

$$\alpha_L = \frac{1}{L} \frac{dL}{dT}$$

$$\Delta L \approx L_0 \alpha_L \Delta T$$

$$\frac{dQ}{dt} = \dot{Q} = -\kappa A \frac{dT}{dx}$$

$$C = \frac{dQ}{dT}$$

$$\Delta U = \Delta Q - \Delta W$$

$$dS = \frac{dQ_{\text{rev}}}{T}$$

$$PV = nRT$$

$$dV = 0 \Rightarrow$$

$$dP = 0 \Rightarrow$$

$$dQ = 0 \Rightarrow dU = -PdV \Rightarrow$$

$$dT = 0 \Rightarrow dQ = PdV$$

$$\eta = \frac{W}{Q_q} = 1 - \frac{Q_f}{Q_q}$$

$$\frac{U}{N} = \langle K_{\text{trans}} \rangle + \langle K_{\text{rot}} \rangle + \langle E_{\text{vib}} \rangle$$

$$\langle K_{\text{trans}} \rangle = \frac{3}{2} kT$$

$$\beta = \alpha_V = \frac{1}{V} \frac{dV}{dT}$$

$$\Delta V \approx V_0 \alpha_V \Delta T$$

$$\frac{dQ}{dt} = \dot{Q} = -\frac{\kappa A}{L} \Delta T$$

$$Q = mc\Delta T$$

$$Q = nc\Delta T$$

$$dU = dQ - PdV$$

$$\Delta S = \int_{\text{rev}} \frac{dQ}{T}$$

$$U = U(T) = nc_V T$$

$$dQ = dU = nc_V dT$$

$$dQ = dU + PdV = nc_P dT$$

$$\begin{cases} TV^{\gamma-1} = \text{constante} \\ PV^{\gamma} = \text{constante} \end{cases}$$

$$\Delta Q = \Delta W = nRT \ln(V_f/V_i)$$

$$K = \text{CoD} = \frac{Q_{f,q}}{W} = \frac{Q_{f,q}}{Q_q - Q_f}$$

$$U = \frac{1}{2} f N k R T = \frac{1}{2} f n R T$$

$$v_{\text{rqm}} = \sqrt{\langle v^2 \rangle} = \sqrt{\frac{3kT}{m}} = \sqrt{\frac{3P}{\rho}}$$

$$\beta = \alpha_V = 3\alpha_L$$

$$\frac{t}{^\circ\text{C}} = \frac{T}{\text{K}} - 273.0$$

$$Q = \pm \Delta m L$$

$$Q = \pm \Delta n L$$

$$dU = TdS - PdV$$

$$dU = nc_V dT$$

$$c_P - c_V = R$$

$$\gamma = c_P/c_V$$

$$\eta \leq \eta_{\text{rev}} = 1 - \frac{Q_f^{\text{rev}}}{Q_q^{\text{rev}}} = 1 - \frac{T_f}{T_q}$$

$$c_V = \frac{1}{2} f R$$

$$\lambda = \bar{\ell} = \frac{V}{N} \frac{1}{\sqrt{2}\sigma} = \frac{1}{\sqrt{2}n\pi d^2}$$

$$R = 8,314 \text{ J}/(\text{mol} \cdot \text{K}) \quad N_A = 6,023 \times 10^{23} \text{ mol}^{-1} \quad k = R/N_A = 1,38 \times 10^{-23} \text{ J/K}$$

$$\text{cal} = 4,20 \text{ J} \quad \text{L} = 10^3 \text{ cm}^3 = 10^{-3} \text{ m}^3$$