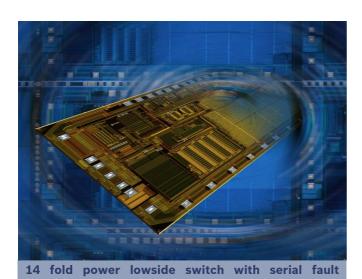
Automotive Electronics

Product Information Motronic IC CJ920





Customer benefits:

diagnostic interface

- Excellent system know-how
- Smart concepts for system safety
- Secured supply
- Long- term availability of manufacturing processes and products
- QS9000 and ISO/TS16949 certified

Features

- 4 relay drivers (...0.6A)
- 4 valve drivers (...2.2A)
- 6 injection valve drivers
- Package: Power-QFP 64

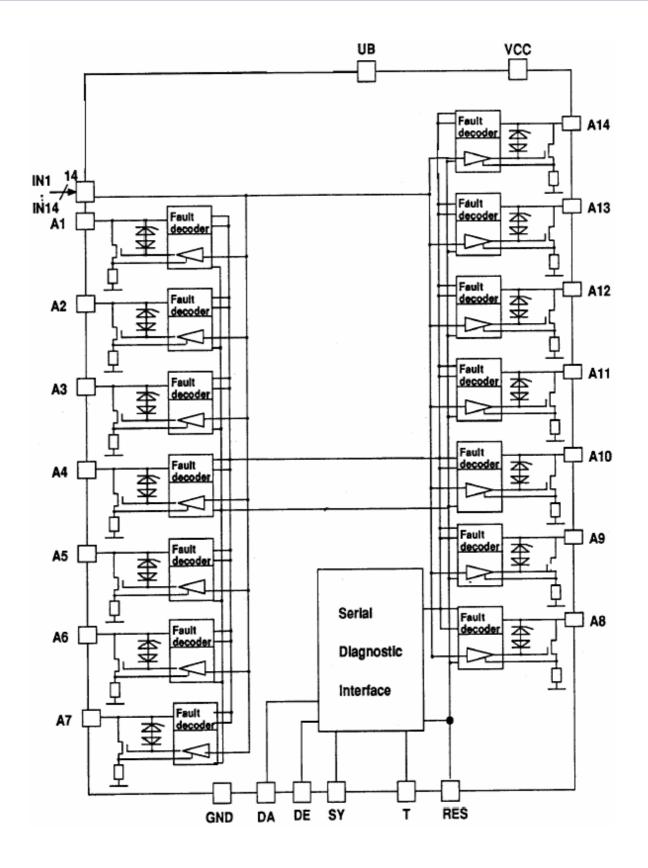
General description

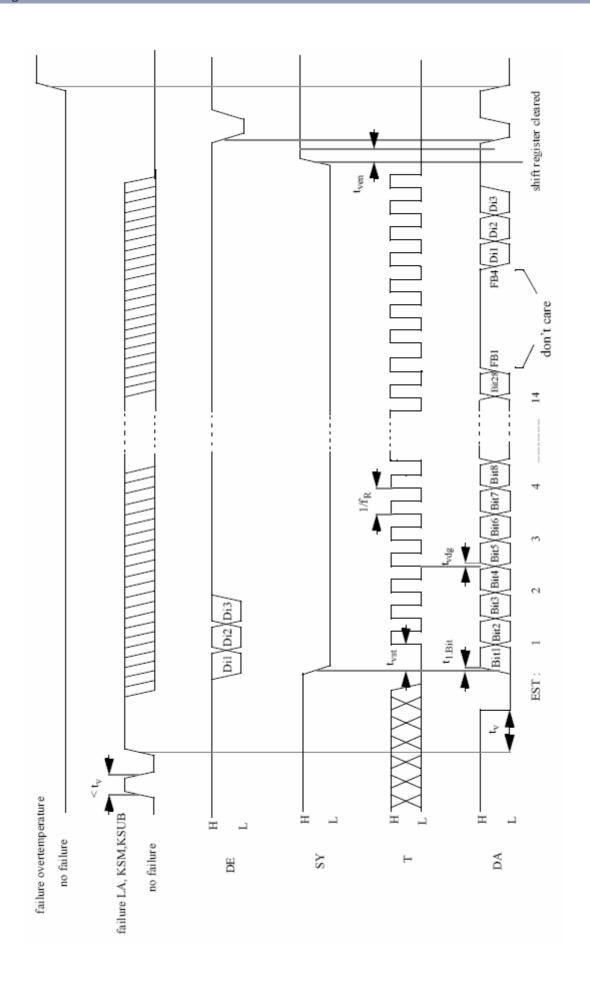
14 output stages

- 6 non inverting 2.2A low side switches
 - ON resistance < 500mW
 - 70V clamping
- 2 non inverting 2.2A low side switches
 - ON resistance < 500mW
 - 45V clamping
- 2 non inverting 2.7A low side switches
 - ON resistance < 1W
 - 40V clamping
- 4 non inverting 0.6A low side switches
 - ON resistance < 500mW
 - 45V clamping
- 2 outputs of each type, can be connected in parallel all outputs are short circuit protected

Serial diagnostic interface

- Errors detected:
 - short circuit to VBatt (KSUB) (output on)
 - short circuit to ground (KSM) (output off)
 - over temperature (ÜT) (output on)
 - open load (output off) (LA) (no hot open load detection)
- Individually detected for each output
- Serial transmission of the output status via a cascadable error shift register
- Register output usable as error signal flag





Functional description

The device contains 6+2+2+4 DMOS low side switches

- 6 for up to 2.2A, with Ron < 0.5W and a clamping voltage of 70V
- 2 for up to 2.2A, with Ron < 0.5W and a clamping voltage of 45V
- 2 for up to 2.7A, with Ron < 0.5W and a clamping voltage of 45V
- 4 for up to 2.2A, with Ron < 1.0W and a clamping voltage of 40V

The on resistance values can be reduced to 90% of the nominal value by applying an auxiliary voltage of >12V at the pin UB. It is possible to connect 2 switches, out of each group, in parallel.

The switches are short circuit protected. In case of overload (overcurrent) they will be turned off after a given filter/delay time. During the delay phase the output current is limited by an internal current control loop. To turn them on again, it is necessary to apply before, either an off signal at the correspondent input pin, or the reset signal.

For supply voltages below 4.4V at pin VCC all outputs are turned off.

All the low side switches are equipped with fault diagnostic functions

- Short to battery (KSUB) can be detected at switches which are turned on
- Short to ground (KSM) can be detected at switches which are turned off
- Open load (LA) can be detected at switches which are turned off, the device possesses no hot open load detecting function
- Overtemperature(ÜT) will only be detected at switches which are turned on and encoded in the same bit as the open load signal

If, at one output, several failures occur in a sequence, always the last one will be stored. The failure conditions KSUB, KSM, LA will only be recognized after an integrated filter time. If any failure is recognized, this will be shown by a low signal at the output of the serial interface.

All failure conditions are encoded in two bits per switch and are stored in an internal shift register. This shift register can be read out via a cascadable serial diagnostic interface. After each read out cycle this register will be cleared.

The whole status information is encoded in 28 bits. To set the diagnostics information in an 8 bit frame, 4 "high" bits are added to the status information. So after 32 bits the (optional) input data will be present at the diagnostics output.

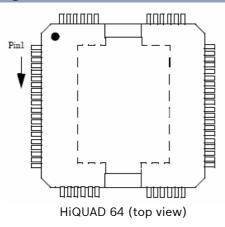
Encoding of the output information

	DIT 4
Output 1	BIT 1
	BIT 2
Output 2	BIT 3
<u> </u>	BIT 4
Output 3	BIT 5
	BIT 6
Output 4	BIT 7
Output 4	BIT 8
Output 5	BIT 9
Output 3	BIT 10
Output 6	BIT 11
Output 6	BIT 12
Output 7	BIT 13
Output 7	BIT 14
0.1.10	BIT 15
Output 8	BIT 16
0 0	BIT 17
Output 9	BIT 18
	BIT 19
Output 10	BIT 20
	BIT 21
Output 11	BIT 22
	BIT 23
Output 12	BIT 24
	BIT 25
Output 13	BIT 26
	BIT 27
Output 14	BIT 28
	BIT 29
Don't care	BIT 30
	BIT 31
Don't care	BIT 32
DE	BIT n
DL	וווט

Output 13

Н	Н	o.k.
L	Н	LA/ÜT (open load/ over temperature)
Н	L	KSUB (i.e. short to battery)
L	L	KSM (i.e. short to ground)

PIN configuration



Pin	Name	Function
16	A11	Output 11
15	A12	Output 12
37	A13	Output 13
38	A14	Output 14
57	RES	Reset
60	VCC	Supply voltage Vcc
62	UB	Auxiliary supply U _B
26+27	GND	Ground
+58+59	14	
56	DE	Diag. data in
61	DA	Diag. data out
55	SY	Diag. synchronization
54	Т	Diag. clock

Pin Description

Pin	Name	Function
45	E1	Input 1
43	E2	Input 2
42	E3	Input 3
8	E4	Input 4
11	E5	Input 5
10	E6	Input 6
9	E7	Input 7
12	E8	Input 8
44	E9	Input 9
41	E10	Input 10
13	E11	Input 11
14	E12	Input 12
40	E13	Input 13
39	E14	Input 14
46+47	A1	Output 1
50+51	A2	Output 2
33+34	А3	Output 3
6+7	A4	Output 4
19+20	A5	Output 5
2+3	A6	Output 6
4+5	A7	Output 7
17+18	A8	Output 8
48+49	A9	Output 9
35+36	A10	Output 10

PIN description and pinout

E1...E14: Signal inputs (with internal pull up) for the low side switches, a low signal will turn on the corresponding switch

A1...A14: Low side switch outputs, if more than 1 pin is assigned to an output, these pins have to be connected in parallel

VCC: Supply voltage (typ. 5V)

UB: Auxiliary supply voltage (typ 14V) to reduce

Ror

 $\ensuremath{\mathsf{GND1..4}}\xspace$. Ground pins, all of them have to be connected

in parallel

RES: Reset input, active low, turns off all switches

and clears the error shift register

Diagnostic interface DE, DA, T, SY:

DE: Data input, with an internal pull up, to daisy

chain the interface with other devices (e.g.

CJ920 or one out of the CJ4xx family)

DA: Diagnostics data output (open drain), gives a

low signal if an error at any output channel

within the device or in the chain is detected

A low level, applied to this input, freezes the

status of the error shift register, the register

now can be read out via the serial output DA

hu annivir a the aleast signal

by applying the clock signal

T: Clock signal, each rising edge shifts the next bit to the output DA (and reads in the next bit

bit to the output DA (and reads in the next bit

at the input DE)

Contact

Robert Bosch GmbH Sales Semiconductors Postbox 13 42 72703 Reutlingen Germany

Tel.: +49 7121 35-2979 Fax: +49 7121 35-2170 Robert Bosch Corporation Component Sales 38000 Hills Tech Drive Farmington Hills, MI 48331 USA

SY:

Tel.: +1 248 876-7441 Fax: +1 248 848-2818 Robert Bosch K.K.
Component Sales
9-1, Ushikubo 3-chome
Tsuzuki-ku, Yokohama 224
Japan

Tel.: +81 45 9 12-83 01 Fax: +81 45 9 12-95 73

Internet: www.bosch-semiconductors.de

E-Mail: bosch.semiconductors@de.bosch.com

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