PEF 5737 - Nonlinear dynamics and stability Direct parametrization of invariant manifolds

Prof. Carlos Eduardo Nigro Mazzilli Associate Professor Guilherme Rosa Franzini

Escola Politécnica, University of São Paulo, Brazil

cenmazzi@usp.br gfranzini@usp.br

11/15/2023



11/15/2023

1/13

Escola Politécnica da Universidade de São Paulo

PEF 5737 - Nonlinear dynamics and stability Direct parametrization of invariant manifolds

Prof. Carlos Eduardo Nigro Mazzilli Associate Professor Guilherme Rosa Franzini

Escola Politécnica, University of São Paulo, Brazil

cenmazzi@usp.br gfranzini@usp.br

11/15/2023

Image: A matrix and a matrix

11/15/2023

2/13

- To present a big picture on the method of direct parametrization of invariant manifolds;
- Reference
 - Alessandra Vizzaccaro, Andrea Opreni, Loïc Salles, Atilio Frangi, Cyril Touzé. High order direct parametrisation of invariant manifolds for model order reduction of finite element structures: application to large amplitude vibrations and uncovering of a folding point. Nonlinear Dynamics, 110(1), 521-575, 2022.

(日)

Full-order model

• Consider the full-order model (FOM) with N degrees of freedom

$$M\ddot{U} + C\dot{U} + KU + G(U, U) + H(U, U, U) = 0$$
 (1)

with linear mass, damping and stiffness matrices known. Tensors ${\cal G}_{rs}$ and ${\cal H}_{rst}$ are also known.

Properties of the undamped linear system

$$(-\omega_j^2 M + K)\Phi_j = 0$$
⁽²⁾

$$\boldsymbol{\Phi_j}^T \boldsymbol{M} \boldsymbol{\Phi_j} = 1 \tag{3}$$

$$\boldsymbol{\Phi_j}^T \boldsymbol{K} \boldsymbol{\Phi_j} = \omega_j^2 \tag{4}$$

• Nodal displacements and velocities $U, V = \dot{U} \Rightarrow$. Modal displacement and velocities $u_j = \Phi_j^T M U$ and $v_j = \Phi_j^T M V$

• Lightly damped systems, with $C = a_1 M + a_2 K \Rightarrow$ Vector Φ_j make C diagonal $(\Phi_j{}^T C \Phi_j = 2\xi_j \omega_j)$

Full-order model

Damped eigenvalue problem

$$(\Lambda_j^2 \boldsymbol{M} + \Lambda_j \boldsymbol{C} + \boldsymbol{K}) \boldsymbol{\Phi}_j = \boldsymbol{0}$$
(5)

$$\Lambda_j = -\xi\omega_j + i\omega_j\sqrt{1-\xi_j^2} \tag{6}$$

$$\bar{\Lambda}_j = -\xi \omega_j - i\omega_j \sqrt{1 - \xi_j^2} \tag{7}$$

First-order FOM

$$M\dot{V} + CV + KU + G(U, U) + H(U, U, U) = 0$$
 (8)
 $M\dot{U} = MV$ (9)

• Since the first-order FOM has dimension 2N, we sort the eigenvalues as $\Lambda_j = -\xi \omega_j + i\omega_j \sqrt{1-\xi_j^2}$ and $\Lambda_{j+N} = -\xi \omega_j - i\omega_j \sqrt{1-\xi_j^2}$

Right eigenvectors of the first-order FOM

$$\begin{pmatrix} \Lambda_s \begin{bmatrix} \boldsymbol{M} & \boldsymbol{0} \\ \boldsymbol{0} & \boldsymbol{M} \end{bmatrix} + \begin{bmatrix} \boldsymbol{C} & \boldsymbol{K} \\ -\boldsymbol{M} & \boldsymbol{0} \end{bmatrix} \end{pmatrix} \mathbb{Y}_s = \boldsymbol{0}$$
(10)

$$\mathbb{Y}_{s} = \left\{ \begin{array}{c} \Phi_{s} \Lambda_{s} \\ \Phi_{s} \end{array} \right\} \in \mathbb{C} \tag{11}$$

Full-order model

• We sort the right eigenvectors as

$$\mathbb{Y}_{j} = \left\{ \begin{array}{c} \Phi_{j} \Lambda_{j} \\ \Phi_{j} \end{array} \right\}, \mathbb{Y}_{j+N} = \left\{ \begin{array}{c} \Phi_{j} \bar{\Lambda}_{j} \\ \Phi_{j} \end{array} \right\} = \bar{\mathbb{Y}}_{j}$$
(12)

• Left eigenvectors of the first-order FOM

$$\mathbb{X}_{s}^{T}\left(\Lambda_{s}\begin{bmatrix}\boldsymbol{M} & \boldsymbol{0}\\ \boldsymbol{0} & \boldsymbol{M}\end{bmatrix} + \begin{bmatrix}\boldsymbol{C} & \boldsymbol{K}\\ -\boldsymbol{M} & \boldsymbol{0}\end{bmatrix}\right) = \boldsymbol{0}$$
(13)
(14)

• The left eigenvectors are sorted as

$$\mathbb{X}_{j} = \frac{1}{\Lambda_{j} - \bar{\Lambda}_{j}} \left\{ \frac{\Phi_{j}}{-\bar{\Lambda}_{j} \Phi_{j}} \right\}, \mathbb{X}_{j+N} = \bar{\mathbb{X}}_{j}$$
(15)

Properties

$$\mathbb{X}_{r}^{T}\begin{bmatrix}\boldsymbol{M} & \boldsymbol{0}\\ \boldsymbol{0} & \boldsymbol{M}\end{bmatrix}\mathbb{Y}_{s} = \delta_{rs} \qquad \qquad \mathbb{X}_{r}^{T}\begin{bmatrix}\boldsymbol{C} & \boldsymbol{K}\\ -\boldsymbol{M} & \boldsymbol{0}\end{bmatrix}\mathbb{Y}_{s} = -\Lambda_{r}\delta_{rs} \qquad (16)$$

6/13

Preparing the reduced-order model (ROM)

- $\mathcal{M} = \{m_1 \ m_2 \ \dots \ m_n\}$ is a set of master modes. $n \ll N$ is the number of master modes and corresponds to the dimension of the ROM
- We define the following matrices

$$\begin{aligned} \boldsymbol{X} &= [\boldsymbol{\mathbb{X}}_{m_1} \ \boldsymbol{\mathbb{X}}_{m_2} \dots \boldsymbol{\mathbb{X}}_{m_n} \ \bar{\boldsymbol{\mathbb{X}}}_{m_1} \ \bar{\boldsymbol{\mathbb{X}}}_{m_2} \dots \bar{\boldsymbol{\mathbb{X}}}_{m_n}] = [\boldsymbol{X}_1 \ \boldsymbol{X}_2 \ \dots \boldsymbol{X}_n \ \bar{\boldsymbol{X}}_1 \ \bar{\boldsymbol{X}}_2 \ \dots \bar{\boldsymbol{X}}_n] \quad (17) \\ \boldsymbol{Y} &= [\boldsymbol{\mathbb{Y}}_{m_1} \ \boldsymbol{\mathbb{Y}}_{m_2} \dots \boldsymbol{\mathbb{Y}}_{m_n} \ \bar{\boldsymbol{\mathbb{Y}}}_{m_1} \ \bar{\boldsymbol{\mathbb{Y}}}_{m_2} \dots \bar{\boldsymbol{\mathbb{Y}}}_{m_n}] = [\boldsymbol{Y}_1 \ \boldsymbol{Y}_2 \ \dots \boldsymbol{Y}_n \ \bar{\boldsymbol{Y}}_1 \ \bar{\boldsymbol{Y}}_2 \ \dots \bar{\boldsymbol{Y}}_n] \quad (18) \\ \boldsymbol{\lambda} &= diag(\boldsymbol{\Lambda}_{m_1} \ \boldsymbol{\Lambda}_{m_2} \ \dots \ \boldsymbol{\Lambda}_{m_n} \ \bar{\boldsymbol{\Lambda}}_{m_1} \ \bar{\boldsymbol{\Lambda}}_{m_2} \ \dots \ \bar{\boldsymbol{\Lambda}}_{m_n}) = \\ &= diag(\boldsymbol{\lambda}_1 \ \boldsymbol{\lambda}_2 \ \dots \ \boldsymbol{\lambda}_n \ \bar{\boldsymbol{\lambda}}_1 \ \bar{\boldsymbol{\lambda}}_2 \ \dots \ \bar{\boldsymbol{\lambda}}_n) \quad (19) \\ \boldsymbol{\phi} &= [\boldsymbol{\Phi}_{m_1} \ \boldsymbol{\Phi}_{m_2} \ \dots \ \boldsymbol{\Phi}_{m_n} \ \boldsymbol{\Phi}_{m_1} \ \boldsymbol{\Phi}_{m_2} \ \dots \ \boldsymbol{\Phi}_{m_n}] = [\boldsymbol{\Phi}_1 \ \boldsymbol{\Phi}_2 \ \dots \ \boldsymbol{\Phi}_n \ \boldsymbol{\Phi}_1 \ \boldsymbol{\Phi}_2 \ \dots \ \boldsymbol{\Phi}_n] \quad (20) \end{aligned}$$

• Dimensions:
$$m{X}_{2N imes 2n}$$
, $m{Y}_{2N imes 2n}$, $m{\lambda}_{2n imes 2n}$, $\phi_{N imes 2n}$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Definitions

- The dynamics will be described in a 2n-dimensional manifold. The coefficient 2 is due to the pair displacement-velocity
- We introduce $z_{2n \times 1}$ normal coordinates for describing the dynamics on the mentioned manifold $\Rightarrow \dot{z} = f(z)$
- Nonlinear mappings: $oldsymbol{U} = oldsymbol{\Psi}(oldsymbol{z})$ and $oldsymbol{V} = oldsymbol{\Upsilon}(oldsymbol{z})$
- Idea: We will expand the nonlinear mappings Ψ, Υ and the reduced dynamics f as polynomial functions of z. The goal is to identify the coefficients of the mentioned expansion
- Notice that
 - **1** ROMs from the normal forms: Expand \Rightarrow Reduce
 - ② ROMs from DPIM: Reduce ⇒ Expand

and here we go ...

• Chain rule:

$$\dot{\boldsymbol{U}} = \boldsymbol{\nabla}_{\boldsymbol{z}} \boldsymbol{\Psi}(\boldsymbol{z}) \dot{\boldsymbol{z}} = \boldsymbol{\nabla}_{\boldsymbol{z}} \boldsymbol{\Psi}(\boldsymbol{z}) \boldsymbol{f}(\boldsymbol{z}) = \sum_{s=1}^{2n} \frac{\partial \boldsymbol{\Psi}(\boldsymbol{z})}{\partial z_s} f_s(\boldsymbol{z})$$
(21)

$$\dot{\boldsymbol{V}} = \boldsymbol{\nabla}_{\boldsymbol{z}} \boldsymbol{\Upsilon}(\boldsymbol{z}) \dot{\boldsymbol{z}} = \boldsymbol{\nabla}_{\boldsymbol{z}} \boldsymbol{\Upsilon}(\boldsymbol{z}) \boldsymbol{f}(\boldsymbol{z}) = \sum_{s=1}^{2n} \frac{\partial \boldsymbol{\Upsilon}(\boldsymbol{z})}{\partial z_s} f_s(\boldsymbol{z})$$
(22)

• Substituting the above quantities into the first-order equation of motion of the FOM

$$M\nabla_{\boldsymbol{z}}\Upsilon(\boldsymbol{z})f(\boldsymbol{z}) + C\Upsilon(\boldsymbol{z}) + K\Psi(\boldsymbol{z}) + G(\Psi(\boldsymbol{z}),\Psi(\boldsymbol{z})) + H(\Psi(\boldsymbol{z}),\Psi(\boldsymbol{z}),\Psi(\boldsymbol{z})) = 0$$
(23)

$$M\nabla_{\boldsymbol{z}}\Psi(\boldsymbol{z})\boldsymbol{f}(\boldsymbol{z}) = M\Upsilon(\boldsymbol{z}) \tag{24}$$

▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ 三臣 - のへで 11/15/2023

Homological equations

- Since the expansion is made around an equilibrium position, the zero-order term is not included in the expansion.
- Assuming that o is the maximum order employed in the expansion and that []p contains only monomials of order p in the components of z, we have

$$\Psi(z) = \sum_{p=1}^{o} [\Psi(z)]_p$$
(25)
$$\Upsilon(z) = \sum_{p=1}^{o} [\Upsilon(z)]_p$$
(26)
$$f(z) = \sum_{p=1}^{o} [f(z)]_p$$
(27)

11/15/2023

10/13

The order-p homological equations read

$$M[
abla_{oldsymbol{z}} \Upsilon(oldsymbol{z}) f(oldsymbol{z})]_p + C[\Upsilon(oldsymbol{z})]_p + K[\Psi(oldsymbol{z})]_p + [G(\Psi(oldsymbol{z}),\Psi(oldsymbol{z}))]_p +$$

$$+ [H(\Psi(\boldsymbol{z}), \Psi(\boldsymbol{z}), \Psi(\boldsymbol{z}))]_p = 0$$
 (28)

$$M[\nabla_{\boldsymbol{z}} \Psi(\boldsymbol{z}) f(\boldsymbol{z})]_p = M[\Upsilon(\boldsymbol{z})]_p$$
(29)

As in other methods, the solution is started with p = 1 and, then, the homological equations are solved in sequential order

Mazzilli & Franzini (EPUSP)

Homological equation for p = 1

• For p = 1, the nonlinear terms associated with tensors G_{rs} and H_{rst} do not appear. Hence, we have:

$$M[\nabla_{\boldsymbol{z}} \Upsilon(\boldsymbol{z}) \boldsymbol{f}(\boldsymbol{z})]_1 + C[\Upsilon(\boldsymbol{z})]_1 + K[\Psi(\boldsymbol{z})]_1 = 0$$
(30)

$$M[\nabla_{\boldsymbol{z}}\Psi(\boldsymbol{z})f(\boldsymbol{z})]_1 = M[\Upsilon(\boldsymbol{z})]_1$$
(31)

• Notice that p = 1 corresponds to the linear part of the expansion. The unknowns for this problem read:

$$[\Upsilon(z)]_1 = \Upsilon_{N \times 2n}^{(1)} z$$
(32)

$$[\boldsymbol{\Psi}(\boldsymbol{z})]_1 = \boldsymbol{\Psi}_{N \times 2n}^{(1)} \boldsymbol{z}$$
(33)

$$[f(z)]_1 = f_{2n \times 2n}^{(1)} z$$
 (34)

イロト イポト イヨト イヨト 二日

11/15/2023

11/13

• With the above definitions, the homological equations for p = 1 become:

$$M\Upsilon^{(1)}f^{(1)}z + C\Upsilon^{(1)}z + K\Psi^{(1)}z = 0$$
(35)

$$M\Psi^{(1)}f^{(1)}z = M\Upsilon^{(1)}z$$
(36)

Homological equation for p = 1

• The last set of equation must be valid for any z. Hence, we obtain:

$$\begin{bmatrix} M & 0\\ 0 & M \end{bmatrix} \begin{pmatrix} \Upsilon^{(1)}\\ \Psi^{(1)} \end{pmatrix} f^{(1)} + \begin{bmatrix} C & K\\ -M & 0 \end{bmatrix} \begin{pmatrix} \Upsilon^{(1)}\\ \Psi^{(1)} \end{pmatrix} = \begin{cases} 0\\ 0 \end{cases}$$
(37)

• The above equation has the same form of the right eigenvalue problem and, then,

$$\begin{cases} \Upsilon^{(1)} \\ \Psi^{(1)} \end{cases} = \begin{cases} \phi \lambda \\ \phi \end{cases} = Y$$
 (38)

$$f^{(1)} = \lambda \tag{39}$$

▲□▶ ▲圖▶ ▲国▶ ▲国▶ - 国 - のQの

12/13

11/15/2023

• Conclusion (as expected): The linear part of the expansion matches the solution of the linearized problem. Higher-order terms (p > 1) correspond to corrections applied to the linearized problem

An introduction to the case with p > 1

• With the results for p = 1 at hand, the expansions read:

$$\Psi(z) = \phi z + \sum_{p=2}^{o} [\Psi(z)]_p$$

$$\Upsilon(z) = \phi \lambda z + \sum_{p=2}^{o} [\Upsilon(z)]_p$$
(40)
(41)

• Explicitly (similar expansion also valid for p > 1

$$[\Psi(z)]_p = \sum_{i_1=1}^{2n} \sum_{i_2=1}^{2n} \dots \sum_{i_p=1}^{2n} \Psi^{(p)}_{\{i_1 i_2 \dots i_p\}} z_{i_1} z_{i_2} \dots z_{i_p}$$
(42)

• For a more compact nomenclature, it is introduced set $\mathcal{I} = \{i_1 i_2 \dots i_p\}$ with p elements (cardinality). The monomial associated with a certain set \mathcal{I}^* is $\pi_{\mathcal{I}}^* = z_{i_1} z_{i_2} \dots$ and $\pi_{\mathcal{I}}^{(p)}$ represents all the monomials of order p for gathering all the monomials of order p.

• For example, the set $\mathcal{I} = \{1134\}$ is associated with the monomial $z_1^2 z_3 z_4$.

• With the introduced nomenclature, the expansion for $[\Psi]_p$ is $\sum_{\mathcal{I}} \Psi_{\mathcal{I}}^{(p)} \pi_{\mathcal{I}}^{(p)}$. Similar expression is valid for $[\Upsilon(z)]_p$

Mazzilli & Franzini (EPUSP)