Visualization techniques for hierarchical/network data

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Visual Mapping

https://www.data -to-viz.com/

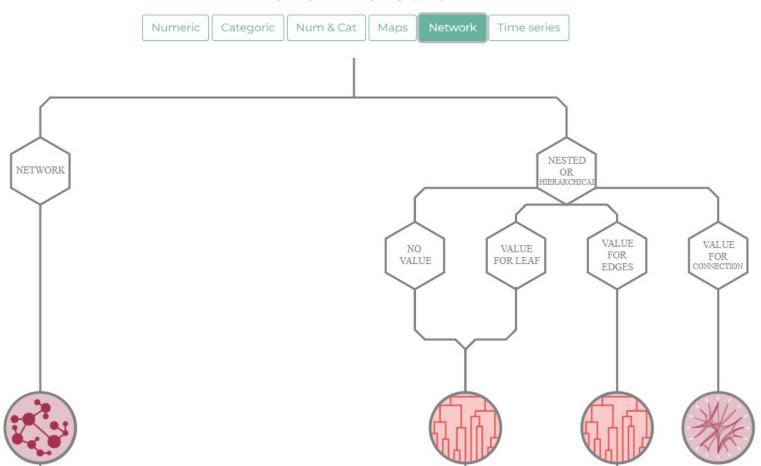
What kind of data do you have? (*network*)

Which goal? (show part of a whole, show data flow, data connections)

Which techniques are available?

data vs (task) vs visualization technique

What kind of data do you have? Pick the main type using the buttons below. Then let the decision tree guide you toward your graphic possibilities.



A WORLD OF POSSIBILITIES



Sunburst

A WORLD OF POSSIBILITIES

Here is an overview of all the graph types presented in this website.

Show all

Distribution

Correlation

Ranking

Part of a whole

Evolution

Мар

Flow







Network



Sankey



Arc diagram



Edge bundling

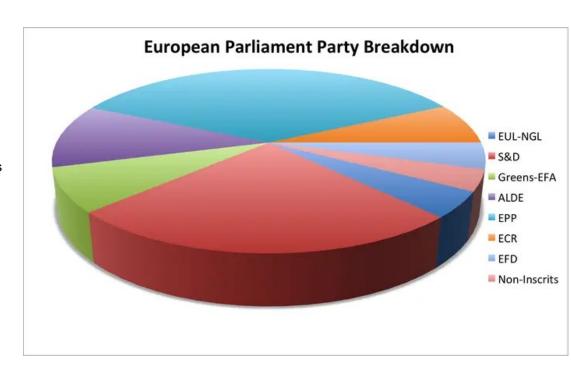
Examples

Task: show part of a whole (proportions/hierarchies), show nested or hierarchical data: pie chart, doughnut chart, dendogram, treemap,...

3D Pie chart

Looking at this chart, S&D—the red party —appears to be roughly even with EPP, the teal party.

But the reality is, that's becausel've distorted your perspective to make it seemas if red is in fact bigger.



source: https://www.businessinsider.com/pie-charts-are-the-worst-2013-6

Dendogram

a way to visualize ahierarchy or the results of a hierarchical clustering what is hierarchical clustering?

https://www.displayr.com/what -is-hierarchical-clustering/

Treemap

a treemap chart represents hierarchical data in atree-like structure data, organized as branches and sub-branches, is represented using rectangles the area and color of the rectangles can represent two numerical values it is possible to drill down within the data to, theoretically, an unlimited number of levels

area filling or spacefilling technique

Treemap

Example

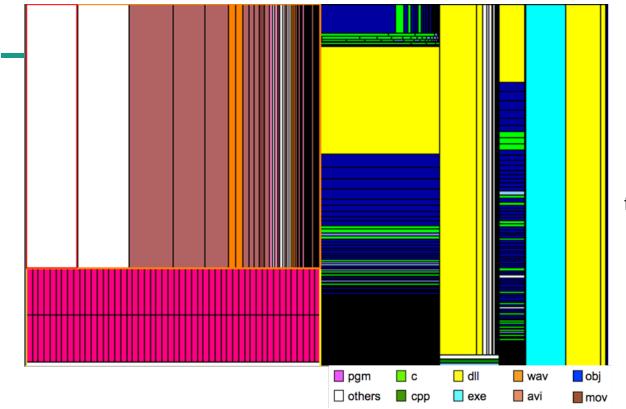
https://www.fusioncharts.com/resources/chart -primers/treemap -chart

interactivity is very important

Treemaps

Basic idea: 'slice and dice' layout

- 1 node = 1 rectangle
- child node rectangles: nested in the parent node rectangle (recursive subdivision)
- leaf rectangle size and color show data attributes
- edges: not drawn explicitly!
- very compact: tens of thousands of nodes on one screen
- aspect ratios are not very good; hierarchy depth unclear



ffmpeg C library

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source: Alex Telea

Example

https://newsmap.ijmacd.com/

Alternative approaches to visualize `trees

Many approachesto improve basicidea of treemap

Many alternative approachesto visualize trees...

https://treevis.net/

Example

www.onezoom.org

Networks/Graphs

Force-based placement layout

Force-directed graph layout algorithms are a class of algorithms for drawing graphs in an aesthetically-pleasing way.

Also called *spring-embedders*

Goal is to position the nodes of a graph in two-dimensional or threedimensional space so that all the edges are of more or less equal length and there are as few crossing edges as possible.

General layout problem

Input: Graph G = (V, E)

Output: clear and readable node-link drawing of G (straight line edges)

Aesthetics criteria?

Aesthetics criteria

Adjacent vertices close

Non-adjacent vertices far apart

Edgesshort, straight lines, similarlength

Densely connected parts (clusters) form `communities'

As few line crossings aspossible

Even distribution of vertices in space

Optimization criteria partially contradict each other... nooptimal solution meets all

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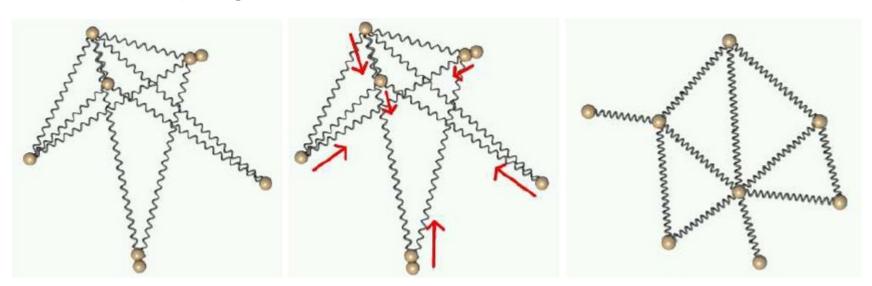
Even distribution of vertices in space

Peter Eades84 - "analogy with a mechanical system" Vertices as steel rings, edges as springs

Initial layout with the rings placed at arbitrary places Adjacent vertices connected by springs (edges)

Let go, spring forces act on the rings and move them, until the overall system reaches a stable minimum energy state

Generic spring embedder



https://arxiv.org/abs/1201.3011

Peter Eades84 - "analogy with a mechanical system" Vertices as steel rings, edges as springs

Attractive spring forces alone would collapse the system

Also needs repulsive forces – imagine rings are magnets all positive (or negative) which repel each other

Typically, the attractive force between the nodes modeled as springs are calculated using <u>Hooke's law</u>.

On the other hand, the magnet forces to push two nodes away from each other are modeled using <u>Coulomb's law</u>.

Hooke's law

the force (F) needed to extend or compress a spring by some distance (x) scales linearly with respect to that distance—that is, $F_s = kx$, where k is a constant factor characteristic of the spring (i.e., its stiffness), and x is small compared to the total possible deformation of the spring.

https://en.wikipedia.org/wiki/Hooke%27s_law

Coulomb's law

the magnitude of the electrostatic force of attraction or repulsion between two point charges is directly proportional to the product of the magnitudes of charges and inversely proportional to the square of the distance between them

$$|F|=k_{\mathrm{e}}rac{|q_{1}||q_{2}|}{r^{2}}$$

 $k_{\rm e}$ is Coulomb's constant ($k_{\rm e} \approx 8.988 \times 10^9 \,\mathrm{N \cdot m^2 \cdot C^{-2}}$), [1] $q_{\rm l}$ and $q_{\rm e}$ are the signed magnitudes of the charges, and the scalar r is the distance between the charges.

Example D3

https://observablehq.com/@d3/force -directed -graph

force-layout: many algorithms, basisfor node-link graph visualizations...

in Python: NetworkX and PyVis

Example yFiles

https://www.yworks.com/pages/force -directed-graph-layout

Force-directed layouts - algorithm

The attractive `spring´ forces attract pairs of nodes linked by edgestowards each other, while simultaneously the repulsive `electrical´ forces tend to pull all pairs of nodes apart

The behavior of the entire graph under these forces is simulated as if it were a physical system: the forces are applied to the all the nodes, pulling them closer together or pushing them further apart

This is repeated iteratively until the system comesto a mechanical equilibrium state; i.e.,their relative positions do not change anymore from one iteration to the next.

The positions of the nodes in this equilibrium are used to generate a drawing of the graph

```
Given G(V, E) {the vertices are assigned random initial positions}

At each iteration {parameters: # iterations, threshold value}

for each vertex v in V

compute the repulsive forces relative to all other vertices update resultant force in V

for each edge e = (µ, v) in E

compute the attractive forces relative to end nodes u and v

update resultant forces in u and V

for each vertex v in V

adjust placement of vaccording to final force in v

update parameters for iteration

end
```

See example (graph-based visualization) here:

https://colah.github.io/posts/2014-10-Visualizing-MNIST/

design an energy function $E : \mathbb{R}^{m} \rightarrow \mathbb{R}_{+}$ which is low when layout is 'good'

connected nodes should be close -> layout distance should reflect graph-theoretic distance

nodes should not overlap

aspect ratio should be balanced

Decisions to make

how to measure the quality of a layout (define 🖹), (e.g.,edge length, node overlap, edge crossing...)

what elements of the layout we parameterize (e.g., node position)

how to efficiently and effectively minimize the energy function

define *E* in terms of forces ($F = -\nabla E$)

$$egin{array}{ll} \mathbf{F}_a(n_i,n_j) &= rac{|\mathbf{p}_i - \mathbf{p}_j|^2}{k}, \ \mathbf{F}_r(n_i,n_j) &= -rac{k^2}{|\mathbf{p}_i - \mathbf{p}_j|} \end{array}$$

$$\mathbf{F}_{a}(n_{i}, n_{j}) = \frac{|\mathbf{p}_{i} - \mathbf{p}_{j}|^{2}}{k}, \qquad \mathbf{F}_{a}(n_{i}, n_{j}) = k \log |\mathbf{p}_{i} - \mathbf{p}_{j}|$$

$$\mathbf{F}_{r}(n_{i}, n_{j}) = -\frac{k^{2}}{|\mathbf{p}_{i} - \mathbf{p}_{j}|} \qquad \mathbf{F}_{r}(n_{i}, n_{j}) = -\frac{k}{|\mathbf{p}_{i} - \mathbf{p}_{j}|^{2}}.$$

[Fruchterman and Reingold '91]

[Eades '84]

or else directly:

$$=rac{1}{2}\sum_{i=1}^{N-1}\sum_{j=i+1}^{N}c_{ij}(|\mathbf{p}_i-\mathbf{p}-j|-d_{ij})^2.$$

[Kamada and Kawai '89]

find node positions p_i by minimizing E:

move nodes iteratively along F (since $F = -\nabla E$) with some small distance compute F, only w.r.t. close nodes (to save time)

use spatial search data structures (e.g. octrees) to find close nodes stop when E low enough or max #iterations reached

```
/*assign nodes to random initial positions
for (int i=0; i < N; i++)
       \mathbf{p}_i = \text{random position}
float t = t0
                                              /*initial maximal allowed move
for (int i=1; i < ITER; i++) { /*compute layout
               for (int i=0; i< N; i++) {
                              f_{i} = 0;
                              for (int j=0; j<N; j++) /* compute repulsive forces

if (j!=i) \mathbf{f}_i += \mathbf{F}_r(i,j);
                               for (int edge=0; edge<|E|; edge++) { /*compute attractive forces
                                              int i = edge.first; j = edge.second; /*get nodes adjacent to edge
                                              \mathbf{f}_{i} = \mathbf{F}_{a}(i,j); \quad \mathbf{f}_{i} + = \mathbf{F}_{a}(i,j);
       for (int i=0; i < N; i++) {
                                                                              /*move the nodes by applying forces
               \mathbf{p}_i += \mathbf{f}_i / || \mathbf{f}_i || * \min(\text{delta,t} * || \mathbf{f}_i ||);
       t = -= t*delta;
                                                                              /*reduce maximal allowed move t
                                                                                  source: Listing 1.1 Chap. 11, Book A. Telea<sub>7</sub>
```

Given G(V, E), N nodes

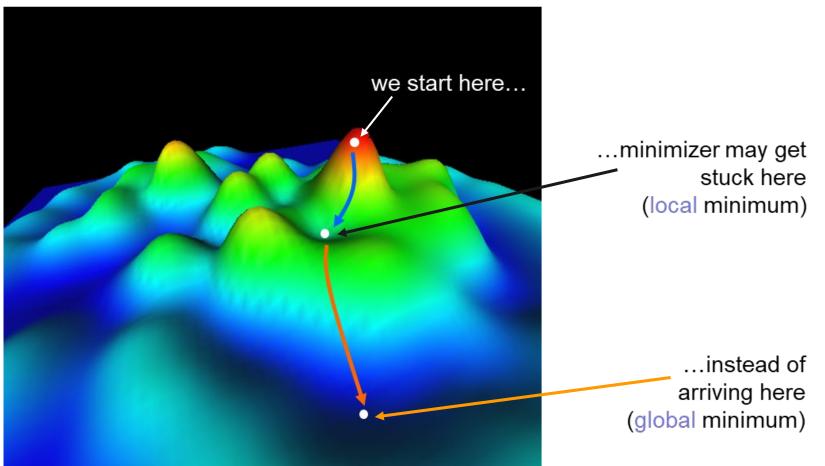
Problems

the energy function is not monotonic!

minimizers such as gradient descent work locally -> can get stuck in local minima

solve this by more advanced minimizers (see e.g. [Di Battista et al '94])

drawings not intuitive; no clear ordering -> where to start reading the drawing??



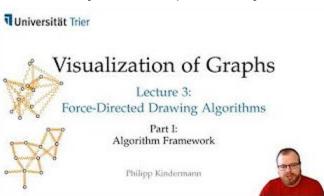
REPRODUZIR TUDO

Philipp Kindermann

Force - directed layouts

Excelente série de aulas:

https://www.youtube.comem/playlist?list=PLubYOWSI9mlvtnRjCCHP3wqNETTHYjQex



Limitation of node link views

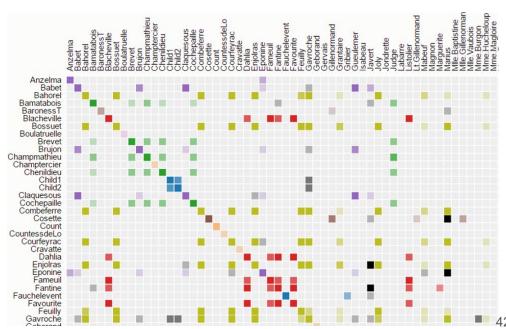
`hairball´effect on large graphs alternatives?

https://eagereyes.org/techniques/graphs-hairball

Alternative approaches to visualize

`graphs/networks

https://bost.ocks.org/mike/miserables/



Alternative layouts

radial/circular layouts, e.g.chord diagram and others

Graph visualization libraries

Cytoscape, software for visualising biological networks. The basepackage includes force-directed layouts asone of the built-in methods.

Gephi, an interactive visualization and exploration platform for all kinds of networks and complex systems, dynamic and hierarchical graphs.

Graphviz, software that implements a multilevel force-directed layout algorithm (among many others) capable of handling very large graphs.

Tulip, software that implements most of the force-directed layout algorithms (GEM, LGL, GRIP, FM³).

Prefuse, a Javabased toolkit for building interactive information visualization applications. https://github.com/prefuse/Prefuse

Improvement

edgebundling (networks, trees, trajectories,)

https://vega.github.io/vega/examples/edge-bundling/

References

Eades, Peter(1984), "A Heuristic for Graph Drawing", *Congressus Numerantium*, **42** (11): 149–160.

Fruchterman, Thomas M. J.; Reingold, Edward M. (1991), "Graph Drawing by Force-Directed Placement", *Software: Practice and Experiente* ley, **21** (11): 1129–1164, doi:10.1002/spe.4380211102, S2CID 31468174.