}=\mathbf{b}$$

The augmented matrix is formed by concatenating the vector **b** onto the matrix **A**.

$$[\mathbf{A} \ \mathbf{b}]$$

# Determinants and Linear Systems

---

The system has a solution if and only if  $\text{rank}(\mathbf{A}) = \text{rank}([\mathbf{A} \ \mathbf{b}])$ . If the rank is equal to  $n$ , then the system has a unique solution.

If  $\text{rank}(\mathbf{A}) = \text{rank}([\mathbf{A} \ \mathbf{b}])$  but the rank  $< n$ , there are infinite number of solutions. If we denote the rank by  $r$ , then  $r$  of the unknown variables can be expressed as linear combination of  $n-r$  the other variables.

# Determinants and Linear Systems

---

To compute the rank of a matrix, you can use the Matlab command `rank(A)`, for example.

```
>> rank(A);
```



# Hands on!

---

Let's consider the linear system

$$x-2y+z=12$$

$$3x+4y+5z=20$$

$$-2x+y+7z=11$$

Find the solution using the Matlab command *rank* and the left division.

# Inverse and pseudoinverse of a matrix

---

Matlab has commands to compute the inverse and pseudoinverse of a matrix. The syntax is:

```
>> A = [1, 2; 3, 4];  
>> inv(A); %For inverse of the matrix A  
>> pinv(A); %For the pseudoinverse of  
the matrix A
```

# Decomposition of a matrix

---

Matlab can compute the LU decomposition of a matrix using the command *lu*.

```
>> A = [1 2 3; 3 2 1; 7 5 11]; b = [4; 2; -1];
```

```
>> [L,U] = lu(A);
```

L =

```
0.1429 1.0000 0
0.4286 -0.1111
1.0000
1.0000 0 0
```

U =

```
7.0000 5.0000 11.0000
0 1.2857 1.4286
0 0 -3.555659
```

# Decomposition of a matrix

---

Matlab can compute the LU decomposition of a matrix using the command *lu*.

```
>> A = [1 2 3; 3 2 1; 7 5 11]; b = [4; 2; -1];
```

```
>> [L,U] = lu(A);
```

L =

```
0.1429  1.0000  0
0.4286 -0.1111  1.0000
1.0000  0  0
```

U =

```
7.0000  5.0000  11.0000
0  1.2857  1.4286
0  0  -3.5556
```

# Decomposition of a matrix

---

To solve the linear system, you need to solve the equation:

$$x = U \setminus (L \setminus b)$$

```
>> x = U \setminus (L \setminus b)
```

```
x =
```

```
-1.8125
```

```
4.1250
```

```
-0.8125
```

# Checkpoint

---

Let's put our hands on practical programming things.  
Go to EESC Moodle's website and download the file Checkpoint  
1.pdf

# References

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**[1] Matlab Product Help.**

**[2] Matlab Demystified. A Self-Teaching Guide, David McMahan, McGraw Hill.**

**[3] Matlab: An Introduction with Applications, Amos Gilat, Fourth Edition,  
JOHN WILEY & SONS.**