

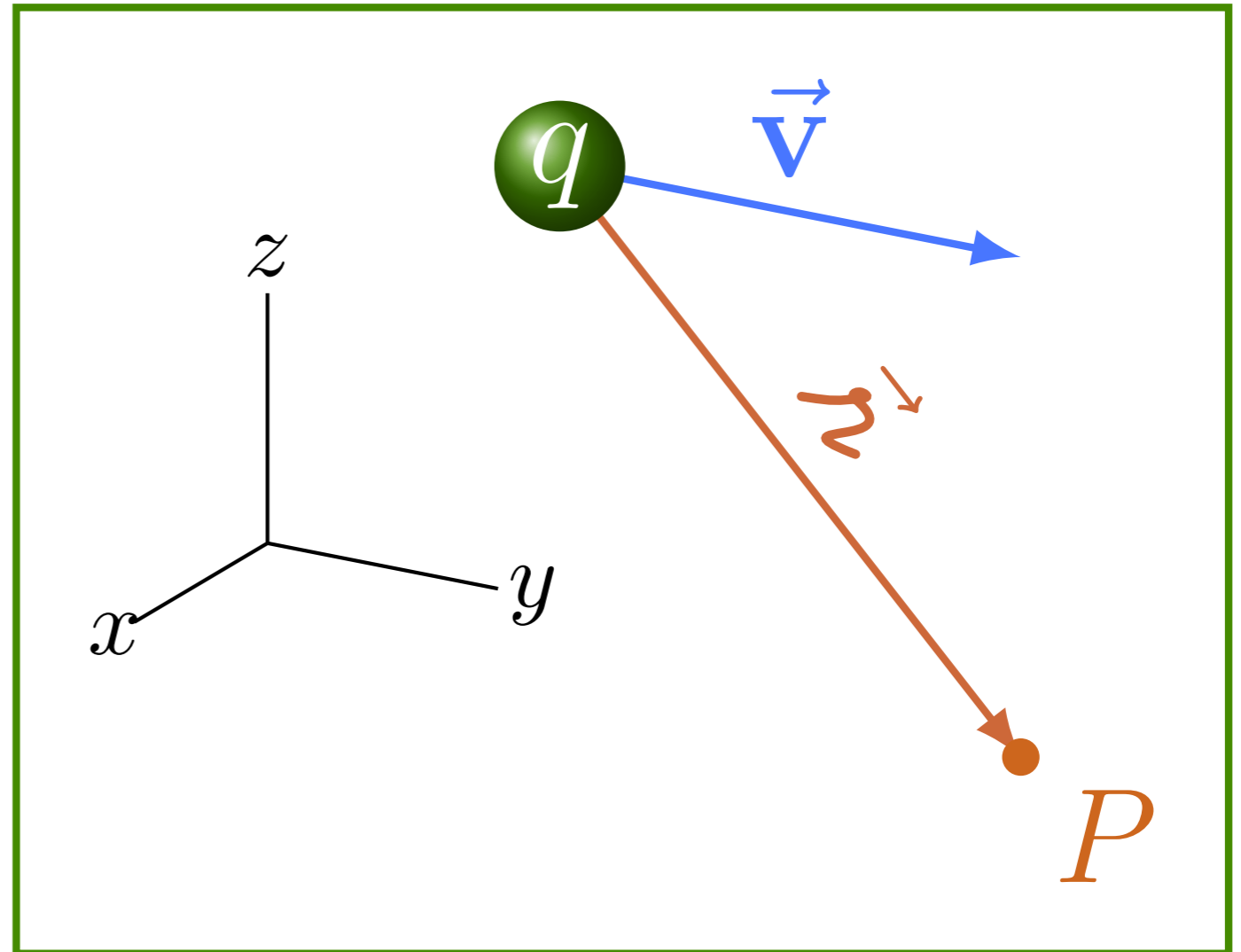
Eletrromagnetismo Avançado

*27 de novembro
Potenciais e campos*

Potenciais de Liénard e Wiechert

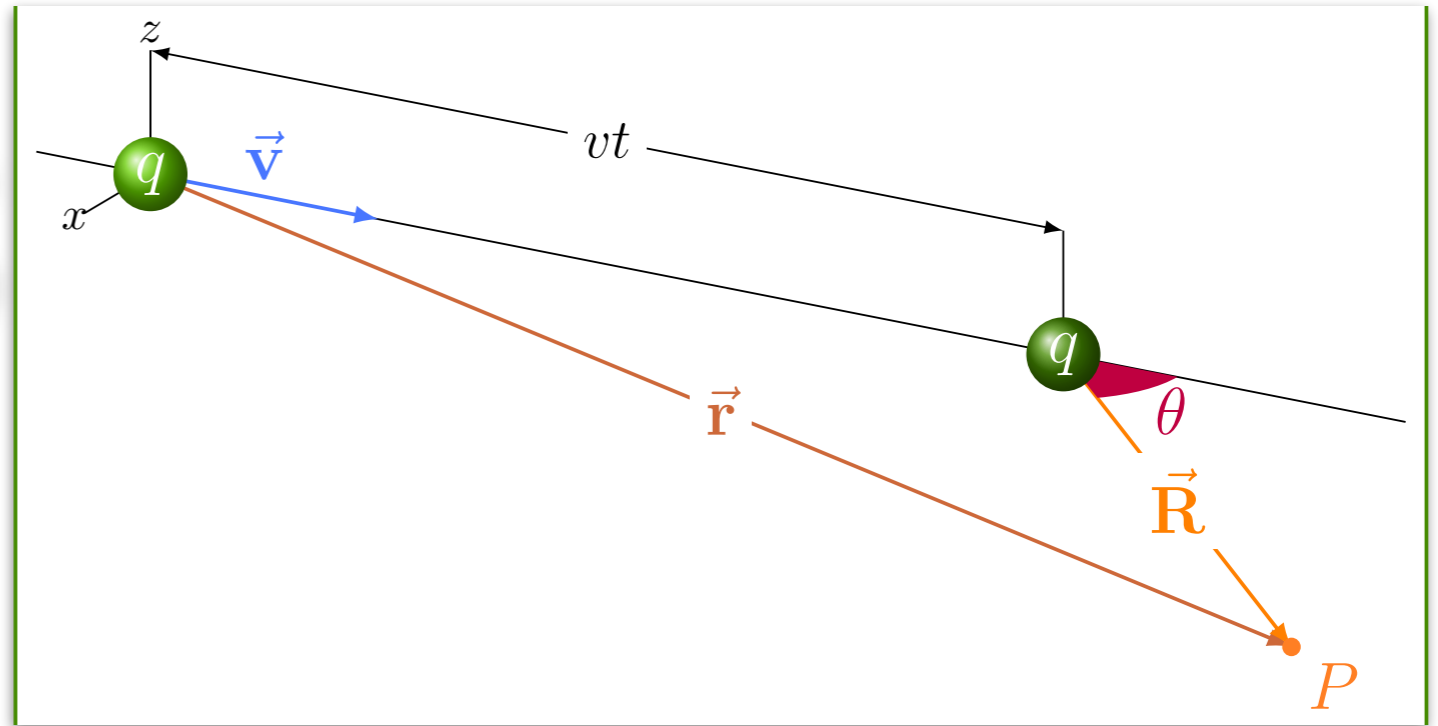
$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{r - \frac{\vec{v}}{c} \cdot \vec{r}}$$

$$\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi} \frac{q\vec{v}}{r - \frac{\vec{v}}{c} \cdot \vec{r}}$$



Movimento uniforme

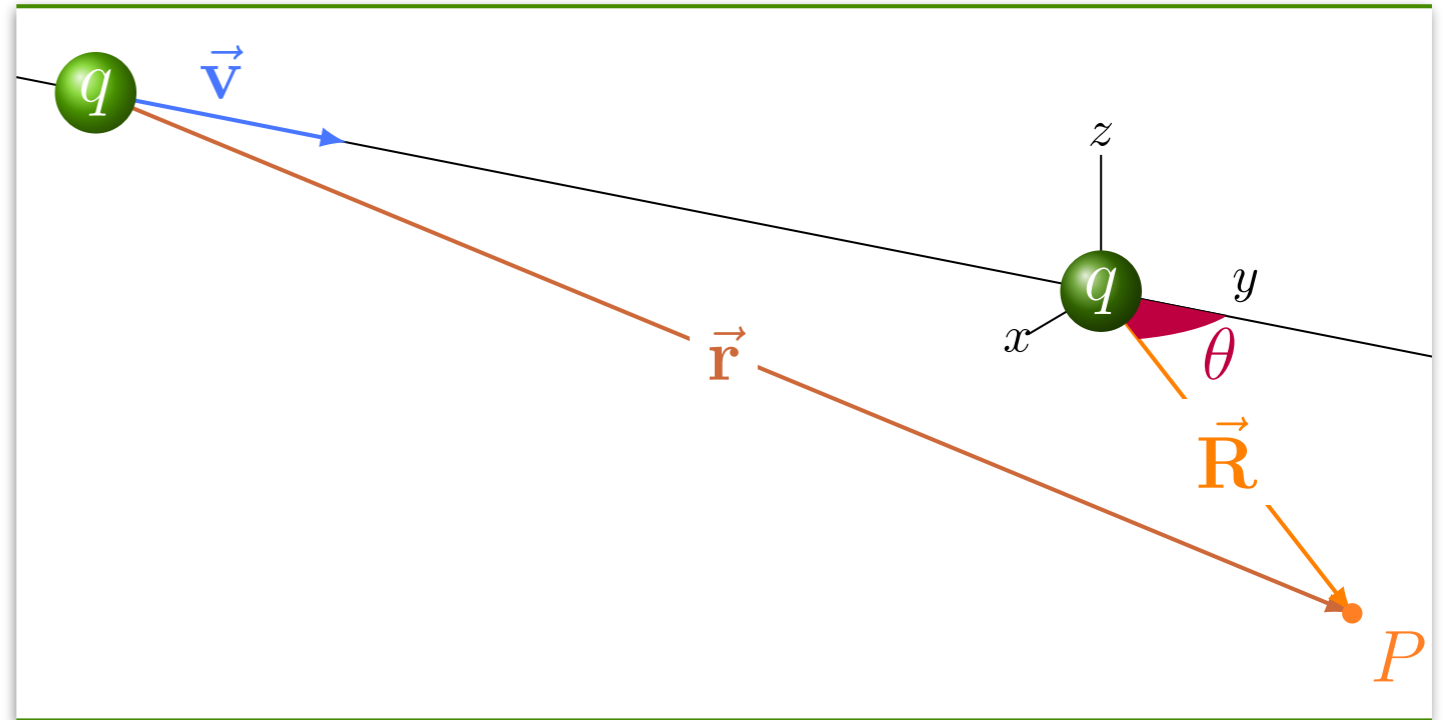
$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$



Movimento uniforme

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

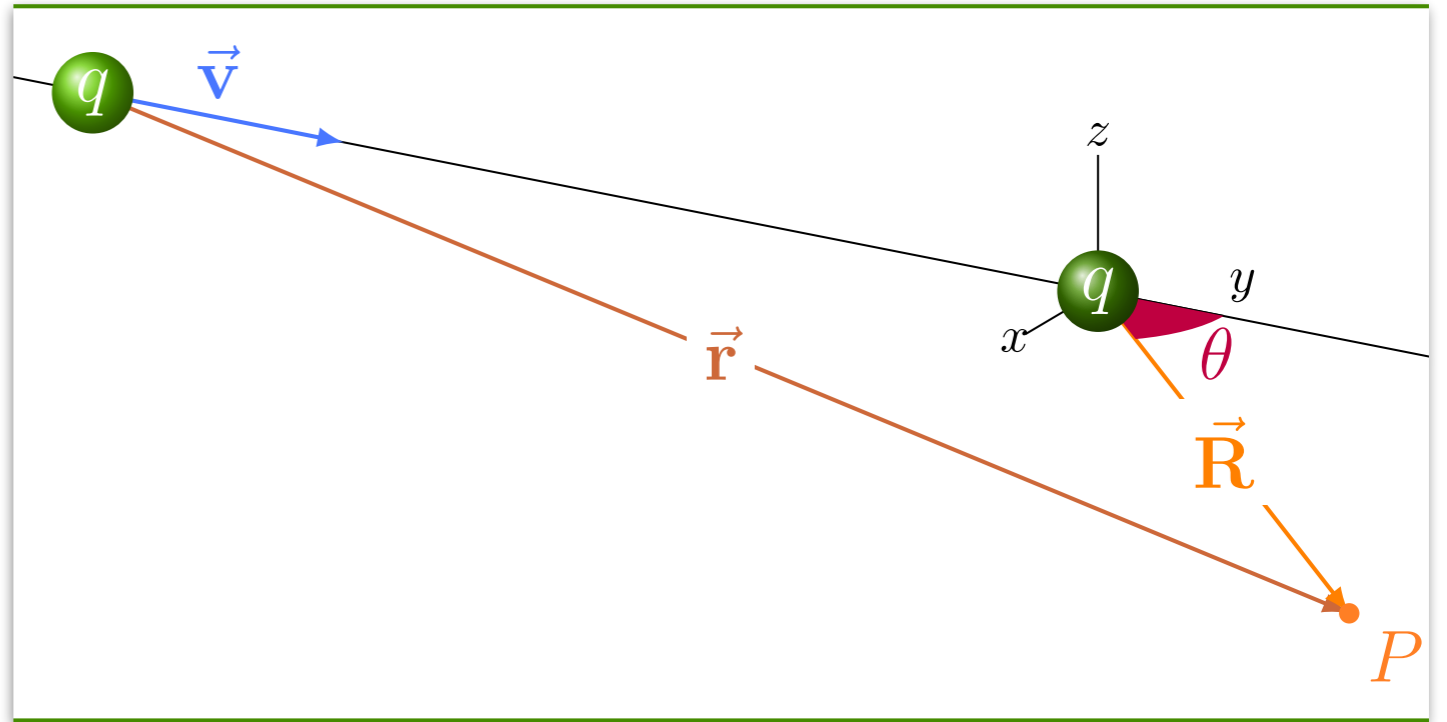


Movimento uniforme

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2}$$



Campo magnético

$$\vec{\mathbf{A}}(\vec{\mathbf{r}}, t) = \frac{\vec{\mathbf{v}}}{4\pi\epsilon_0 c^2} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

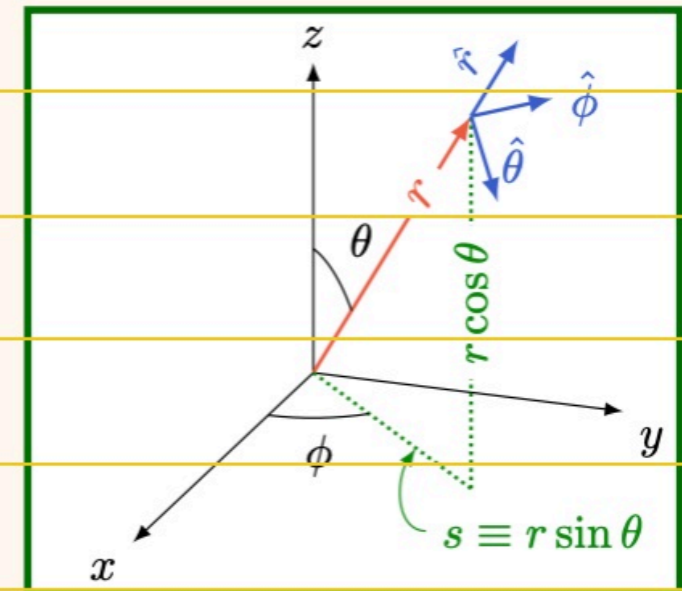
$$\vec{\mathbf{A}}(\vec{\mathbf{r}}, t) = \frac{qv}{4\pi\epsilon_0 c^2} \frac{\cos \theta \hat{\mathbf{R}} - \sin \theta \hat{\boldsymbol{\theta}}}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

Campo magnético

Coordenadas esféricas

$$d\vec{\ell} = dr \hat{r} + r d\theta \hat{\theta} + r \sin \theta d\phi \hat{\phi}$$

$$\vec{\nabla} t = \frac{\partial t}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial t}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial t}{\partial \phi} \hat{\phi}$$



$$\vec{\nabla} \cdot \vec{v} = \frac{1}{r^2} \frac{\partial (r^2 v_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial (\sin \theta v_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$$

$$\begin{aligned} \vec{\nabla} \times \vec{v} = & \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta v_\phi) - \frac{\partial v_\theta}{\partial \phi} \right] \hat{r} \\ & + \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\theta} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\phi} \end{aligned}$$

$$\nabla^2 t = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial t}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial t}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 t}{\partial \phi^2}$$

Campo magnético

$$\vec{\mathbf{A}}(\vec{\mathbf{r}}, t) = \frac{\vec{\mathbf{v}}}{4\pi\epsilon_0 c^2} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{\mathbf{A}}(\vec{\mathbf{r}}, t) = \frac{qv}{4\pi\epsilon_0 c^2} \frac{\cos \theta \hat{\mathbf{R}} - \sin \theta \hat{\boldsymbol{\theta}}}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{\nabla} \times \vec{\mathbf{A}} = \frac{1}{R} \left(\frac{\partial(Rv_\theta)}{\partial R} - \frac{\partial v_R}{\partial \theta} \right) \hat{\boldsymbol{\phi}}$$

Campo magnético

$$\vec{\mathbf{A}}(\vec{\mathbf{r}}, t) = \frac{\vec{\mathbf{v}}}{4\pi\epsilon_0 c^2} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{\mathbf{A}}(\vec{\mathbf{r}}, t) = \frac{qv}{4\pi\epsilon_0 c^2} \frac{\cos \theta \hat{\mathbf{R}} - \sin \theta \hat{\boldsymbol{\theta}}}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

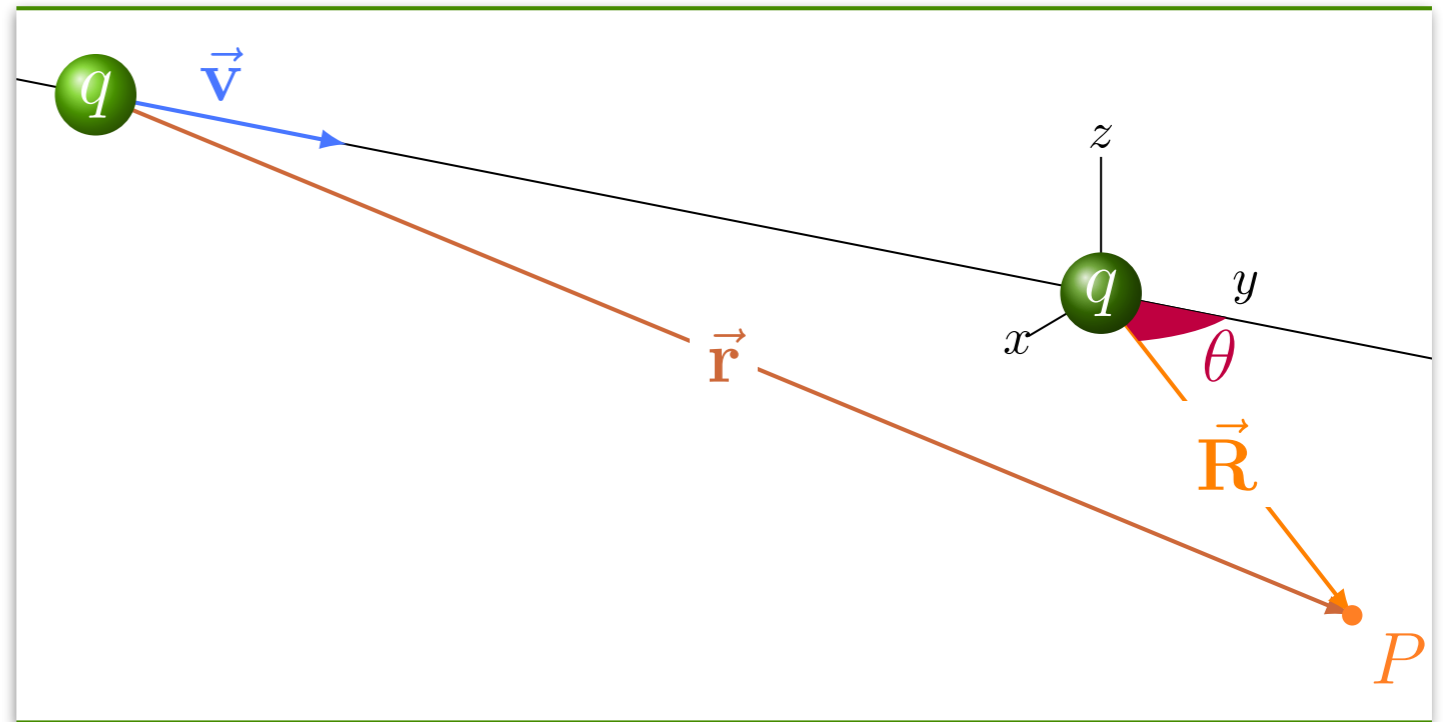
$$\vec{\nabla} \times \vec{\mathbf{A}} = \frac{1}{R} \left(\frac{\partial(Rv_\theta)}{\partial R} - \frac{\partial v_R}{\partial \theta} \right) \hat{\boldsymbol{\phi}}$$

$$\vec{\mathbf{B}} = \frac{qv \sin \theta}{4\pi\epsilon_0 c^2} \frac{1 - \frac{v^2}{c^2}}{R^2 \left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \hat{\boldsymbol{\phi}}$$

Movimento uniforme

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$



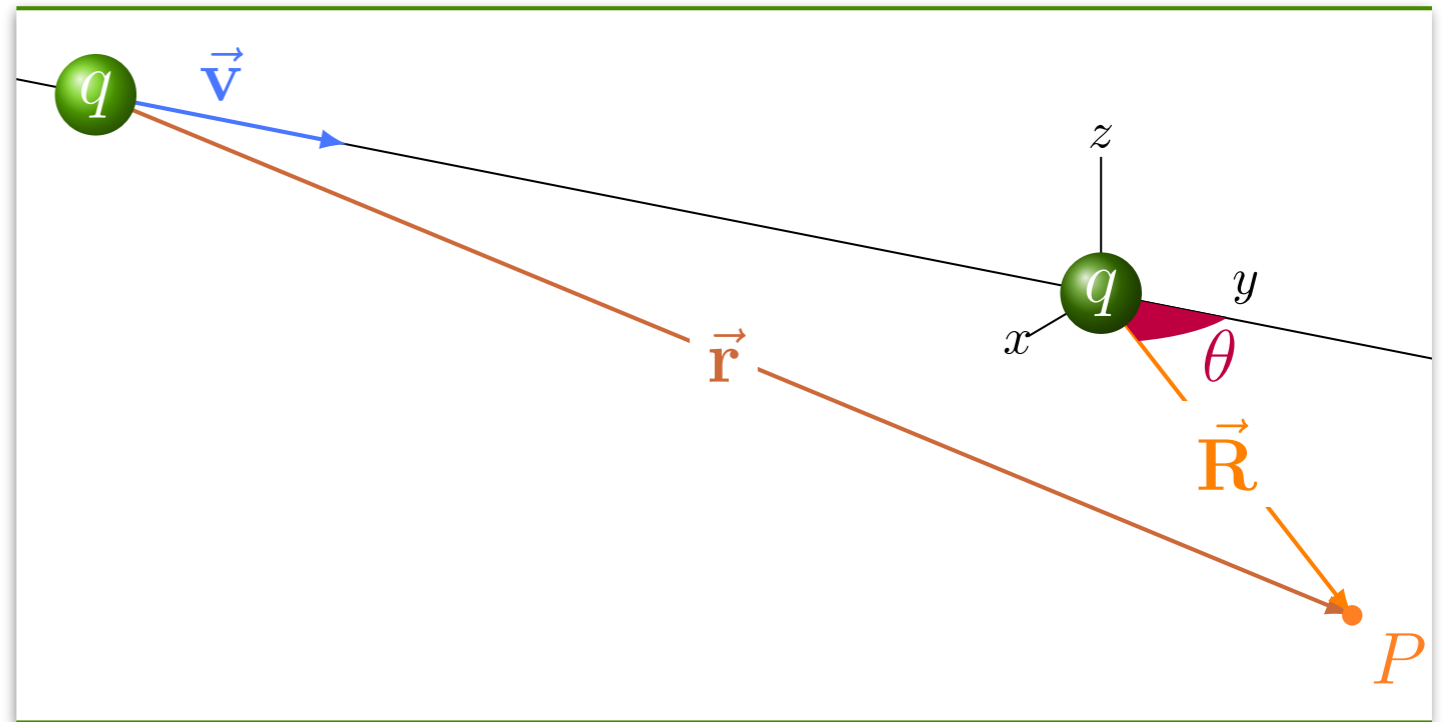
$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2}$$

$$\vec{B} = \frac{\mu_0 q}{4\pi} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} v \sin \theta \frac{\hat{\varphi}}{R^2}$$

Movimento uniforme

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$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$



$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2}$$

$$\vec{B} = \frac{\mu_0 q}{4\pi} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} v \sin \theta \frac{\hat{\phi}}{R^2}$$

$$\vec{B} = \frac{\vec{v}}{c^2} \times \vec{E}$$

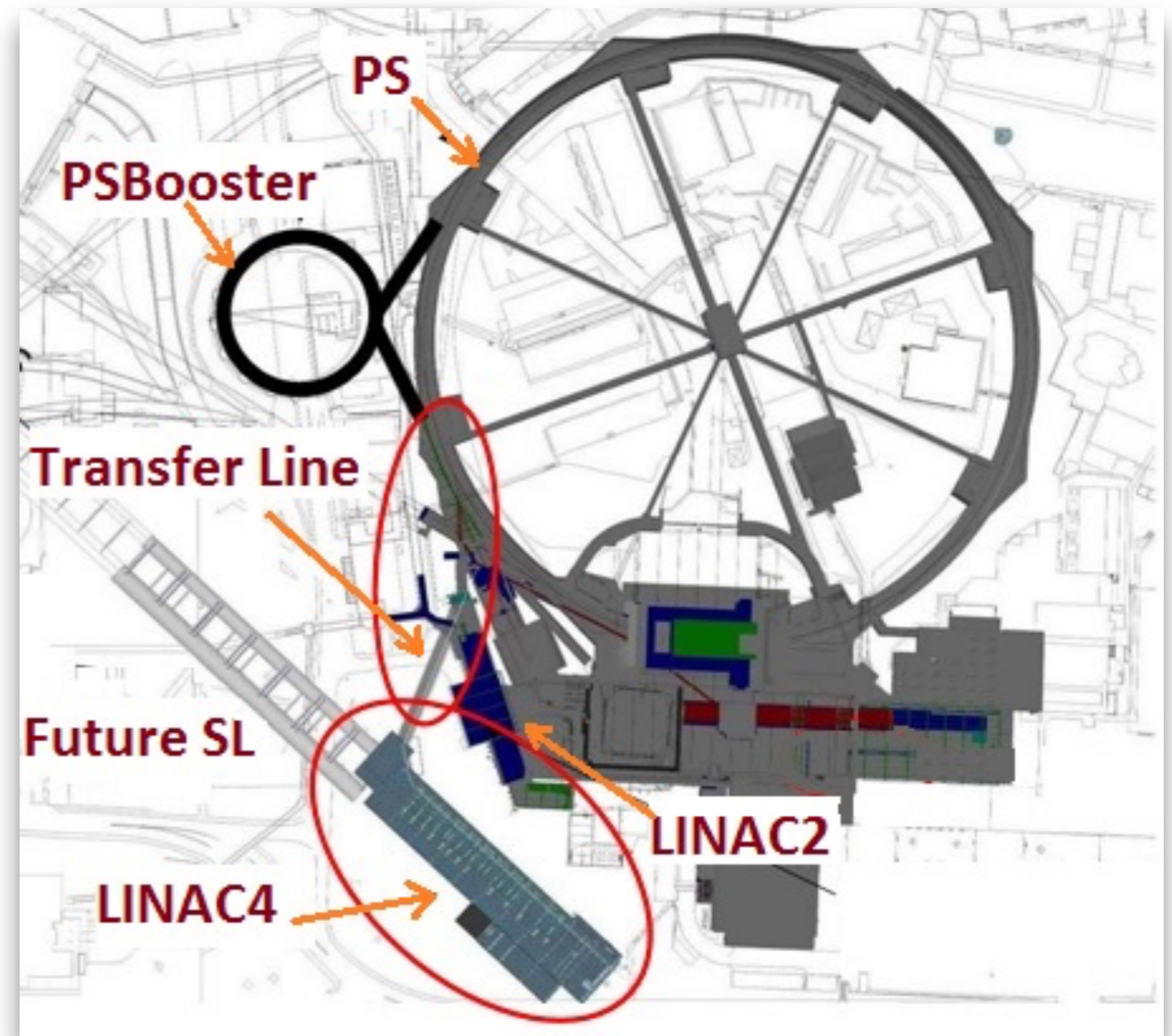
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$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

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$$\vec{B} = \frac{\mu_0 q}{4\pi} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} v \sin \theta \frac{\hat{\varphi}}{R^2}$$



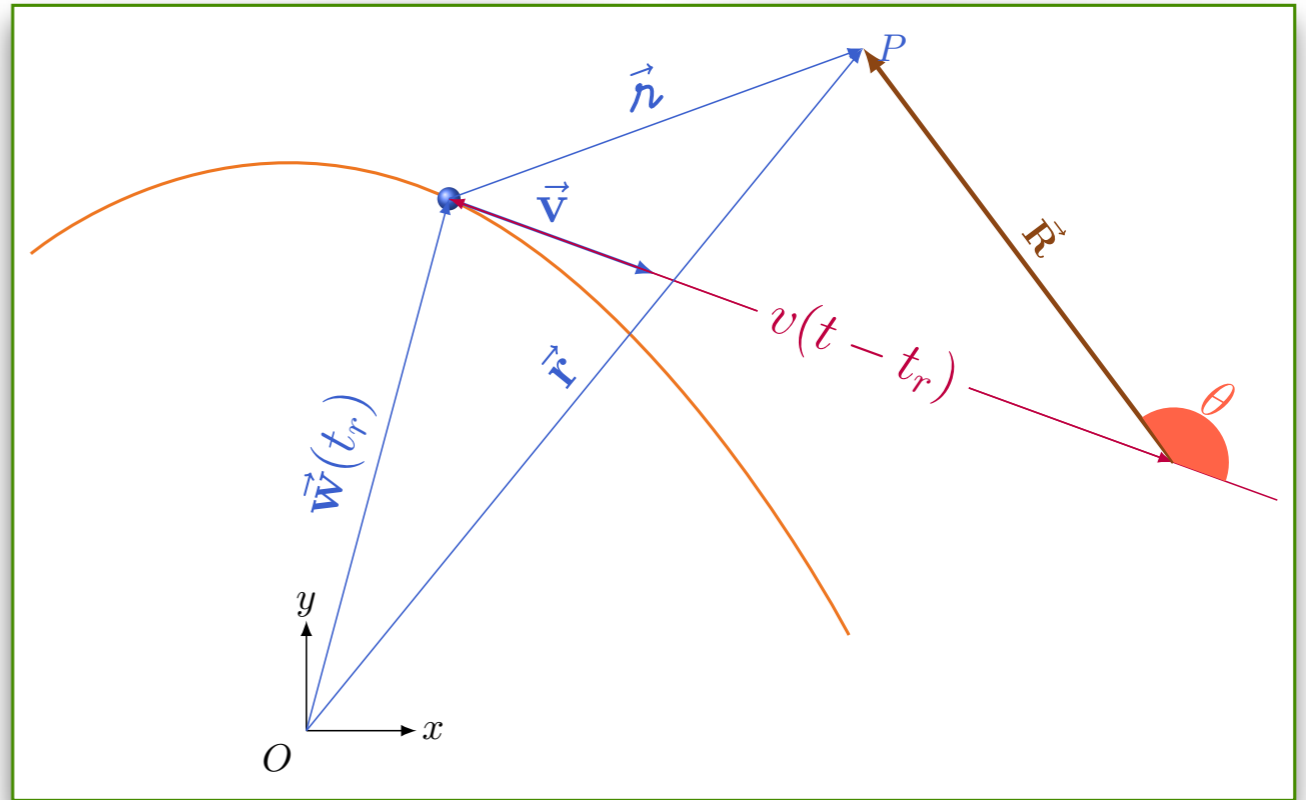
Movimento acelerado

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2} - \left(\frac{\partial \vec{A}}{\partial t}\right)_{\vec{v}}$$



Movimento acelerado

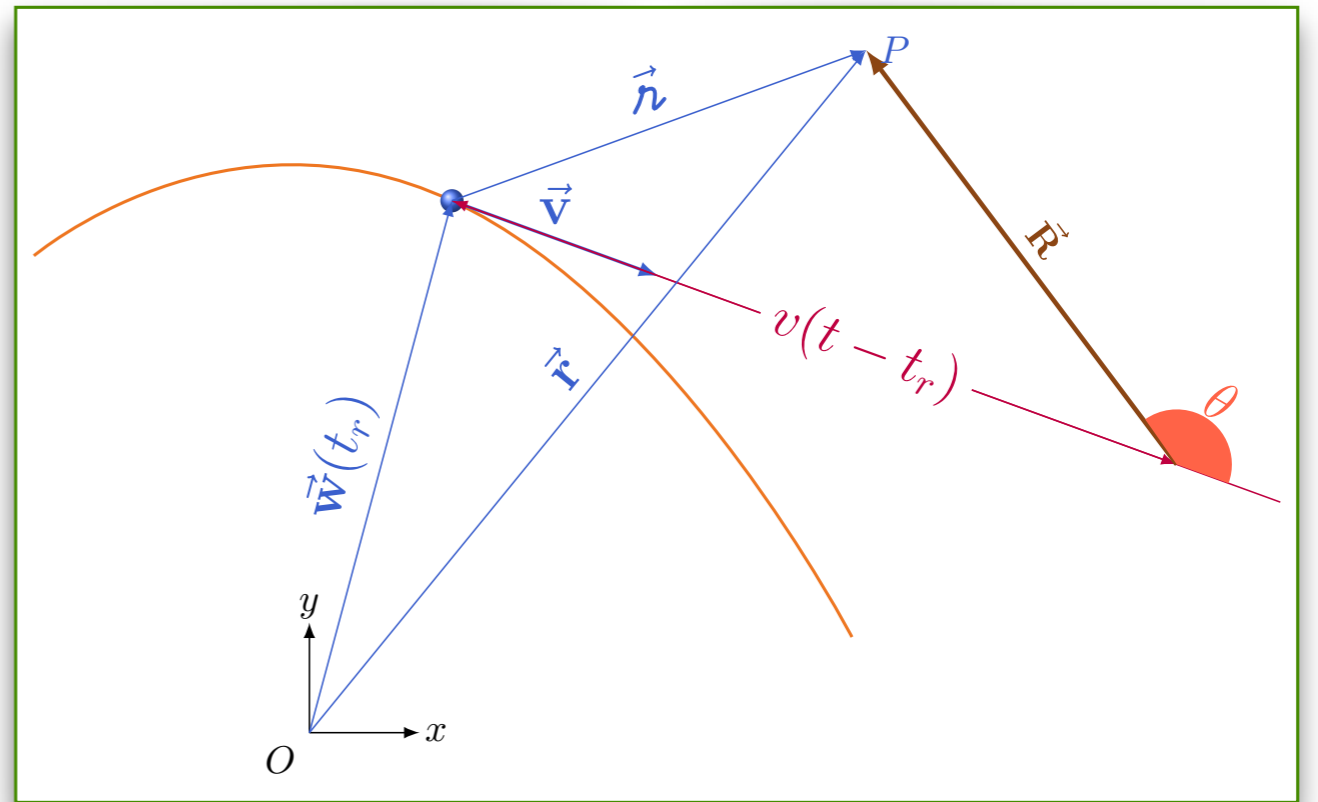
$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{1}{2}}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2} - \left(\frac{\partial \vec{A}}{\partial t}\right)_{\vec{v}}$$

$$\frac{\partial \vec{A}}{\partial t} \Big|_v = \frac{q}{4\pi\epsilon_0 c^2} \left(\frac{\vec{a}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{1}{2}}} + \frac{\vec{v} \frac{v\dot{v}}{c^2} \sin^2 \theta}{(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}} R} \right)$$



Movimento acelerado

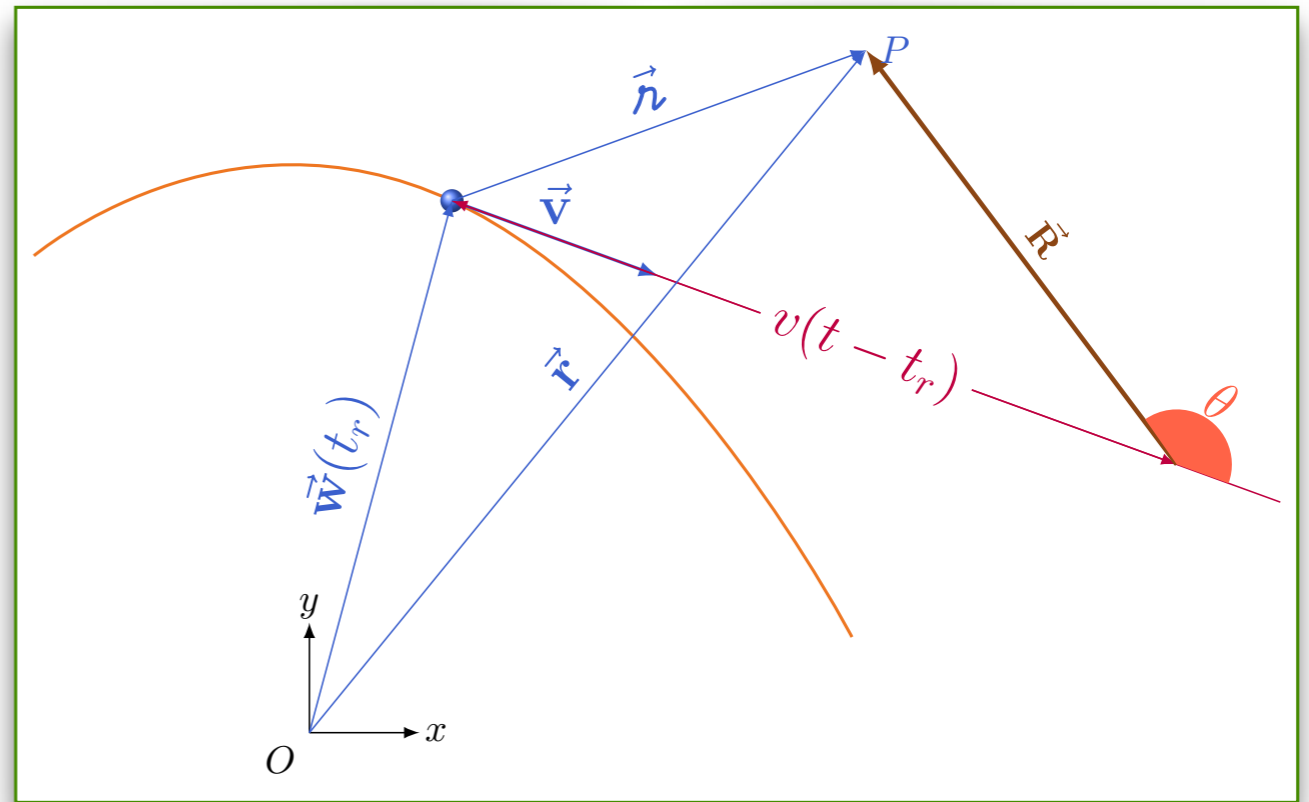
$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{1}{2}}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2} - \left(\frac{\partial \vec{A}}{\partial t}\right)_{\vec{v}}$$

$$\frac{\partial \vec{A}}{\partial t} \Big|_v = \frac{q}{4\pi\epsilon_0 c^2} \left(\frac{\vec{a}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}}} + \frac{\frac{\vec{v}v\dot{v} - \vec{a}v^2}{c^2} \sin^2 \theta}{(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}} R} \right)$$

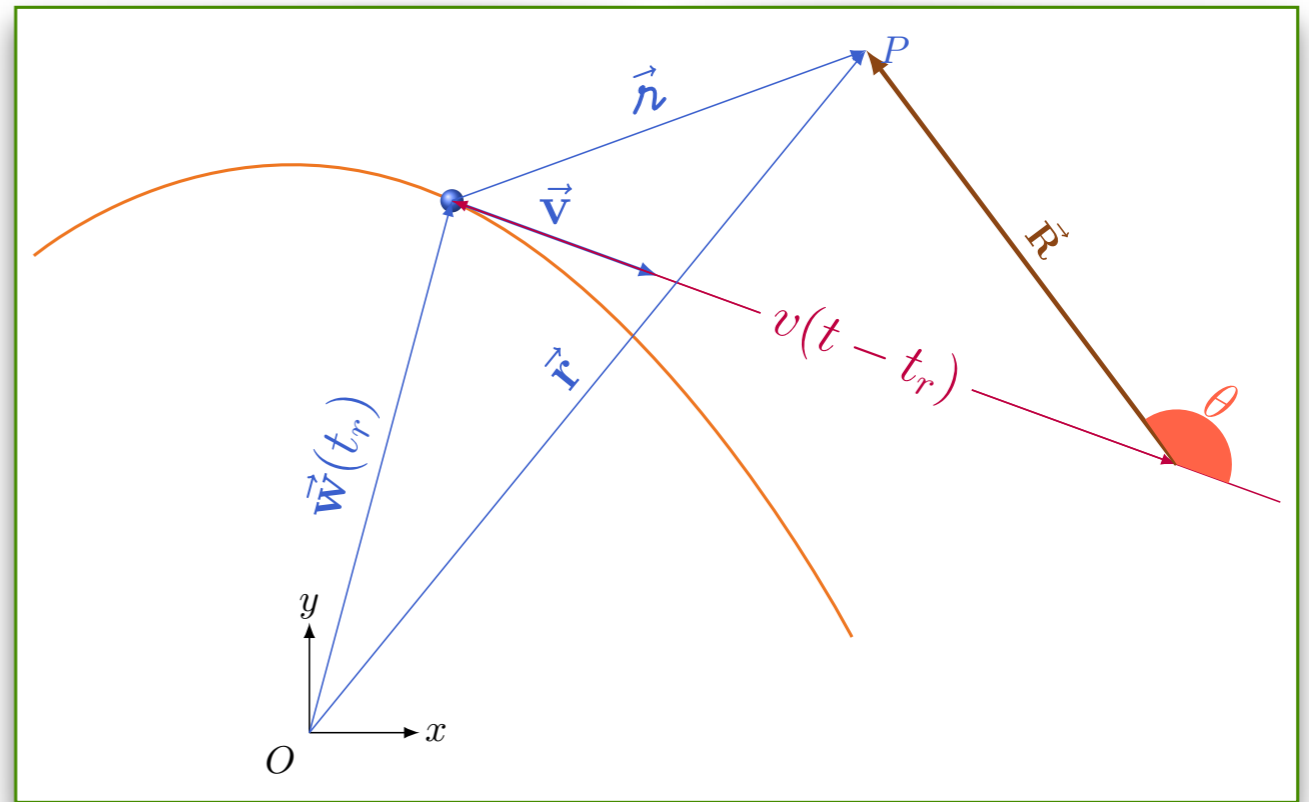


Movimento acelerado

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{1}{2}}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$



$$\vec{v} = v(\cos \theta \hat{R} - \sin \theta \hat{\theta})$$

$$\vec{a} = \dot{v}(\cos \theta \hat{R} - \sin \theta \hat{\theta}) - v\dot{\theta}(\sin \theta \hat{R} + \cos \theta \hat{\theta})$$

$$\Rightarrow \vec{v} \cdot \vec{a} = v\dot{v}$$

Movimento acelerado

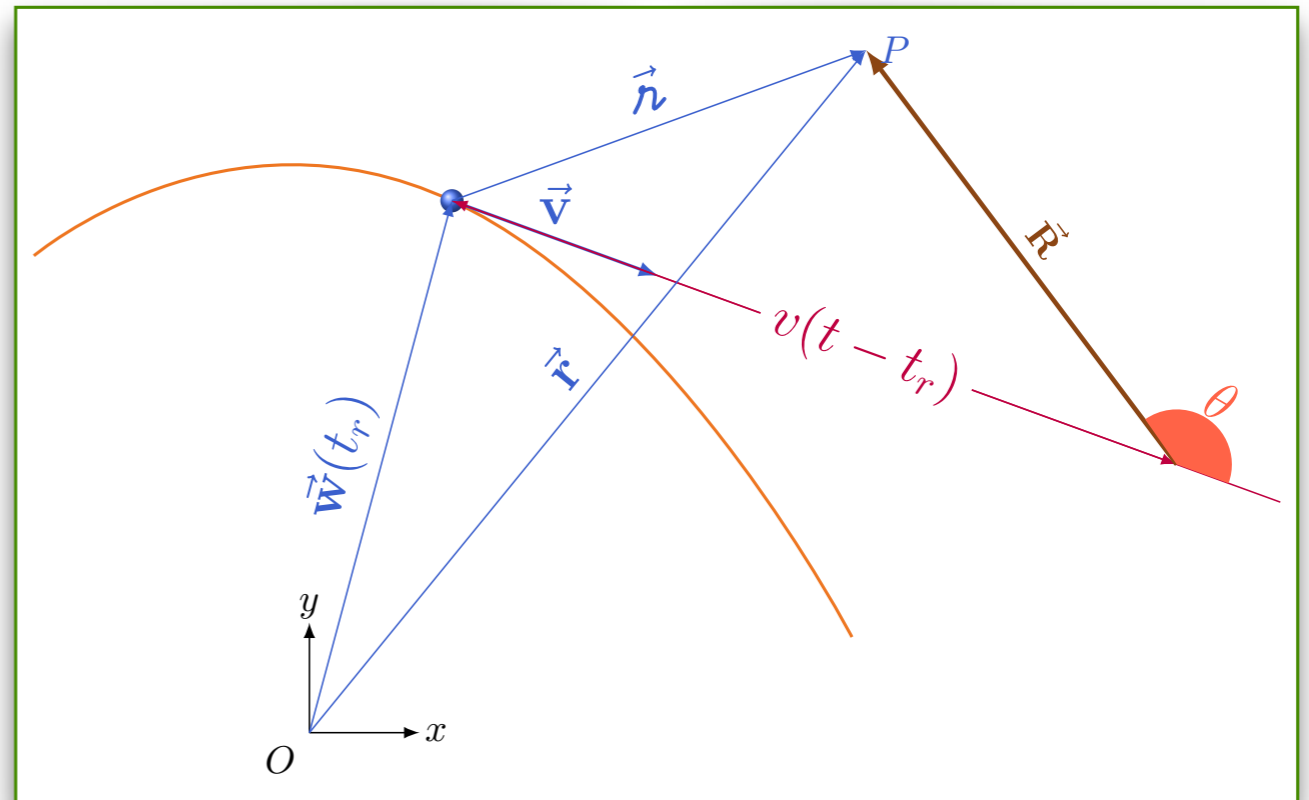
$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2} - \left(\frac{\partial \vec{A}}{\partial t}\right)_{\vec{v}}$$

$$\frac{\partial \vec{A}}{\partial t} \Big|_v = \frac{q}{4\pi\epsilon_0 c^2} \left(\frac{\vec{a}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}}} + \frac{(\vec{v} \cdot \vec{a})\vec{v} - v^2 \vec{a}}{c^2 (1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}} R} \right)$$



Movimento acelerado

$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0} \frac{q}{R\sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}}$$

$$\vec{A}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\vec{v}}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}}}$$

$$\vec{E} = -\vec{\nabla}V - \partial_t \vec{A}$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{\frac{3}{2}}} \frac{\hat{R}}{R^2} - \left(\frac{\partial \vec{A}}{\partial t}\right)_{\vec{v}}$$

$$\frac{\partial \vec{A}}{\partial t}_v = \frac{q}{4\pi\epsilon_0 c^2} \frac{1}{R(1 - \frac{v^2}{c^2} \sin^2 \theta)^{\frac{3}{2}}} \left(\vec{a} + \vec{v} \times (\vec{v} \times \vec{a}) \frac{\sin^2 \theta}{c^2} \right)$$

