



1) a) Problema do Consumidor: $\max_{c_t, \alpha_{t+1}, n_t} \sum_{t=0}^{\infty} \beta^t u(c_t, l-n_t, g_t)$
 s.t. $\sum_{t=0}^{\infty} g_t (c_t + \alpha_{t+1} - (l-\delta)\alpha_t) = \sum_{t=0}^{\infty} g_t ((l-\tau_{n_t}) w_t n_t + (l-\tau_{n_t}) v_t \alpha_t)$

$$C.P.O.: [c_t] \beta^t u_{c_t} = \lambda g_t \quad (1)$$

$$[n_t] \beta^t u_{n_t} = \lambda g_t (l - \tau_{n_t}) w_t \quad (2)$$

$$[\alpha_{t+1}] \lambda g_t = \lambda g_{t+1} [(1-\delta) + (l-\tau_{n_t}) v_t] \quad (3)$$

$$C.T.: \lim_{t \rightarrow \infty} \beta^t u_{c_t} \alpha_{t+1} = 0$$

Normalização: $g_0 = 1$

$$\stackrel{(1)}{\Rightarrow} \lambda = u_{c_0} \Rightarrow g_t = \beta^t \left(\frac{u_{c_t}}{u_{c_0}} \right) \quad (4)$$

$$\stackrel{(4)+(2)}{\Rightarrow} \frac{u_{n_t}}{u_{c_0}} = (l - \tau_{n_t}) w_t \quad (5)$$

$$\stackrel{(4)+(3)}{\Rightarrow} u_{c_t} = \beta^t u_{c_{t+1}} [(1-\delta) + (l-\tau_{n_t}) v_t] \quad (6)$$

b) Problema da Firma: $\max_{\alpha_t, n_t} F(\alpha_t, n_t) - r_t \alpha_t - w_t n_t$

$$C.P.O.: [\alpha_t] F_{\alpha_t} = r_t$$

$$[n_t] F_{n_t} = v_t$$

c) O equilíbrio é uma sequência $\{c_t, \alpha_{t+1}, n_t, g_t\}_{t=0}^{\infty}$ tal que:

(i) O problema do consumidor é resolvido, i.e., a utilidade U é maximizada;

(ii) No market clearing: $\begin{cases} n_t^s = n_t^d \\ c_t + \alpha_{t+1} - (l-\delta)\alpha_t + g_t = F(\alpha_t, n_t) \end{cases}$

Dados $\{g_t, w_t, v_t\}_{t=0}^{\infty} \in \mathcal{K}_0$

$$d) \text{ Da R.O.: } \sum_{r=0}^{\infty} q_r (c_r + \alpha_{r+1} - (1-\delta)\alpha_r) = \sum_{r=0}^{\infty} q_r ((1-\tau_{ar}) w_{r+1} + (1-\tau_{ar}) v_r + \alpha_r) \\ \Rightarrow \sum_{r=0}^{\infty} q_r (c_r - (1-\tau_{ar}) w_r + \alpha_r) = \sum_{r=0}^{\infty} q_r [(1-\tau_{ar}) v_r \alpha_r + (1-\delta) \alpha_{r+1} - \alpha_r]$$

$$\Rightarrow \sum_{r=0}^{\infty} q_r (c_r - (1-\tau_{nr}) u_r n_r) = q_0 [(1-\tau_{n0}) v_0 + (1-\delta)] \alpha_0$$

$$- q_0 \alpha_1 + q_1 [(1-\tau_{n1}) v_1 + (1-\delta)] \alpha_1$$

$$- q_1 \alpha_2 + q_2 [(1-\tau_{n2}) v_2 + (1-\delta)] \alpha_2 \quad \left. \right\} \text{Equação de Euler}$$

$$+ \dots$$

C.T. $\rightarrow 0$

$$+ \lim_{r \rightarrow \infty} q_r \alpha_{r+1}$$

$$\Rightarrow \sum_{r=0}^{\infty} q_r \left(c_r - \underbrace{(1-\tau'_{n,r}) u_r}_{(4)} n_r \right) = q_0 \left[(1-\tau'_{\alpha,0}) v_0 + (L-\xi) \right] K_0$$

$$\Rightarrow \sum_{r=0}^{\infty} \beta^r \frac{u_r}{u_{\alpha,0}} \left(c_r - \underbrace{\left(\frac{u_{r+1}}{u_r} \right) n_r}_{(5)} \right) = \left[(1-\tau'_{\alpha,0}) v_0 + (L-\xi) \right] K_0$$

$$(4) q_r = \beta^+ \left(\frac{u_{cr}}{u_{co}} \right)$$

$$(5) \quad \underline{u_{ct}} = (1 - T_{nr}) u_s$$

$$\Rightarrow \sum_{n=0}^{\infty} \beta^n [u_{cr} c_+ - u_{ss, n+}] = u_{cr} u_0 [(1-\tau_{\alpha}) r_0 + (1-\delta)]$$

$$e) \text{ Problema de Romney: } \underset{\alpha_{ct}, n_{ct}, \alpha_{nt}, g_t}{\max} \sum_{t=0}^{\infty} \beta^t u(c_t, l_t, g_t)$$

s.t.

$$\begin{cases} c_t + \alpha_{ct+1} - (L-\delta)\alpha_{ct} + g_{t+1} = F(\alpha_{ct}, n_{ct}) & \forall t \\ \sum_{t=0}^{\infty} \beta^t [u_{ct} c_t - u_{at} n_{ct}] = u_{co} \alpha_{co} [(L-\delta) + (L-\alpha_{co}) n_{co}] \end{cases}$$

$$\Leftrightarrow \max_{c_t, n_t, \alpha_t, g_t} \sum_{t=0}^{\infty} \left\{ \beta^t u(c_t, l_t, g_t) - \delta_t [c_t + \alpha_{t+1} - (1-\delta)\alpha_t + g_t - F(\alpha_t, n_t)] + \mu \sum_{t=0}^{\infty} \beta^t [u_{ct} c_t + u_{nt} n_t] \right. \\ \left. - \mu u_{co} \alpha_0 [(1-\delta) + (1-\tau_{\alpha_0}) r_0] \right\}$$

$$\Leftrightarrow \max_{c_t, n_t, \alpha_{t+1}, g_t} \sum_{t=0}^{\infty} \beta^t \left\{ u(c_t, l_t, g_t) + \mu u_{ct} c_t - \mu u_{nt} n_t \right\} - \delta_t [c_t + \alpha_{t+1} - (1-\delta) \alpha_t + g_t - F(\alpha_t, n_t)] \\ - \mu u_{co} \alpha_0 [(1-\delta) + (1-\tau_{\alpha_0}) r_0]$$

$$\Leftrightarrow \max_{C_0, n_0, K_{t+1}, g_{t+1}} \sum_{s=t+1}^{\infty} \beta^s \left\{ W(c_s, l_s, g_s) - \delta_s [c_s + K_{s+1} - (1-\delta_s)K_s + g_s - F(K_s, n_s)] \right\} - \mu u_{CO} K_0 [(1-\delta_s) + (1-\tau_{CO}) r_0]$$

$$\begin{aligned} \text{C.P.O. : } & [c_t] W_{ct} = \delta_t \\ & [n_t] W_{nt} = \delta_t F_{nt} \\ & [g_t] W_{gt} = \delta_t \\ & [K_{t+1}] \delta_t = \beta \delta_{t+1} [(1-\delta) + F_{kt}] \end{aligned}$$

$$\Rightarrow \begin{cases} F_{nt} = W_{nt}/W_{ct} \\ V_{gt} = W_{ct} \\ W_{ct} = \beta W_{ct+1} [(1-\delta) + F_{kt+1}] \end{cases}$$

p) $x_t = x_{t+1} = x \quad \forall t \quad \forall x = c, n, K, g, r_n, r_K, u, r$

$$\text{Do problema de Ramsey: } L = \beta [(1-\delta) + F_K] \quad \Rightarrow \quad r_K = 0$$

$$\text{Do problema Descentralizado: } L = \beta [(1-\delta) + (1-r_K) F_K]$$

$$\begin{aligned} g) W(c_t, l_t, g_t) &= u(c_t, l_t, g_t) + \mu u_{ct} c_t - \mu u_{lt} l_t \\ W(c_t, l_t, g_t) &= \frac{c_t^{1-\delta} - 1}{1-\delta} + r(l_t, g_t) + \mu c_t^{1-\delta} - \mu r_{lt} l_t \end{aligned}$$

$$\Rightarrow W_{ct} = c_t^{-\delta} + \mu (1-\delta) c_t^{-\delta} = c_t^{-\delta} (1 + \mu (1-\delta))$$

$$\text{Do Problema de Ramsey: } c_t^{-\delta} (1 + \mu (1-\delta)) = \beta c_{t+1}^{-\delta} (1 + \mu (1-\delta)) [(1-\delta) + F_{Kt+1}]$$

$$c_t^{-\delta} = \beta c_{t+1}^{-\delta} [(1-\delta) + F_{Kt+1}] \quad \Rightarrow \quad r_{Kt+1} = 0 \quad \forall t \geq 1$$

$$\text{Do Problema Descentralizado: } c_t^{-\delta} = \beta c_{t+1}^{-\delta} [(1-\delta) + (1-r_{Kt+1}) F_{Kt+1}] \quad \Rightarrow \quad r_{Kt+1} = 0 \quad \forall t \geq 1$$

h) $\frac{\partial f}{\partial r_{Kt}} = \mu u_{Kt} l_{Kt} r_{Kt} > 0$ H_0 : aumento da taxa-átar com $r_{Kt} > 0$. Para um governo benevolente é ótimo taxar capital já acumulado (K_t).
 $\frac{\partial f}{\partial r_{Kt}} = \mu u_{Kt} l_{Kt} r_{Kt}$
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$$2) Y_t = Y_n + \alpha (\tilde{Y}_t + \tilde{\pi}_t^e)$$

$$L = \left\{ \frac{1}{2} \left[\lambda (Y_t - Y^*)^2 + (\tilde{Y}_t - \tilde{Y}^*)^2 \right] \right\}$$

$$Y^* > Y_n, \quad \alpha > 0, \quad \lambda > 0$$

a) Comportamento com credibilidade:

$$\min_{Y_t, \tilde{Y}_t} \left(\frac{1}{2} \left\{ \lambda (Y_t - Y^*)^2 + (\tilde{Y}_t - \tilde{Y}^*)^2 \right\} \right)$$

A.t. $Y_t = Y_n + \alpha (\tilde{Y}_t - \tilde{\pi}_t^e)$

Por comportamento $\tilde{Y}_t = \tilde{\pi}_t^e \quad \forall t$ [governar apenas expectativas e não demanda]

Das restrições: $Y_t = Y_n \quad \forall t$

Dado o formato da função objetivo, não há nível de \tilde{Y}_t que compense a diferença $(Y_n - Y^*)^2$. Logo, $\tilde{Y}_t = \tilde{Y}^* \quad \forall t$.

$$L^c = \left(\frac{1}{2} \right) \lambda (Y_n - Y^*)^2$$

b) Não Comportamento:

① amárico de \tilde{Y}_t^e ② expectativas formadas ③ reação de \tilde{Y}_t, Y_t

$$\min_{Y_t, \tilde{Y}_t} \left(\frac{1}{2} \left\{ \lambda (Y_t - Y^*)^2 + (\tilde{Y}_t - \tilde{Y}^*)^2 \right\} \right)$$

A.t. $Y_t = Y_n + \alpha (\tilde{Y}_t - \tilde{\pi}_t^e)$

$$\min_{\tilde{Y}_t} \left(\frac{1}{2} \left\{ \lambda (Y_n - Y^* + \alpha (\tilde{Y}_t - \tilde{\pi}_t^e))^2 + (\tilde{Y}_t - \tilde{Y}^*)^2 \right\} \right)$$

$$C.P.Q.: [\tilde{Y}_t] \ll \lambda (Y_n - Y^* + \alpha (\tilde{Y}_t - \tilde{\pi}_t^e)) + (\tilde{Y}_t - \tilde{Y}^*) = 0$$

$$\tilde{Y}_t = \frac{\lambda \alpha^2 \tilde{\pi}_t^e + \tilde{Y}^* + \lambda \alpha (Y^* - Y_n)}{1 + \lambda \alpha^2}$$

$$\text{Público anticipa comportamento ótimo de regulador: } \tilde{\pi}_t^e = \frac{\lambda \alpha^2 \tilde{\pi}_t^e + \tilde{Y}^* + \lambda \alpha (Y^* - Y_n)}{1 + \lambda \alpha^2} \Rightarrow \tilde{\pi}_t^e = \tilde{Y}^* + \lambda \alpha (Y^* - Y_n)$$

$$\text{Pois consequência: } \hat{\pi}_t = \lambda \alpha^2 [\hat{\pi}^* + \lambda \alpha (Y^* - Y_t)] + \hat{\pi}^* + \lambda \alpha (Y^* - Y_t)$$

$$1 + \lambda \alpha^2$$

$$\Rightarrow \hat{\pi}_t = \hat{\pi}^* + \lambda \alpha (Y^* - Y_t) \quad \forall t$$

[Expectativa Recursiva]

$$\Rightarrow Y_t = Y_n \quad \forall t$$

Nota que não haverá 'erro' sobre Y_t , mas haverá 'erro' sobre $\hat{\pi}_t$.

$$L^{nc} = \left(\frac{1}{2} \right) \lambda (1 + \lambda \alpha^2) (Y_n - Y^*)^2 \}$$

$$L^{nc} > L^c$$

c) Comportamento para sempre: $W_c = \frac{L^c}{1-\beta}$

Dúvida: $W^D = 0$

↳ Deixe $Y^*, \hat{\pi}^*$. Vai determinar $\hat{\pi}_t^*$ para depois chegar (pelo ato de momento, ou círculo)

$$Y_t = Y_n + \alpha (\hat{\pi}_t - \hat{\pi}_t^*) \Rightarrow \hat{\pi}_t^* = \hat{\pi}^* - \frac{(Y^* - Y_n)}{\alpha}.$$

$$\text{Uma vez que estes são os expectativas, devia para } \hat{\pi}_t = \hat{\pi}^* \Rightarrow Y_t = Y_n + \alpha (\hat{\pi}^* - \hat{\pi}^* + \frac{(Y^* - Y_n)}{\alpha}) = Y^*.$$

$$\text{Portanto, a partir do próximo período haverá 'erro' só sobre o ponto de credibilidade. Logo, } W^R = 0 + \left(\frac{\beta}{1-\beta} \right) L^{nc}.$$

Pra haver equilíbrio com comportamento: $\frac{L^c}{1-\beta} \leq \left(\frac{\beta}{1-\beta} \right) L^{nc} \Leftrightarrow \beta \geq \frac{L^c}{L^{nc}}$

Como $L^c < L^{nc}$, $\exists \sigma \in [L^c/L^{nc}, 1)$ tal que $\beta \geq \sigma$, comportamento estima-se equilíbrio.

$$3) a) \max_{c_t, \alpha_{t+1}} \sum_{t=0}^{\infty} \beta^t h_{ct}$$

$\text{st. } c_t + \alpha_{t+1} \leq (1-\tau)r_t \alpha_t + \Pi_t$

$$\left. \begin{array}{l} \text{C.P.O.: } [c_t] \quad \lambda_t = \frac{1}{c_t} \\ \quad [\alpha_{t+1}] \quad \lambda_t = \beta \lambda_{t+1} (1-\tau) r_{t+1} \end{array} \right\} \quad \frac{1}{c_t} = \beta E_t \left[\left(\frac{1}{c_{t+1}} \right) (1-\tau) r_{t+1} \right]$$

$$\text{C.T.: } \lim_{t \rightarrow \infty} \beta^t \lambda_t \alpha_{t+1} = 0$$

$$b) \max_{\alpha_t, h_t} \Pi_t = A \alpha_t^{1-\alpha} h_t^{\alpha} - r_t \alpha_t$$

$$\text{C.P.O.: } [\alpha_t] \quad A \alpha_t \left(\frac{h_t}{\alpha_t} \right)^{1-\alpha} = r_t$$

$$\frac{\partial \Pi_t}{\partial h_t} \quad A (1-\alpha) \left(\alpha_t/h_t \right)^{\alpha} > 0 \quad \forall h_t \quad \Rightarrow h_t^* = h^{\max} \quad \forall t$$

c) O eq. competitivo é uma equação de preços e deságios tão que tanto como dívidas, resolvem o problema dos agentes e há market-clearing.

d) Apesar de haver retornos marginais decrescentes p/ cada investimento individual, temos retorno constante de escala quando tratando os investimentos combinados ($\frac{\partial F}{\partial (\alpha_t, h_t^{1-\alpha})} = A > 0$). Esse é o motor da acumulação. O ponto principal é que estes investimentos não acumulam. A infraestrutura cresce à medida que o capital cresce. Assim, o modelo escapa da ameaça dos retornos marginais decrescentes (AK).

$$e) \text{Equação de Euler: } 1+g = \beta (1-\tau) r_{t+1} \Rightarrow r_{t+1} = \frac{(1+\alpha)}{[\beta(1-\tau)]} \quad \forall t \quad \left. \begin{array}{l} (h_{t+1}/\alpha_{t+1}) = \frac{\tau}{\beta(1-\tau)} \quad \forall t \\ \text{Regras de } h: \quad h_{t+1} + \tau r_t \alpha_t \Rightarrow \left(h_{t+1}/\alpha_{t+1} \right) = \tau r_t / (1+\alpha) \end{array} \right\} \Rightarrow (\alpha/h) = \beta/\tau - \beta$$

$$\text{Demanda de } \alpha: \quad r_t = A \alpha \left(\frac{h_t}{\alpha_t} \right)^{1-\alpha}$$

$$\Rightarrow \frac{(1+\alpha)}{\beta(1-\tau)} = A \alpha \left(\frac{\tau}{\beta(1-\tau)} \right)^{1-\alpha} \Rightarrow g = A \alpha \beta^{\alpha} \tau^{1-\alpha} (1-\tau)^{\alpha} - 1$$

$$f) \frac{\partial g}{\partial \tau} = A \alpha \beta^{\alpha} \left[(1-\alpha) \left(\frac{1-\tau}{\tau} \right)^{\alpha} + \alpha \left(\frac{\tau}{1-\tau} \right)^{1-\alpha} \right] = A \alpha \beta^{\alpha} \left[\frac{(1-\alpha)(1-\tau) + \alpha \tau}{\tau^{\alpha} (1-\tau)^{1-\alpha}} \right]$$

$$\frac{\partial(\alpha/h)}{\partial \tau} = -\frac{\beta}{\tau^2} < 0$$

$$g) \underset{c_i, \alpha_{r+s}, h_{rs}}{\max} \sum_{r=0}^{\infty} \beta^r h_r c_r$$

$$\text{p.t. } c_r = \alpha_{r+s} + h_{rs} = A \alpha_s^s h_s^{1-s}$$

C.P.O.: $[c_i] \lambda_i = v_{ci}$

$$[\alpha_{r+s}] \lambda_r = \beta \lambda_{r+s} A \alpha_s^s \left(h_{rs} / \alpha_{r+s} \right)^{1-s}$$

$$[h_{rs}] \lambda_r = \beta \lambda_{r+s} A (1-s) (\alpha_{r+s} / h_{rs})^s$$

$$\text{C.T. : } \begin{cases} \lim_{r \rightarrow \infty} \beta^r \lambda_r \alpha_{r+s} = 0 \\ \lim_{r \rightarrow \infty} \beta^r \lambda_r h_{rs} = 0 \end{cases}$$

h) Combinando Equas: $\frac{h_{rs}}{\alpha_{r+s}} = \frac{(1-s)}{s} \Rightarrow g = \beta A \alpha^s (1-s) - 1$

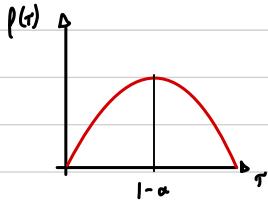
i) Desneutralizado: $1+g = A \alpha^s \beta^s (1-\tau)^s \tau^{1-s}$

Eficazida: $1+g = A \beta \alpha^s (1-s)^{1-s}$

$$(1-\tau)^s \tau^{1-s} = \left(\frac{\beta (1-s)}{s} \right)^{1-s}$$

$$\rho(\tau) = (1-\tau)^s \tau^{1-s}$$

$$\rho'(\tau) = -s \left(\frac{\tau}{1-\tau} \right)^{1-s} + (1-s) \left(\frac{\tau}{1-\tau} \right)^{-s} = 0 \quad \Leftrightarrow \tau^s = 1-s$$



$$\rho(\tau^s) = s^{-s} (1-s)^{1-s}$$

$$\rho(\tau^d) = \left(\frac{\beta}{s} \right) s^{-s} (1-s)^{1-s}$$

Se $\beta = e^{\frac{s(1-s)}{s}}$, τ^d é ótimo exequente.

C.C., τ^d não é ótimo exequente.

$$4) g = \frac{\lambda L_a - p}{\delta + \alpha}$$

$$\frac{\partial g}{\partial \lambda} = \frac{L_a}{\delta + \alpha} > 0 \quad \uparrow \lambda \text{ aumenta de especificação do projeto} \Rightarrow \uparrow \text{projeto técnico} \Rightarrow g$$

$$\frac{\partial g}{\partial L} = \frac{\lambda \alpha}{\delta + \alpha} > 0 \quad \uparrow L \Rightarrow \uparrow L_A \Rightarrow \uparrow \text{produtividade} \Rightarrow \uparrow g$$

$$\frac{\partial g}{\partial \delta} = -\frac{g}{\delta + \alpha} < 0 \quad \uparrow \delta \Rightarrow \begin{cases} \uparrow \text{aviso ao risco} \\ \downarrow \text{custo produtividade} \end{cases} \Rightarrow \downarrow K_A \Rightarrow \downarrow g$$

$$\frac{\partial g}{\partial \rho} = -\frac{1}{\delta + \alpha} < 0 \quad \uparrow \text{impostação} = \downarrow \text{projeto} \Rightarrow \downarrow g$$

$$b) \max \int_0^t e^{-pt} \left(\frac{C_r^{1-\alpha}-1}{1-\delta} \right) dt$$

p.t.

$$\begin{cases} \dot{K}_r = (L_{Y,r})^\alpha \int_0^t x_r(i)^{1-\alpha} dt - C_r \\ \dot{A}_r = \lambda A_r + L_{A,r} \\ L_{A,r} + L_{Y,r} = L \end{cases}$$

$$\begin{aligned} x_r(i) &= \bar{x}_r \quad \forall i \Rightarrow \dot{K}_r = (L_{Y,r})^\alpha A_r x_r^{1-\alpha} - C_r \\ &\Rightarrow \dot{K}_r = (L_{Y,r})^\alpha A_r \left(K_r / A_r \right)^{1-\alpha} - C_r \\ &\Rightarrow \dot{K}_r = (A + L_{Y,r})^\alpha K_r^{1-\alpha} - C_r \quad \rightarrow \text{nova variação da restrição.} \end{aligned}$$

Hamiltoniano:

$$H = e^{-pt} \left(\frac{C_r^{1-\alpha}-1}{1-\delta} \right) + \mu_r \left[(A + L_{Y,r})^\alpha K_r^{1-\alpha} - C_r \right] + \delta_r [\lambda A_r + (L - L_{Y,r})]$$

$$H_C = e^{-pt} C_r^{-\alpha} - \mu_r = 0 \Rightarrow \mu_r = e^{-pt} C_r^{-\alpha} \quad (0)$$

$$\lambda \ln(\mu_r) = -p + -\mu_r \ln(C_r)$$

$$\frac{\partial \ln(\mu_r)}{\partial \mu_r} = -\rho - \delta_r (\dot{c}_r / c_r) \quad (1)$$

$$H_{L_Y} = 0 \Rightarrow \alpha \mu_r A_r \left(\frac{K_r}{L_{Y,r}} \right)^{1-\alpha} = \delta_r \lambda A_r \quad (3)$$

$$H_{A_r} = -\mu_r \Rightarrow -\frac{\dot{\mu}_r}{\mu_r} = (1-\alpha) \left(\frac{A_r + L_{Y,r}}{K_r} \right)^\alpha \quad (2)$$

$$H_A = -\dot{\delta}_r \Rightarrow \alpha \mu_r L_{Y,r}^\alpha \left(\frac{K_r}{A_r} \right)^{1-\alpha} + \delta_r \lambda (L - L_{Y,r}) = -\dot{\delta}_r \quad (4)$$

$$\begin{aligned} \text{C.T. } \Delta: \begin{cases} \lim_{t \rightarrow \infty} \mu_r A_r = 0 & (5) \\ \lim_{t \rightarrow \infty} \delta_r A_r = 0 & (6) \end{cases} \end{aligned}$$

$$c) \quad (1) + (2) \Rightarrow \frac{\dot{C}_+}{C_+} = \left(\frac{1-\alpha}{\delta}\right) \left(\frac{A_+ + L_{Y_+}}{K_+}\right) - \frac{\rho}{\delta} \quad (7)$$

$$(3) \Rightarrow \frac{\mu_L}{\delta_L} = \left(\frac{\lambda}{\alpha}\right) \left(\frac{A_+ + L_{Y_+}}{K_+}\right)^{1-\alpha} \quad (8)$$

$$(8) \text{ em } (4) \Rightarrow -\frac{\dot{\delta}_+}{\delta_+} = \left(\frac{\lambda}{\alpha}\right) \left(\frac{A_+ + L_{Y_+}}{K_+}\right)^{1-\alpha} - \left(\frac{\lambda}{\alpha}\right) \left(\frac{K_+}{A_+}\right)^{1-\alpha} + \lambda(L - L_{Y_+})$$

$$\Rightarrow \frac{-\dot{\delta}_+}{\delta_+} = \lambda L \Rightarrow \delta_+ = e^{-\lambda L t} \quad (9)$$

$$(9) \text{ em } (8) \Rightarrow \mu_L = \left(\frac{\lambda}{\alpha}\right) \left(\frac{A_+ + L_{Y_+}}{K_+}\right)^{1-\alpha} e^{-\lambda L t} \quad \left\{ \left(\frac{\lambda}{\alpha}\right) \left(\frac{A_+ + L_{Y_+}}{K_+}\right)^{1-\alpha} = e^{-(\rho - \lambda L)t} C_+^{-\alpha} \Rightarrow \right.$$

$$(10) \Rightarrow \mu_L = e^{-\rho t} C_+^{-\alpha}$$

$$\frac{\frac{\partial}{\partial t} (\ln(\lambda/\alpha) + (1-\alpha)[\ln A_+ + \ln L_{Y_+} - \ln K_+])}{\delta_L} = -(\rho - \lambda L) t - \rho \ln C_+$$

$$\frac{\partial}{\partial t} \left((1-\alpha) \left[\frac{A_+ + L_{Y_+} - K_+}{A_+ L_{Y_+}} \right] - (\rho - \lambda L) - \rho \frac{\dot{C}_+}{C_+} \right)$$

$$L_{Y_+} = L_Y \forall t \Rightarrow \dot{L}_{Y_+} = 0 \forall t \Rightarrow (1-\alpha)[g^* + 0 - g^*] = -(\rho - \lambda L) - \rho g^* \Rightarrow g^* = \frac{\lambda L - \rho}{\delta}$$

$$d) \quad g = \frac{\lambda L \alpha - \rho}{\delta + \alpha} = \frac{\lambda L - \rho \alpha}{1 + \delta/\alpha}$$

$$g^* = \underline{\lambda L - \rho}$$

$$g^* - g = \frac{((\rho + \alpha)(\lambda L - \rho) - \rho(\lambda L \alpha - \rho)) / (\rho(\rho + \alpha))}{(\rho(\rho + \alpha))}$$

$$= \frac{(\lambda L \rho - \cancel{\rho \alpha} + \lambda L \alpha - \alpha \rho - \lambda L \alpha \cancel{\rho} + \cancel{\rho \rho}) / (\rho(\rho + \alpha))}{(\rho(\rho + \alpha))}$$

$$= \frac{(\lambda L \rho (1-\alpha) + \alpha(\lambda L - \rho)) / (\rho(\rho + \alpha))}{(\rho(\rho + \alpha))} > 0$$

$$\Rightarrow g^* > g$$

Isso ocorre pq o sistema é associado à economia descentralizada num concorrente perfeito no mercado do bem intromissório. (Padão de mercado).

5) Acnogla p. 465, nroº 14.1.4