



Modelos de misturas de gaussianas (GMMs)

Miguel Arjona Ramírez maramire@usp.br

Escola Politécnica
Universidade de São Paulo



Roteiro

1. Componentes da mistura e densidade composta.
2. Introdução de uma variável latente vetorial discreta.
3. Densidades condicional, conjunta e marginal reconstruída.
4. Função de log verossimilhança e possíveis singularidades.
5. Estimação de GMM pelo algoritmo da Esperança-Maximização (EM)



Modelos de misturas de gaussianas

1.

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k N(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

2. z : VA binária K -dimensional 1-de- K com $z_k \in \{0, 1\}$ e $\sum_{k=1}^K z_k = 1$.

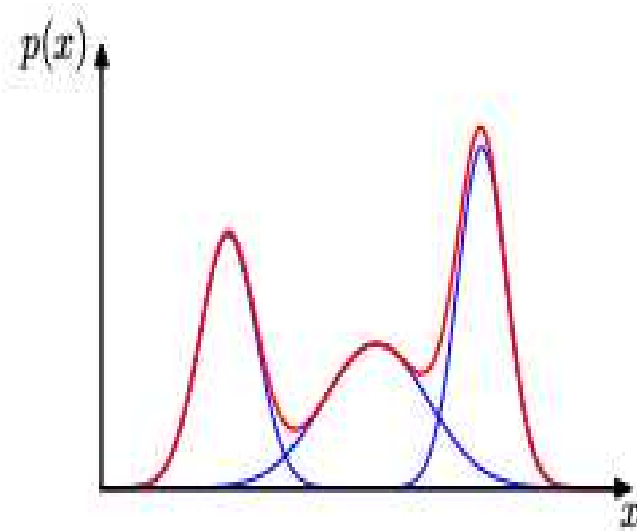
3. Função massa de probabilidade (fmp) da VA z é dada pelos coeficientes da mistura

$$P\{z_k = 1\} = \pi_k$$

com as $K + 1$ condições $0 \leq \pi_k \leq 1$ e $\sum_{k=1}^K \pi_k = 1$.

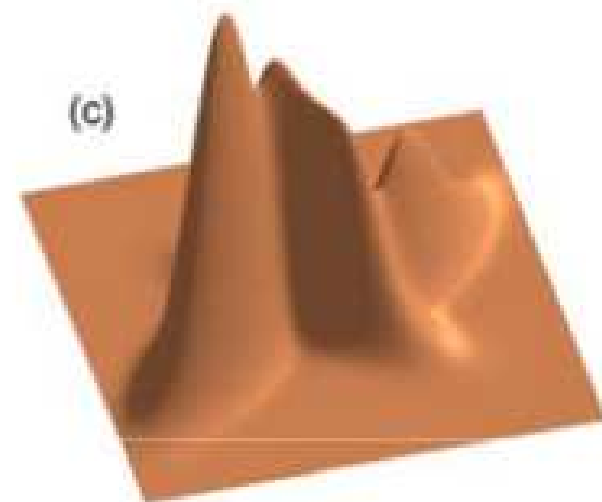
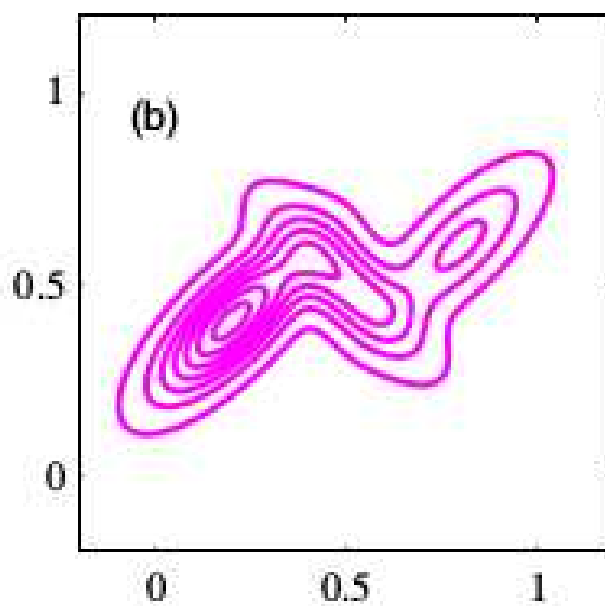
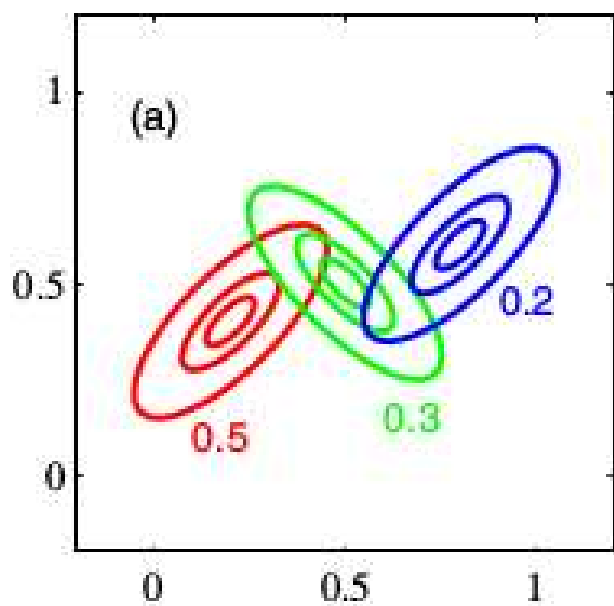


GMM com as componentes gaussianas





GMM como uma densidade em si





Massa de probabilidade da variável latente

1. Função massa de probabilidade (fmp) da VA z é dada pelos coeficientes da mistura

$$P\{z_k = 1\} = \pi_k$$

com as $K + 1$ condições $0 \leq \pi_k \leq 1$ e $\sum_{k=1}^K \pi_k = 1$.

- 2.

$$p(\mathbf{z}) = \prod_{k=1}^K \pi_k^{z_k}$$



Densidade condicional

1.

$$p(\mathbf{x}|z_k = 1) = N(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

2.

$$p(\mathbf{x}|\mathbf{z}) = \prod_{k=1}^K N^{z_k}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$



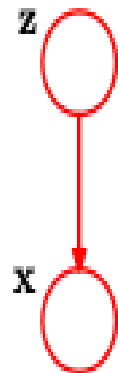
Densidades conjunta e marginal

$$\begin{aligned} p(\mathbf{x}, \mathbf{z}) &= p(\mathbf{z})p(\mathbf{x}|\mathbf{z}) \\ &= \prod_{k=1}^K \pi_k^{z_k} \prod_{k=1}^K N^{z_k}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \end{aligned} \quad (1)$$

$$\begin{aligned} p(\mathbf{x}) &= \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z}) \\ &= \sum_{k=1}^K \pi_k N(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \end{aligned} \quad (2)$$



GMM com variável latente





Densidades a posteriori

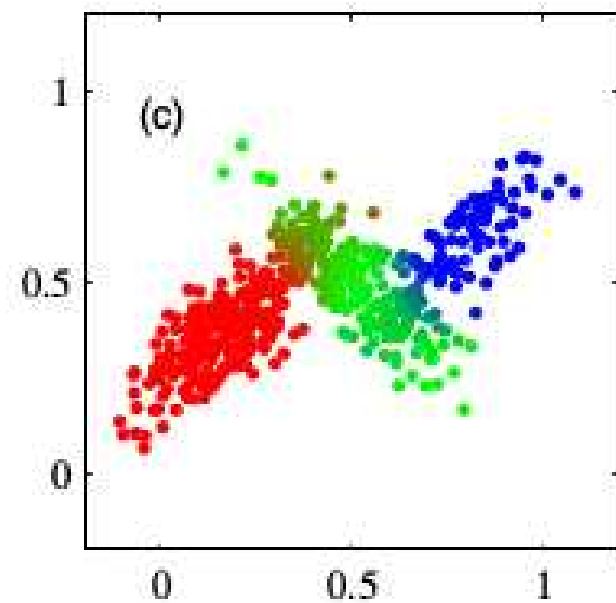
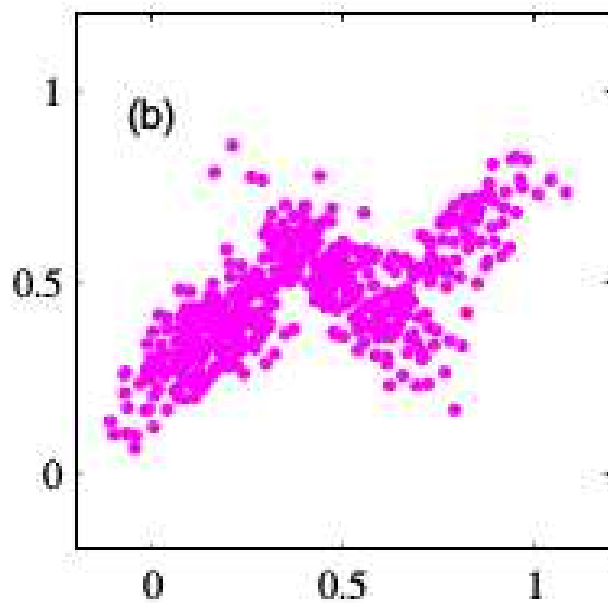
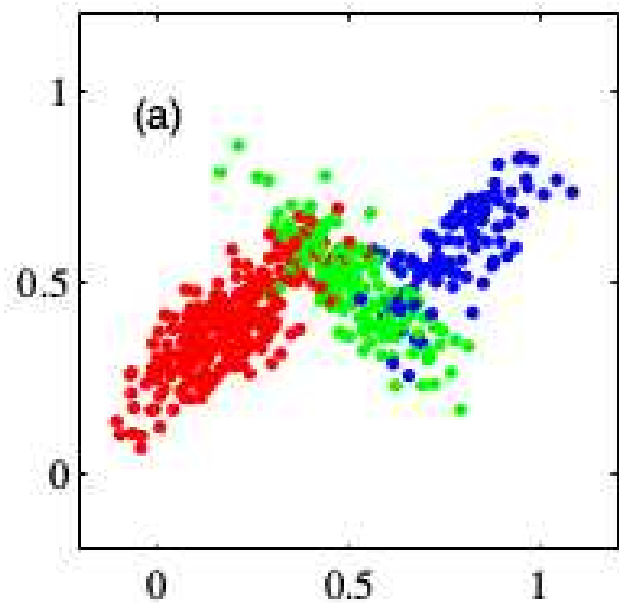
Pelo Teorema de Bayes, obtemos

$$\begin{aligned}\gamma(z_k) \equiv p(z_k = 1|\mathbf{x}) &= \frac{p(z_k = 1)p(\mathbf{x}|z_k = 1)}{\sum_{i=1}^K p(z_i = 1)p(\mathbf{x}|z_i = 1)} \\ &= \frac{\pi_k N(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{i=1}^K \pi_i N(\mathbf{x}|\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i)}\end{aligned}$$

(3)

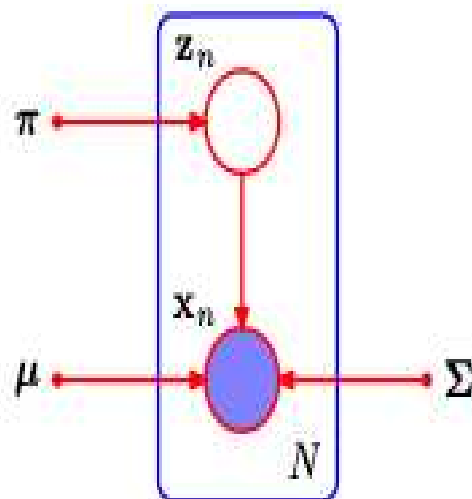


GMM de $K = 3$ componentes e $N = 500$ dados





Grafo de GMM com N dados para treino



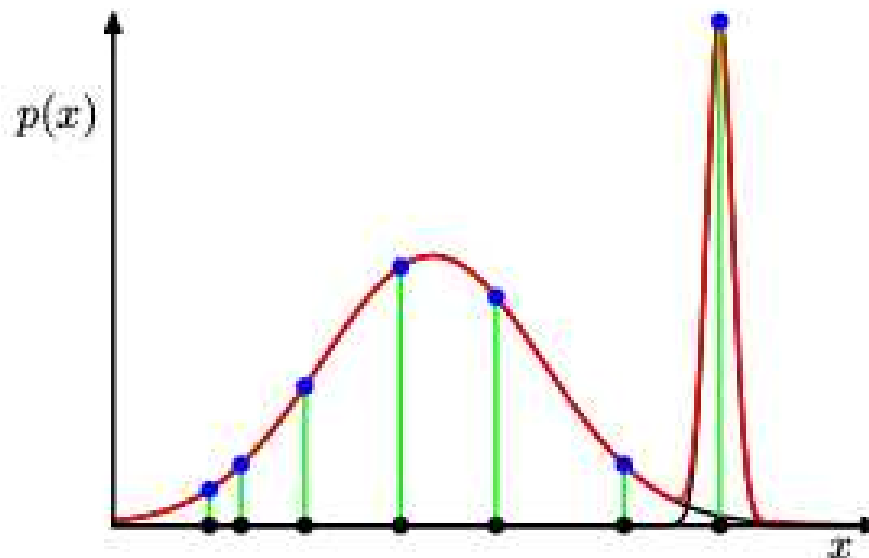


Função de verossimilhança de GMM

$$\ln p(\mathbf{x}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \sum_{n=1}^N \ln \left[\sum_{k=1}^K \pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right]$$



Singularidades na verossimilhança de GMM



Se $\mu_j = x_n$, com $\Sigma_j = \sigma_j^2 \mathbf{I}$, a verossimilhança tem uma parcela

$$N(x_n | x_n, \sigma_j^2 \mathbf{I}) = \frac{1}{(2\pi)^{\frac{D}{2}}} \frac{1}{\sigma_j^D}$$



Esperança-Maximização (EM) para GMM

$L = \sum_{n=1}^N \ln G$: log verossimilhança

G : GMM

$$N_k = \frac{1}{(2\pi)^{\frac{D}{2}} \det^{\frac{1}{2}}(\Sigma_k)} \exp \left[-\frac{1}{2} (\mathbf{x}_n - \boldsymbol{\mu}_k)^T \Sigma_k^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_k) \right]$$

Gaussiana

A_k : Expoente de gaussiana

$$\nabla_{\boldsymbol{\mu}_k} L \equiv \frac{\partial L}{\partial \boldsymbol{\mu}_k} = \frac{\partial L}{\partial G} \frac{\partial G}{\partial N_k} \frac{\partial N_k}{\partial A_k} \frac{\partial A_k}{\partial \boldsymbol{\mu}_k}$$

$$\frac{\partial L}{\partial G} = \sum_{n=1}^N \frac{1}{G}, \quad \frac{\partial G}{\partial N_k} = \pi_k, \quad \frac{\partial N_k}{\partial A_k} = N_k, \quad \frac{\partial A_k}{\partial \boldsymbol{\mu}_k} = \Sigma_k^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_k).$$



Maximização (M) para as médias do GMM (1)

$$\nabla_{\mu_k} L = \frac{\partial L}{\partial G} \frac{\partial G}{\partial N_k} \frac{\partial N_k}{\partial A_k} \frac{\partial A_k}{\partial \mu_k}$$

$$\nabla_{\mu_k} L = \sum_{n=1}^N \frac{1}{G} \pi_k N_k \Sigma_k^{-1} (\mathbf{x}_n - \mu_k) = \mathbf{0}$$

$$\sum_{n=1}^N \frac{\pi_k N(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{i=1}^K N(\mathbf{x}_n | \mu_i, \Sigma_i)} \Sigma_k^{-1} (\mathbf{x}_n - \mu_k) = \mathbf{0}$$

$$\sum_{n=1}^N \gamma(z_{nk}) \Sigma_k^{-1} (\mathbf{x}_n - \mu_k) = \mathbf{0}$$



Maximização (M) para as médias do GMM (2)

$$\sum_{n=1}^N \gamma(z_{nk}) \Sigma_k^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_k) = \mathbf{0}$$

$$\boldsymbol{\mu}_k \sum_{n=1}^N \gamma(z_{nk}) = \sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}_n$$

$$\boldsymbol{\mu}_k = \frac{\sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}_n}{\sum_{n=1}^N \gamma(z_{nk})}$$

$$\boldsymbol{\mu}_k = \frac{\sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}_n}{N_k}$$



Etapa M para as covariâncias do GMM (1)

$$\nabla_{\Sigma_k} L = \frac{\partial L}{\partial G} \frac{\partial G}{\partial N_k} \left[\frac{\partial N_k}{\partial F_k} \frac{\partial F_k}{\partial D_k} \frac{\partial D_k}{\partial \Sigma_k} + \frac{\partial N_k}{\partial A_k} \frac{\partial A_k}{\partial \Sigma_k} \right]$$

$$F_k = \frac{1}{D_k}, \quad D_k = (2\pi)^{\frac{D}{2}} \det^{\frac{1}{2}}(\Sigma_k).$$

$$\frac{\partial N_k}{\partial F_k} = \exp(A_k), \quad \frac{\partial F_k}{\partial D_k} = -\frac{1}{D_k^2}.$$



Etapa M para as covariâncias do GMM (2)

$$\nabla_{\Sigma_k} L = \frac{\partial L}{\partial G} \frac{\partial G}{\partial N_k} \left[\frac{\partial N_k}{\partial F_k} \frac{\partial F_k}{\partial D_k} \frac{\partial D_k}{\partial \Sigma_k} + \frac{\partial N_k}{\partial A_k} \frac{\partial A_k}{\partial \Sigma_k} \right]$$

$$\begin{aligned} \frac{\partial D_k}{\partial \Sigma_k} &= (2\pi)^{\frac{D}{2}} \frac{1}{2} \det^{-\frac{1}{2}}(\Sigma_k) \frac{\partial \det(\Sigma_k)}{\partial \Sigma_k} \\ &= (2\pi)^{\frac{D}{2}} \frac{1}{2} \det^{-\frac{1}{2}}(\Sigma_k) \det(\Sigma_k) \Sigma_k^{-1} \\ &= \frac{1}{2} (2\pi)^{\frac{D}{2}} \det^{\frac{1}{2}}(\Sigma_k) \Sigma_k^{-1} \\ &= \frac{1}{2} D_k \Sigma_k^{-1}. \end{aligned}$$



Derivada matricial do próprio determinante

$$\mathbf{B} = \frac{\partial \det(\mathbf{A})}{\partial \mathbf{A}}$$

$$\det(\mathbf{A}) = \sum_{j=1}^D (-1)^{i+j} a_{ij} M_{ij} = \sum_{i=1}^D (-1)^{i+j} a_{ij} M_{ij}$$

$$\mathbf{B} = \text{adj}^T(\mathbf{A})$$

$$\mathbf{A}^{-1} = \det^{-1}(\mathbf{A}) \text{adj}(\mathbf{A})$$

$$\mathbf{B} = \det(\mathbf{A}) \mathbf{A}^{-T}.$$



Etapa M para as covariâncias do GMM (3)

$$\nabla_{\Sigma_k} L = \frac{\partial L}{\partial G} \frac{\partial G}{\partial N_k} \left[\frac{\partial N_k}{\partial F_k} \frac{\partial F_k}{\partial D_k} \frac{\partial D_k}{\partial \Sigma_k} + \frac{\partial N_k}{\partial A_k} \frac{\partial A_k}{\partial \Sigma_k} \right]$$

$$\begin{aligned} \frac{\partial A_k}{\partial \Sigma_k} &= -\frac{1}{2} (\mathbf{x}_n - \boldsymbol{\mu}_k) (\mathbf{x}_n - \boldsymbol{\mu}_k)^T \frac{\partial \Sigma_k^{-1}}{\partial \Sigma_k} \\ &= \frac{1}{2} (\mathbf{x}_n - \boldsymbol{\mu}_k) (\mathbf{x}_n - \boldsymbol{\mu}_k)^T (\Sigma_k^{-1})^2. \end{aligned}$$

$$\frac{\partial L}{\partial G} = \sum_{n=1}^N \frac{1}{G}, \quad \frac{\partial G}{\partial N_k} = \pi_k, \quad \frac{\partial N_k}{\partial A_k} = N_k, \quad \frac{\partial A_k}{\partial \boldsymbol{\mu}_k} = \Sigma_k^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_k).$$



Derivada da matriz inversa

$$0 = I' = A' \cdot A^{-1} + A \cdot (A^{-1})'$$

$$A \cdot (A^{-1})' = -A' \cdot A^{-1}$$

$$(A^{-1})' = -A^{-1} \cdot A' \cdot A^{-1}$$



Etapa M para as covariâncias do GMM (4)

$$\nabla_{\Sigma_k} L = \frac{\partial L}{\partial G} \frac{\partial G}{\partial N_k} \left[\frac{\partial N_k}{\partial F_k} \frac{\partial F_k}{\partial D_k} \frac{\partial D_k}{\partial \Sigma_k} + \frac{\partial N_k}{\partial A_k} \frac{\partial A_k}{\partial \Sigma_k} \right]$$

$$\nabla_{\Sigma_k} L = \sum_{n=1}^N \frac{1}{G} \pi_k \left[D_k N_k \left(-\frac{1}{D_k^2} \right) \frac{1}{2} D_k \Sigma_k^{-1} \right. \\ \left. + N_k \cdot \left(\frac{1}{2} (\mathbf{x}_n - \boldsymbol{\mu}_k) (\mathbf{x}_n - \boldsymbol{\mu}_k)^T (\Sigma_k^{-1})^2 \right) \right].$$



Etapa M para as covariâncias do GMM (5)

$$\nabla_{\Sigma_k} L = 0$$

$$\sum_{n=1}^N \frac{\pi_k N_k}{G} \Sigma_k = \sum_{n=1}^N \frac{\pi_k N_k}{G} \cdot (\mathbf{x}_n - \boldsymbol{\mu}_k) (\mathbf{x}_n - \boldsymbol{\mu}_k)^T$$

$$\sum_{n=1}^N \gamma(z_{nk}) \Sigma_k = \sum_{n=1}^N \gamma(z_{nk}) \cdot (\mathbf{x}_n - \boldsymbol{\mu}_k) (\mathbf{x}_n - \boldsymbol{\mu}_k)^T .$$

$$\Sigma_k = \frac{\sum_{n=1}^N \gamma(z_{nk}) \cdot (\mathbf{x}_n - \boldsymbol{\mu}_k) (\mathbf{x}_n - \boldsymbol{\mu}_k)^T}{N_k}$$



Etapa M para os coeficientes da mistura (1)

$$\nabla_{\pi_k} L = \frac{\partial L}{\partial G} \frac{\partial G}{\partial \pi_k}$$

Restrição: $\sum_{i=1}^K \pi_i - 1 = 0$

Lagrangiano: $J = L + \lambda \left(\sum_{i=1}^K \pi_i - 1 \right)$

$$\nabla_{\pi_k} J = \frac{\partial L}{\partial G} \frac{\partial G}{\partial \pi_k} + \lambda$$

$$\nabla_{\pi_k} L = 0$$



Etapa M para os coeficientes da mistura (2)

$$\nabla_{\pi_k} J = \frac{\partial L}{\partial G} \frac{\partial G}{\partial \pi_k} + \lambda$$

$$\nabla_{\pi_k} L = 0$$

$$\lambda = - \sum_{n=1}^N \frac{1}{G} N_k = - \frac{\sum_{n=1}^N \gamma(z_{nk})}{\pi_k}$$

$$\lambda \sum_{k=1}^K \pi_k = \sum_{n=1}^N \frac{\sum_{k=1}^K \pi_k N_k}{G}.$$

$$\lambda = -N.$$



Etapa M para os coeficientes da mistura (3)

$$\nabla_{\pi_k} J = \frac{\partial L}{\partial G} \frac{\partial G}{\partial \pi_k} + \lambda$$

$$\lambda = - \sum_{n=1}^N \frac{1}{G} N_k = - \frac{\sum_{n=1}^N \gamma(z_{nk})}{\pi_k}$$

$$\lambda = -N.$$

$$\pi_k = \frac{N_k}{N}.$$



Algoritmo EM para GMM (i), (ii)

(i) Inicialize as médias μ_k , as covariâncias Σ_k e os pesos das componentes π_k e calcule o valor inicial da log verossimilhança.

(ii) Etapa E: Calcule as responsabilidades ou probabilidades a posteriori usando os valores atuais dos parâmetros

$$\gamma(z_{nk}) = \frac{\pi_k N(\mathbf{x}_n | \mu_k, \Sigma_k)}{\sum_{i=1}^K \pi_i N(\mathbf{x}_n | \mu_i, \Sigma_i)}$$



Algoritmo EM para GMM (iii)

(iii) Etapa M: Reestime os parâmetros usando as responsabilidades ou probabilidades atuais

$$\boldsymbol{\mu}_k^{\text{nova}} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \boldsymbol{x}_n$$

$$\boldsymbol{\Sigma}_k^{\text{nova}} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (\boldsymbol{x}_n - \boldsymbol{\mu}_k^{\text{nova}}) (\boldsymbol{x}_n - \boldsymbol{\mu}_k^{\text{nova}})^T$$

$$\pi_k^{\text{novo}} = \frac{N_k}{N},$$

sendo $N_k = \sum_{n=1}^N \gamma(z_{nk})$.



Algoritmo EM para GMM (iv)

(iv) Calcule a log verossimilhança

$$\ln p(\mathbf{X} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) = \sum_{n=1}^N \ln \left[\sum_{k=1}^K \pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right]$$

e verifique a convergência dos parâmetros ou da log verossimilhança. Se não for satisfeito o critério de convergência, retorne à etapa (ii).