



Dinamica Non Lineare di Strutture e Sistemi Meccanici

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Lezione 6

Reduced-Order Modelling

Historical notes

- Steindl & Troger (2001): analytical and numerical (finite-difference); linear and non-linear; pre- and post-processing (Karhunen-Loeve)
 - Shaw & Pierre & Peschek (2001-2009): analytical projection of dynamics onto non-linear modes defined by invariant manifolds
 - Mazzilli & Baracho Neto (2006-2008): analytical projection of dynamics onto non-linear modes defined by invariant manifolds or multiple time scales
 - Amabili & Touzé (2007): numerical methods
 - Kerschen & Peeters & Golinval & Vakakis (2008): numerical methods
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Reduced-Order Modelling

Non-linear Galerkin procedures

Equations of motion of wide class of discrete systems

$$M_{rs}(\mathbf{p}) \ddot{p}_s + D_{rs}(\mathbf{p}, \dot{\mathbf{p}}) \dot{p}_s + K_{rs}(\mathbf{p}) p_s = R_r, \quad r = 1, 2, \dots, n, \quad \text{sum in } s = 1 \text{ to } n,$$

$$M_{rs}(\mathbf{p}) = M_{rs}^0 + M_{rsk}^1 p_k + M_{rsk\ell}^2 p_k p_\ell$$

$$D_{rs}(\mathbf{p}, \dot{\mathbf{p}}) = D_{rs}^0 + D_{rsk}^1 \dot{p}_k + D_{rsk\ell}^2 \dot{p}_k p_\ell$$

$$K_{rs}(\mathbf{p}) = K_{rs}^0 + K_{rsk}^1 p_k + K_{rsk\ell}^2 p_k p_\ell$$

$$M_{rs}^0, M_{rsk}^1, M_{rsk\ell}^2$$

$$D_{rs}^0, D_{rsk}^1, D_{rsk\ell}^2$$

$$K_{rs}^0, K_{rsk}^1, K_{rsk\ell}^2$$

constants

Reduced-Order Modelling

Non-linear Galerkin procedures

Modal relationships

$$p_r(\mathbf{U}, \dot{\mathbf{U}}) = p_{0r} + a_{1r}^u U_u + a_{2r}^u \dot{U}_u + a_{3r}^{uv} U_u U_v + a_{4r}^{uv} U_u \dot{U}_v + a_{5r}^{uv} \dot{U}_u \dot{U}_v \\ + a_{6r}^{uvw} U_u U_v U_w + a_{7r}^{uvw} U_u U_v \dot{U}_w + a_{8r}^{uvw} U_u \dot{U}_v \dot{U}_w + a_{9r}^{uvw} \dot{U}_u \dot{U}_v \dot{U}_w,$$

$$\dot{p}_r(\mathbf{U}, \dot{\mathbf{U}}) = b_{1r}^u U_u + b_{2r}^u \dot{U}_u + b_{3r}^{uv} U_u U_v + b_{4r}^{uv} U_u \dot{U}_v + b_{5r}^{uv} \dot{U}_u \dot{U}_v \\ + b_{6r}^{uvw} U_u U_v U_w + b_{7r}^{uvw} U_u U_v \dot{U}_w + b_{8r}^{uvw} U_u \dot{U}_v \dot{U}_w + b_{9r}^{uvw} \dot{U}_u \dot{U}_v \dot{U}_w,$$

where the coefficients a_1 to a_9 and b_1 to b_9 are supposed known; they are naturally obtained via the invariant manifold procedure; they must be 'extracted' from the multiple time scales approach

Reduced-Order Modelling

Non-linear Galerkin procedures

Forced non-linear modal oscillator equation

$$\ddot{U}_u + c_1^u U_u + c_2^u \dot{U}_u + c_3^{uv} U_u U_v + c_4^{uv} U_u \dot{U}_v + c_5^{uv} \dot{U}_u \dot{U}_v \\ + c_6^{uvw} U_u U_v U_w + c_7^{uvw} U_u U_v \dot{U}_w + c_8^{uvw} U_u \dot{U}_v \dot{U}_w + c_9^{uvw} \dot{U}_u \dot{U}_v \dot{U}_w = P_u ,$$

where the coefficients c_1 to c_9 are supposed known;
they are naturally obtained via the invariant manifold procedure;
they must be 'extracted' from the multiple time scales approach.

Key-question: how to obtain the modal force P_u ?

Once known, the usual analysis methods can be applied
to the modal oscillator equation...

Reduced-Order Modelling

Non-linear Galerkin procedures

Balance of virtual works

$$R_r \delta p_r = P_u M_u \delta U_u$$

$$\delta p_r(\mathbf{U}, \dot{\mathbf{U}}) = \left[a_{1r}^u + (a_{3r}^{uv} + a_{3r}^{vu}) U_v + a_{4r}^{uv} \dot{U}_v + (a_{6r}^{uvw} + a_{6r}^{vuw} + a_{6r}^{wvu}) U_v U_w + (a_{7r}^{uvw} + a_{7r}^{vuw}) U_v \dot{U}_w + a_{8r}^{uvw} \dot{U}_v \dot{U}_w \right] \delta U_u$$

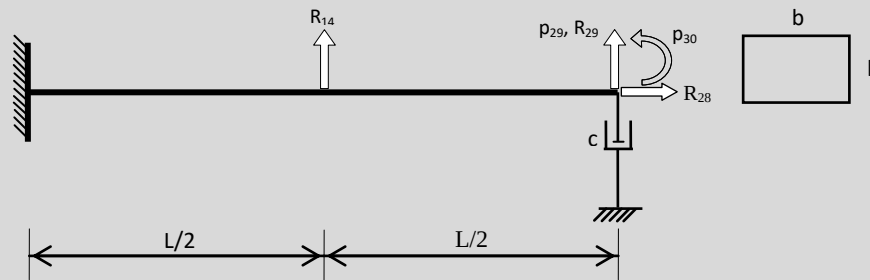


$$P_u = \gamma_u^r \left[a_{1r}^u + (a_{3r}^{uv} + a_{3r}^{vu}) U_v + a_{4r}^{uv} \dot{U}_v + (a_{6r}^{uvw} + a_{6r}^{vuw} + a_{6r}^{wvu}) U_v U_w + (a_{7r}^{uvw} + a_{7r}^{vuw}) U_v \dot{U}_w + a_{8r}^{uvw} \dot{U}_v \dot{U}_w \right]$$

$$\gamma_u^r = \frac{R_r}{M_u}$$

Reduced-Order Modelling

Example 1 (classical resonance)



$$b = 0.010m$$

$$h = 0.010m$$

$$E = 2.1 \times 10^{11} N / m^2$$

$$\rho = 7,800 kg / m^3$$

$$c = 0.7 Ns / m$$

$$R_{14}(t) = 6.6 \cos(82.2 t)$$

$$R_{29}(t) = 6.6 \cos(13.0 t)$$

$$R_{28}(t) = 0$$

FE model with 30 degrees of freedom.

Chosen modal coordinates: $U_u = p_{29}$, with $u = 1, 2$

Reduced-Order Modelling

Example 1 (classical resonance)

First-mode coefficients

$$\begin{array}{lll} c_1^1 = 0.17345E + 03 & c_2^1 = 0.17959E + 01 & c_6^{111} = -0.40506E + 02 \\ c_7^{111} = -0.28403E + 00 & c_8^{111} = 0.21383E + 00 & c_9^{111} = -0.59973E - 03 \\ a_{1,14}^1 = 0.33951E + 00 & a_{6,14}^{111} = -0.57529E - 02 & a_{7,14}^{111} = -0.91501E - 04 \\ a_{8,14}^{111} = 0.47231E - 04 & a_{1,29}^1 = 0.10000E + 01 & \end{array}$$

$$\left\{ \begin{array}{l} \omega_{01} = \sqrt{c_1^1} = 13.17 \text{ rad / s} \\ \xi_1 = \frac{c_2^1}{2\sqrt{c_1^1}} = 0.0681 \end{array} \right.$$

Second-mode coefficients

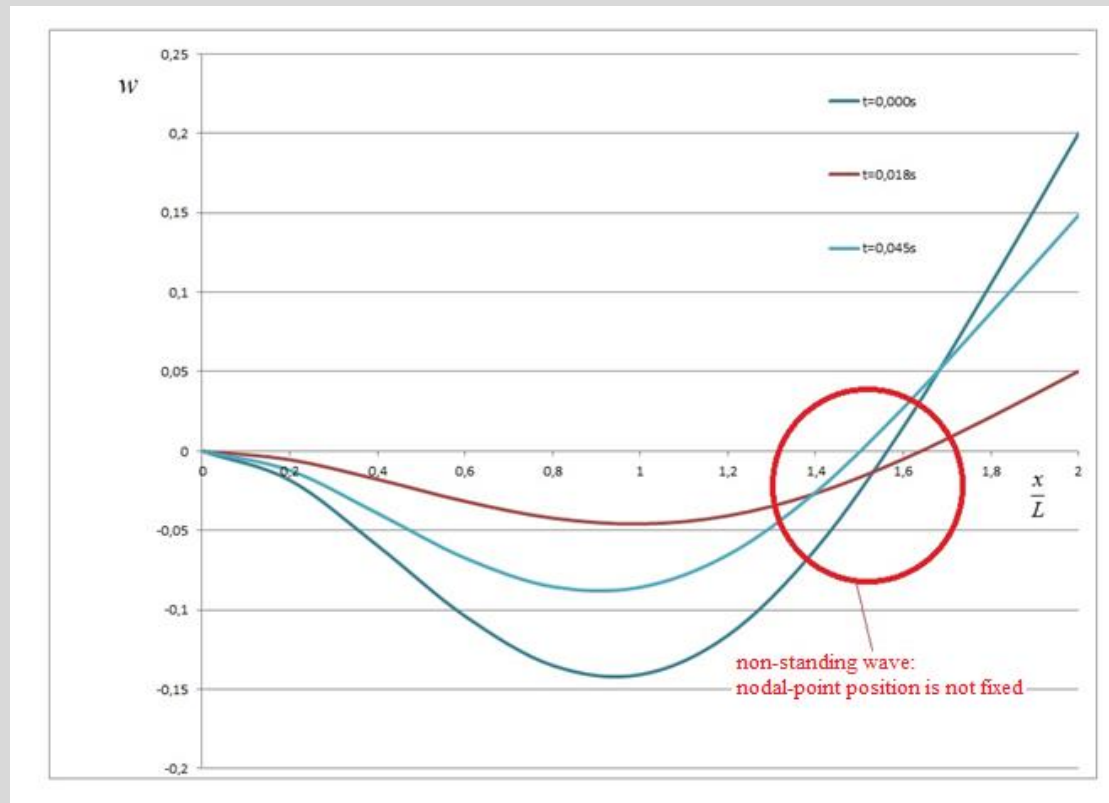
$$\begin{array}{lll} c_1^2 = 0.68055E + 04 & c_2^2 = 0.17946E + 01 & c_6^{222} = -0.10416E + 06 \\ c_7^{222} = 0.18909E + 03 & c_8^{222} = 0.27836E + 02 & c_9^{222} = -0.93038E - 02 \\ a_{1,14}^2 = -0.71314E + 00 & a_{6,14}^{222} = -0.133399E + 01 & a_{7,14}^{222} = 0.75882E - 02 \\ a_{8,14}^{222} = 0.17499E - 03 & a_{1,29}^2 = 0.1000E + 01 & \end{array}$$

$$\left\{ \begin{array}{l} \omega_{02} = \sqrt{c_1^2} = 82.49 \text{ rad / s} \\ \xi_2 = \frac{c_2^2}{2\sqrt{c_1^2}} = 0.0108 \end{array} \right.$$

Reduced-Order Modelling

Example 1 (classical resonance)

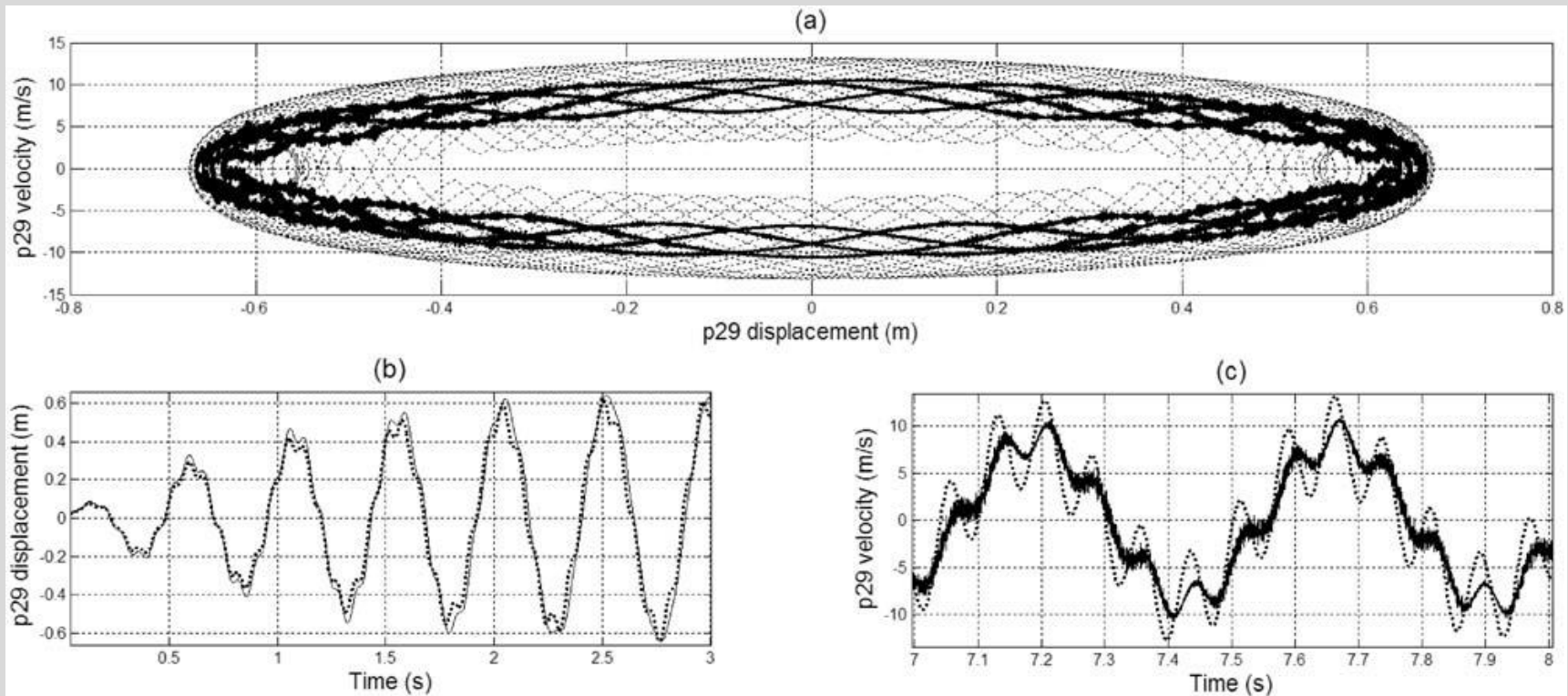
Second mode is not a standing wave!



Reduced-Order Modelling

Example 1 (classical resonance)

First-mode generalized force is not strongly influenced by non-linearities, but second-mode generalized force is influenced by non-linearities



Master (modal) coordinate response (ROM in dotted line; FEM in continuous line)

Reduced-Order Modelling

Example 1 (classical resonance)

Use of modal relationships to recover other generalized displacements and velocities

Example: p_{30} and $\dot{p}_{30}$

$$\begin{aligned} p_{30} = & a_{1,30}^1 U_1 + a_{1,30}^2 U_2 + a_{2,30}^1 \dot{U}_1 + a_{2,30}^2 \dot{U}_2 + a_{3,30}^{11} (U_1)^2 + a_{3,30}^{22} (U_1)^2 \\ & + a_{4,30}^{11} U_1 \dot{U}_1 + a_{4,30}^{22} U_2 \dot{U}_2 + a_{5,30}^{11} (\dot{U}_1)^2 + a_{5,30}^{22} (\dot{U}_2)^2 + a_{6,30}^{111} (U_1)^3 + a_{6,30}^{222} (U_2)^3 \\ & + a_{7,30}^{111} (U_1)^2 \dot{U}_1 + a_{7,30}^{222} (U_2)^2 \dot{U}_2 + a_{8,30}^{111} U_1 (\dot{U}_1)^2 + a_{8,30}^{222} U_2 (\dot{U}_2)^2 + a_{9,30}^{111} (\dot{U}_1)^3 + a_{9,30}^{222} (\dot{U}_2)^3 \end{aligned}$$

$$\begin{aligned} \dot{p}_{30} = & b_{1,30}^1 U_1 + b_{1,30}^2 U_2 + b_{2,30}^1 \dot{U}_1 + b_{2,30}^2 \dot{U}_2 + b_{3,30}^{11} (U_1)^2 + b_{3,30}^{22} (U_1)^2 \\ & + b_{4,30}^{11} U_1 \dot{U}_1 + b_{4,30}^{22} U_2 \dot{U}_2 + b_{5,30}^{11} (\dot{U}_1)^2 + b_{5,30}^{22} (\dot{U}_2)^2 + b_{6,30}^{111} (U_1)^3 + b_{6,30}^{222} (U_2)^3 \\ & + b_{7,30}^{111} (U_1)^2 \dot{U}_1 + b_{7,30}^{222} (U_2)^2 \dot{U}_2 + b_{8,30}^{111} U_1 (\dot{U}_1)^2 + b_{8,30}^{222} U_2 (\dot{U}_2)^2 + b_{9,30}^{111} (\dot{U}_1)^3 + b_{9,30}^{222} (\dot{U}_2)^3 \end{aligned}$$

Reduced-Order Modelling

Example 1 (classical resonance)

Use of modal relationships to recover other generalized displacements and velocities

Example: p_{30} and $\dot{p}_{30}$

First-mode coefficients

$$\begin{array}{lll} a_{1,30}^1 = 0.68828E + 00 & a_{2,30}^1 = -0.67052E - 03 & a_{6,30}^{111} = 0.76285E - 02 \\ a_{7,30}^{111} = 0.13231E - 03 & a_{8,30}^{111} = -0.69597E - 04 & \\ b_{1,30}^1 = 0.11630E + 00 & b_{2,30}^1 = 0.68948E + 00 & b_{6,30}^{111} = -0.50102E - 01 \\ b_{7,30}^{111} = 0.46600E - 01 & b_{8,30}^{111} = 0.69290E - 03 & b_{9,30}^{111} = -0.69117E - 04 \end{array}$$

Second-mode coefficients

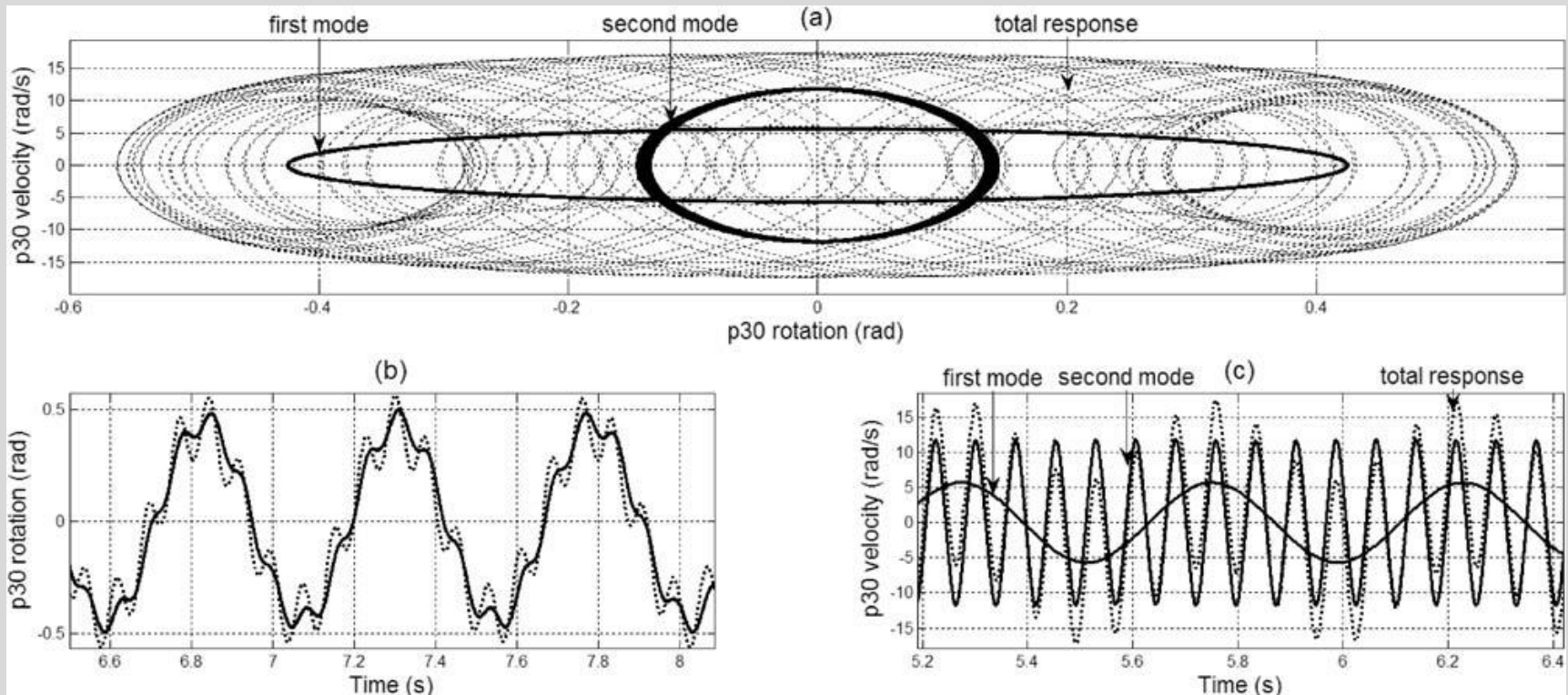
$$\begin{array}{lll} a_{1,30}^2 = 0.23896E + 01 & a_{2,30}^2 = -0.59586E - 03 & a_{6,30}^{222} = 0.20454E + 00 \\ a_{7,30}^{222} = -0.28702E - 02 & a_{8,30}^{222} = 0.63985E - 04 & \\ b_{1,30}^2 = 0.40551E + 01 & b_{2,30}^2 = 0.23907E + 01 & b_{6,30}^{222} = -0.42533E + 02 \\ b_{7,30}^{222} = -0.79776E + 01 & b_{8,30}^{222} = 0.17033E - 01 & b_{9,30}^{222} = 0.63941E - 03 \end{array}$$

Reduced-Order Modelling

Example 1 (classical resonance)

Use of modal relationships to recover other generalized displacements and velocities

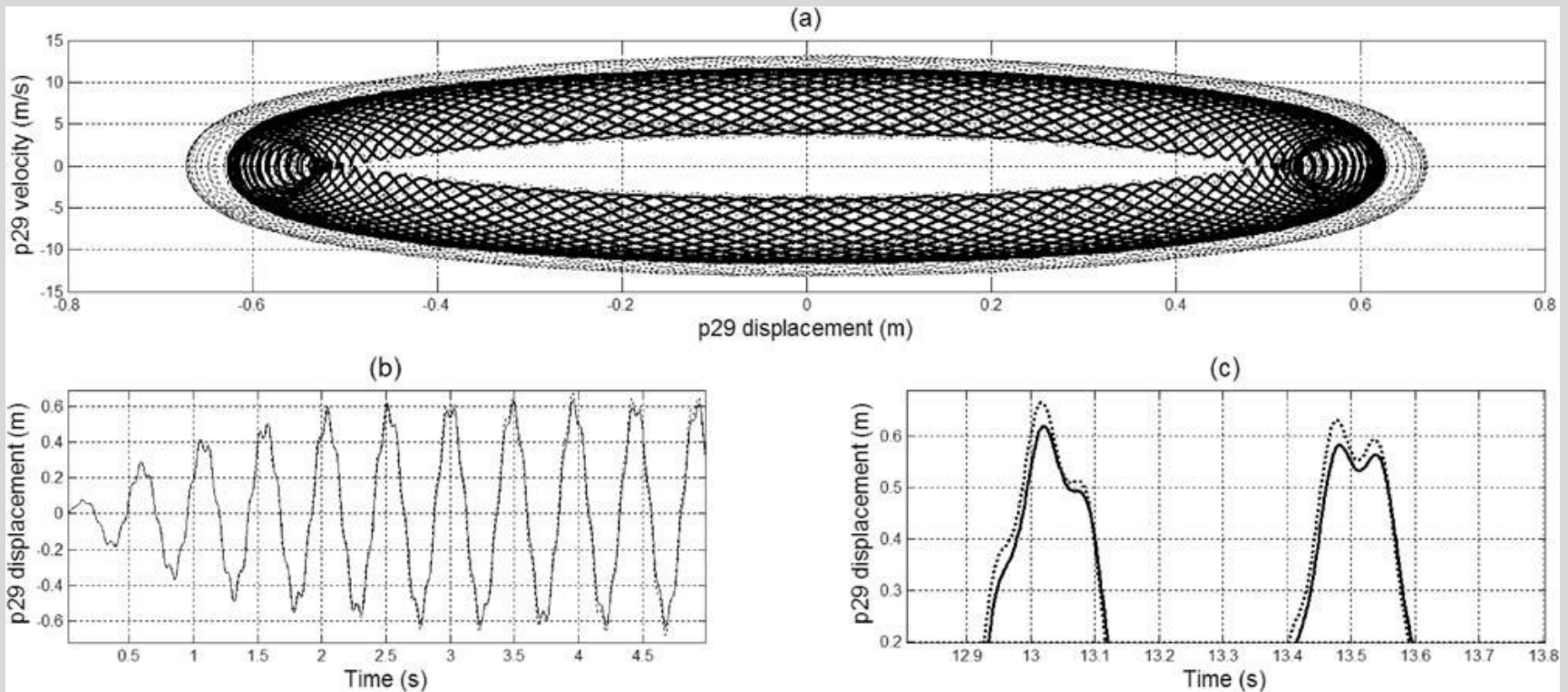
Example: p_{30} and $\dot{p}_{30}$



Slave coordinate response (ROM in dotted line; FEM in continuous line)

Reduced-Order Modelling

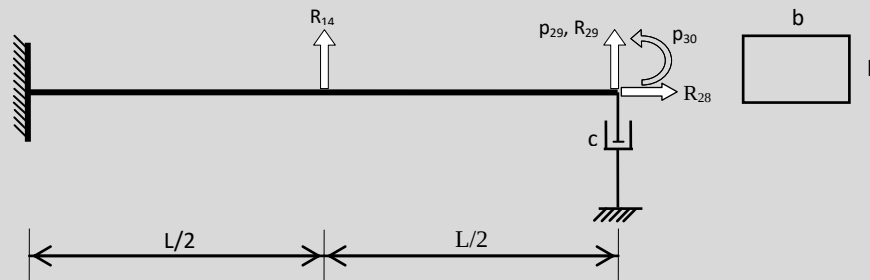
Example 1 (classical resonance)



Master (modal) coordinate response with (dotted line) and without (continuous line) velocity contents in the non-linear mode

Reduced-Order Modelling

Example 2 (parametric resonance)



$$b = 0.040m$$

$$h = 0.003m$$

$$E = 2.1 \times 10^{11} N / m^2$$

$$\rho = 7,800 kg / m^3$$

$$c = 0$$

$$R_{14}(t) = R_{29}(t) = 0$$

$$R_{28}(t) = 1.62 \cos(2\omega_{0u} t)$$

FE model with 30 degrees of freedom.

Chosen modal coordinates: $U_u = p_{29}$, with $u = 1, 2$

Reduced-Order Modelling

Example 2 (parametric resonance)

First-mode coefficients

$$\begin{aligned} c_1^1 &= 0.15602E+02 & c_6^{111} &= 0.53036E+00 & c_8^{111} &= 0.28812E+00 \\ a_{3,28}^{11} &= -0.29049E+00 \end{aligned} \quad \Rightarrow \quad \omega_{01} = \sqrt{c_1^1} = 3.95 \text{ rad / s}$$

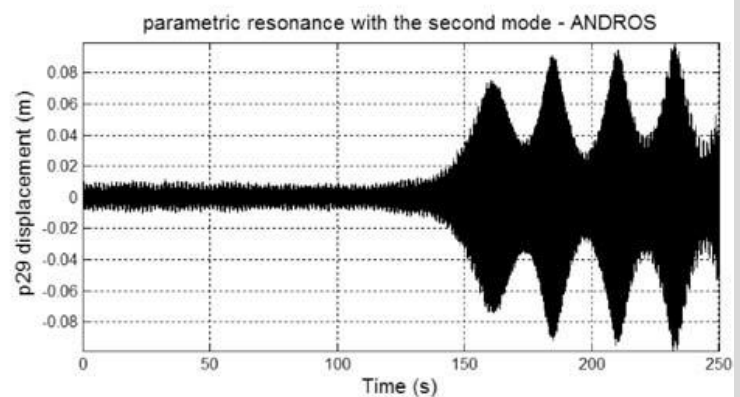
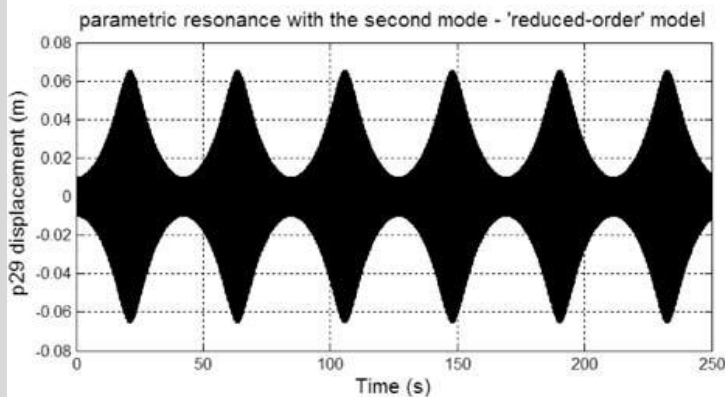
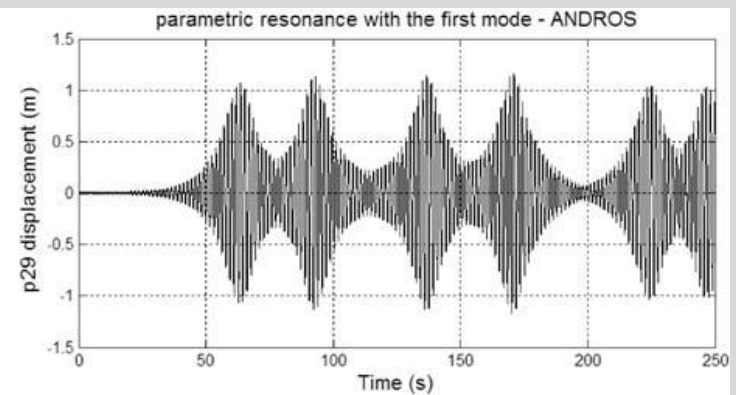
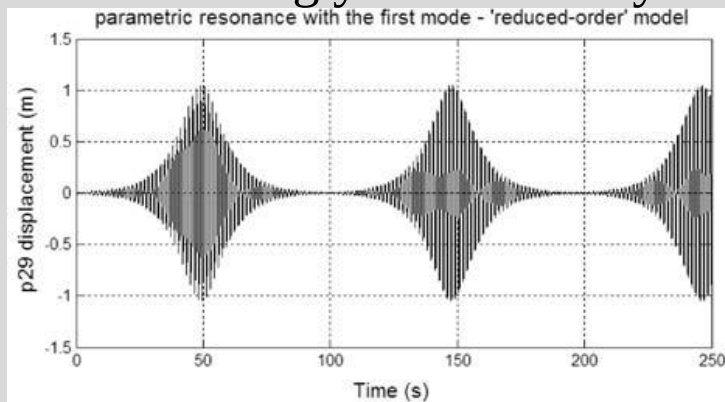
Second-mode coefficients

$$\begin{aligned} c_1^2 &= 0.61277E+03 & c_6^{222} &= -0.93646E+04 & c_8^{222} &= 0.27923E+02 \\ a_{3,28}^{22} &= -0.20261E+01 \end{aligned} \quad \Rightarrow \quad \omega_{02} = \sqrt{c_1^2} = 24.75 \text{ rad / s}$$

Reduced-Order Modelling

Example 2 (parametric resonance)

Generalized modal forces and modal oscillators are strongly influenced by non-linearities in both modes



Master (modal) coordinate response: comparison between ROM and FE

Reduced-Order Modelling

Example 2 (parametric resonance)

Use of modal relationships to recover other generalized displacements and velocities

Example: p_{30} and $\dot{p}_{30}$

$$\begin{aligned} p_{30} = & a_{1,30}^1 U_1 + a_{1,30}^2 U_2 + a_{2,30}^1 \dot{U}_1 + a_{2,30}^2 \dot{U}_2 + a_{3,30}^{11} (U_1)^2 + a_{3,30}^{22} (U_1)^2 \\ & + a_{4,30}^{11} U_1 \dot{U}_1 + a_{4,30}^{22} U_2 \dot{U}_2 + a_{5,30}^{11} (\dot{U}_1)^2 + a_{5,30}^{22} (\dot{U}_2)^2 + a_{6,30}^{111} (U_1)^3 + a_{6,30}^{222} (U_2)^3 \\ & + a_{7,30}^{111} (U_1)^2 \dot{U}_1 + a_{7,30}^{222} (U_2)^2 \dot{U}_2 + a_{8,30}^{111} U_1 (\dot{U}_1)^2 + a_{8,30}^{222} U_2 (\dot{U}_2)^2 + a_{9,30}^{111} (\dot{U}_1)^3 + a_{9,30}^{222} (\dot{U}_2)^3 \end{aligned}$$

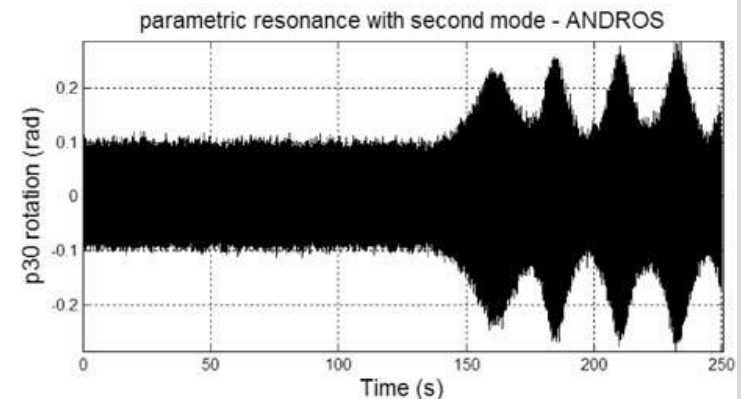
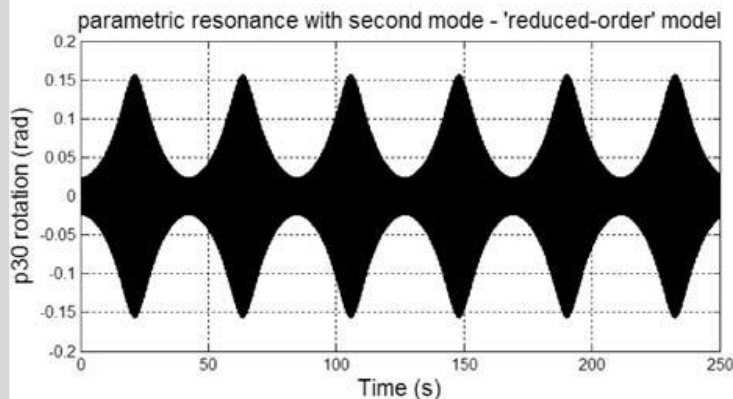
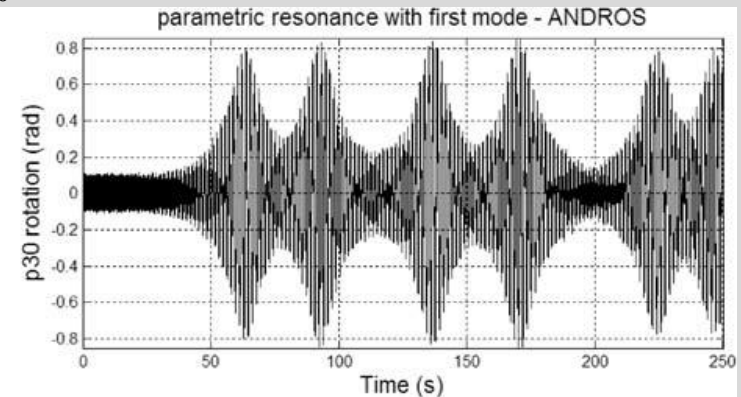
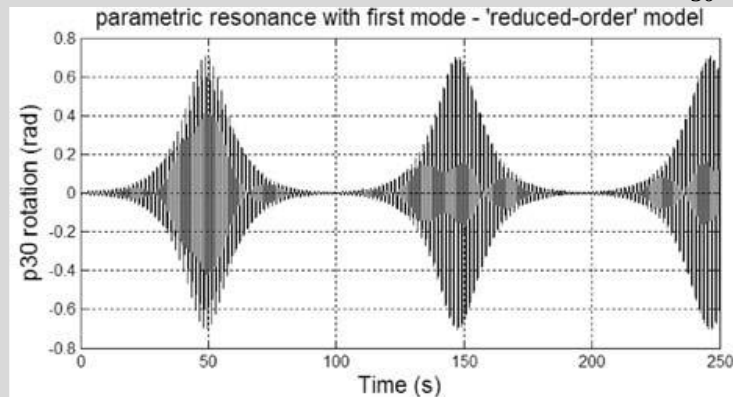
$$\begin{aligned} \dot{p}_{30} = & b_{1,30}^1 U_1 + b_{1,30}^2 U_2 + b_{2,30}^1 \dot{U}_1 + b_{2,30}^2 \dot{U}_2 + b_{3,30}^{11} (U_1)^2 + b_{3,30}^{22} (U_1)^2 \\ & + b_{4,30}^{11} U_1 \dot{U}_1 + b_{4,30}^{22} U_2 \dot{U}_2 + b_{5,30}^{11} (\dot{U}_1)^2 + b_{5,30}^{22} (\dot{U}_2)^2 + b_{6,30}^{111} (U_1)^3 + b_{6,30}^{222} (U_2)^3 \\ & + b_{7,30}^{111} (U_1)^2 \dot{U}_1 + b_{7,30}^{222} (U_2)^2 \dot{U}_2 + b_{8,30}^{111} U_1 (\dot{U}_1)^2 + b_{8,30}^{222} U_2 (\dot{U}_2)^2 + b_{9,30}^{111} (\dot{U}_1)^3 + b_{9,30}^{222} (\dot{U}_2)^3 \end{aligned}$$

Reduced-Order Modelling

Example 2 (parametric resonance)

Use of modal relationships to recover other generalized displacements and velocities

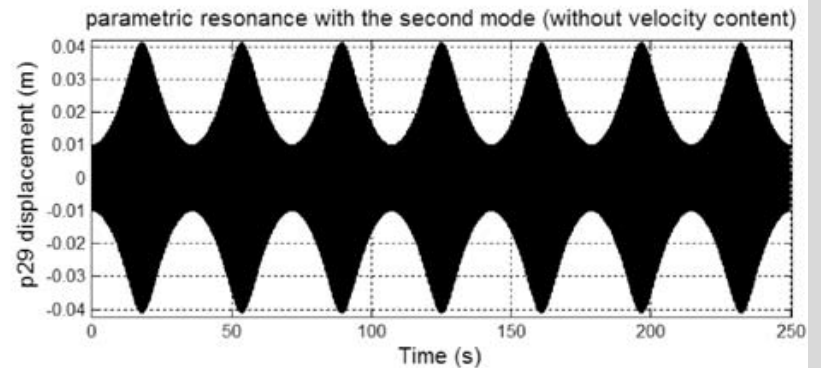
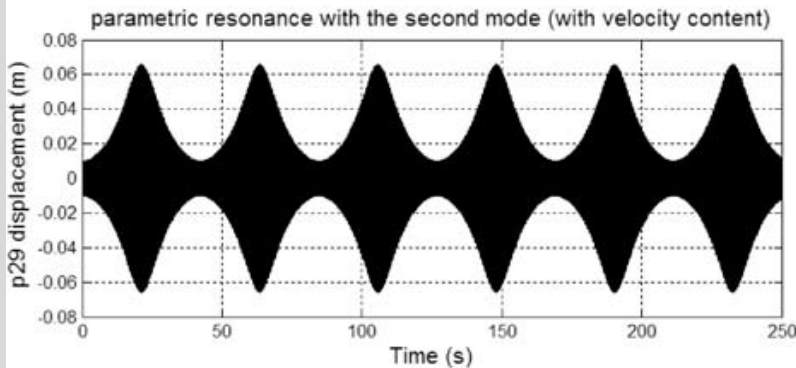
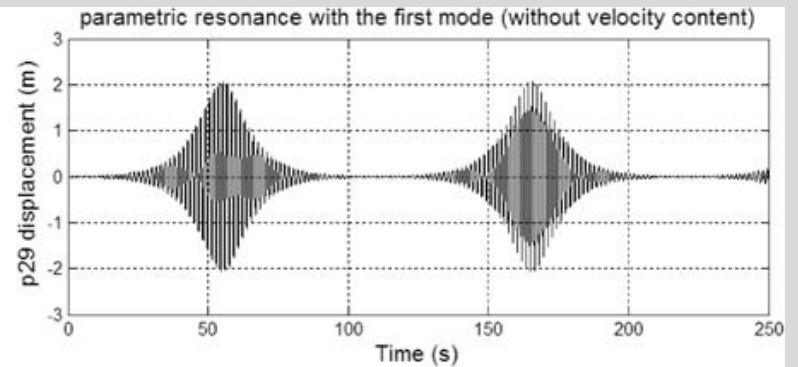
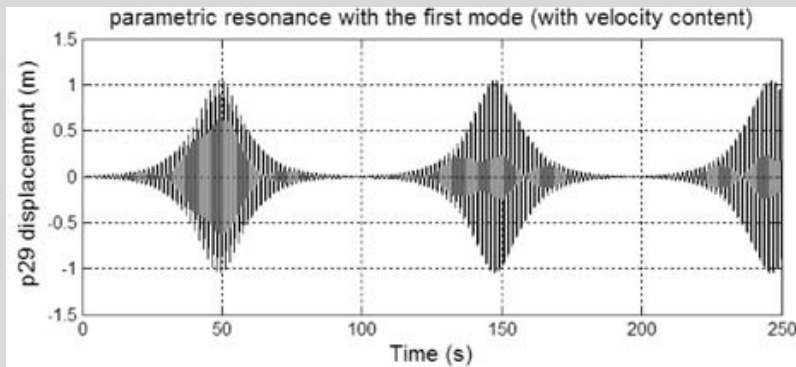
Example: p_{30} and $\dot{p}_{30}$



Slave coordinate response: comparison between ROM and FE

Reduced-Order Modelling

Example 2 (parametric resonance)

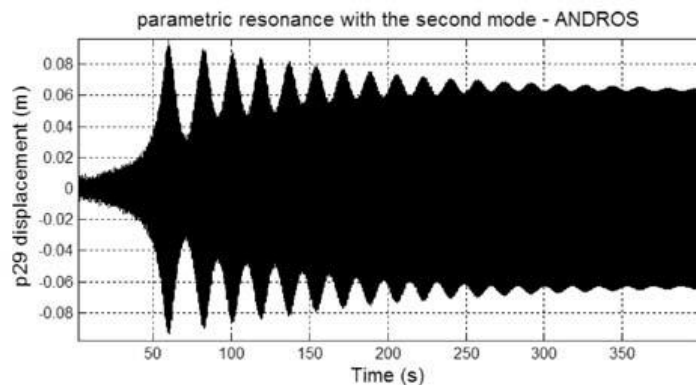
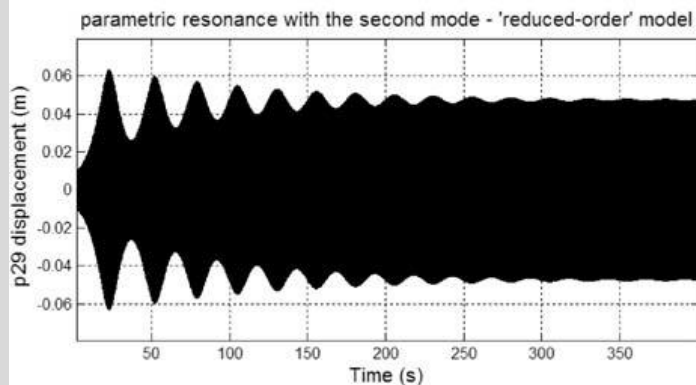
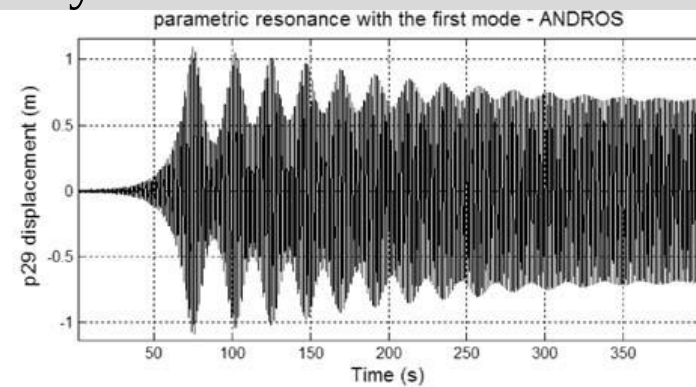
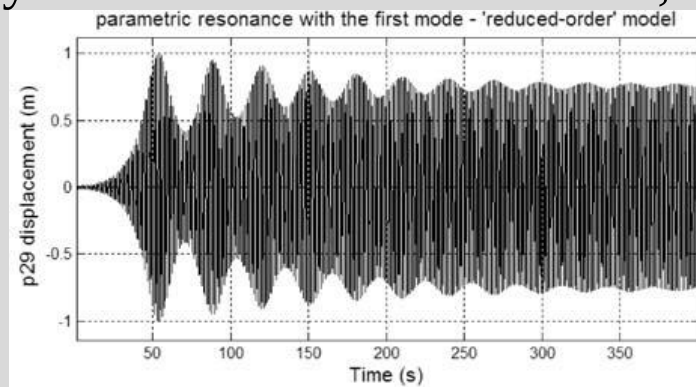


Master (modal) coordinate response with/without velocity contents within the non-linear mode

Reduced-Order Modelling

Example 2 (parametric resonance)

Generalized modal forces and modal oscillators are strongly influenced by non-linearities in both modes; damped system $c = 0.01Ns m^{-1}$

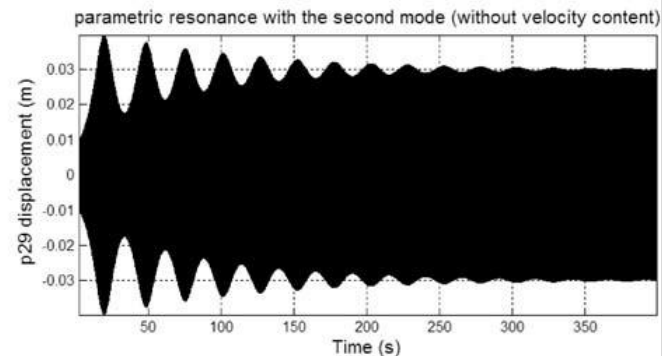
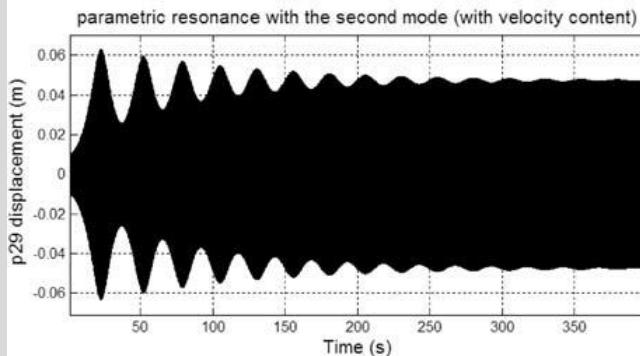
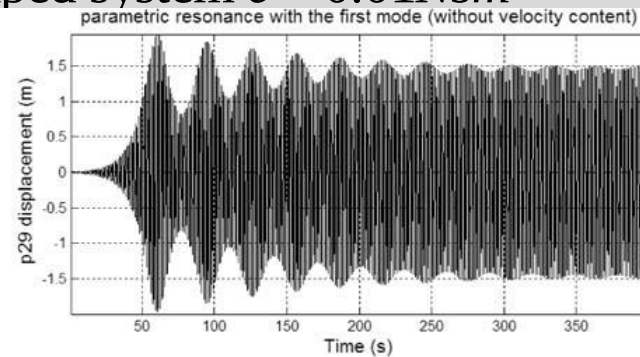
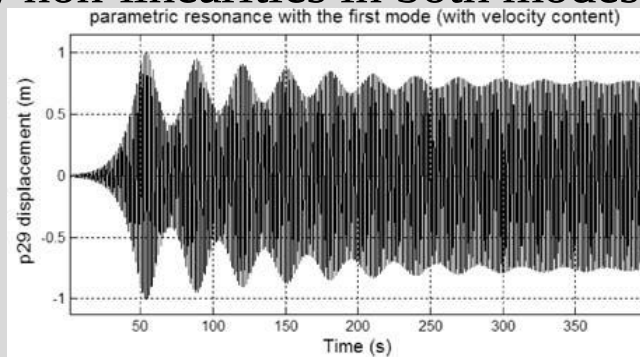


Master (modal) coordinate response: comparison between ROM and FE

Reduced-Order Modelling

Example 2 (parametric resonance)

Generalized modal forces and modal oscillators are strongly influenced by non-linearities in both modes; damped system $c = 0.01Ns m^{-1}$



Master (modal) coordinate response with and without velocity contents in the non-linear mode