

# • Multi-objective Optimization Aiming to Minimize the Number of Power Quality Monitors and Multiple Fault Estimations in Unbalanced Power Distribution Systems

- Paulo E. T. Martins, Mário Oleskovicz
- University of de São Paulo – USP
- São Carlos School of Engineering – EESC
- Department of Electrical and Computer Engineering - SEL
- ICHQP 2022, May 29-June 1, Naples, Italy



## • Recently published article:

- MARTINS, P. E. T. and OLESKOVICZ, M. Multi-objective optimization aiming to minimize the number of power quality monitors and multiple fault estimations in unbalanced power distribution systems. **IEEE Transactions on Power Delivery**, vol. 37, no. 2, pp. 1315—1323, 2022.

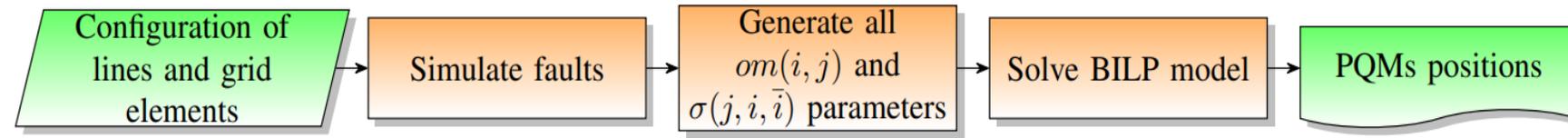
# • Topics

- Introduction and contributions
- Methodology
- Results and discussion
- Conclusions

# • Introduction and contributions

- **Several papers in transmission systems:** the **best locations** to install power quality monitors, **minimizing the investment cost** by focusing on the **observability of power quality disturbances**, mostly voltage sags.
- **Papers in distribution systems:** many problems remain unsolved, such as power quality monitor allocation in **unbalanced distribution systems**, the impact of **distributed generation** in allocation methods, and allocation of power quality monitor for **fault location**.
- **This paper** makes contributions to all these three points.
- The allocation method is based only on the **root mean square voltages ( $V_{rms}$ )** measured at the buses.

# • Methodology



- Step 1: Configuration of lines and grid elements;
- Step 2: Fault simulations;
- Step 3: Generate binary parameters BILP (Binary Integer Linear Programming) model;
- Step 4: Solve the BILP model; and
- Step 5: PQMs positions.

- **Methodology**

- **Step 1: Configuration of lines and grid elements**

- This step builds an **electrical model for the PDS** from a database containing information on the types of cables, geometries and spacing in the towers, among other data. This model consists of self and mutual impedances, which allow the **PDS representation in fault simulations**.
- This paper considered the **European Medium Voltage System of 15 buses** proposed by **CIGRÉ** for the tests. Moreover, the method was applied to the **IEEE 123-bus Test System**. Finally, we considered a large, médium voltage PDS named **Ckt5 with 2998 buses of EPRI**.

- **Methodology**

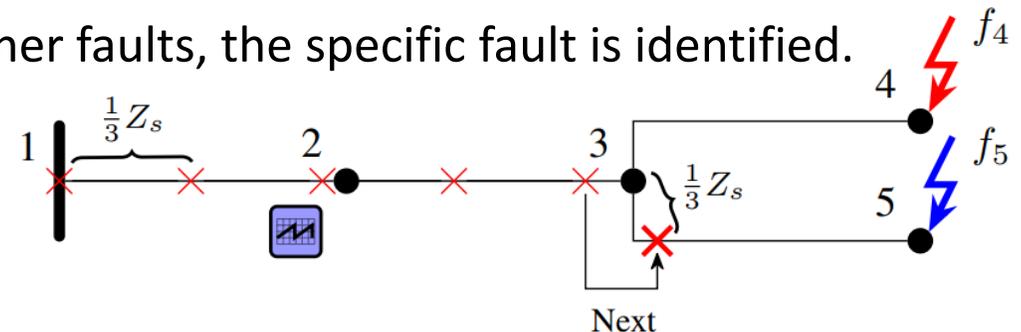
- **Step 2: Fault simulations**

- The fault simulations were carried out by implementing a **fault analysis program** and by using the **OpenDSS software** (Version 9.2.0.1).
- The database can also be obtained with any transient analysis software without any changes in the allocation method.
- We considered **no-load conditions** for the **CIGRÉ** and the **IEEE systems**. However, **load conditions** were considered for the **EPRI system**.
- The faults were uniformly distributed with a simulation step of **one third of the branch with the smallest impedance**.

# • Methodology

## • Step 3: Generate binary parameters

- The optimization problem was described as a Binary Integer Linear Programming (BILP) problem with two objectives: to **minimize the number of PQMs** and to **maximize the number of identified faults**.
- A particular fault is identified when installed PQMs can differentiate this fault from all other simulated faults.
- **The concept adopted** is that two faults that produce similar residual voltage at a particular measurement bus are called **symmetrical faults**.
- The voltages were compared using a specified range around these faults' voltage, where any voltage within the specified range is considered the same voltage (**symmetry condition**).
- If the set of PQMs can break the symmetry of all other faults, the specific fault is identified.



# • Methodology

## • Step 3: Generate binary parameters

TABLE I  
SUGGESTED PRIORITY ORDER FOR CHOOSING THE REFERENCE PHASE

Fault Type	AT, AB, ABT, ABC	BT	CT, AC, ACT	BC, BCT
Priority order	A, B, C	B, A, C	C, A, B	B, C, A

$$\sigma(j, i, \bar{i}) \equiv \begin{cases} 0, & v(i, j) - \zeta \leq v(\bar{i}, j) \leq v(i, j) + \zeta \\ 1, & \text{otherwise} \end{cases} \quad (3)$$

$$y(i) \equiv \begin{cases} 1, & \text{if } i \text{ fault is identified} \\ 0, & \text{otherwise} \end{cases} \quad (4)$$

$$x(j) \equiv \begin{cases} 1, & \text{if installing a PQM at the } j \text{ bus} \\ 0, & \text{otherwise} \end{cases} \quad (5)$$

$$om(i, j) \equiv \begin{cases} 1, & v(i, j) \leq \tau \\ 0, & \text{otherwise} \end{cases} \quad (6)$$

$$t^k(j) \equiv \begin{cases} 1, & \text{if } k \text{ phase is present at a } j \text{ bus} \\ 0, & \text{otherwise} \end{cases} \quad (13)$$

$$\zeta(j) = |v(\bar{f}, j) - v(f, j)| \quad (43)$$

- The general model for balanced and unbalanced systems is represented by (18)—(42).

$$\min \sum_{j \in N} x(j) \quad (18)$$

$$\max \sum_{i \in E} y(i) \quad (19)$$

$$\text{s.t.:} \quad (20)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{AT}^k(i, j) t^k(j) \geq t^A(i) \quad (21)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{BT}^k(i, j) t^k(j) \geq t^B(i) \quad (22)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{CT}^k(i, j) t^k(j) \geq t^C(i) \quad (23)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{AB}^k(i, j) t^k(j) \geq t^A(i) t^B(i) \quad (24)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{BC}^k(i, j) t^k(j) \geq t^B(i) t^C(i) \quad (25)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{AC}^k(i, j) t^k(j) \geq t^A(i) t^C(i) \quad (26)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{ABT}^k(i, j) t^k(j) \geq t^A(i) t^B(i) \quad (27)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{BCT}^k(i, j) t^k(j) \geq t^B(i) t^C(i) \quad (28)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{ACT}^k(i, j) t^k(j) \geq t^A(i) t^C(i) \quad (29)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} om_{ABC}^k(i, j) t^k(j) \geq t^A(i) t^B(i) t^C(i) \quad (30)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{AT}^k(i, \bar{i}, j) t^k(j) \geq y(i) t^A(i) t^A(\bar{i}) \quad (31)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{BT}^k(i, \bar{i}, j) t^k(j) \geq y(i) t^B(i) t^B(\bar{i}) \quad (32)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{CT}^k(i, \bar{i}, j) t^k(j) \geq y(i) t^C(i) t^C(\bar{i}) \quad (33)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{AB}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in A, B} t^k(i) t^k(\bar{i}) \quad (34)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{BC}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in B, C} t^k(i) t^k(\bar{i}) \quad (35)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{AC}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in A, C} t^k(i) t^k(\bar{i}) \quad (36)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{ABT}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in A, B} t^k(i) t^k(\bar{i}) \quad (37)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{BCT}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in B, C} t^k(i) t^k(\bar{i}) \quad (38)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{ACT}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in A, C} t^k(i) t^k(\bar{i}) \quad (39)$$

$$\sum_{j \in N} x(j) \sum_{k \in F} \sigma_{ABC}^k(i, \bar{i}, j) t^k(j) \geq y(i) \prod_{k \in F} t^k(i) t^k(\bar{i}) \quad (40)$$

$$x(j) \in \{0, 1\} \quad (41)$$

$$y(i) \in \{0, 1\} \quad (42)$$

- **Methodology**

- **Step 4: Solve the BILP model**

- The PQM's allocation problem has multiple nondominated solutions related to a single Pareto front's point. In other words, the PQMs can be combined in several ways reaching the same identification of faults with the exact number of PQMs.
- The multi-objective model was solved through the **Algorithm for Bicriteria Discrete Optimization (ABCDO)**. However, **ABCDO** returns only one solution for each Pareto front's point.
- Therefore, we explore the **Nondominated Sorting Genetic Algorithm II (NSGA-II)** population characteristic to find other solutions. The obtained solutions from ABCDO were included in the initial population of an NSGA-II.

- **Methodology**

- **Step 5: PQMs positions**

- This step chooses one Pareto point and processes all related solutions found by the NSGA-II.
- It identifies **groups of buses** and **combines one bus of each group to form a solution**.
- This step also evaluates the **second objective function (maximising the number of identified faults)** for all combinations to ensure dominance level.
- If one combination does not belong to the Pareto front, this step excludes it from the final set of solutions.

- **Results and discussion**
- **CIGRÉ 15-bus test system**

- Since we considered no-load conditions in fault simulations, the results show four-fault types (**187 solid faults x 4 = 748 faults**).
- **First scenario:** DG disconnected
- **Second scenario:** DG connected
- The results suggest that the DG presence reduces the identification capability of monitoring programs.

TABLE II  
ABCDO RESULTS CONSIDERING SOLID FAULTS AND  $\tau = 0.6$  P.U.

Instance	First scenario		Second scenario	
	Pareto point ( <i>o1</i> , <i>o2</i> )	PQMs positions	Pareto point ( <i>o1</i> , <i>o2</i> )	PQMs positions
AG	(2, 187)	<b>11, 14</b>	(2, 169)	<b>11, 14</b>
			(3, 178)	<b>3, 11, 14</b>
			(4, 179)	<b>3, 4, 11, 14</b>
BC	(2, 134)	<b>11, 14</b>	(2, 118)	<b>11, 14</b>
	(3, 167)	<b>1, 11, 14</b>	(3, 151)	<b>11, 13, 14</b>
	(4, 169)	<b>1, 2, 11, 14</b>	(4, 153)	<b>2, 11, 13, 14</b>
	(5, 171)	<b>2, 5, 10, 13, 15</b>	(5, 155)	<b>2, 11, 12, 13, 15</b>
BCG	(2, 187)	<b>12, 14</b>	(2, 173)	<b>11, 14</b>
			(3, 177)	<b>6, 11, 14</b>
ABC	(2, 154)	<b>11, 14</b>	(2, 139)	<b>11, 14</b>
	(3, 187)	<b>11, 13, 15</b>	(3, 172)	<b>1, 11, 14</b>
			(4, 177)	<b>6, 11, 13, 15</b>
All types together	(2, 662)	<b>10, 14</b>	(2, 599)	<b>11, 14</b>
	(3, 728)	<b>1, 10, 14</b>	(3, 665)	<b>1, 11, 14</b>
	(4, 730)	<b>1, 2, 10, 14</b>	(4, 680)	<b>1, 6, 11, 14</b>
	(5, 732)	<b>2, 7, 12, 13, 15</b>	(5, 684)	<b>1, 2, 6, 11, 14</b>
			(6, 686)	<b>1, 3, 6, 11, 12, 14</b>
		(7, 688)	<b>2, 3, 6, 11, 12, 13, 15</b>	



# • Results and discussion

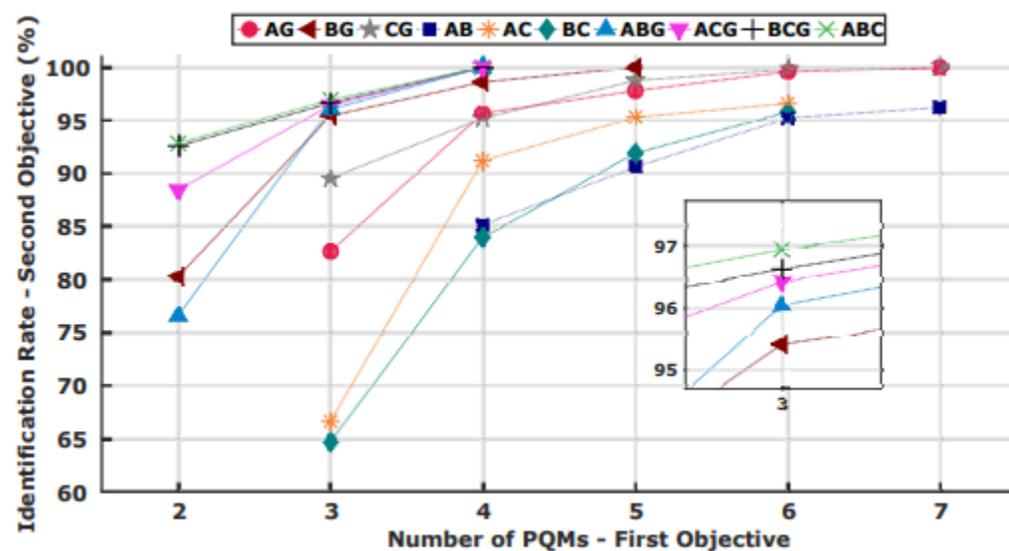
## • CIGRÉ 15-bus test system

- Solution **{11, 14}** suits all instances and has the lowest cost.
- Solution **{2, 3, 6, 11, 12, 13, 14}** reaches the maximum benefit.

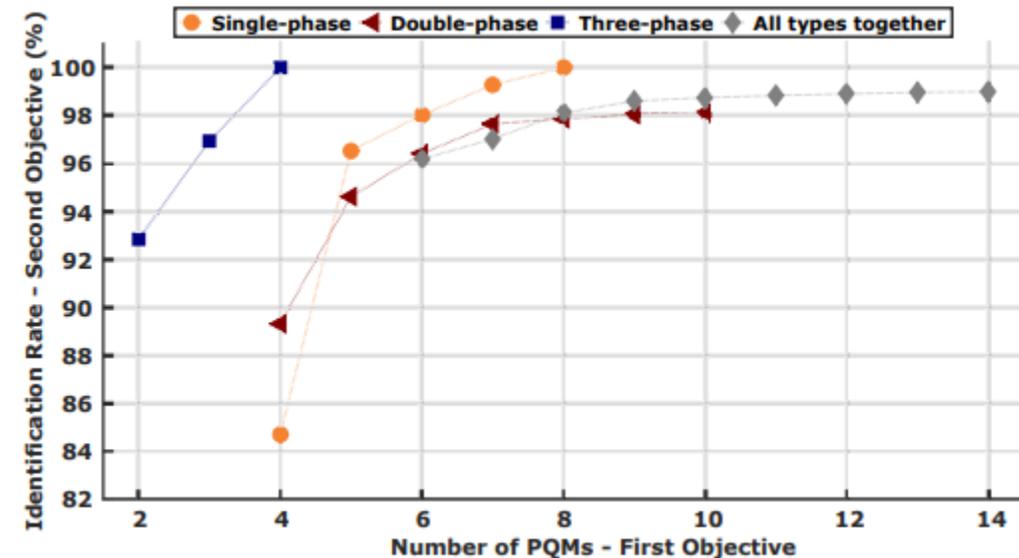
TABLE III  
ALTERNATIVE SOLUTIONS OBTAINED BY NSGA-II FOR EACH POINT IN THE OBJECTIVE SPACE CONSIDERING THE SECOND SCENARIO

Instance	Pareto point (o1, o2)	Optimal solutions
AG	(2, 169)	<b>{11, 14}</b> , {11, 15}
	(3, 178)	<b>{3, 11, 14}</b> , {3, 11, 15}
	(4, 179)	<b>{3, 4, 11, 14}</b> , {3, 4, 11, 15}, {3, 5, 11, 14}, {3, 5, 11, 15}, {3, 6, 11, 14}, {3, 6, 11, 15}, {3, 7, 11, 14}, {3, 7, 11, 15}
BC	(2, 118)	<b>{11, 14}</b> , {12, 14}
	(3, 151)	{1, 11, 14}, {1, 11, 15}, {1, 12, 14}, {1, 12, 15}, <b>{11, 13, 14}</b> , {11, 13, 15}, {12, 13, 14}, {12, 13, 15}
	(4, 153)	{1, 2, 11, 14}, {1, 2, 11, 15}, {1, 2, 12, 14}, {1, 2, 12, 15}, {1, 11, 12, 14}, {1, 11, 12, 15}, <b>{2, 11, 13, 14}</b> , {2, 11, 13, 15}, {2, 12, 13, 14}, {2, 12, 13, 15}, {11, 12, 13, 14}, {11, 12, 13, 15}
	(5, 155)	{1, 2, 11, 12, 14}, {1, 2, 11, 12, 15}, {2, 11, 12, 13, 14}, <b>{2, 11, 12, 13, 15}</b>
BCG	(2, 173)	<b>{11, 14}</b> , {11, 15}
	(3, 177)	<b>{6, 11, 14}</b> , {6, 11, 15}
ABC	(2, 139)	<b>{11, 14}</b>
	(3, 172)	<b>{1, 11, 14}</b> , {1, 11, 15}, {11, 13, 14}, {11, 13, 15}
	(4, 177)	{1, 6, 11, 14}, {1, 6, 11, 15}, {6, 11, 13, 14}, <b>{6, 11, 13, 15}</b>
All types together	(2, 599)	<b>{11, 14}</b>
	(3, 665)	<b>{1, 11, 14}</b> , {1, 11, 15}, {11, 13, 14}, {11, 13, 15}
	(4, 680)	<b>{1, 6, 11, 14}</b> , {1, 6, 11, 15}, {6, 11, 13, 14}, {6, 11, 13, 15}
	(5, 684)	<b>{1, 2, 6, 11, 14}</b> , {1, 2, 6, 11, 15}, {1, 3, 6, 11, 14}, {1, 3, 6, 11, 15}, {2, 6, 11, 13, 14}, {2, 6, 11, 13, 15}, {3, 6, 11, 13, 14}, {3, 6, 11, 13, 15}
	(6, 686)	{1, 2, 3, 6, 11, 14}, {1, 2, 3, 6, 11, 15}, {1, 2, 6, 11, 12, 14}, {1, 2, 6, 11, 12, 15}, <b>{1, 3, 6, 11, 12, 14}</b> , {1, 3, 6, 11, 12, 15}, {2, 3, 6, 11, 13, 14}, {2, 3, 6, 11, 13, 15}, {2, 6, 11, 12, 13, 14}, {2, 6, 11, 12, 13, 15}, {3, 6, 11, 12, 13, 14}, {3, 6, 11, 12, 13, 15}
(7, 688)	{1, 2, 3, 6, 11, 12, 14}, {1, 2, 3, 6, 11, 12, 15}, <b>{2, 3, 6, 11, 12, 13, 14}</b> , <b>{2, 3, 6, 11, 12, 13, 15}</b>	

- Results and discussion
- IEEE 123-bus test system



Pareto front obtained for all fault types solved individually to IEEE 123-bus.

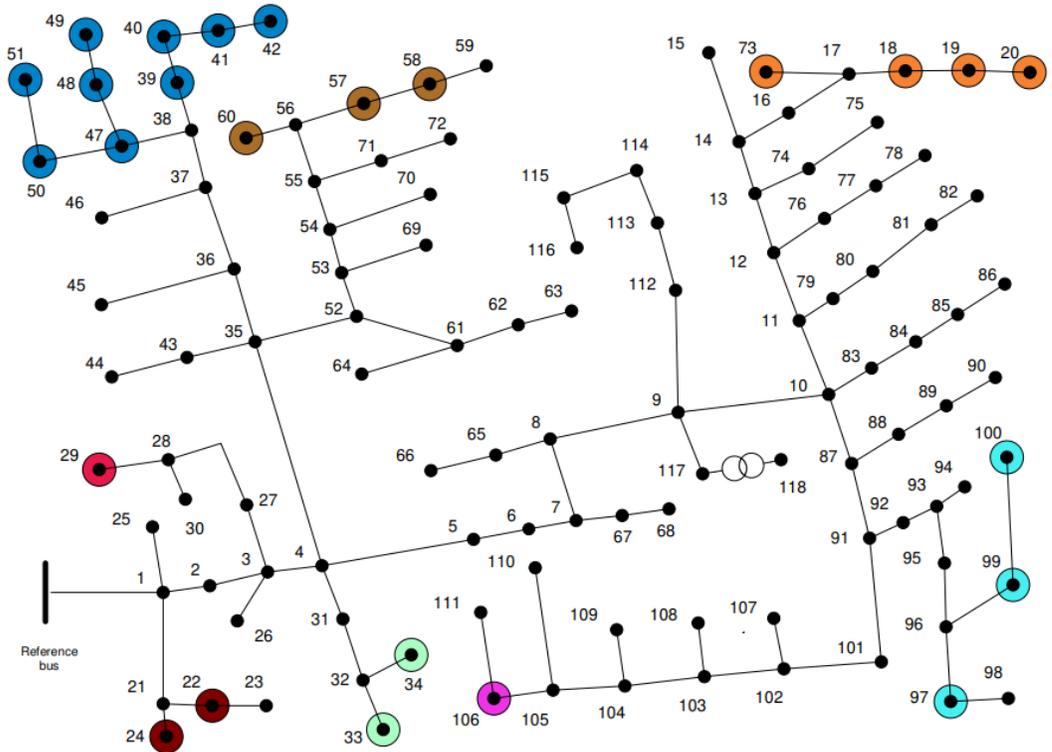


The Pareto front obtained for all fault types solved together to IEEE 123-bus.

# • Results and discussion

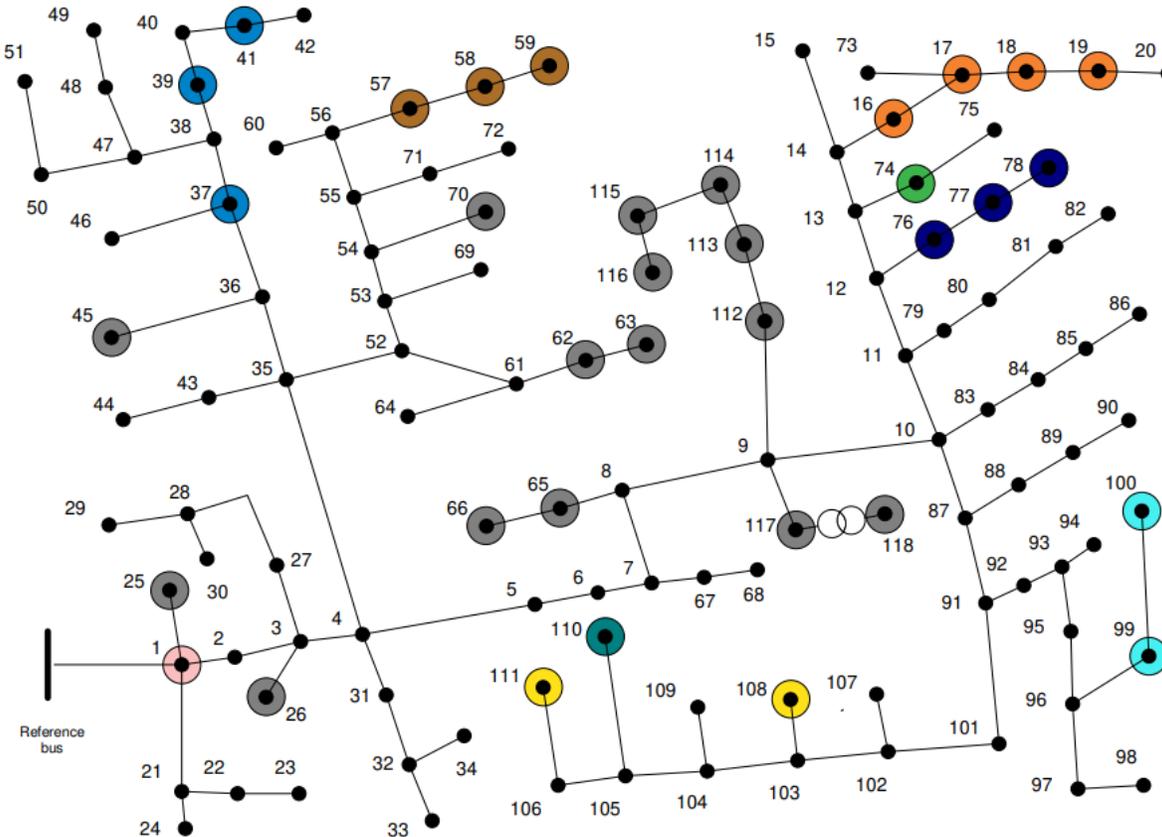
## • IEEE 123-bus test system

- The figure has **eight different colors**.
- Then each solution has eight PQMs.
- Any combination made with buses within these eight sets is a solution.



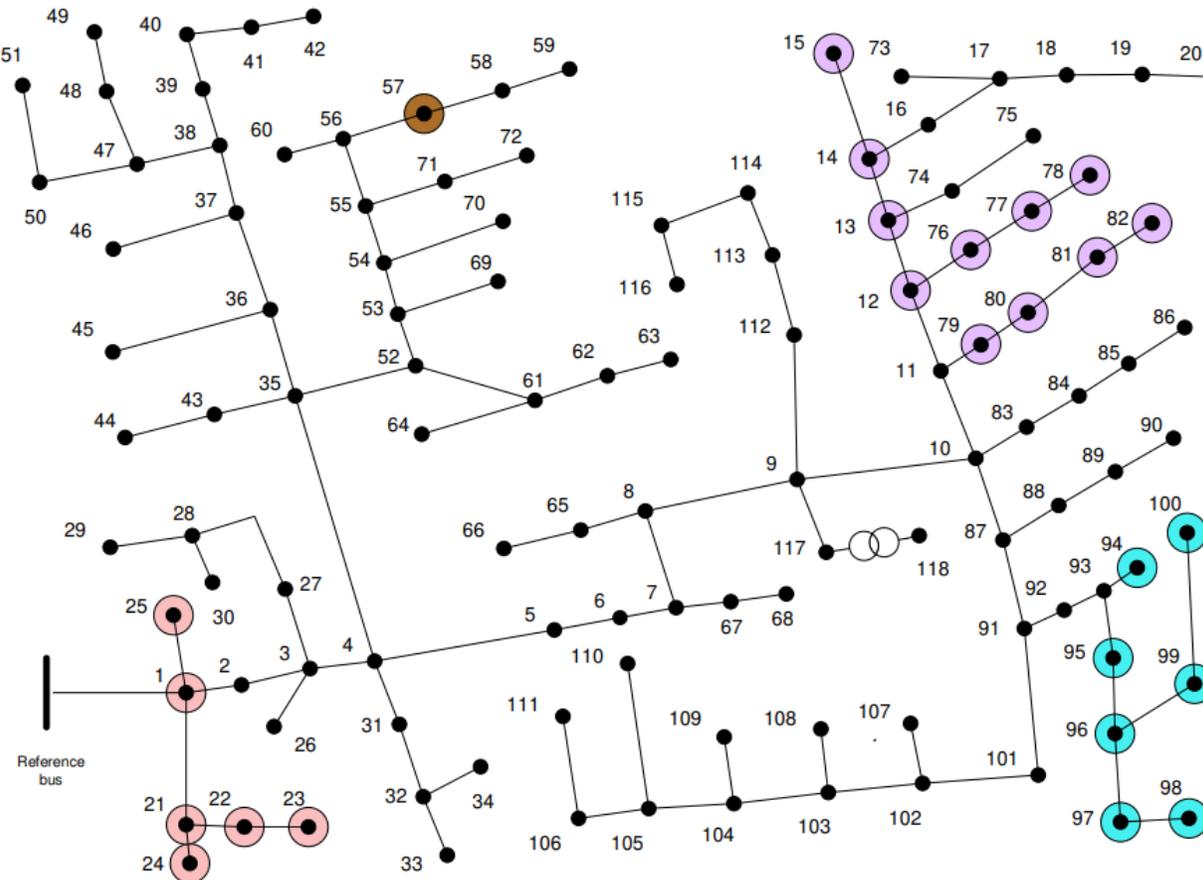
Set of PQMs for single-phase to ground faults.

- Results and discussion
- IEEE 123-bus test system



Set of PQMs for double-phase faults (with and without ground connection).

- Results and discussion
- IEEE 123-bus test system

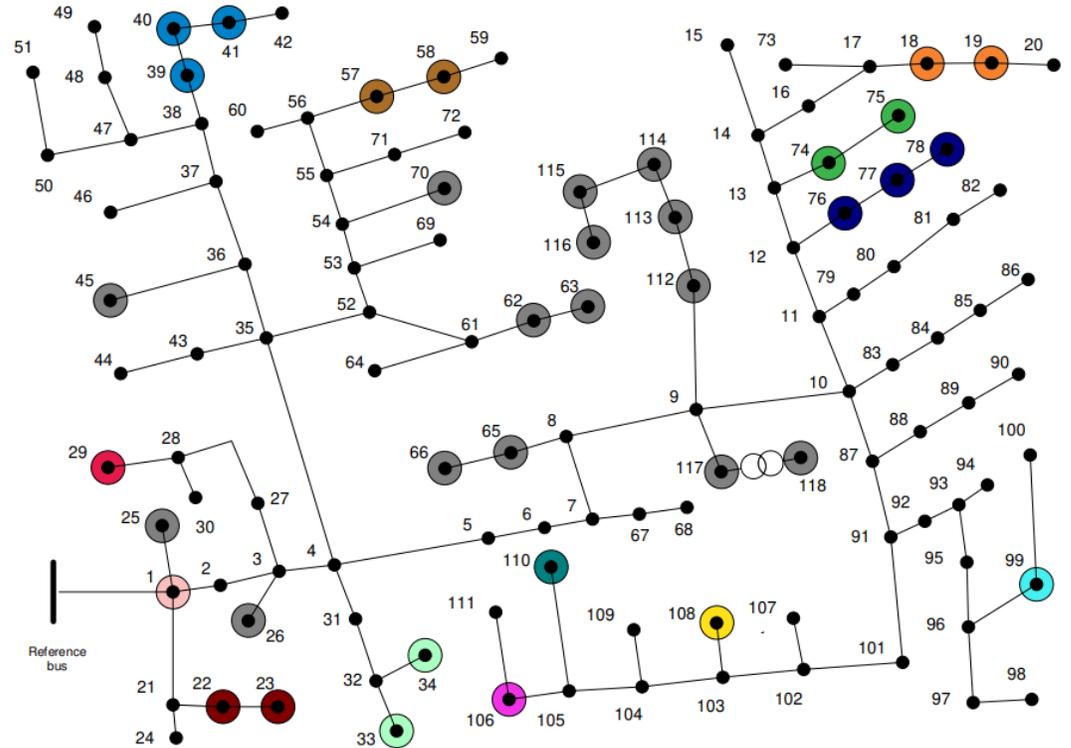


Set of PQMs for three-phase faults.

# • Results and discussion

## • IEEE 123-bus test system

- These solutions correspond to the Pareto point of **14 PQMs** and **99% of identification rate**.
- But it is worth mentioning that an **identification rate above 96%** was obtained with **only six PQMs**.



Set of PQMs for all types of faults.

- **Results and discussion**

- **EPRI's Ckt5 2998-bus test system**

- We simulated three-phase faults at all buses of the **EPRI's Ckt5 2998-bus system** to determine if the proposed methodology applies to large power systems.
- We ran **pre-fault conditions in the EPRI's system** to investigate the method's practical application.
- The results presented three Pareto points. And with **four PQM** it was obtained a **68.75% identification rate**.

# • Conclusions

- **Allocation method:** based only on the **root mean square voltages ( $V_{rms}$ )** measured at the buses.
- **The method considered the unbalanced nature of PDS** (selecting the appropriate method for short-circuits simulations; adding **topology** constants in the BILP model; and suggesting a **sequence of the reference phase selection**).
- **This paper investigated** the impacts of the connection/disconnection of a DG on the monitoring system performance. It was observed a **slight reduction in the monitoring set's identification capability after the DG connection**. These results are essential since utilities cannot predict low power DG connections.
- **The fault location in PDS remains an unsolved problem**, this paper contributes with a method that presents solutions with a significant reduction of multiple estimations.



# Thank you!

- Mário Oleskovicz
- olesk@sc.usp.br

