EXAMPLE SQP

Minimize

$$f(x) = (x_1 - 1)^2 + (x_2 - 2)^2$$

subject to

$$h_1(x) = 2x_1 - x_2 = 0$$

$$g_1(x) = x_1 \le 5$$

from a starting point (10, –5). Iteration 1

$$f(x) = 130; \quad \nabla f(x) = \begin{bmatrix} 18 \\ -14 \end{bmatrix}; \quad \nabla h = \begin{bmatrix} 2 \\ -1 \end{bmatrix}; \quad \nabla g = \begin{bmatrix} 1 \\ 0 \end{bmatrix}; \quad \nabla^2 L = \begin{bmatrix} 12 & -4 \\ -4 & 4 \end{bmatrix}$$

ITERATION 1 - Write the quadratic problem, obtain the solution and the new point:

The quadratic problem is

Minimize

$$Q = \Delta x^{T} \begin{bmatrix} 18 \\ -14 \end{bmatrix} + \frac{1}{2} \Delta x^{T} \begin{bmatrix} 12 & -4 \\ -4 & 4 \end{bmatrix} \Delta x$$

subject to

$$25 + [2 \quad -1]\Delta x = 0$$

$$5 + [1 \quad 0]\Delta x = 0$$

The solution of the quadratic problem is

$$\Delta x = \begin{bmatrix} -7.5 \\ 10 \end{bmatrix}$$

Now *x* is updated as

$$x = x + \Delta x = \begin{bmatrix} 10 \\ -5 \end{bmatrix} + \begin{bmatrix} -7.5 \\ 10 \end{bmatrix} = \begin{bmatrix} 2.5 \\ 5 \end{bmatrix}$$

ITERATION 2 - Write the quadratic problem, obtain the solution and the new point:

$$f(x) = 11.25; \quad \nabla f(x) = \begin{bmatrix} 3 \\ 6 \end{bmatrix}; \quad \nabla h = \begin{bmatrix} 2 \\ -1 \end{bmatrix}; \quad \nabla g = \begin{bmatrix} 1 \\ 0 \end{bmatrix}; \quad \nabla^2 L = \begin{bmatrix} 10 & -4 \\ -4 & 4 \end{bmatrix}$$

The quadratic problem is

Minimize

$$Q = \Delta \mathbf{x}^T \begin{bmatrix} 3 \\ 6 \end{bmatrix} + \frac{1}{2} \Delta \mathbf{x}^T \begin{bmatrix} 10 & -4 \\ -4 & 4 \end{bmatrix} \Delta \mathbf{x}$$

subject to

$$0 + [2 \quad -1]\Delta x = 0$$

 $-2.5 + [1 \quad 0]\Delta x = 0$

The solution of the quadratic problem is

$$\Delta x = \begin{bmatrix} -1.5 \\ -3.0 \end{bmatrix}$$

Now *x* is updated as

$$x = x + \Delta x = \begin{bmatrix} 2.5 \\ 5 \end{bmatrix} + \begin{bmatrix} -1.5 \\ -3.0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

ITERATION 3 - Write the quadratic problem, obtain the solution and the new point:

$$f(x) = 0; \quad \nabla f(x) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}; \quad \nabla h = \begin{bmatrix} 2 \\ -1 \end{bmatrix}; \quad \nabla g = \begin{bmatrix} 1 \\ 0 \end{bmatrix}; \quad \nabla^2 L = \begin{bmatrix} 10 & -4 \\ -4 & 4 \end{bmatrix}$$

Thus minimum of the function is at $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$. The value of multiplier is zero for the inequality constraint. That is, the inequality constraint is inactive at the optimum point. The MATLAB code sqp.m solves the constrained optimization problem using SQP method.