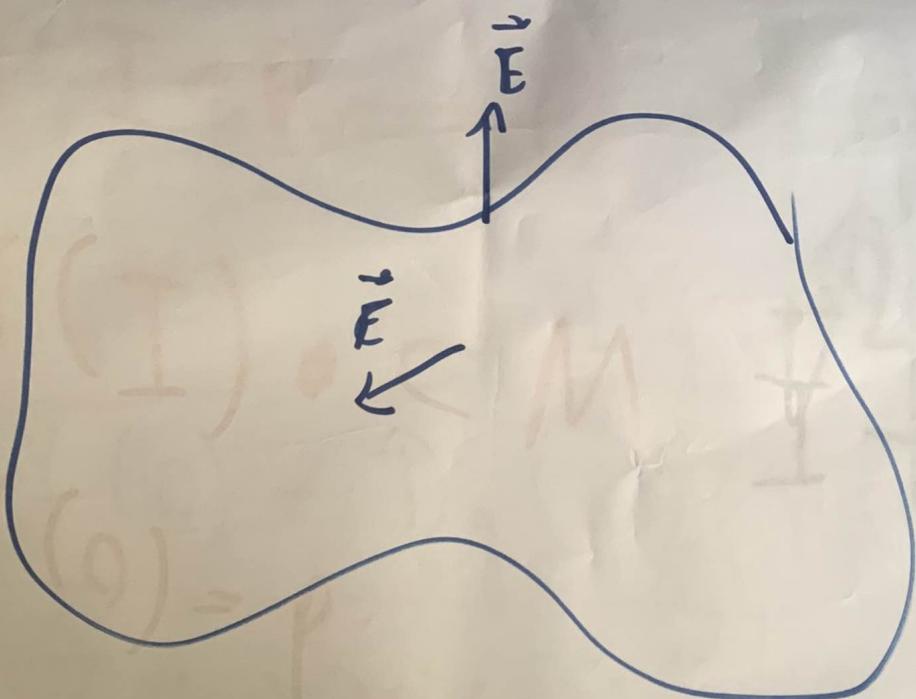
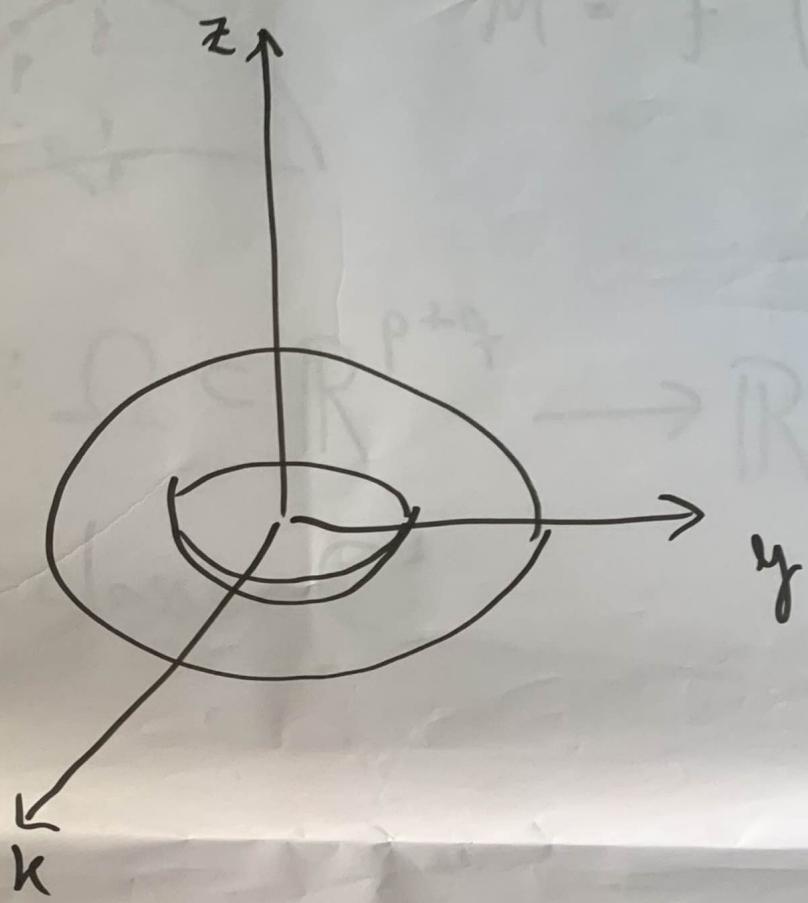
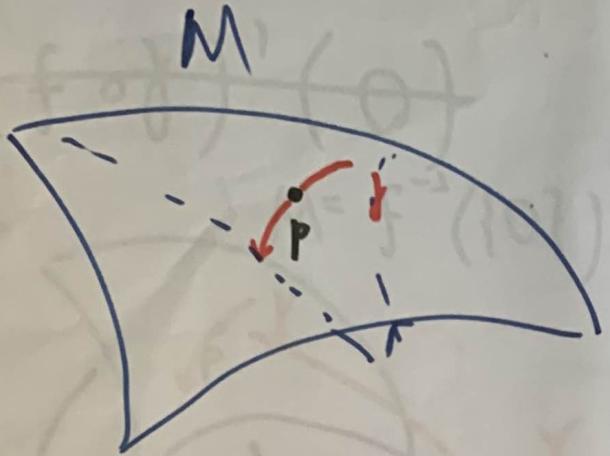


MONITORIA MAT 4 27/05





$$M = f^{-1}(0)$$

$$f: \Omega \subset \mathbb{R}^{p+q} \rightarrow \mathbb{R}^q$$

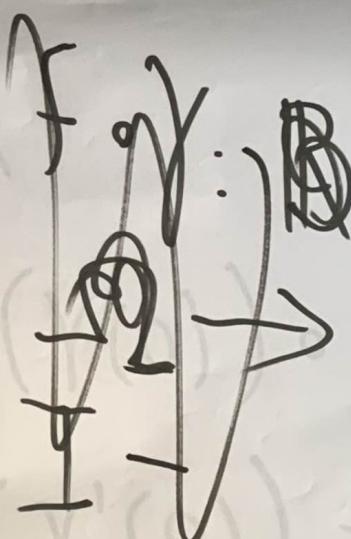
é de classe C^1

$$g: \Omega \rightarrow \mathbb{R} \quad \alpha \text{ maximizar}$$

$$\gamma: I \subset \mathbb{R} \rightarrow \Omega$$

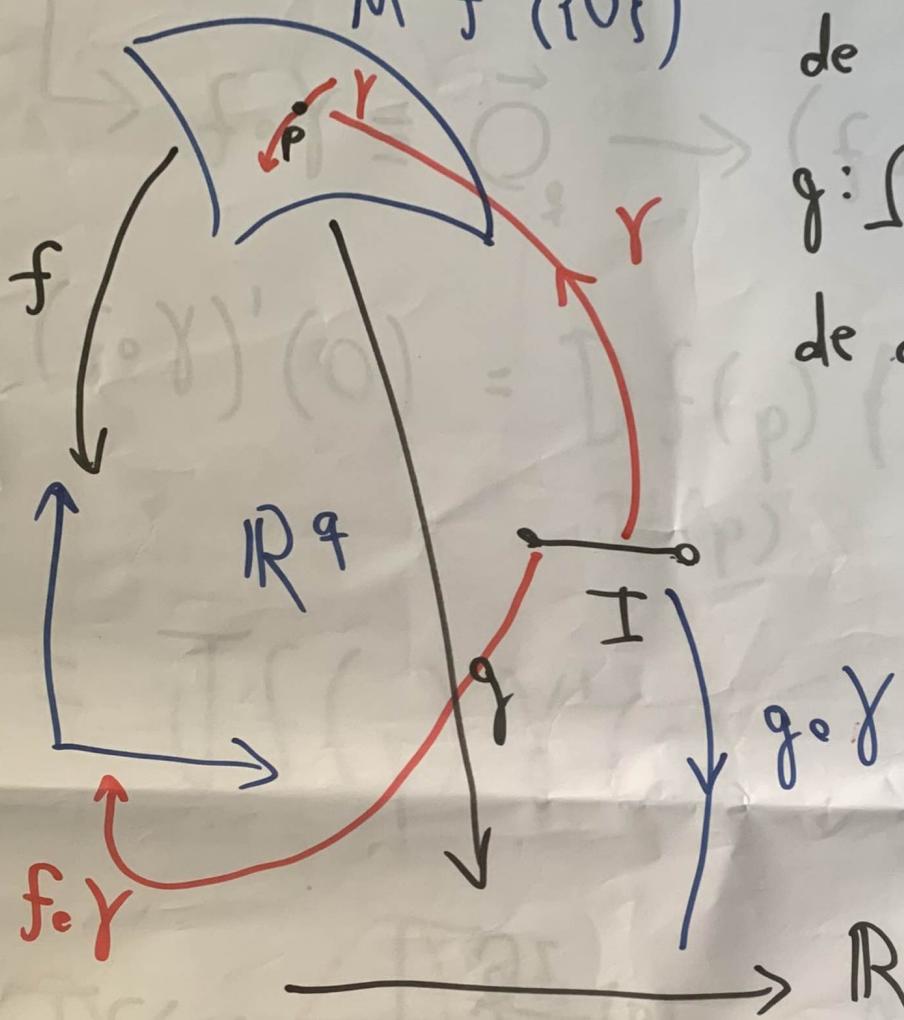
$$\gamma(I) \subset M$$

$$\gamma(0) = p$$



$$\cancel{(f \circ g)'(0)}$$

$$M = f^{-1}(\{0\})$$



$$f: \Omega \subset \mathbb{R}^{p+q} \rightarrow \mathbb{R}^q$$

de classe C^1

$$g: \Omega \rightarrow \mathbb{R}$$

de classe C^1

$$g \circ \gamma$$

$$\rightarrow \mathbb{R}$$

$$\cancel{(f \circ g)'(0)} - D_g(g(0)) \cdot$$

$$Dg(0) = Dg(p)(\gamma'(0)) =$$

$$= \boxed{\langle \nabla g(p), \gamma'(0) \rangle}$$

$$\gamma(I) \subset M, f(M) = \{0\}$$

$$\hookrightarrow f \circ \gamma = \vec{0}_q \rightarrow (f \circ \gamma)'(0) = \vec{0}_q$$

$$(f \circ \gamma)'(0) = Df(p) \{ \gamma'(0) \} = Jf(p) (\dots) \rightarrow \begin{bmatrix} : \\ : \end{bmatrix}$$

$$= Jf(p) \cdot \gamma'(0)$$

$$Jf(p) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1}(p) & \cdots & \frac{\partial f_q}{\partial x_1}(p) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_1}{\partial x_{p+q}}(p) & \cdots & \frac{\partial f_q}{\partial x_{p+q}}(p) \end{bmatrix}$$

$$Jf(p) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1}(p) & \cdots & \frac{\partial f_1}{\partial x_{p+q}}(p) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_q}{\partial x_1}(p) & \cdots & \frac{\partial f_q}{\partial x_{p+q}}(p) \end{bmatrix}$$

$$\gamma = (\gamma_1, \dots, \gamma_{p+q})$$

$$Jf(p) \cdot \gamma'(0) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_{p+q}} \\ \vdots & & \vdots \\ \frac{\partial f_q}{\partial x_1} & \cdots & \frac{\partial f_q}{\partial x_{p+q}} \end{bmatrix} \begin{bmatrix} \gamma'_1(0) \\ \vdots \\ \gamma'_{p+q}(0) \end{bmatrix}$$

! Campos de vetores

$$= \left[\sum_{i=1}^{p+q} \frac{\partial f_i}{\partial x_i}(p) \cdot \gamma'_i(0) \right] \quad \begin{matrix} \text{São normais} \\ \vdots \\ \text{São normais} \end{matrix} =$$

$$= \left[\begin{matrix} \langle \nabla f_1(p), \gamma'(0) \rangle \\ \vdots \\ \langle \nabla f_q(p), \gamma'(0) \rangle \end{matrix} \right]$$

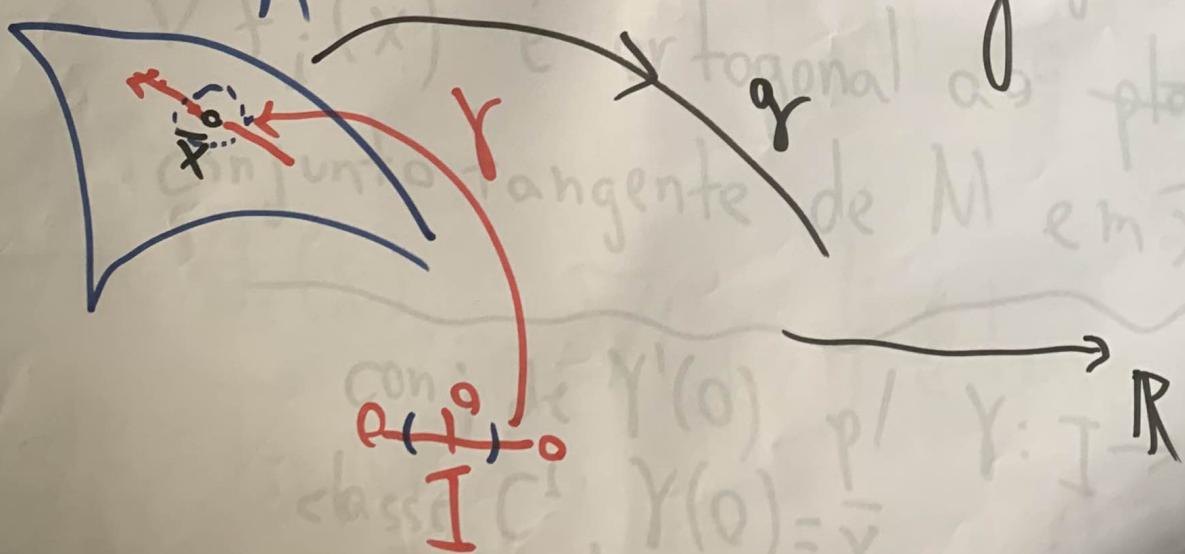
Conclusão: $((f \circ \gamma)'(0) = \vec{0})$

$$\langle \nabla f_i(p), Y'(0) \rangle = 0$$

Os vetores $\nabla f_i(p)$ são normais a M

$\nabla f_1, \nabla f_2, \dots, \nabla f_q$ são normais a M

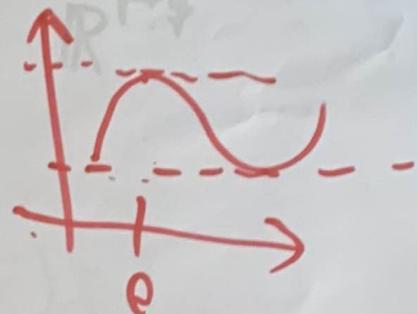
Suponha que \bar{x} é ponto de extremo (máx., min.) local de g em M



Q é um ponto de extremo local de $g \circ \gamma: I \rightarrow \mathbb{R}$

Mat. I

$$(g \circ \gamma)'(0) = Q$$



•

•

$$\langle \nabla g(\bar{x}), \gamma'(0) \rangle = 0$$

Juntando tudo: Se \bar{x} é um pto.

de extremo local

• $\nabla g(\bar{x})$ é ortogonal ao conj. tangente

• $\nabla f_i(\bar{x})$ é ortogonal ao plan espaco conjunto tangente de M em $\bar{x}, T_{\bar{x}}M$

conj de $\gamma'(0)$ p/ $\gamma: I \rightarrow M$ de classe C^1 , $\gamma(0) = \bar{x}$

Hip: $Df(p)$ é sobrej. $\forall p \in M$

TF Imp

$T_{\bar{x}} N$ é subesp. vet. de \mathbb{R}^{p+q}

$$\dim T_{\bar{x}} M = p$$

$\{\nabla f_1(p), \dots, \nabla f_q(p)\}$ é l.i.

Anteriormente, vimos que $\nabla g(\bar{x})$,
 $\nabla f_1(\bar{x}), \dots, \nabla f_q(\bar{x}) \in T_{\bar{x}} M^\perp$

Fato de AlgeLin: $\dim T_{\bar{x}} M^\perp =$
 $= \dim \mathbb{R}^{p+q} - \dim T_{\bar{x}} M = q$

$\{\nabla f_1(\bar{x}), \dots, \nabla f_q(\bar{x})\}$ é base
de $T_{\bar{x}} M^\perp$

Conclusão: $\exists \lambda_1, \dots, \lambda_q \in \mathbb{R}$ t. q.

$$\nabla g(\bar{x}) = \lambda_1 \nabla f_1(\bar{x}) + \dots + \lambda_q \nabla f_q(\bar{x})$$

Sabemos $N = g^{-1}(\{g(\bar{x})\})$

$T_{\bar{x}} N$ é subesp. de \mathbb{R}^{p+q}

$\dim p+q-1$ de

$$e T_{\bar{x}} N^\perp = \{\lambda \nabla g(\bar{x}); \lambda \in \mathbb{R}\}$$

$T_{\bar{x}} M$ é subcsp. de $T_{\bar{x}} N$

