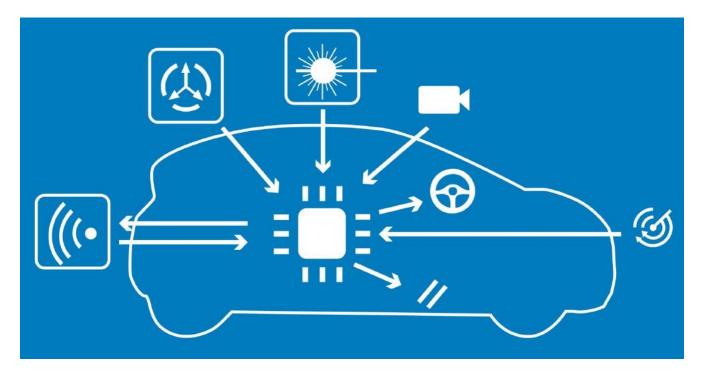


Eletrônica Automotiva



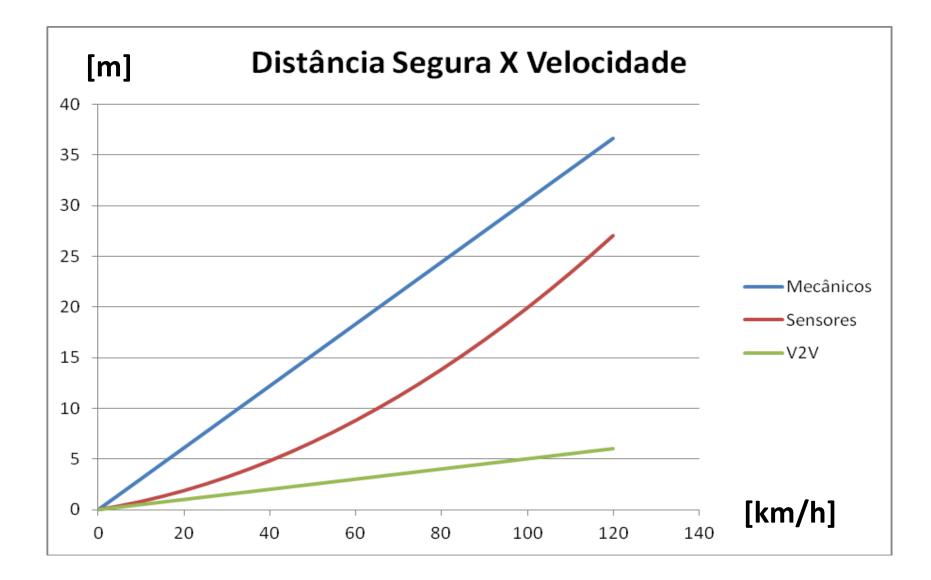
ADAS - Sistema, funções e arquitetura

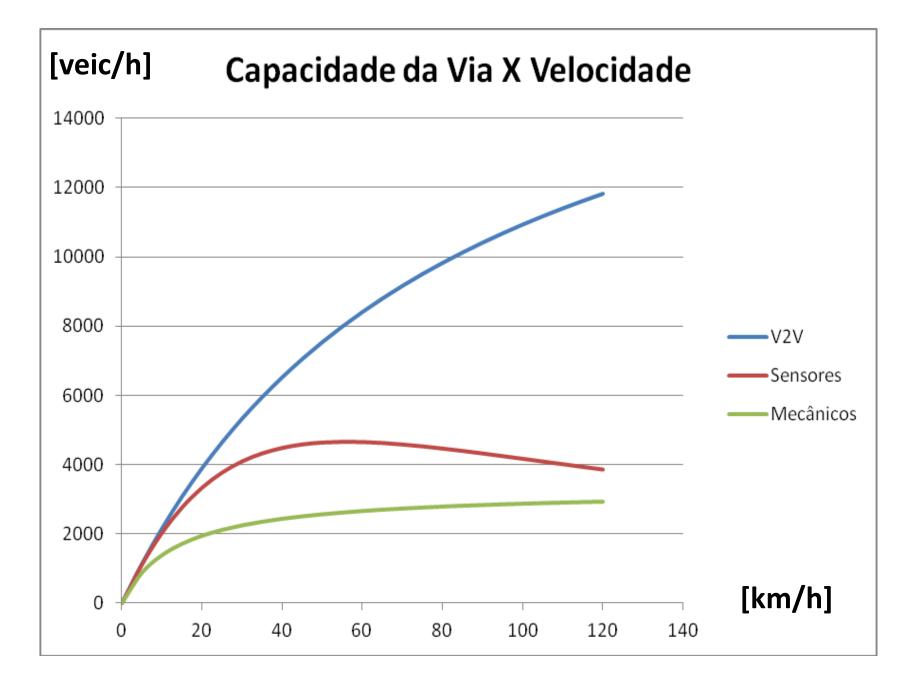


24 Maio 2018 Prof. Leopoldo Yoshioka

Cenário Atual

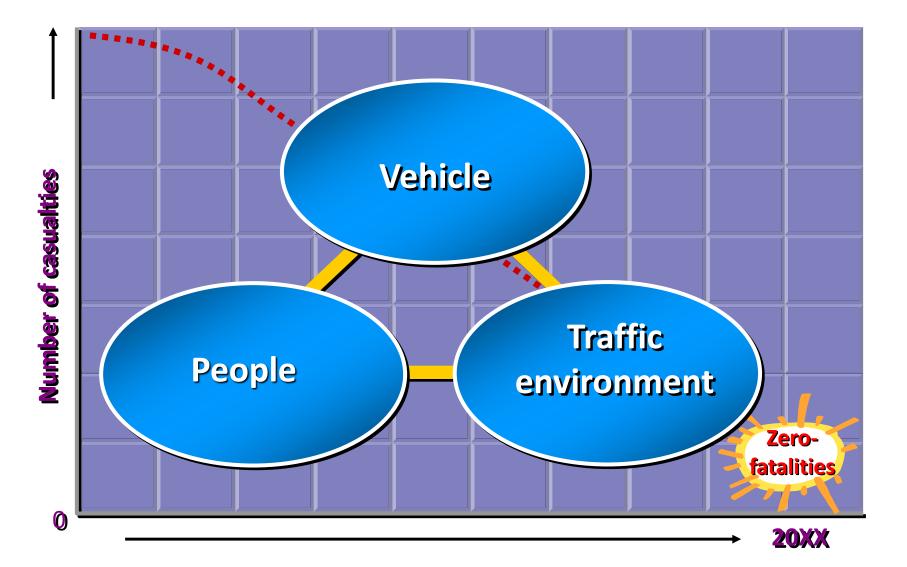
- 90% Inovações => Eletrônica / Software / Inteligência Artificial
- Está ocorrendo uma verdadeira "Revolução de Mobilidade"
- Veículos autônomos disponíveis comercialmente em 5 a 10 anos
- Smart Cities
- Empresa mais inovadora em 2015 e 2016: Tesla (Forbes)
- Oportunidades para empresas e profissionais do mundo inteiro





Acidentes de trânsito

- 1,25 milhões pessoas morrem por ano no mundo devido a acidentes de trânsito.
- 45 mil pessoas/ano morrem no Brasil
- 377 mil acidentes/ano com vítimas no Brasil
- 3^ª causa mortis.



(Toyota, 2007)

Níveis de Automação

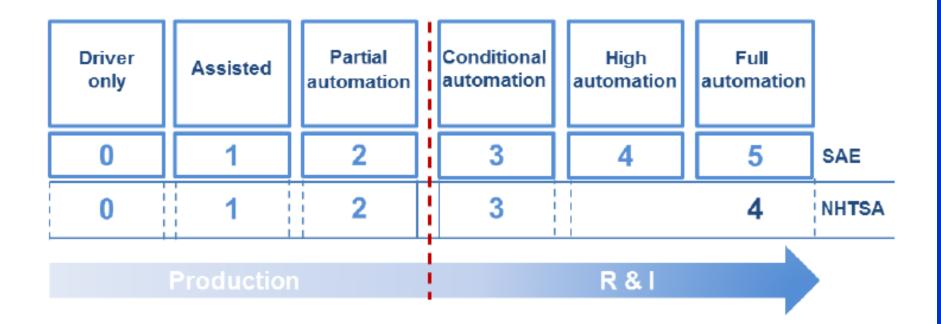
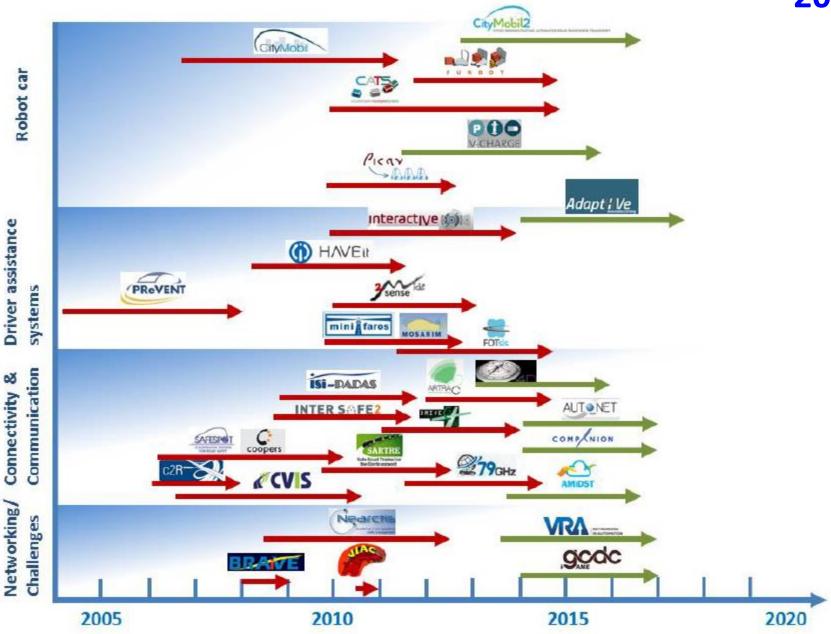
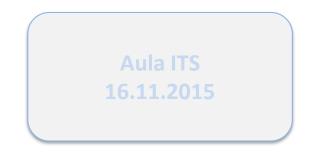
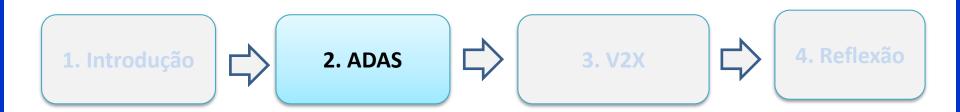


Figure 1: Levels of automated driving as defined by e.g. SAE. For comparison, definitions of automation levels of NHTSA are also given. The latter one comprises high and full automation levels towards level 4 (high automation).

Fonte: EPoSS – European Technology Platform on Smart Systems Integration (2015)







O que é ADAS?

- Advanced Driver Assistance System
- Sistema que auxilia o motorista no processo de condução do veículo
- Busca aumentar a segurança do veículo e a segurança da rodovia

Advanced driver assistance systems are designed to increase car safety more generally road safety.

Basically Advanced driver assists(ADS) systems helps the driver in the driving process and enables safe, relaxed driving. It makes sense to get your new car with driver assist features if you find it at a reasonable price as it helps you drive easily and safely in everyday use.

Here are different examples of driver assistance systems designed to maximise the driver safety -

Objetivos do ADAS

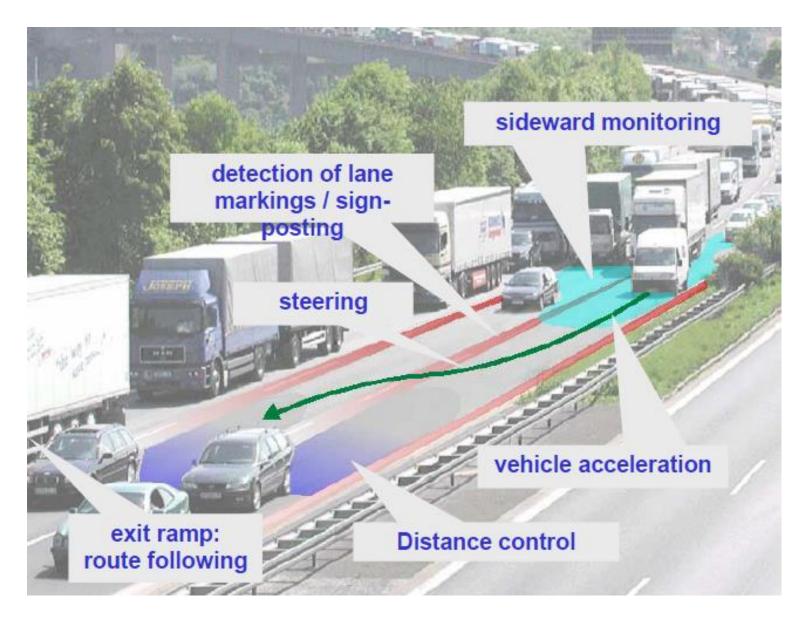
Comfort

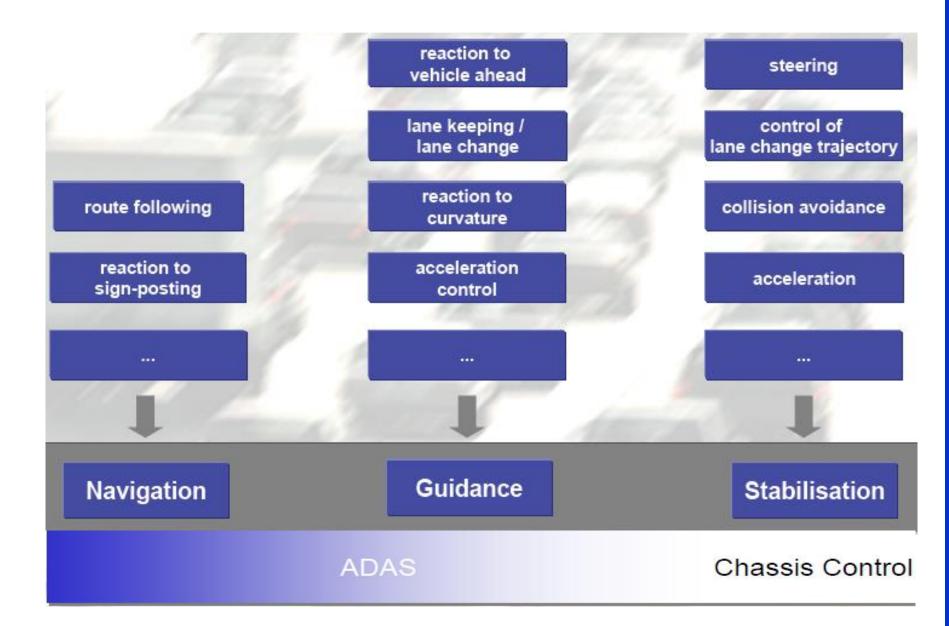
- improvement of driving comfort
- decrease of driver's work-load

Safety

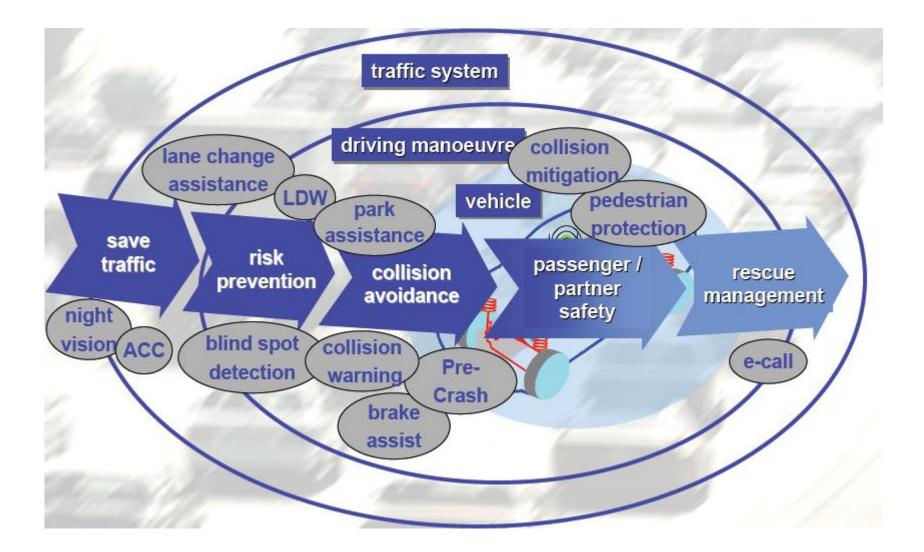
- accident prevention
- crashworthiness reduction
- rescue management
- Traffic efficiency
 - Road capacity usage
 - less congestion
- environmental impact
 - less fuel consumption
 - decrease of traffic noise

Driving Tasks - Exemplo de mudança de faixa

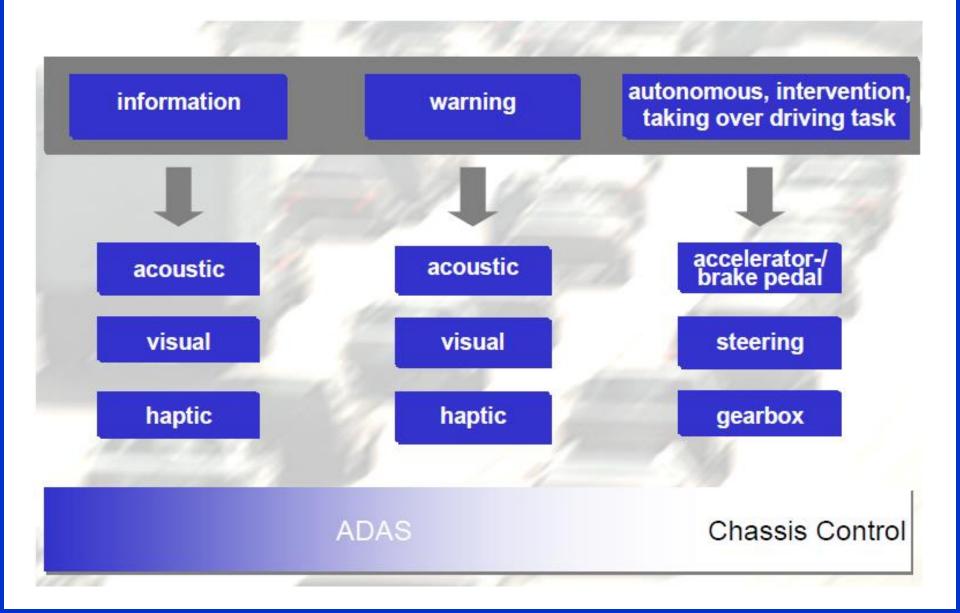


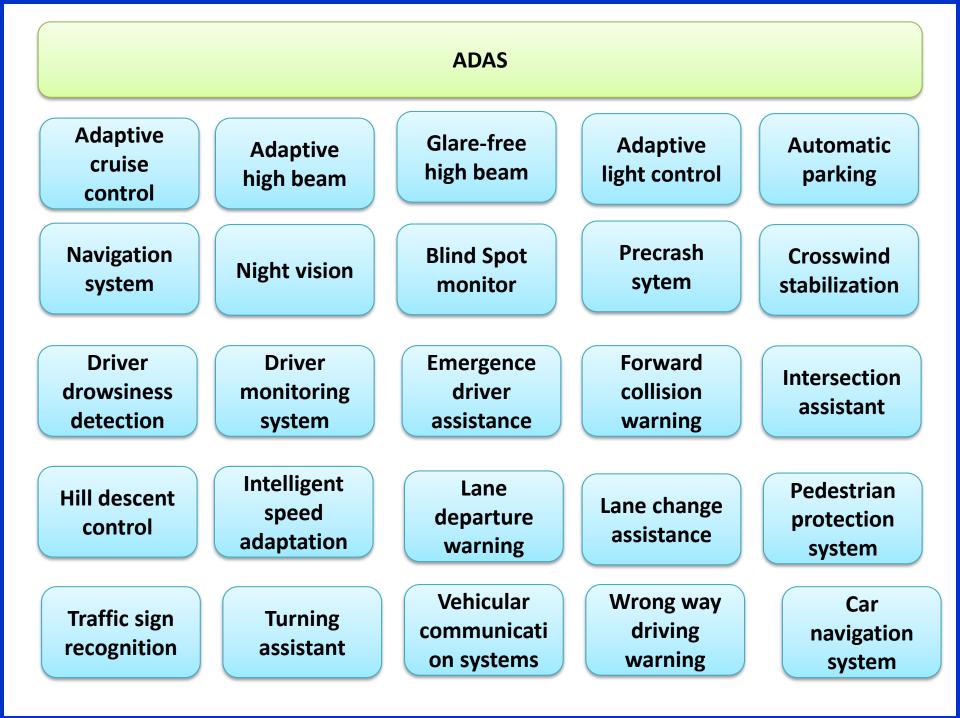


ADAS - Sistemas de Tráfego

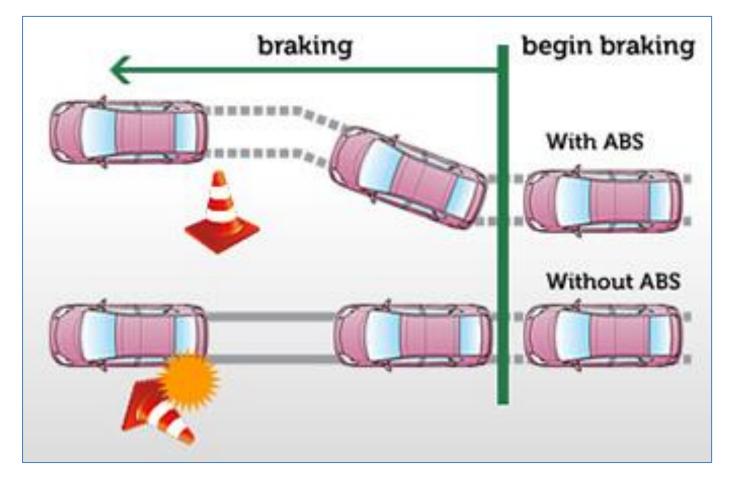


Classification of Driving Tasks





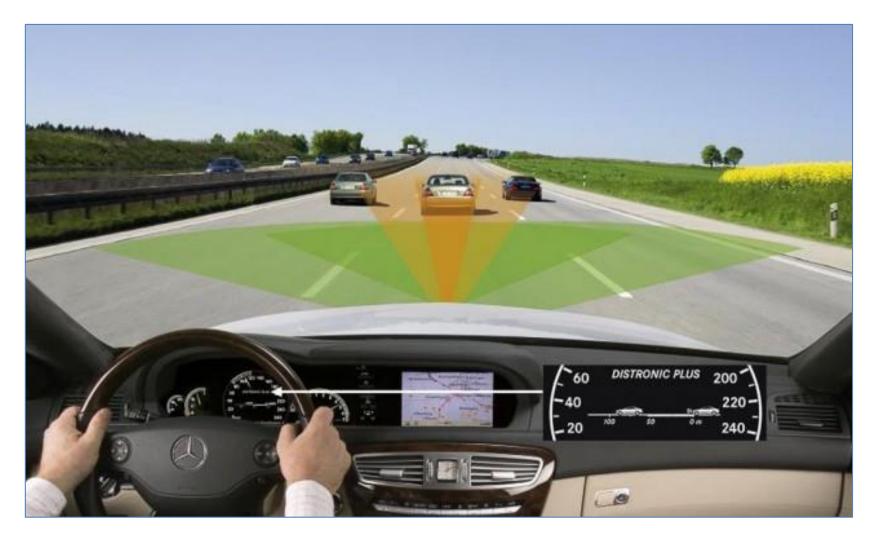
1) Antilock Braking System (ABS)



(Image courtesy - top low rider sites)

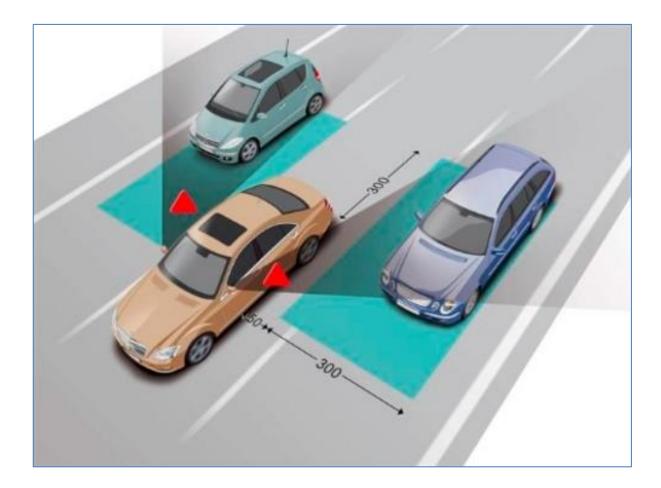
Antilock braking system mainly known as ABS. Basically it allows the wheels to maintain traction control with the road surface while stop braking(emergency braking) and prevents the wheels from locking up and avoid uncontrolled skidding. ABS offers improved vehicle control and decreases stopping distances on dry and slippery roads.

2) Adaptive Cruise Control



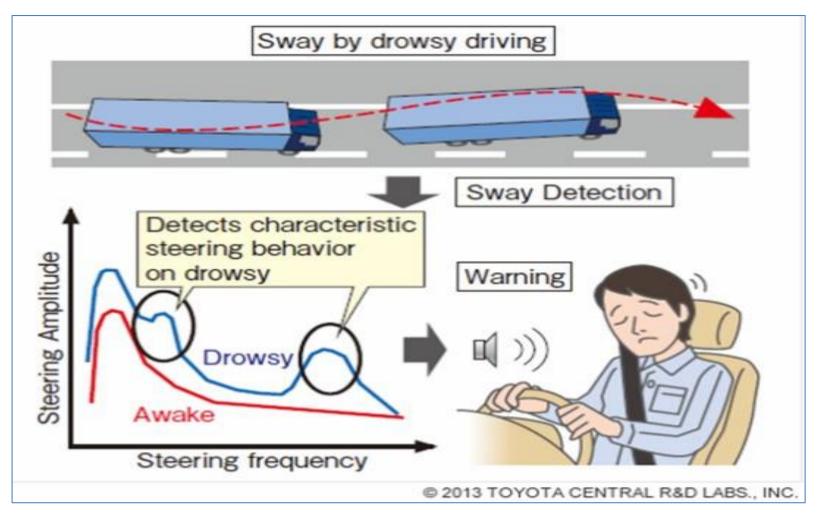
Adaptive Cruise Control (ACC) uses forward looking radar and maintains the safe distance from the car ahead. It is designed to avoid accidents by keeping your vehicle at a safe distance from the traffic ahead.

3) Blind Spot Detection



A blind spot monitor detects other vehicles located in the blind spot areas such as side and rear, however it detects other areas as well. Blind spot areas are hard to detect when you are specially driving in the night and any bicyclist stops in your blind spot area. It gets hard to move and detect the bicyclist. Also the system provides audible and visual sign to backing out of a parking space when traffic is approaching from other sides.

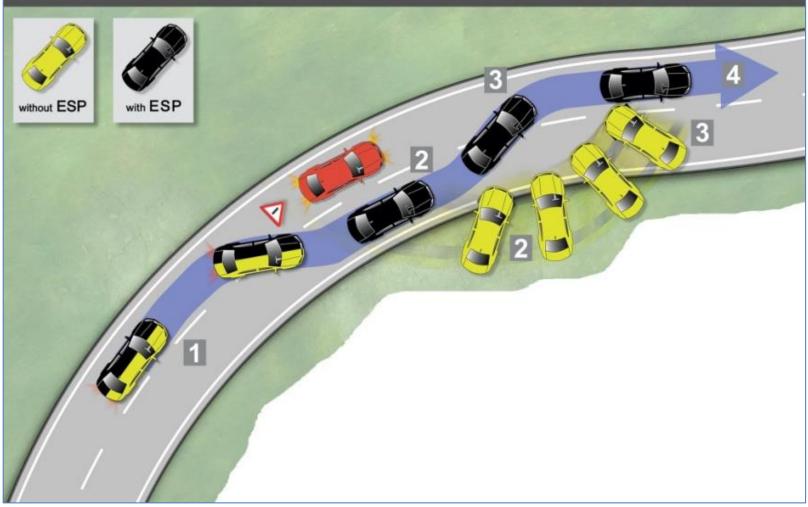
4) Driver Drowsiness Detection



□ Driver drowsiness detection is another car safety technology that designed to prevent accidents when the driver is getting drowsy and often fails to recognise early enough according to the experts.

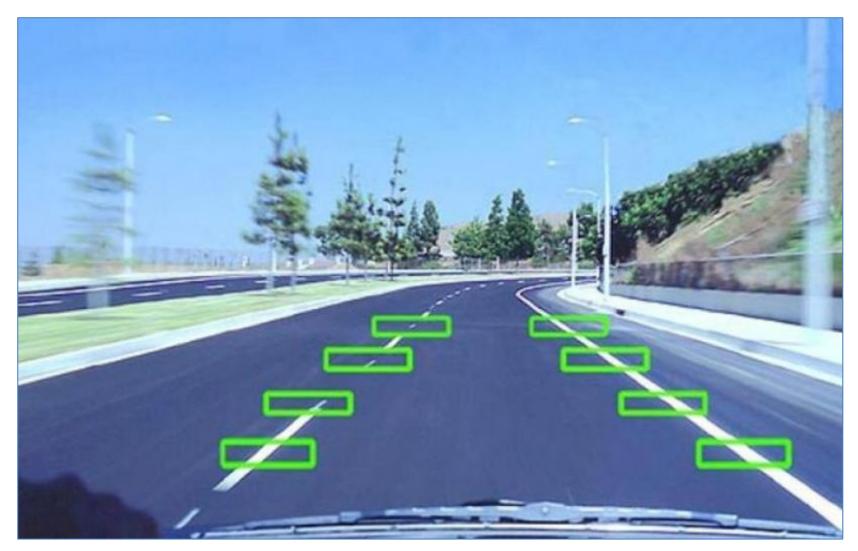
5) Electronic Stability Control

Critical manoeuvre with / without ESP



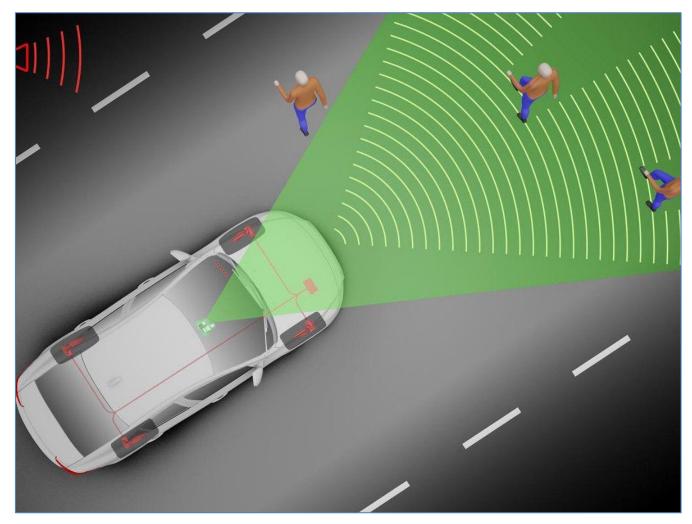
□ Electronic stability control (known as ESC) is a computer technology improves a vehicle stability control by reducing loss of traction or skidding. When ESC detects loss of steering control, automatically applies the brakes to help steer the vehicle.

6) Lane Departure Warning/Lane Assist systems



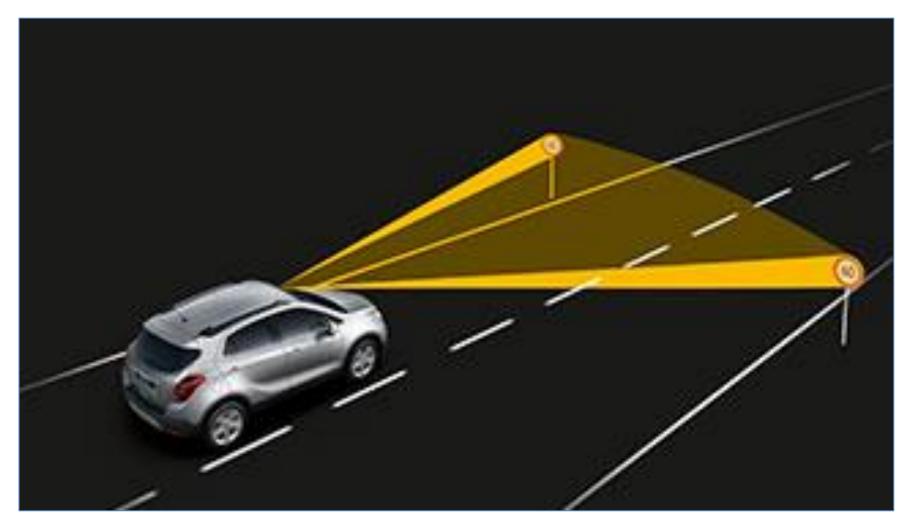
□ Lane departure warning system is designed to warn a driver when the vehicle begins to move out of its lane especially on 70mph motorways. Some advanced system warns the driver and automatically brings the vehicle to safe position if no action taken by the driver.

7) Pedestrian Detection

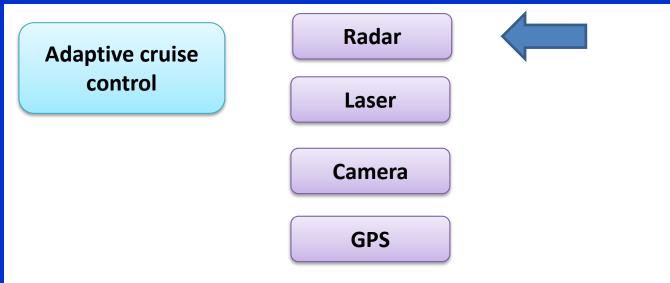


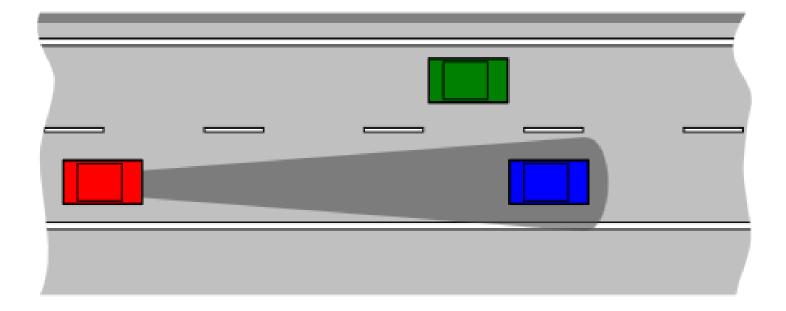
□ The predictive pedestrian protection system helps to prevent collisions and designed to minimise accident cruelty. If the pedestrian and car are in the same lane then the car warns driver or automatically start braking to avoid collision and minimise the accident.

8) Traffic Sign Recognition



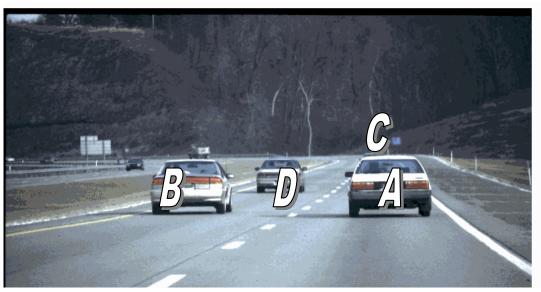
□ Traffic sign recognition(TSR) system detects the road signs such as school, turn ahead, speed limit etc.. and notify or warn the driver by displaying them on a colour screen.



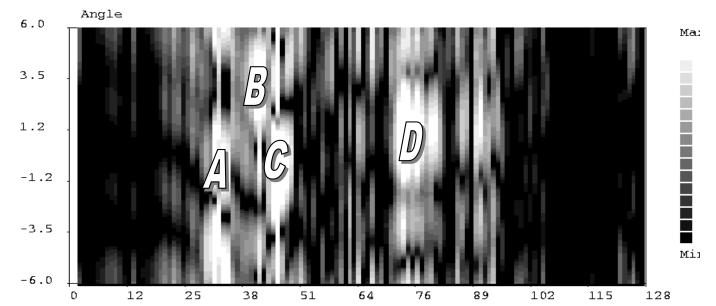


O veículo vermelho automaticamente segue o carro azul.

Radar Data



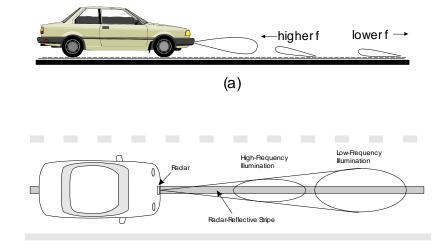
(C) Copyright 1995 by Dirk Langer at CMU



Data from a scanning radar. Top image is video of the scene, bottom is radar data, with corresponding locations have d. The radar d range (horizontal) and bearing angle (vertical; up is left, down is right). Brightness indicates strength of return. Car A is close and he center of the radar return (the video image does not extend as far to the right as the radar); B is further and left; C is further yet and barely visible above the roof of A; D is much further and has a bearing between A and B.

Radar reflective surfaces

- Collision avoidance radar can be used for lateral control with modified lane-marking tape.
- Frequency-dependent tape properties can provide distance and other information

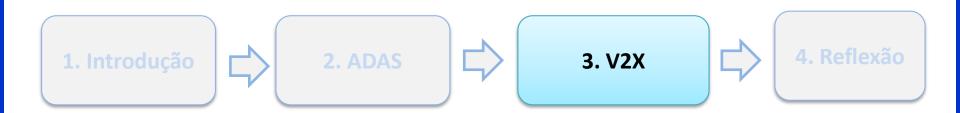


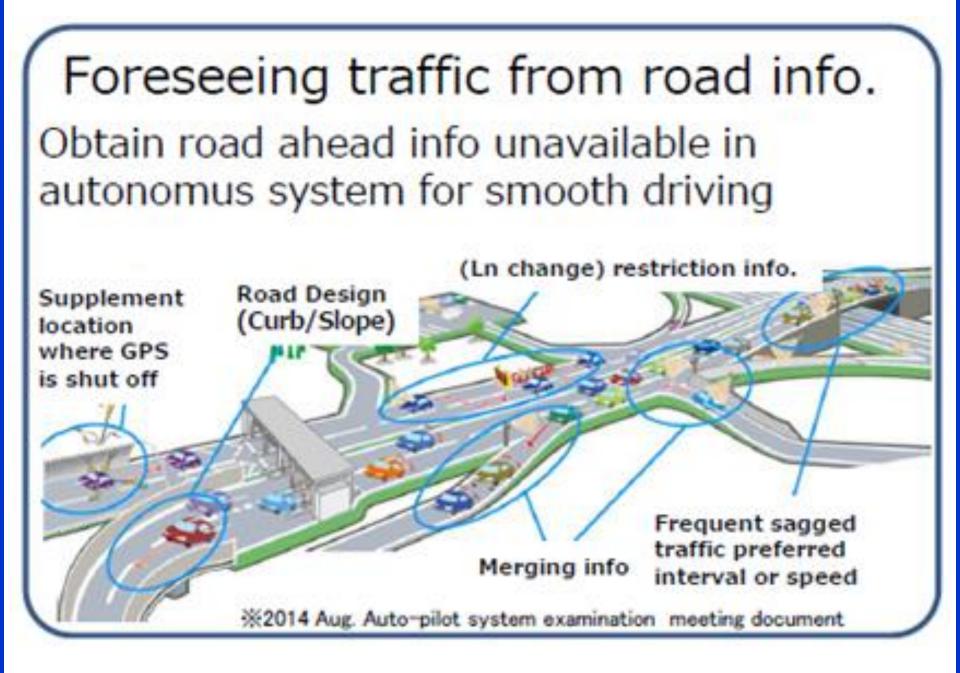


(b)

 Conventional lane marking tape (3M Corp.) punched with specific hole pattern to provide frequency-selective retroreflection

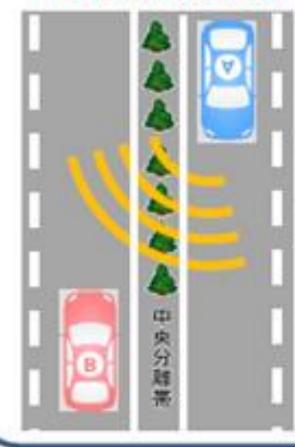






Info collection & delivery via cars

A Info. re-deliverer B Automated car



 Automated car sensor picks up road obstacles like hazard info and return to road system.
(supplement to road side sensors)

2.Road info. obtained from other on-coming traffic is re-delivered as prediction. mainly to supplement emergency road service

At merging/lane change

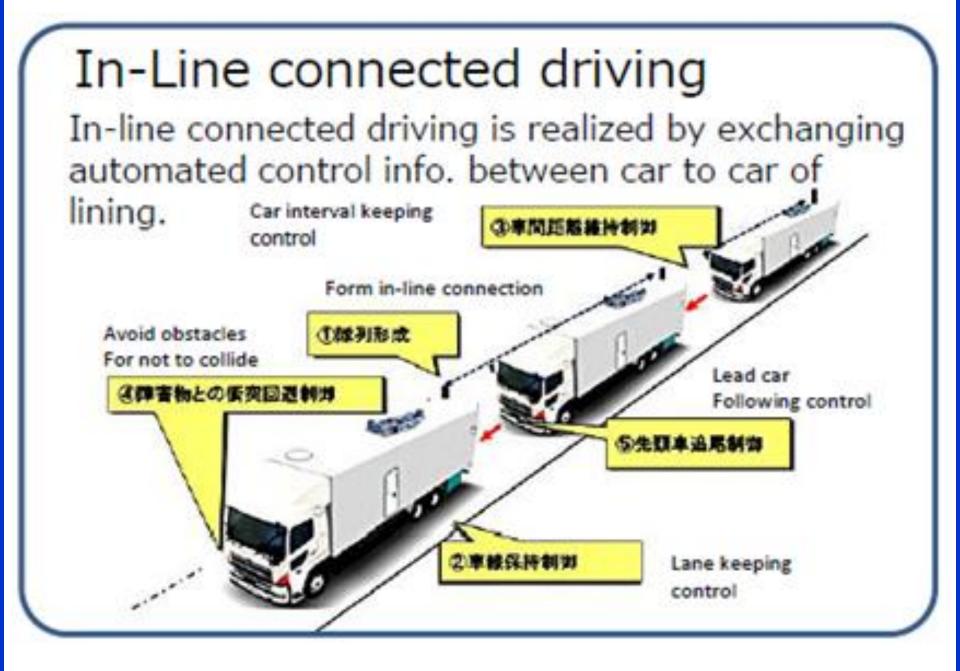
B Lane change

①Send lane change request to rear coming traffic upon changing lane.

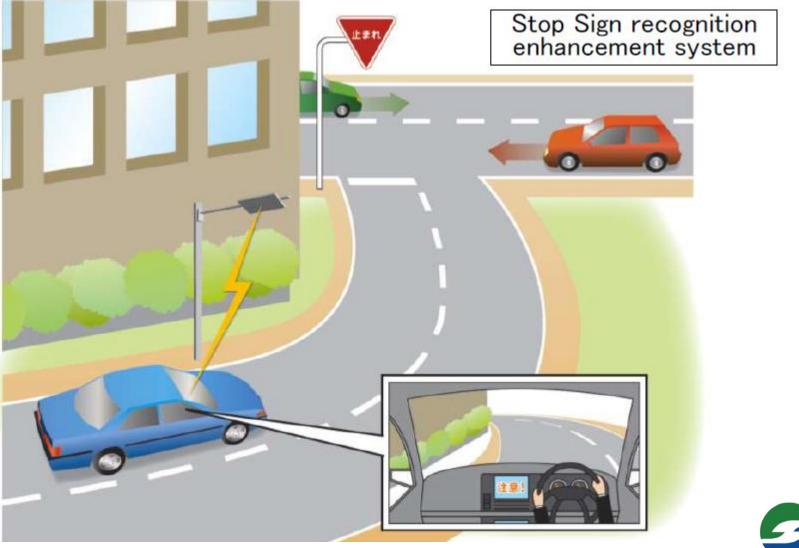
②Rear coming car replies and control car to car interval to allocate.

③Car of changing the lane confirms safety space from onboard sensor and control to change the lane.

Realize safe and smooth merge/lane change.

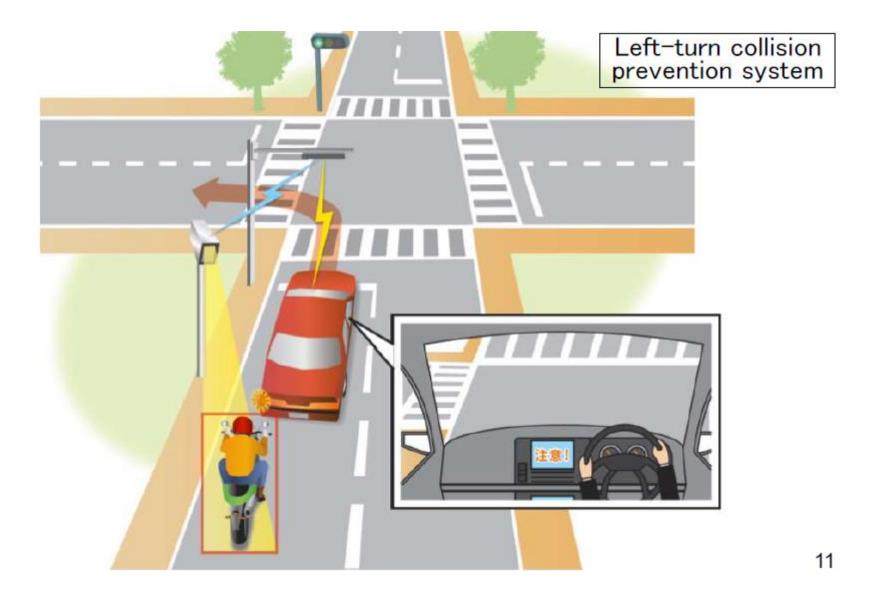


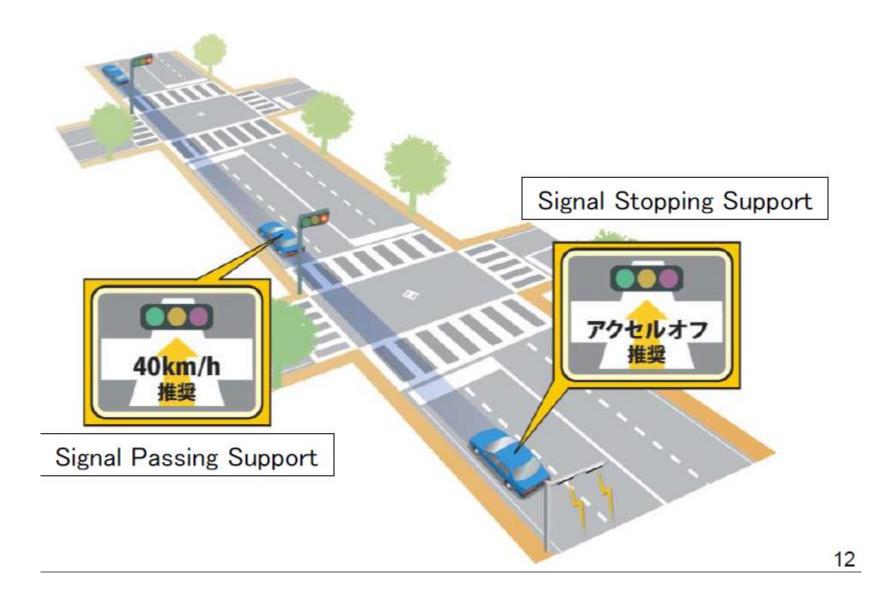
Comunicação V2I

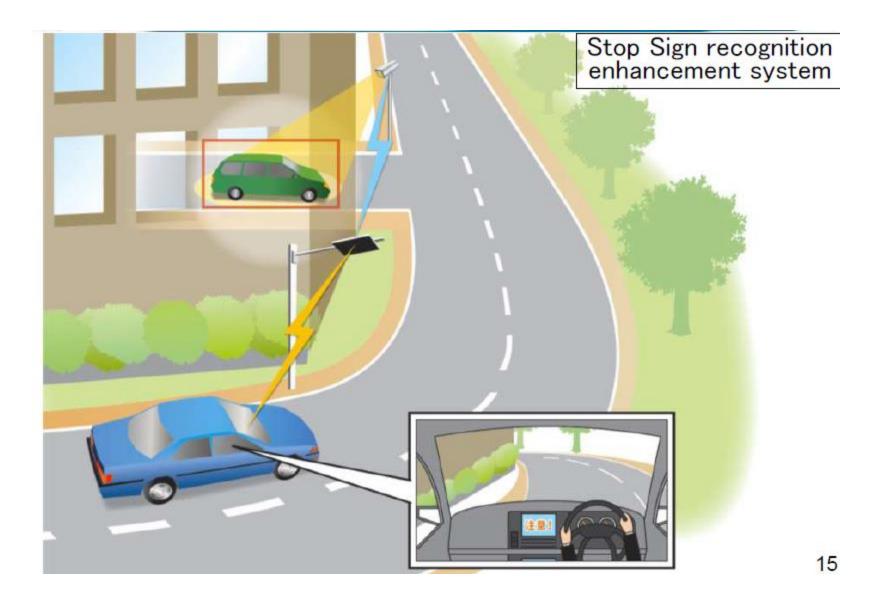


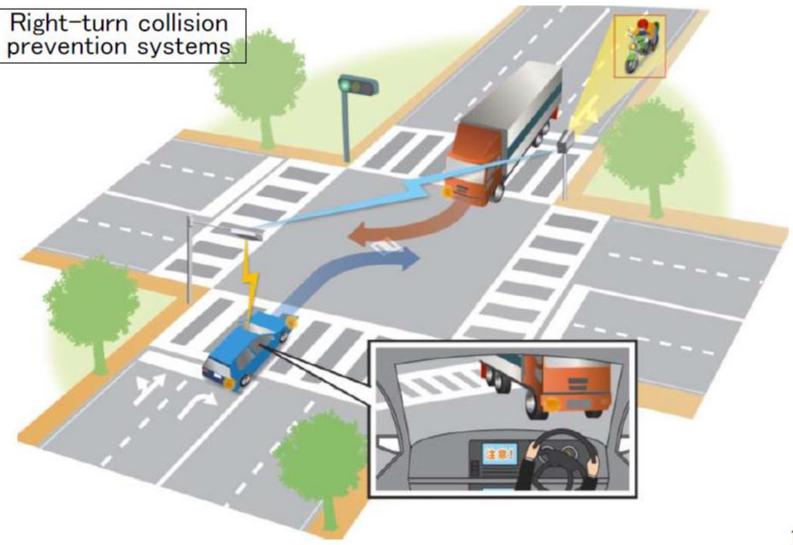


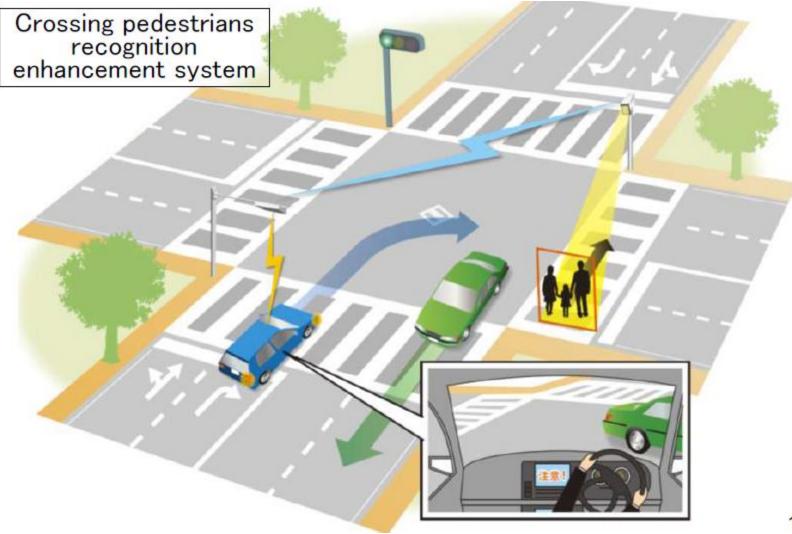


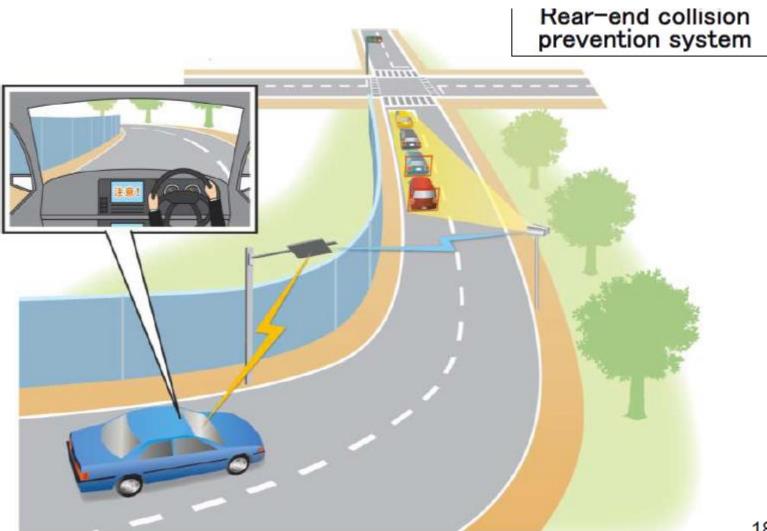


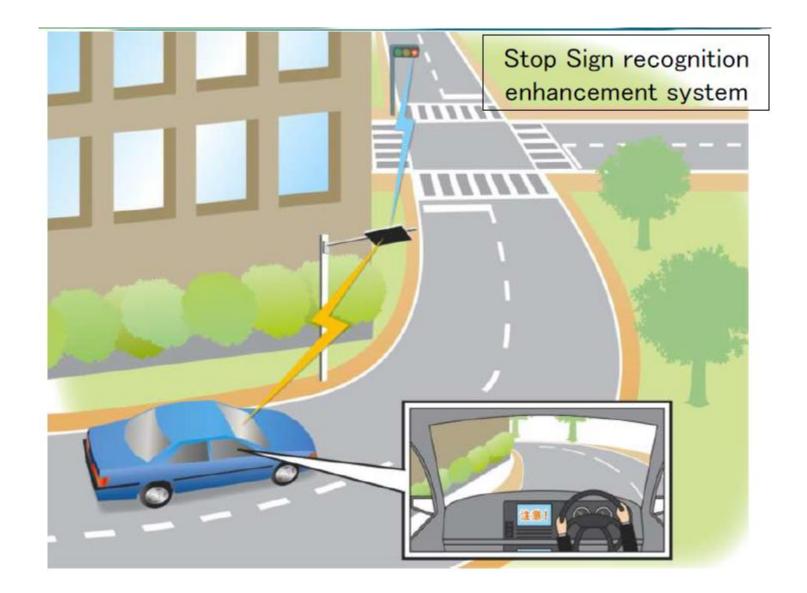












Cooperative Advanced Safety Vehicles

Experience a series of Driving Safety Support Systems functioned by V2V and V2p communication technologies (V2V : 5 scenes, V2P : 1 scene)

