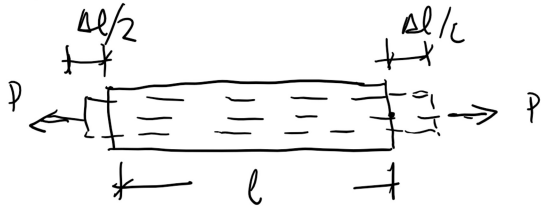
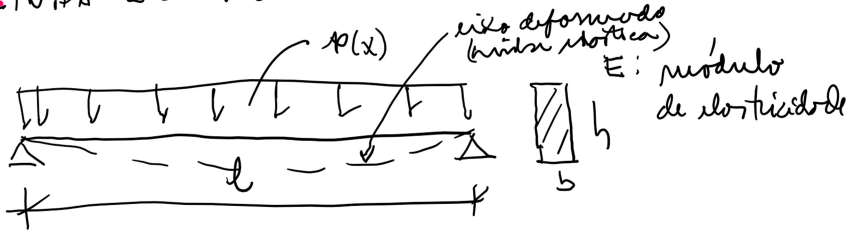
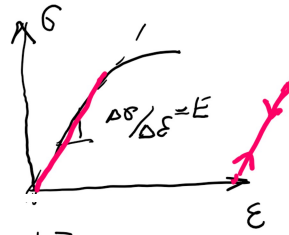


# Linha Elástica

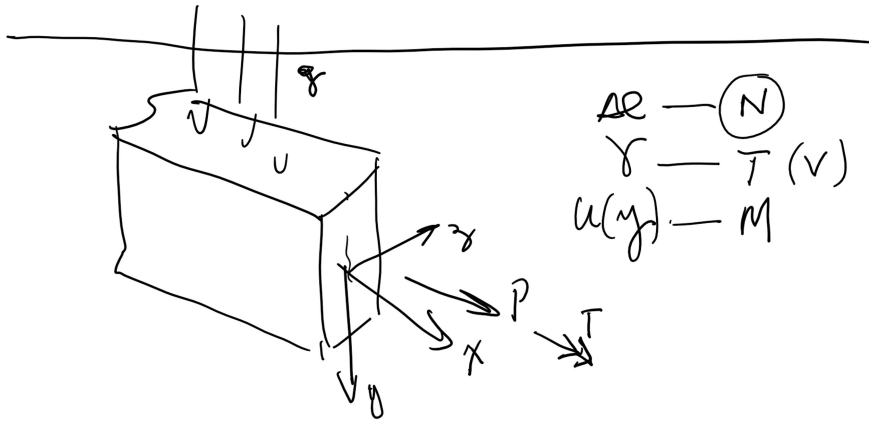
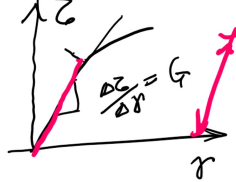


$$\epsilon = \frac{\Delta l}{l} = \frac{l_f - l_i}{l_i}$$

$\sigma \propto \epsilon \Rightarrow \sigma = E \cdot \epsilon$   
Tensões normais

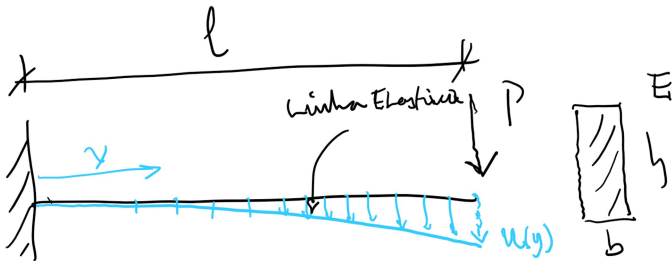


$\tau \propto \gamma \Rightarrow \tau = G \cdot \gamma$



- $\Delta R \rightarrow N$
- $\gamma \rightarrow T (V)$
- $u(y) \rightarrow M$

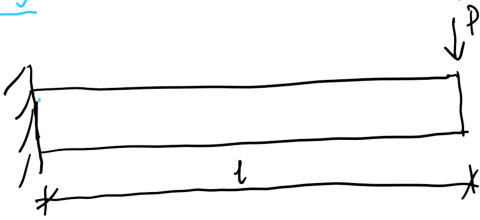
## Efeitos decorrentes do momento fletor







u(y): deslocamento transversal



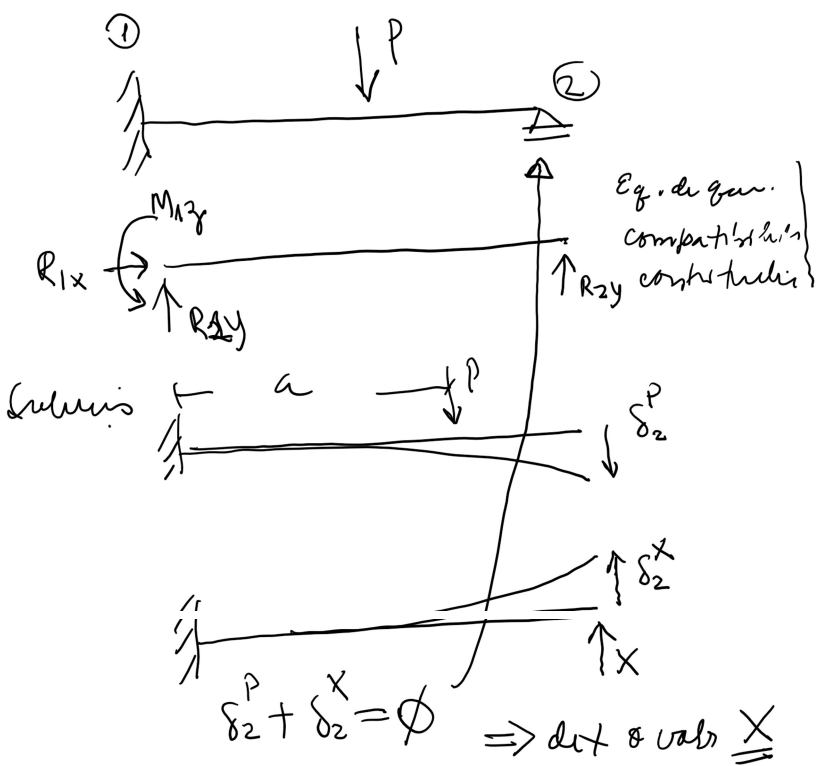
$$\sigma_{\text{act}} \leq \sigma_{\text{adm}}$$

$$u_{\text{max}} \leq u_{\text{limite}} \text{ especificada}$$

$$\downarrow$$

$$\frac{l}{200}$$

problemas hiperestáticos

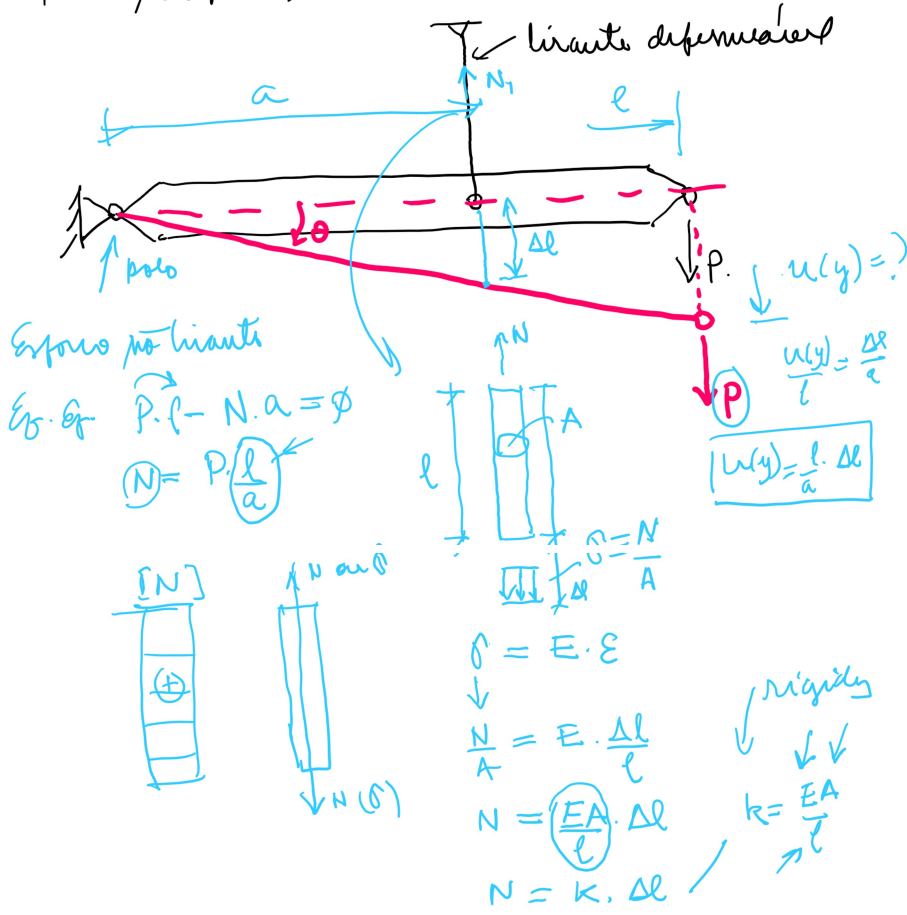


M; N; V; T → (1) e (2) ← para prático ou verificar da estrutura





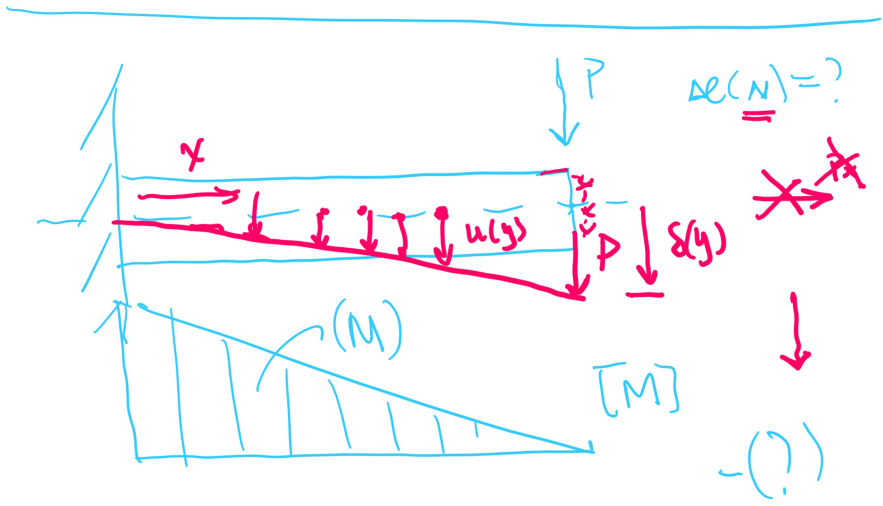
deformações (efeitos) decorrentes dos esforços normais  $\sigma$



$\Delta l =$

$\frac{N \cdot l}{EA}$

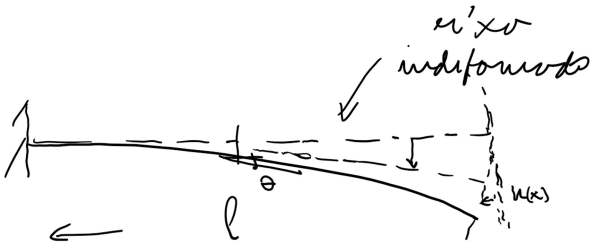
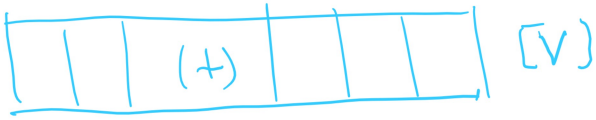
$\frac{l}{EA}$





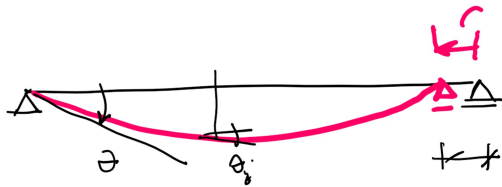
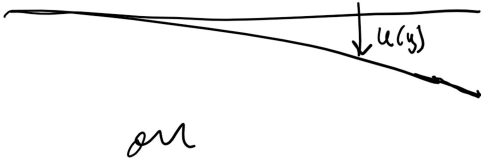




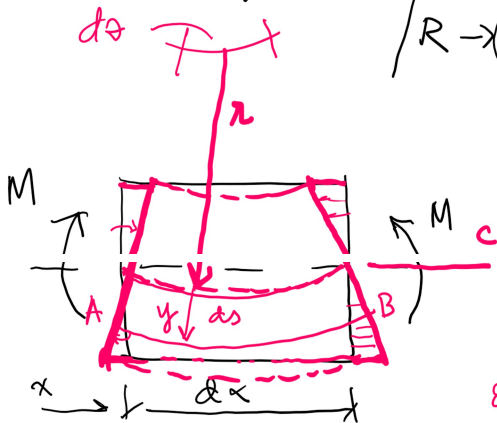
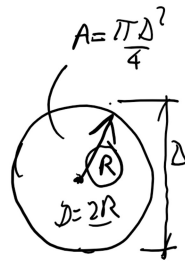
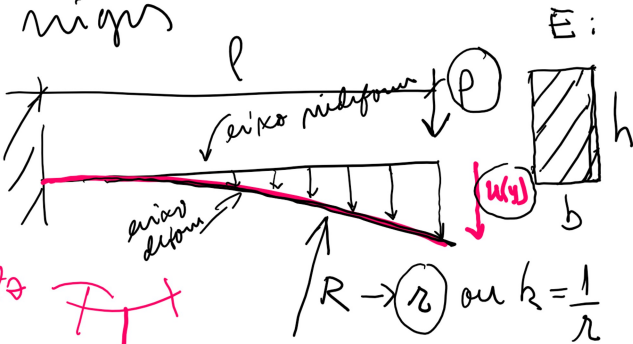


$\theta$ : rot. no topo  
 $\psi$ : rot. na base

$$\theta \approx \text{tg } \theta$$



Cálculo das deformações transversais das vigas



$$ds = dx = R d\theta$$

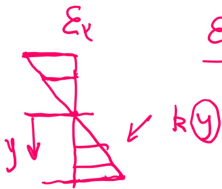
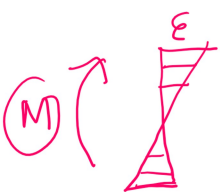
$$\frac{d\theta}{dx} = \frac{1}{R} = k \text{ (curvatura)}$$

$$\widehat{AB} = (R + y) d\theta$$

$$\epsilon_x = \frac{\widehat{AB} - dx}{dx} = \frac{(R + y) d\theta - dx}{dx}$$

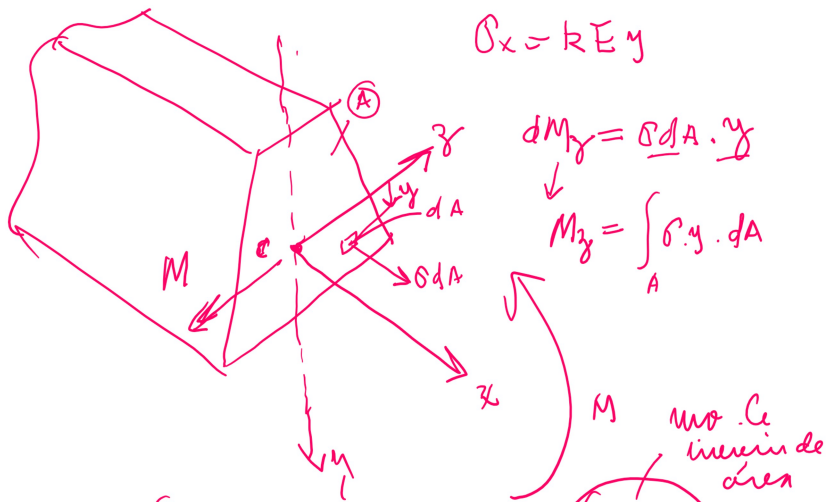
$$\epsilon_x = y \frac{d\theta}{dx} = \frac{y}{R} = ky$$

$$\sigma_x = E \cdot \epsilon_x = E \cdot ky$$









$$M_y = \int_A k E \cdot y \cdot y \cdot dA = k \cdot E \cdot \left( \int y^2 \cdot dA \right)$$

$$M(x) = k \cdot (E I_z)$$

← produto de rigidez à flexão

↑ curvatura do eixo da beam

$$\boxed{M(x) = \left( \frac{1}{R} \right) \cdot E \cdot I_z}$$

$$\frac{M_y}{k} = \left( \frac{1}{R} \right) E$$

ou

$I$

↑

$$\frac{d\theta}{dx} = \frac{1}{R}$$

com  $\theta \approx \tau_y \theta$   $\tau_y \theta = \frac{dy}{dx}$

$$\theta = \frac{dy}{dx}$$

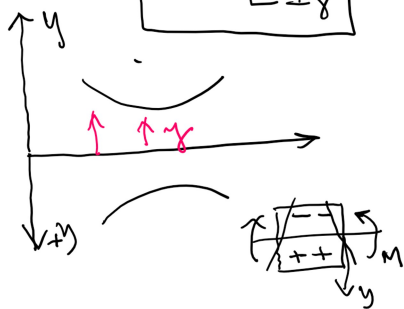
$$\boxed{\frac{d^2y}{dx^2} = \frac{1}{R}}$$

$$\boxed{\frac{d^2y}{dx^2} = k}$$

$$k = \frac{M(x)}{E I_z}$$

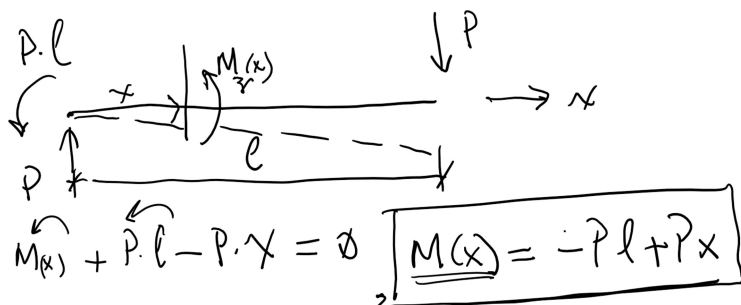
$$\frac{d^2y}{dx^2} = \left( - \right) \frac{M(x)}{E I_z}$$

$y$   $M$









$$\frac{d^2y}{dx^2} = -\frac{M(x)}{EI} \quad \therefore EI \cdot y''$$

$$EI y'' = +Pl - Px$$

$$EI y' = +Plx - \frac{Px^2}{2} + C_1$$

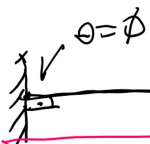
$$= - M(x)$$

$$\left( \frac{P(x)}{EI} \right)$$

$$= \frac{dy}{dx}$$

→

$$EI y = +\frac{Plx^2}{2} - \frac{Px^3}{6} + C_1x + C_2$$



*rotations(x)*

$$\theta(x) = \frac{Plx}{EI} - \frac{Px^2}{2EI}$$

$$\frac{Pl(x=0)}{EI} - \frac{P(x=0)^2}{2EI} + C_1 = 0 \quad \therefore C_1 = 0$$

$$+\frac{Pl(x=0)^2}{2EI} - \frac{P(x=0)^3}{6EI} + (C_1=0) + C_2 = 0 \Rightarrow C_2 = 0$$

$$\boxed{y(x) = \frac{Plx^2}{2EI} - \frac{Px^3}{6EI}} \quad \leftarrow \text{leichter ableiten da wirgen}$$







$$y(x=l) = \frac{Pl \cdot l^2}{2EI} - \frac{Pl^3}{6EI} = \frac{3Pl^3}{6EI} - \frac{Pl^3}{6EI} =$$

$$y(x=l) = \frac{Pl^3}{3EI}$$

deslocamento máximo  
do eixo da base

---

$$w_{zn} = 2.0 \text{ G}$$

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$$y(x=l) \Rightarrow u_{\max} = \frac{Pl^3}{3EI} \quad \begin{matrix} 20 \text{ kN} \\ 20.000 \text{ MPa} \end{matrix}$$

$$P = 20 \text{ kN} \quad l = 400 \text{ cm} \quad E = 20000 \frac{\text{kN}}{\text{cm}^2}$$

$$I = \frac{bh^3}{12} = \frac{10 \times 20^3}{12} =$$

$$u_{\max} = \frac{20 \text{ kN} \cdot (400 \text{ cm})^3 \times 12}{3 \times 20000 \frac{\text{kN}}{\text{cm}^2} \cdot 10 \times (20 \text{ cm})^3} = 32 \text{ cm}$$

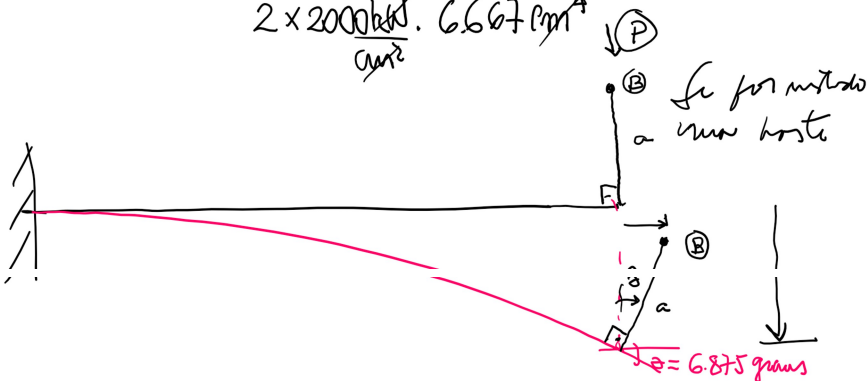
$\rightarrow u_{\max} \rightarrow$  flecha do eixo elástico

Calculo de  $\theta$  em  $x=l$

$$\theta(x) = \frac{P \cdot lx - Px^2}{EI} \frac{Px}{2EI}$$

$$\theta(x=l) = \frac{Pl^2}{EI} - \frac{Pl^2}{2EI} = \frac{Pl^2}{2EI}$$

$$\theta_{\max} \text{ (em } x=l) = \frac{20 \text{ kN} \cdot (400 \text{ cm})^2}{2 \times 20000 \frac{\text{kN}}{\text{cm}^2} \cdot 6667 \text{ cm}^4} = 6.875 \text{ graus.}$$



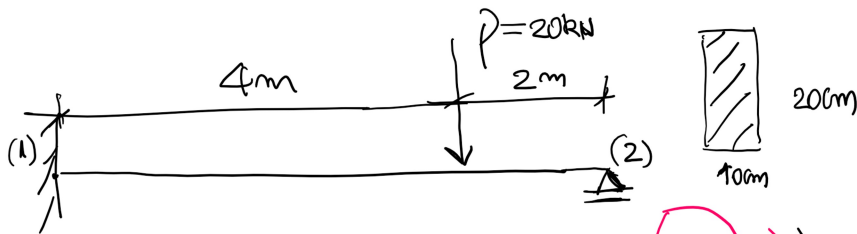
PROBLEMA 4

$$E = 20000 \frac{\text{kN}}{\text{cm}^2}$$





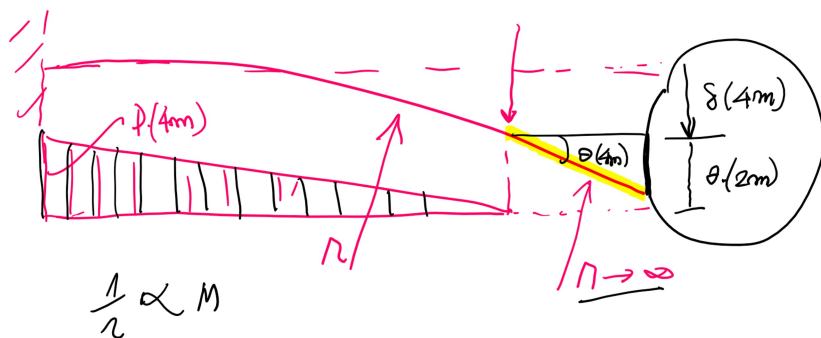




Dat. os esforços solicitantes da viga ( $M$ ,  $V$  e  $N$ )

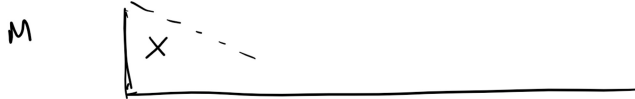
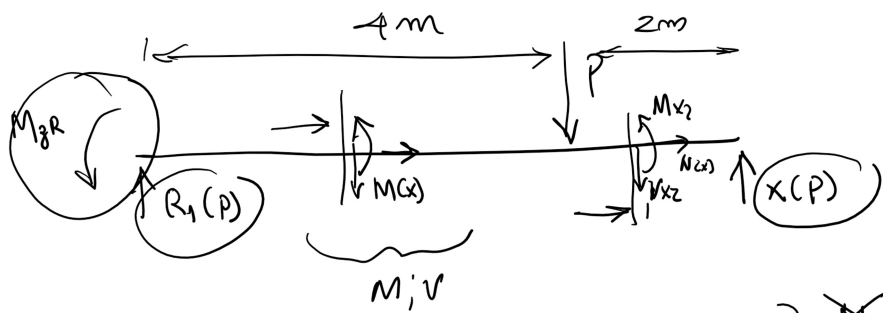
Free body diagrams and equilibrium equations:

- Global equilibrium:
  - $\sum F_y = 0$
  - $R_{1y} + R_{2y} = P$
  - $\sum F_x = 0$
  - $R_{1x} = 0$
- Moment equilibrium:
  - $\sum M_z = 0$
  - $-M_{1z} + P \cdot 4 - 6 \cdot R_{2y} = 0$
  - $-M_{1z} - 6R_{2y} = -4P$
- Section I (at 2m):
  - Internal forces:  $R_{1x}$ ,  $R_{1y}$ ,  $R_{2y}$ ,  $R_{2x}$
  - Displacements:  $\theta_x$ ,  $\theta_y$ ,  $\delta_2$
- Section II (at 4m):
  - Displacements:  $\delta_2$
- Virtual displacement method:
  - $\sum \delta_2^P + \sum \delta_2^X = \delta$   $\Rightarrow$  a valor de  $(X)$
  - $\delta_2^X = \frac{X \cdot l^3}{3EI}$









Entradas no dia 25 às 7h.



