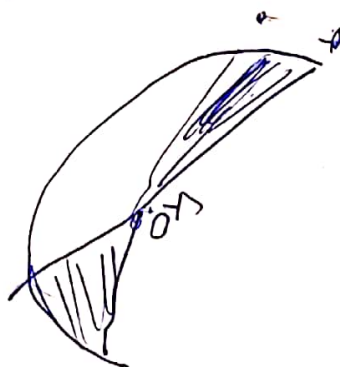


AULA MECÂNICA

07/10/1

- FORÇAS CENTRAIS
- CONSERVAÇÃO DO MOMENTO ANGULAR.
- MOVIMENTO PLANAR EM SISTEMAS C/ FORÇAS CENTRAIS.
- LEI DE KÉPLER SOBRE A VELOCIDADE NO PERCORRER ÁREA.

$$r^2 \cdot \dot{\theta} \text{ é constante.}$$



SISTEMAS BIDIMENSIONAIS COM FORÇAS CENTRAIS

→ O SISTEMA É CONSERVATIVO.

$$\Rightarrow \exists U: \mathbb{R}^2 \setminus \{0\} \rightarrow \mathbb{R}$$

$$\ddot{X} = -\nabla U(X)$$

$$U(X) = \frac{1}{2} (||X||)^2$$

$$\nabla U(x) = \Phi'(\|x\|) \cdot \frac{x}{\|x\|}$$

(2)

Sei que o momento angular é constante

$\exists M$ tal que $\boxed{\dot{\varphi}^2 r^2 = M}$

$$\frac{\dot{x}^2}{2} + U(x) \equiv E$$

numa solução

$$\dot{\varphi}^2 r^2 \equiv M$$

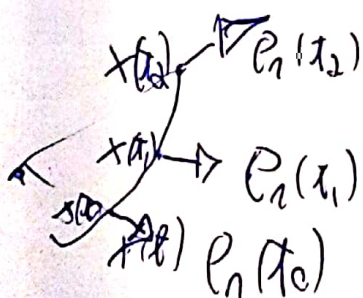
- ESTRATÉGIA!

REDUZIR O PROBLEMA A DESCOBRIR A
SOLUÇÃO DE UM PROBLEMA C/ 1 GRAU
DE LIBERDADE p/ $r(x)$.

$$\ddot{x} = -\Phi'(\|x\|) \cdot e_n$$

$$x(t) = r(t) \cdot e_n(t)$$

$$e_n(t)$$



$$e_n(t) = \frac{x(t)}{\|x(t)\|}$$

$$\dot{X}(t) = \dot{r}(t) e_n + r \cdot \dot{e}_n(t)$$

$$\dot{e}_n(t) = \dot{\theta} \cdot e_\theta$$

$$e_\theta \in \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \cdot e_n(t)$$

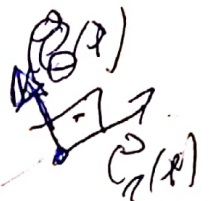
$$\dot{X} = \dot{r} e_n + r \dot{\theta} e_\theta$$

$$\dot{X} = \ddot{r} e_n + \dot{r} \dot{e}_n + \dot{r} \dot{\theta} e_\theta + r \ddot{\theta} e_\theta + r \dot{\theta} \dot{e}_\theta$$

$$\dot{e}_n = \dot{\theta} e_\theta$$

$$e_\theta$$

3



$$\ddot{r} = -\frac{d}{dr} \left(\Phi(r) + \frac{m^2}{2r^2} \right)$$

(4)

$$\ddot{r} = -\frac{d}{dr} \left(\Phi(r) + \frac{m^2}{2r^2} \right)$$

$$\Phi(r) = U(|x|)$$

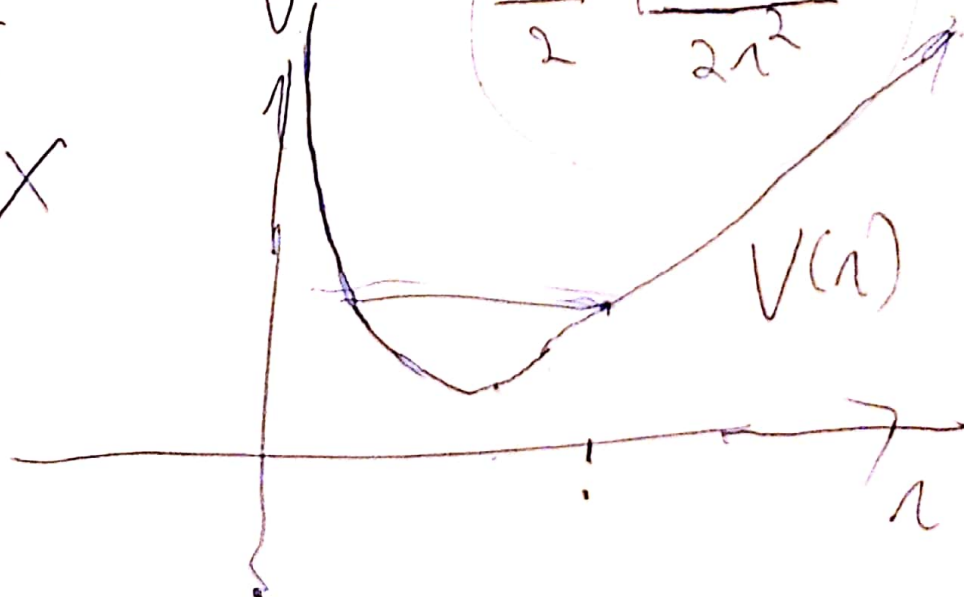
$V(r)$ ENERGIA POTENCIAL EFETIVA.

$$V(r) = \Phi(r) + \frac{m^2}{2r^2}$$

ex: $\phi(r) = \frac{r^2}{2}$

$$\ddot{x} = -x$$

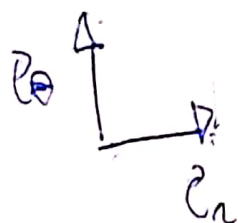
$$V(r) = \frac{r^2}{2} + \frac{2m^2}{2r^2}$$



$$\dot{X} = \dot{r} \vec{e}_r + r \cdot \dot{\vec{e}}_r = \dot{r} \vec{e}_r + r \dot{\theta} \vec{e}_\theta$$

(3)

$$\begin{aligned} \ddot{X} &= \cancel{\dot{r} \vec{e}_r} + \cancel{\dot{r} \vec{e}_r} + \ddot{r} \vec{e}_r + \dot{r} \dot{\vec{e}}_r + \dot{r} \dot{\theta} \vec{e}_\theta + r \ddot{\theta} \vec{e}_\theta + \\ &\quad \underbrace{(r \ddot{\theta} \vec{e}_\theta)}_{= -r \dot{\theta} \dot{\vec{e}}_r} = \\ &= \ddot{r} \vec{e}_r + \dot{r} \dot{\theta} \vec{e}_\theta + \dot{r} \dot{\theta} \vec{e}_\theta + r \ddot{\theta} \vec{e}_\theta - r \dot{\theta} \dot{\vec{e}}_r = \end{aligned}$$



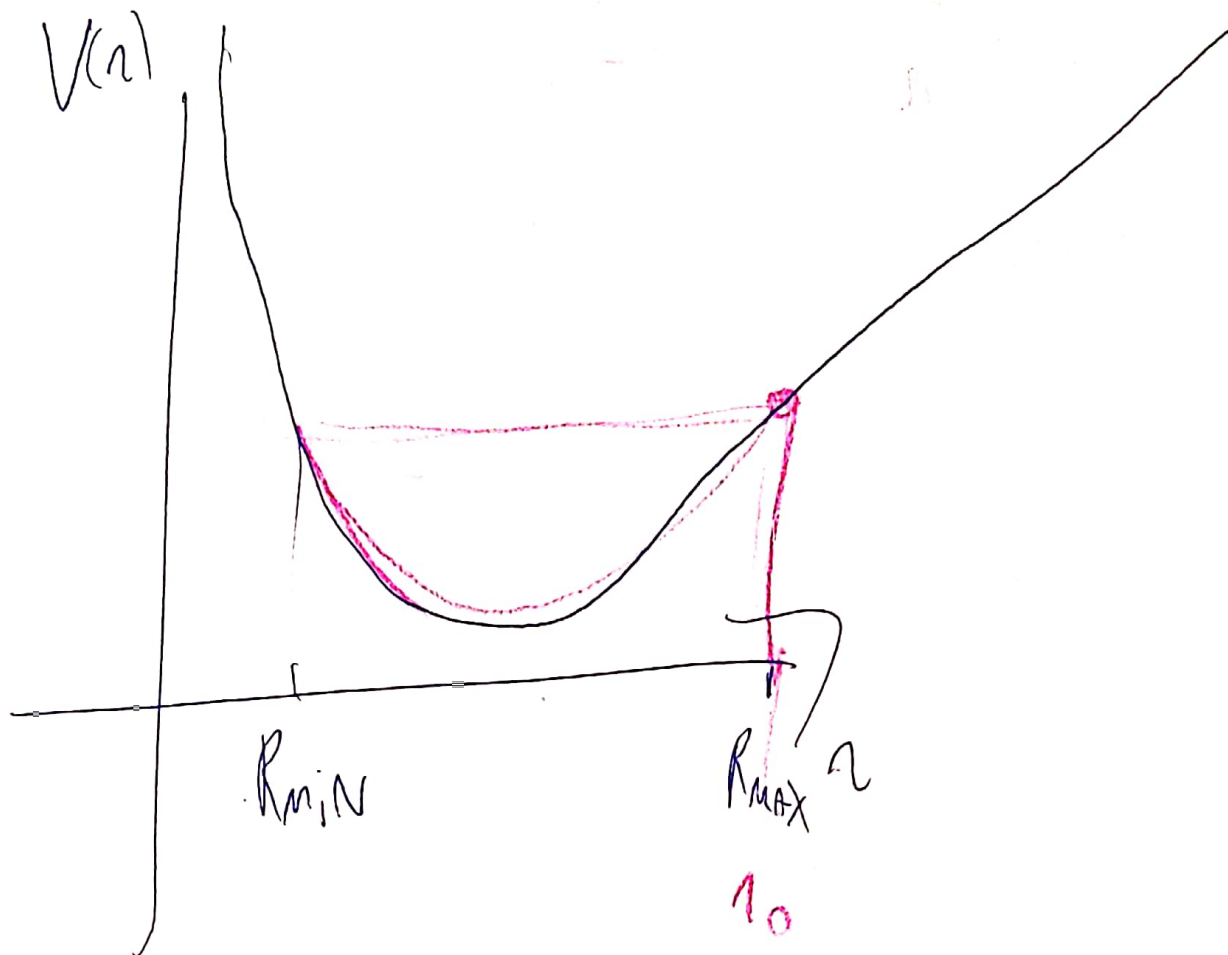
$$\dot{\vec{e}}_\theta = -\dot{\theta} \vec{e}_r$$

$$= \left(\ddot{r} - r \dot{\theta}^2 \right) \vec{e}_r + \left(2\dot{r} \dot{\theta} + r \ddot{\theta} \right) \vec{e}_\theta \equiv \ddot{X}$$

//
0 pois $\ddot{X} = F(r)$
CENTRAL.

Logo - $\mathcal{I}'(r) \equiv \ddot{r} - r \dot{\theta}^2$ ou

$$\ddot{r} = -\mathcal{I}'(r) + r \cdot \frac{M^2}{r^4} = -\mathcal{I}'(r) + \frac{M^2}{r^3}$$



5

Logo $r(t)$ NESTE EXEMPLO OSCILA PERIÓDICA ENTRE O VALOR R_{MAX} E O VALOR R_{min} .

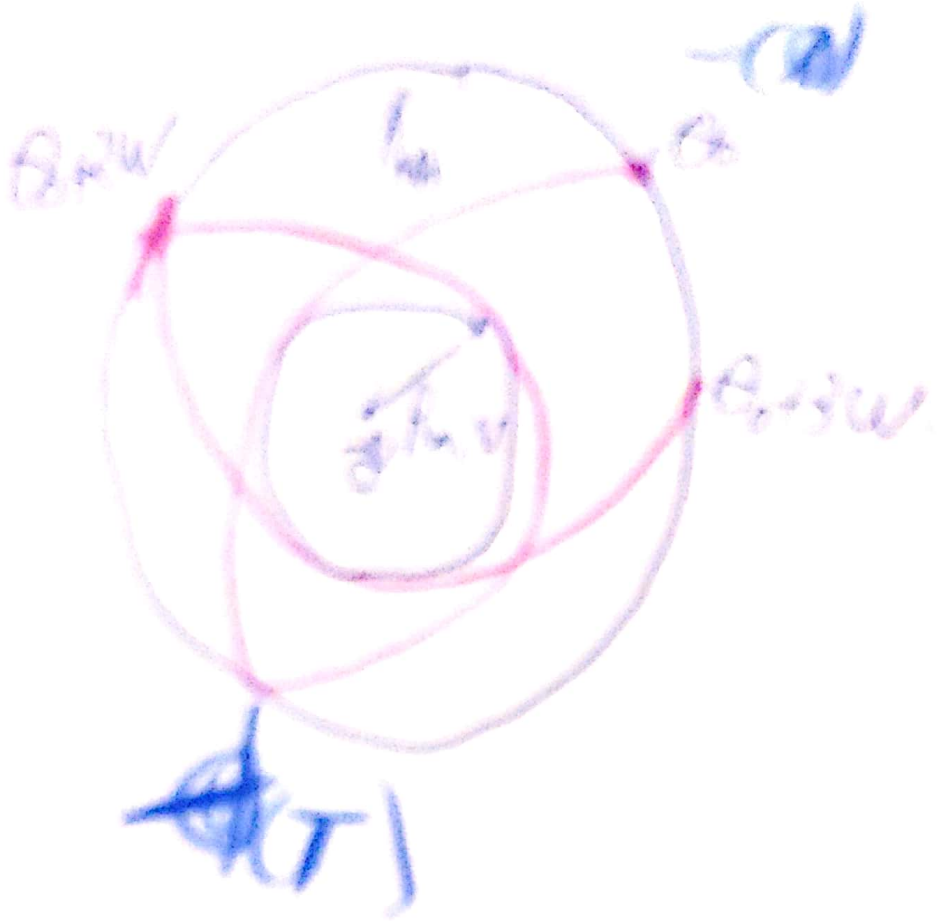
Por outro lado.

$$\dot{\Theta} = \frac{M}{r^2}$$

$$\Theta(t) = \Theta(t_0) + \int_{t_0}^t \frac{M}{R^2(t)} dt$$

Logo Θ É UMA FUNÇÃO PERIÓDICA. E
 $\Theta(t)$ É UMA FUNÇÃO LINEAR + UMA FUNÇÃO PERIÓDICA.

⑥



$$W = Q \cdot T$$

$$P \cdot T$$

Q+3W

so $\frac{W}{T} \in \mathbb{Q} \Rightarrow \exists N_0 \in \mathbb{N}, L \in \mathbb{N}$

$$N_0 W = L \cdot 2\pi$$

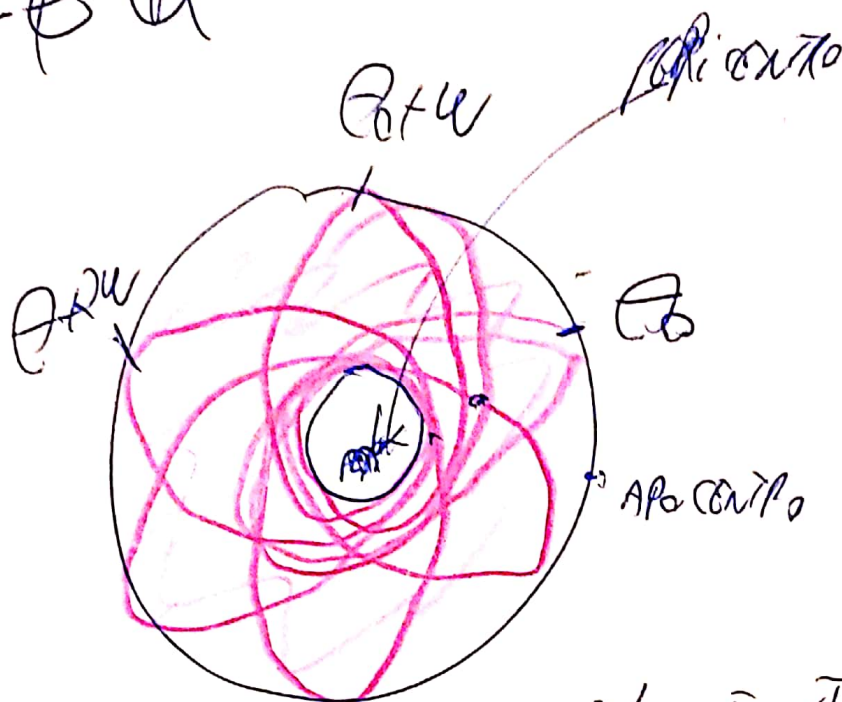
$$L \in \mathbb{N}$$



$$SE \frac{W}{V} \notin \mathbb{Q}$$

(7)

ENTÃO



ÓRBITA DENSE NO ANEL ENTRE R_{min} E R_{MAX} .

OBS:

2 SISTEMAS CONSERVATIVOS:

$$1^o \frac{\|\dot{X}\|^2}{2} + U(X) \quad E = \frac{\|\dot{X}\|^2}{2} + U(X).$$

$$2^o = \frac{\dot{n}^2}{2} + V(n)$$

$$\dot{X} = \dot{n}e_n + n\dot{\theta}e_\theta$$

$$\|\dot{X}\|^2 = \dot{n}^2 + n^2\dot{\theta}^2$$

$$\frac{\|\dot{X}\|^2}{2} = \frac{\dot{n}^2}{2} + \left(\frac{n^2 \dot{\theta}^2}{2} \right) + \dots = \frac{\dot{n}^2}{2} + \frac{m^2}{2n^2} + \dots$$

Como se em t_0

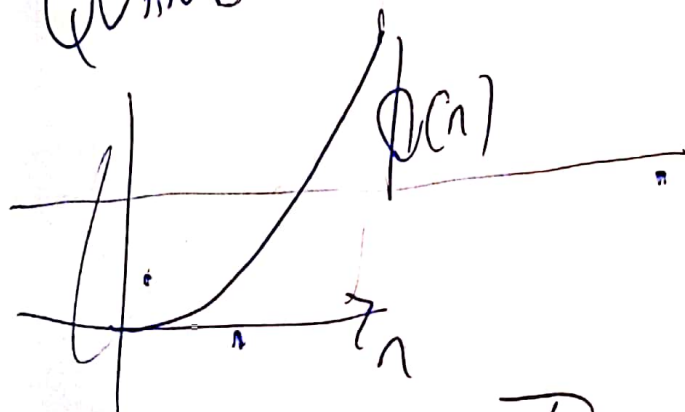
ENERGIA DO SISTEMA INICIAL. $\textcircled{E_0}$

$$E_0 = \frac{\|\dot{X}(t_0)\|^2}{2} + U(X(t_0)) =$$

$$= \left[\frac{\dot{r}^2(t_0)}{2} + \frac{M^2}{2r^2(t_0)} + \Phi(r) \right] =$$

ENERGIA DO SISTEMA DERIVADO

QUANDO UMA ÓRBITA PODE SER LIMITADA?



se $\lim_{r \rightarrow +\infty} \phi(r) = +\infty$

ENTÃO
TODAS
AS ÓRBITAS
SÃO LIMITADAS

$$\lim_{n \rightarrow +\infty} \phi(n) = \lim_{n \rightarrow +\infty} V(n)$$

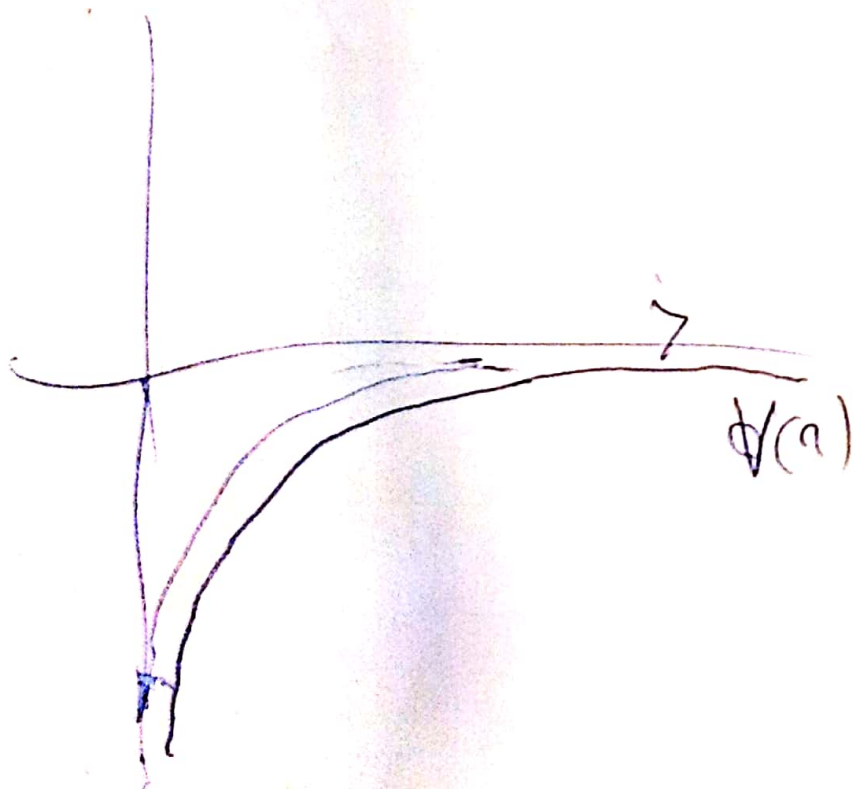
(9)

$$V(n) = \phi(n) \neq \frac{M^2}{2n^2}$$

Se $\lim_{n \rightarrow +\infty} (\phi(n) n^2) \neq 0$ FOR NEGATIVA.

ENTÃO PODERÁ TER SOLUÇÕES QUE CHEGAM ATÉ A ORIGEM.

EX: $\phi(n) = -\frac{1}{n^3}$



6

~~Ex~~ CASO MAIS RELEVANTE É
QUANDO

(10)

~~Ex~~ $\boxed{\ddot{\theta}(t) = -\frac{k}{\lambda}}$

$k > 0$

$$\ddot{X} = -\frac{k}{\|X\|^2} \cdot \frac{X}{\|X\|}$$

$$V(r) = -\frac{k}{r} + \frac{M^2}{2r^2}$$

$$\lim_{r \rightarrow 0} V(r) = +\infty.$$

~~$\dot{\theta} = \frac{M}{r^2}$~~ $\dot{\theta} = \frac{M}{r^2}$

~~Q(n)~~

$$n^2 \dot{\theta} = M$$

(11)

$$\dot{\theta} = \frac{d\theta}{dx}$$

$$\frac{d\theta}{dx} = \frac{d\theta}{dn} \frac{dn}{dx}$$

$$\frac{d\theta}{dn} \cdot \dot{n} = \dot{\theta} = \frac{M}{n^2}$$

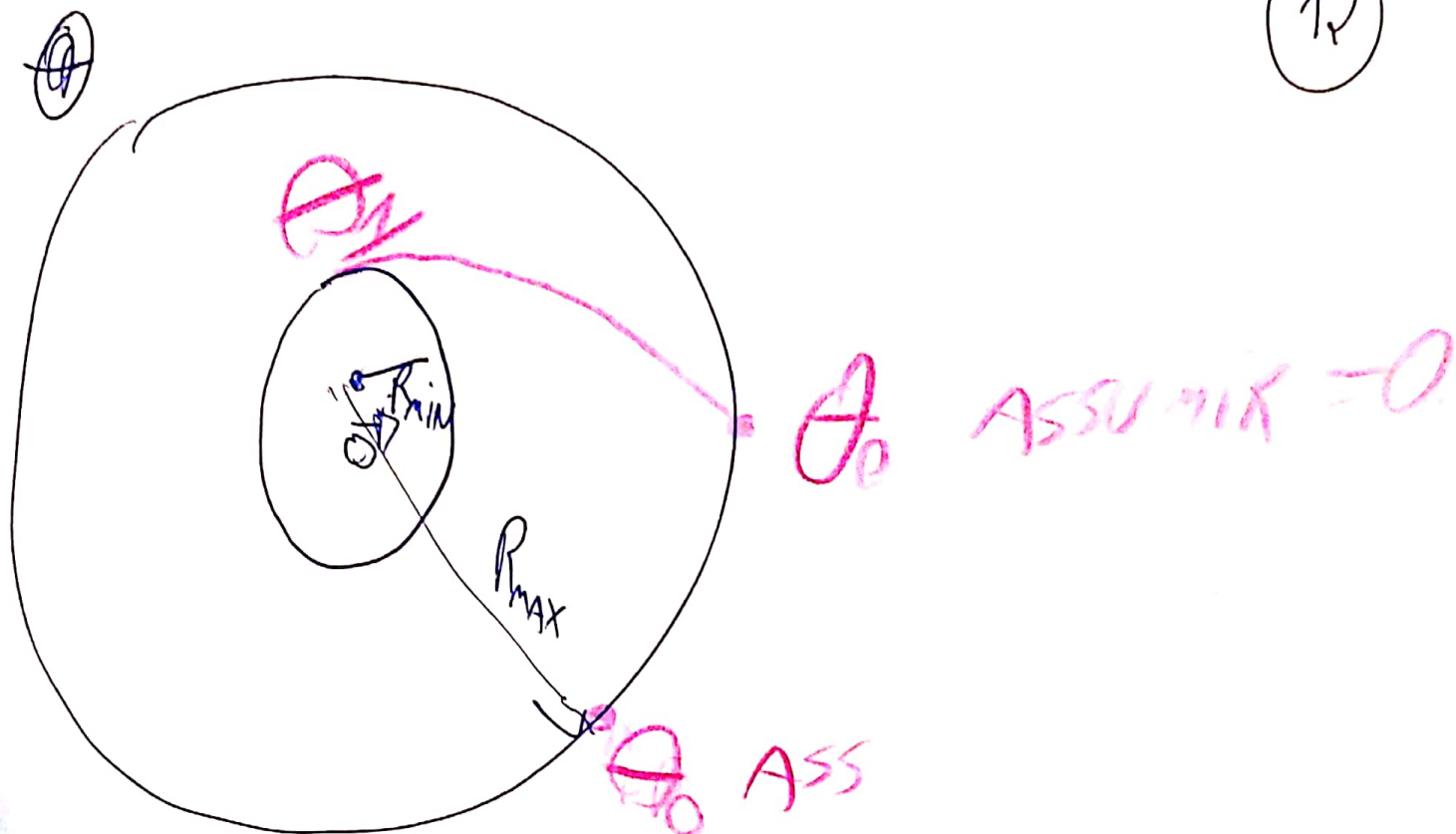
$$\frac{\dot{n}^2}{2} = E - V(n)$$

$$\dot{n} = \sqrt{2(E - V(n))} \quad \text{se } \dot{n} > 0$$

$$\dot{n} = -\sqrt{2(E - V(n))} \quad \text{se } \dot{n} < 0$$

$$\frac{d\theta}{dn} = \frac{M}{n^2} \cdot \frac{1}{\sqrt{2(E - V(n))}}$$

SE n ESTÁ
VARIANDO
DE $n_{\min}$ P/
 $n_{\max}$



$$\Theta(n) = \text{[scribbles]} + \text{[scribbles]} \quad R_{\max}$$

$$= \Theta_0 + \int_0^{R_{\max}} \frac{M}{n^2} \left(\frac{1}{\sqrt{2(E-V(r))}} \right) dr =$$

$$\Theta(n) = \text{ARC COS} \frac{\frac{M}{R} - \frac{K}{M}}{\sqrt{2E - \frac{K^2}{n^2}}}$$