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- Just as a concave (convex) objective function in a static optimization problem is sufficient to identify an extremum as an absolute maximum (minimum), a similar sufficiency theorem holds in the calculus of variations.
- For the fixed-endpoint problem Maximize ou minimize  $V[y] = \int_0^T F[t, y(t), y'(t)]dt$ , if the integrand function F(t, y, y') is concave in (y, y'), then the Euler equation is sufficient for an absolute maximum of V[y].
- Similarly, if F(t, y, y') is convex in (y, y'), then the Euler equation is sufficient for an absolute minimum of V[y].

## Concavity





- It should be pointed out that concavity/convexity in (y, y') means concavity/convexity in the two variables y(t) and y'(t) jointly, not in each variable separately.
- The function F(t, y, y') is concave in (y, y') if, and only if, for any pair of distinct points in the domain,  $(t, y^*, y^{*'})$  and (t, y, y'), we have (5)  $F(t, y, y') - F(t, y^*, y^{*'}) \le F_y(t, y^*, y^{*'})(y - y^*) + F_{y'}(t, y^*, y^{*'})(y' - y^{*'})$
- Since  $y(t) = y^*(t) + \epsilon p(t)$ , and  $y'(t) = y^{*'}(t) + \epsilon p'(t)$ , equation (5) may be expressed as:
  - (5')

$$F(t, y, y') - F(t, y^*, {y^*}') \le F_y(t, y^*, {y^*}') \epsilon p(t) + F_{y'}(t, y^*, {y^*}') \epsilon p'(t)$$

- Here  $y^*(t)$  denotes the optimal path, and y(t) denotes any other path. By integrating both sides of (5') with respect to t over the interval [0, T], we obtain:  $\int_0^T [F(t, y, y') - F(t, y^*, y^{*'})] dt \leq \int_0^T [F_y(t, y^*, y^{*'})\epsilon p(t) + F_{y'}(t, y^*, y^{*'})\epsilon p'(t)] dt$ 
  - (6)  $V[y] V[y^*] \le \epsilon \int_0^T \left[ F_y(t, y^*, {y^*}') p(t) + F_{y'}(t, y^*, {y^*}') p'(t) \right] dt$
- We have already seen that

$$\int_{0}^{T} F_{y'} p'(t) dt = \left[ F_{y'} p(t) \right]_{0}^{T} - \int_{0}^{T} p(t) \frac{d}{dt} F_{y'} dt \quad \text{(integration by parts).}$$
  
• Therefore,  $\int_{0}^{T} \left[ F_{y'} p'(t) \right] dt = -\int_{0}^{T} \left[ p(t) \frac{d}{dt} F_{y'} \right] dt$  when  $p(0) = p(T) = 0$ , and  
(6')  $V[y] - V[y^{*}] \le \epsilon \int_{0}^{T} p(t) \left[ \underbrace{F_{y}(t, y^{*}, y^{*'}) - \frac{d}{dt} F_{y'}(t, y^{*}, y^{*'})}_{Euler Equation} \right] dt = 0$ 

- Equation (6') is equal to zero (= 0) since  $y^*(t)$  satisfies the Euler equation  $\left(F_y \frac{d}{dt}F_{y'} = 0\right)$ .
- In other words,  $V[y] \leq V[y^*]$ , where y(t) can refer to any other path.
- We have thus identified y\*(t) as a V-maximizing path, and at the same time demonstrated that the Euler equation is a sufficient condition, given the assumption of a concave F function.
- The opposite case of a convex *F* function for minimizing V can be proved analogously.
- If the **F** function is strictly concave in (y, y'), then the weak inequality  $(\leq)$  will become the strict inequality (<).

- The proof above is based on the assumption of **fixed endpoints**. But it can easily be generalized to problems with a vertical terminal line or truncated vertical terminal line.
- Recall that the integration-by-parts process:

$$\int_0^T F_{y'} p'(t) dt = \left[ F_{y'} p(t) \right]_0^T - \int_0^T p(t) \frac{d}{dt} F_{y'} dt$$

- originally produced an **extra term**  $[F_{y'}p(t)]_0^T$  which later **drops out** because it reduces to zero because p(0) = p(T) = 0.
- When we switch to the problem with a variable terminal point, with T fixed but y(T) free, p(T) is no longer required to be zero.

• Multiplying the above equation by  $\epsilon$  [see equation (6)]:

• 
$$\epsilon \int_0^T F_{y'} p'(t) dt = \epsilon \left[ F_{y'} p(t) \right]_0^T - \epsilon \int_0^T p(t) \frac{d}{dt} F_{y'} dt$$

• For this reason, we must admit an extra term [recall that  $y(t) = y^*(t) + \epsilon p(t)$ ]:

(7) 
$$\epsilon \left[ F_{y'} p(t) \right]_{0}^{T} = \epsilon \left[ F_{y'} p(t) \right]_{t=T} = \left[ F_{y'} (y - y^{*}) \right]_{t=T}$$

on the right-hand side of the second and the third lines of (6').

• Therefore:

(8) 
$$\epsilon \int_0^T F_{y'} p'(t) dt = \left[ F_{y'} (y - y^*) \right]_{t=T} - \epsilon \int_0^T p(t) \frac{d}{dt} F_{y'} dt$$

• Using (8) in (6):

(9) 
$$V[y] - V[y^*] \le \epsilon \int_0^T p(t) \left[ \frac{F_y(t, y^*, y^{*'}) - \frac{d}{dt}F_{y'}}{Euler Equation} dt + \left[ F_{y'}(y - y^*) \right]_{t=T} \right]_{t=T}$$

- Considering Euler Equation is valid, (9) now becomes (10)  $V[y] - V[y^*] \le [F_{y'}(y - y^*)]_{t=T}$
- where  $F_{y'}$  is to be evaluated along the optimal path, and  $(y y^*)$  represents the deviation of any admissible neighboring path y(t) from the optimal path  $y^*(t)$ .

- If the last term in the last inequality is zero, then obviously the original conclusion-that  $V[y^*]$  is an absolute maximum-still stands.
- It is only when  $[F_{y'}(y y^*)]_{t=T}$  is positive that we are thrown into doubt.
- In short, the concavity condition on  $F(t, y, y^*)$  only needs to be supplemented in the present case by a no positivity condition on the expression  $[F_{y'}(y y^*)]_{t=T}$ .
- But this supplementary condition is automatically met when the transversality condition is satisfied for the vertical-terminal-line problem:  $[F_{y'}]_{t=T} = 0.$

- As for the truncated case, the transversality condition calls for either  $[F_{y'}]_{t=T} = 0$  (when  $y_{min}$  is nonbinding), or  $y^* = y_{min}$  (when that terminal value is binding, thereby in effect turning the problem into one with a fixed terminal point).
- Either way, the supplementary condition is met.
- Thus, if the integrand function F is concave (convex) in the variables (y, y') in a problem with a vertical terminal line or a truncated vertical terminal line, then the Euler equation plus the transversality condition are sufficient for an absolute maximum (minimum) of V[y].