

# Teoria de flexura de placas elásticas

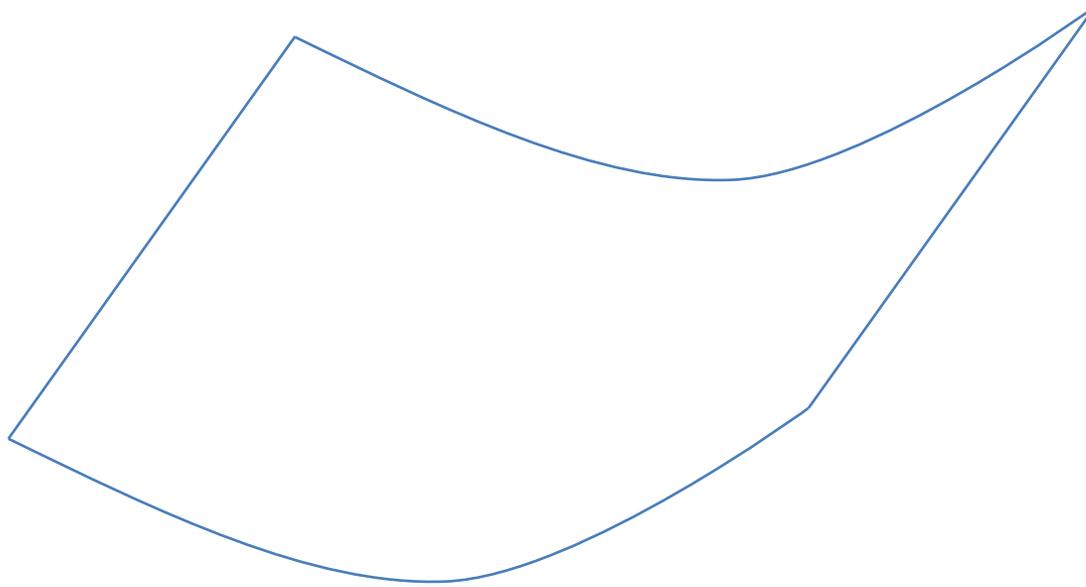
Victor Sacek

# Flexura cilíndrica

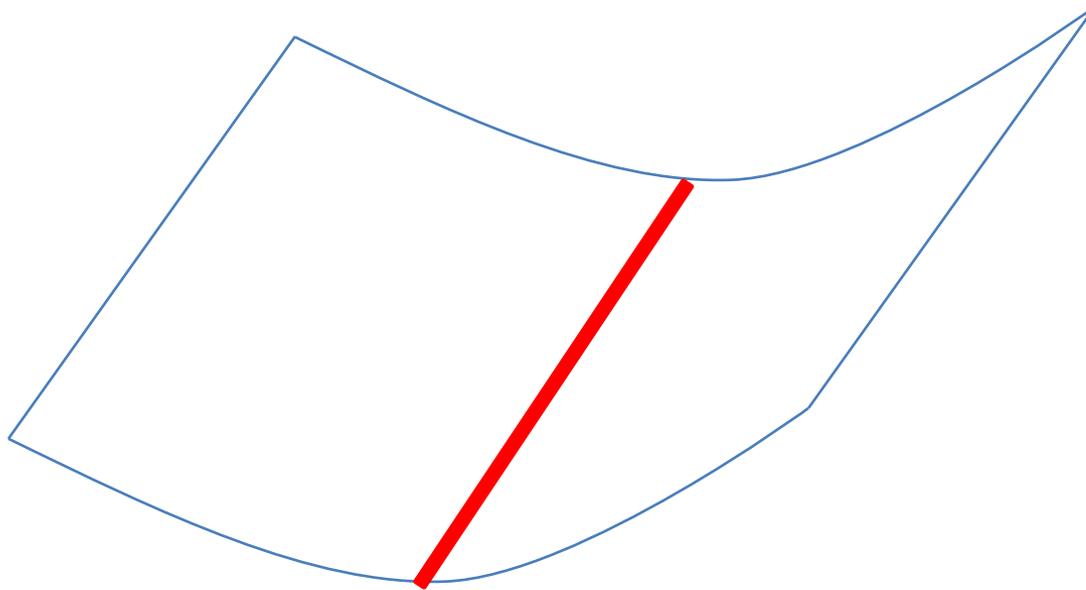
# Flexura cilíndrica



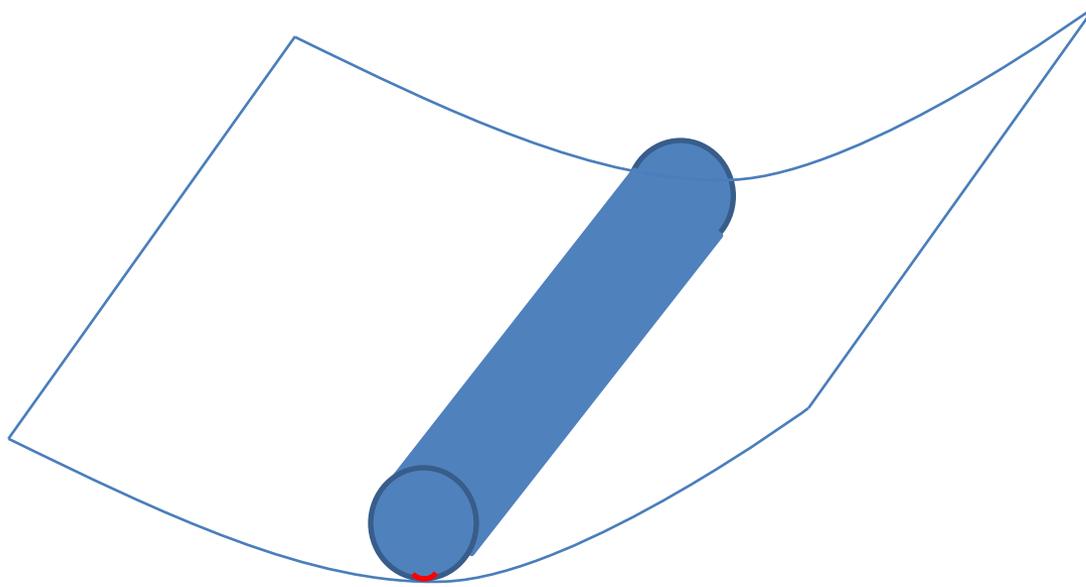
# Flexura cilíndrica



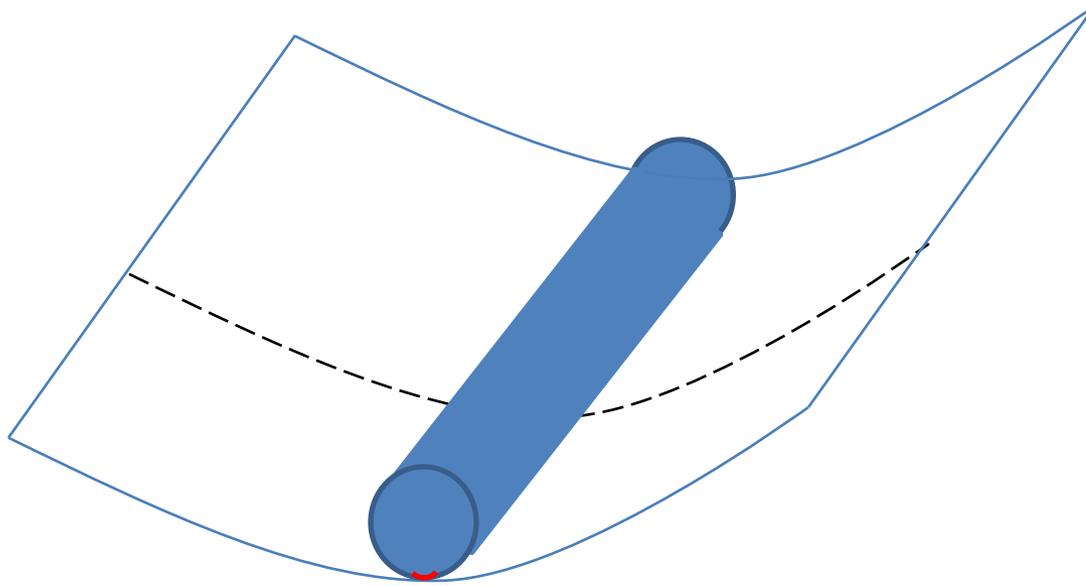
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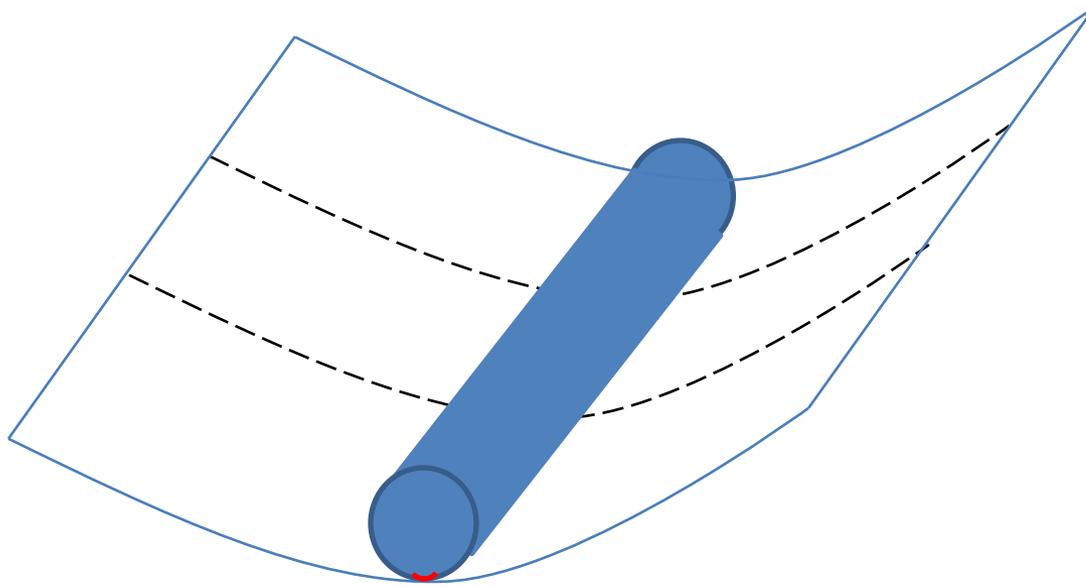
# Flexura cilíndrica



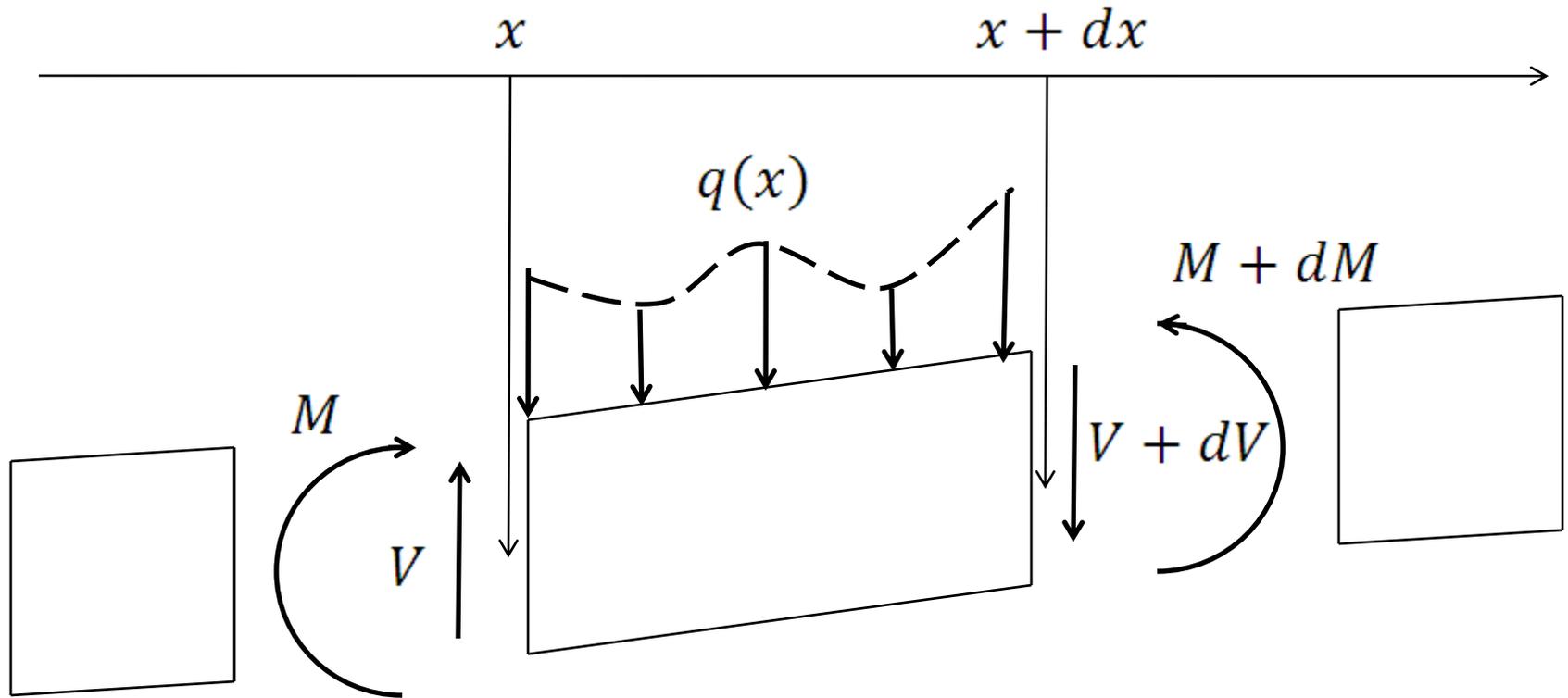
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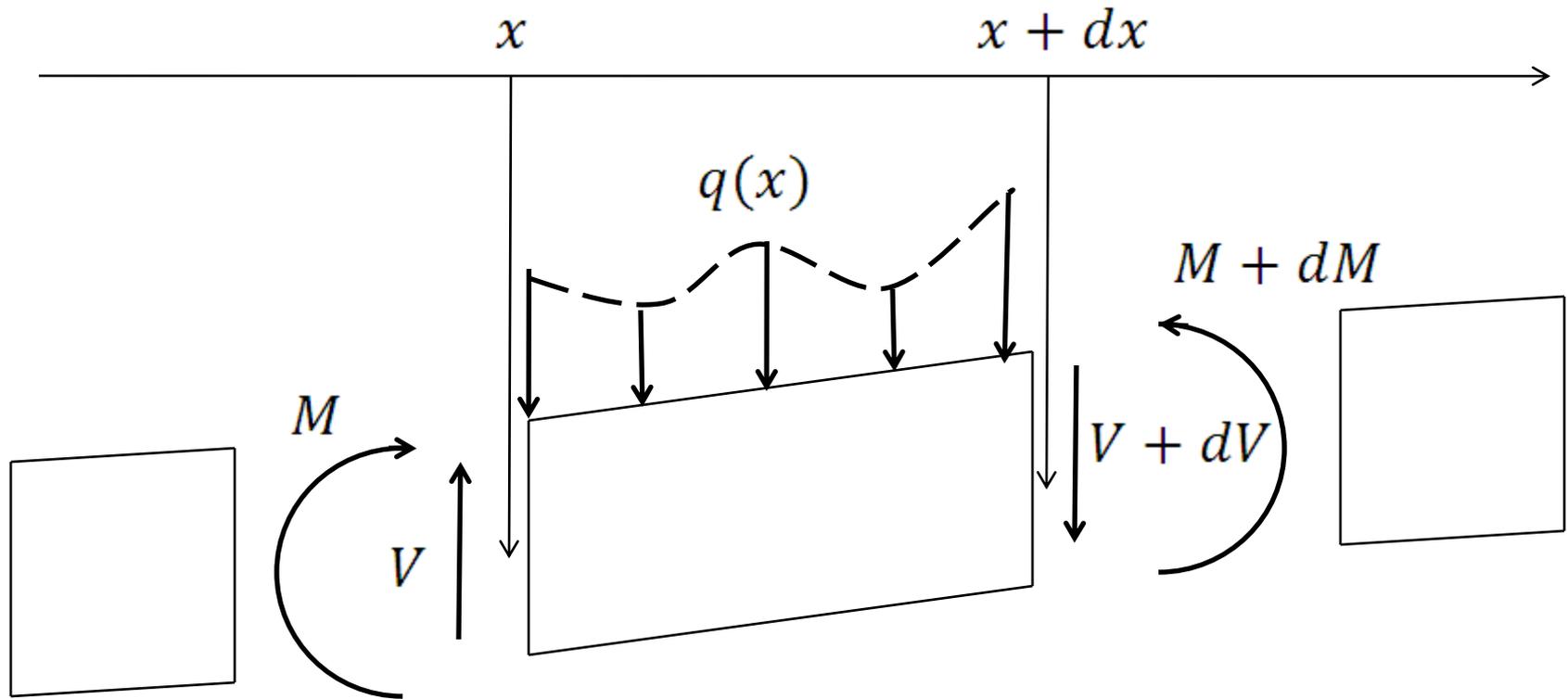
# Flexura cilíndrica



# Forças e torques em uma seção da placa

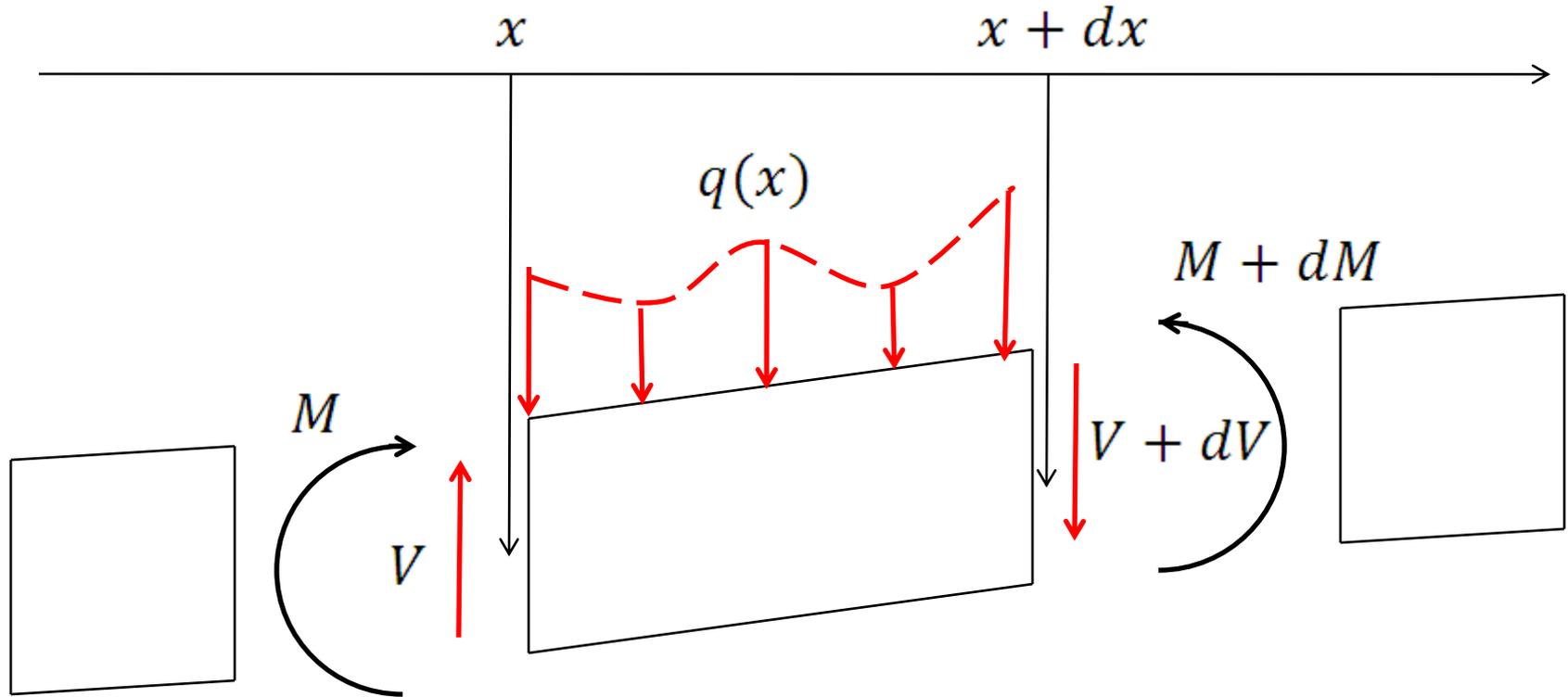


# Forças e torques em uma seção da placa



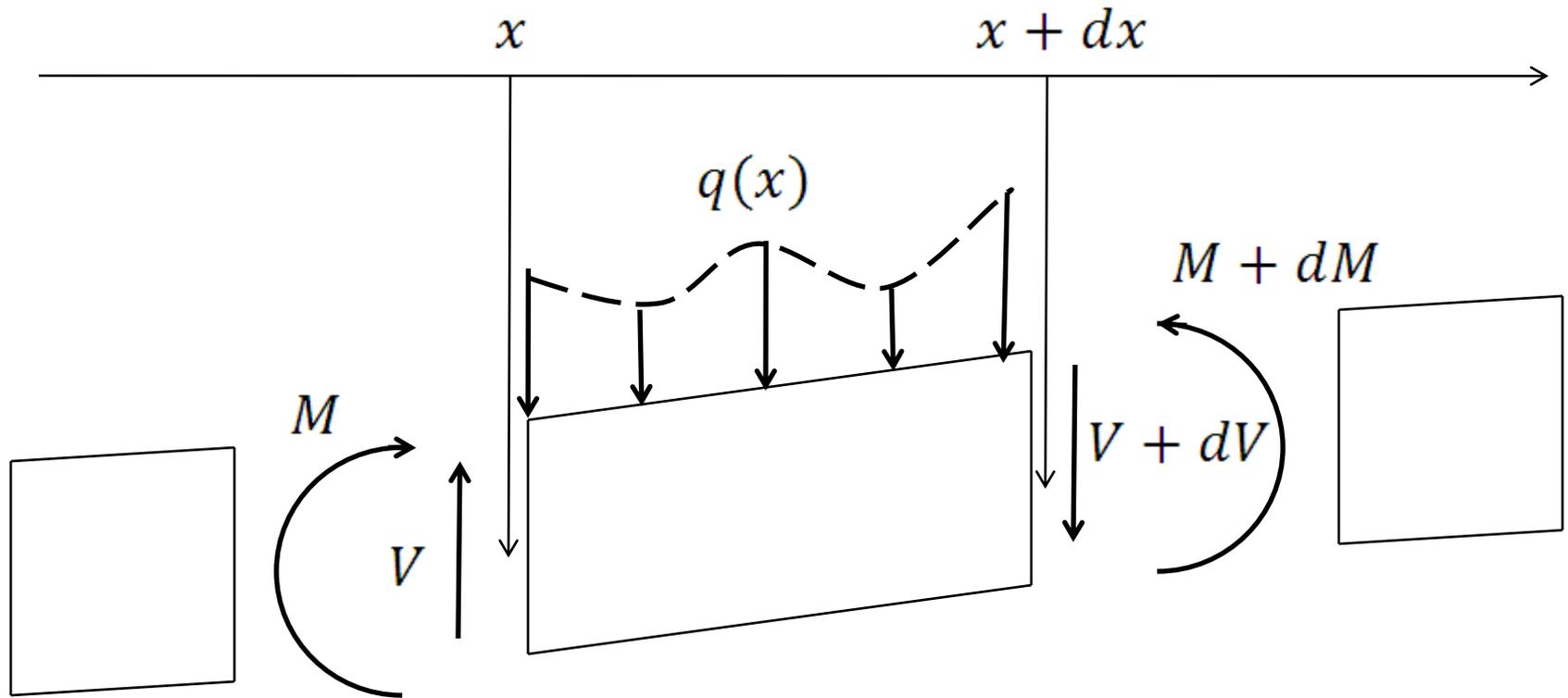
Forças:

# Forças e torques em uma seção da placa



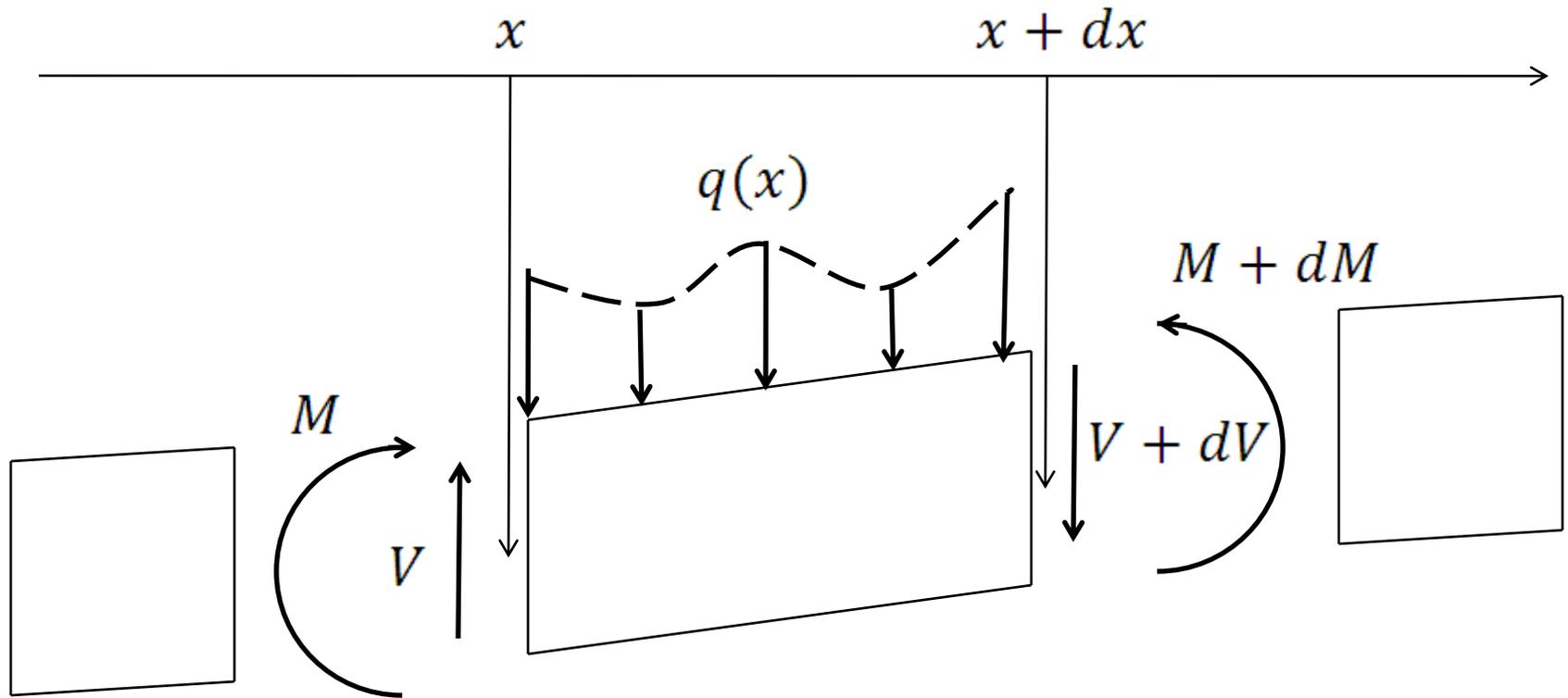
Forças:  $q(x)dx + dV = 0$

# Forças e torques em uma seção da placa



Forças:  $q(x)dx + dV = 0 \rightarrow \frac{dV}{dx} = -q$

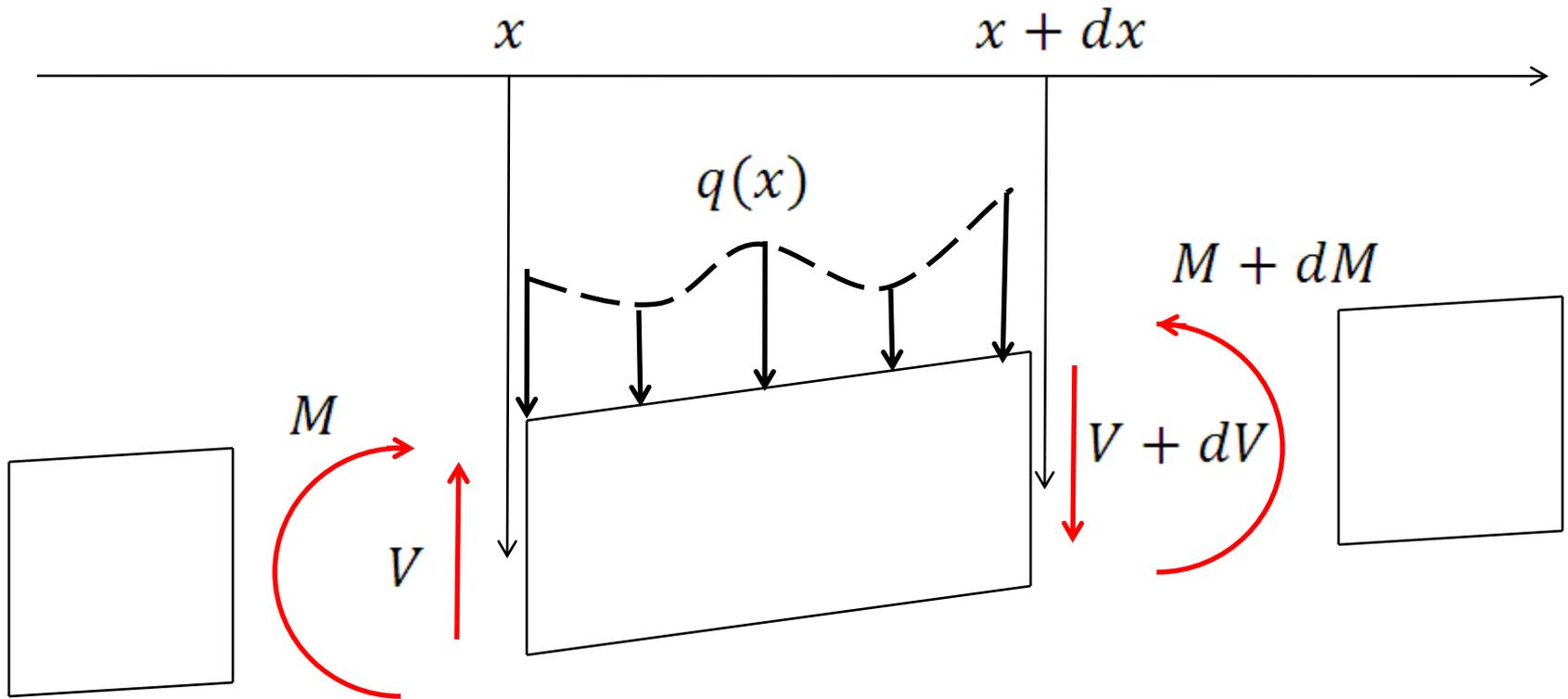
# Forças e torques em uma seção da placa



Forças:  $q(x)dx + dV = 0 \rightarrow \frac{dV}{dx} = -q$

Torques:

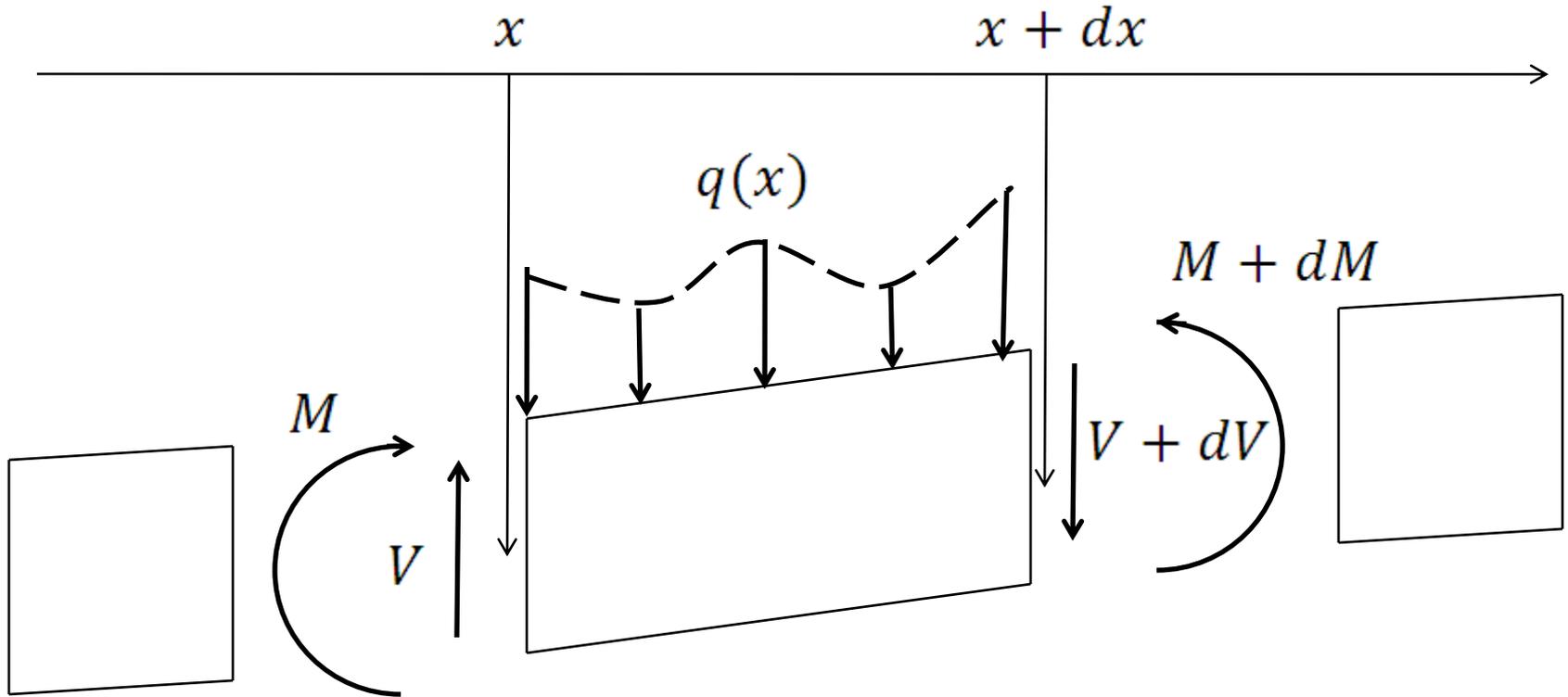
# Forças e torques em uma seção da placa



Forças:  $q(x)dx + dV = 0 \rightarrow \frac{dV}{dx} = -q$

Torques:  $dM = Vdx$

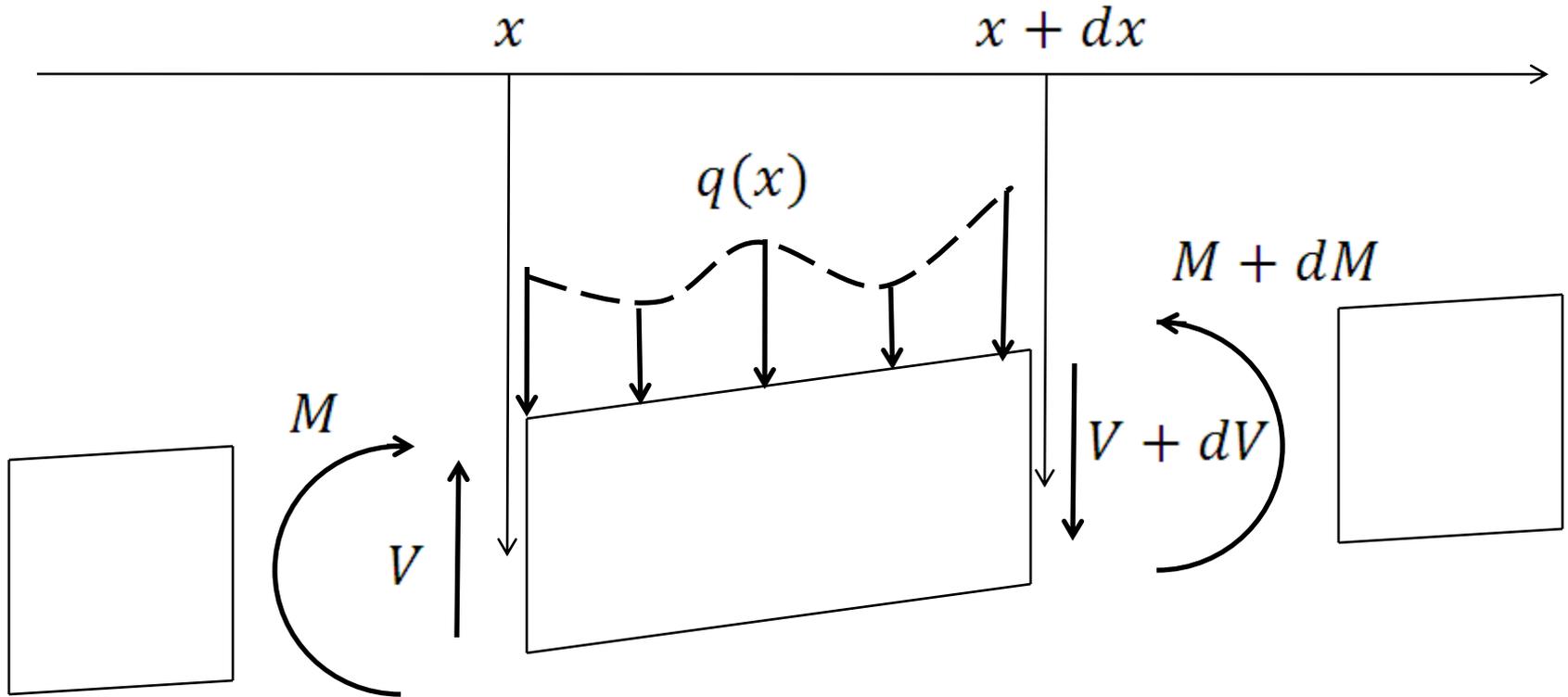
# Forças e torques em uma seção da placa



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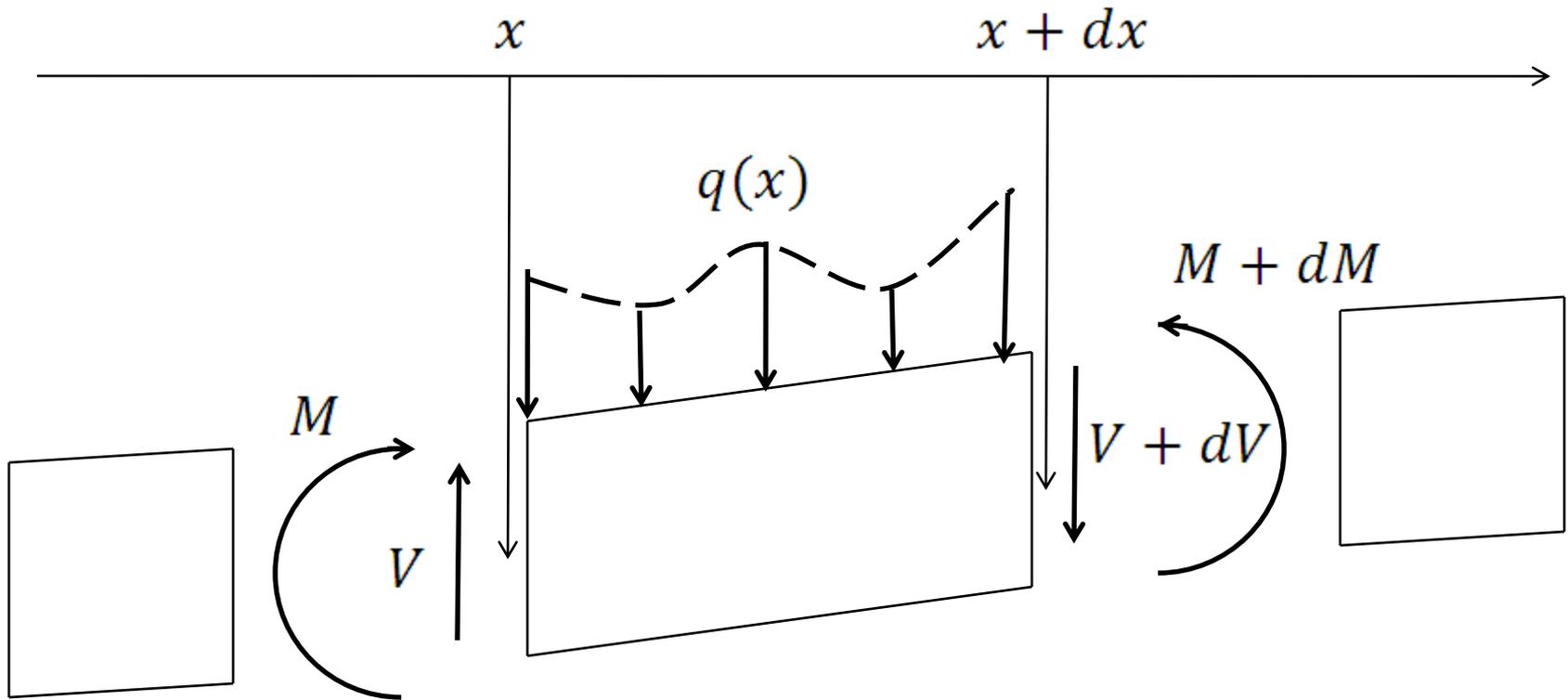
# Forças e torques em uma seção da placa



Forças:  $q(x)dx + dV = 0 \rightarrow \frac{dV}{dx} = -q$

Torques:  $dM = Vdx \rightarrow \frac{dM}{dx} = V \rightarrow \frac{d^2M}{dx^2} = \frac{dV}{dx}$

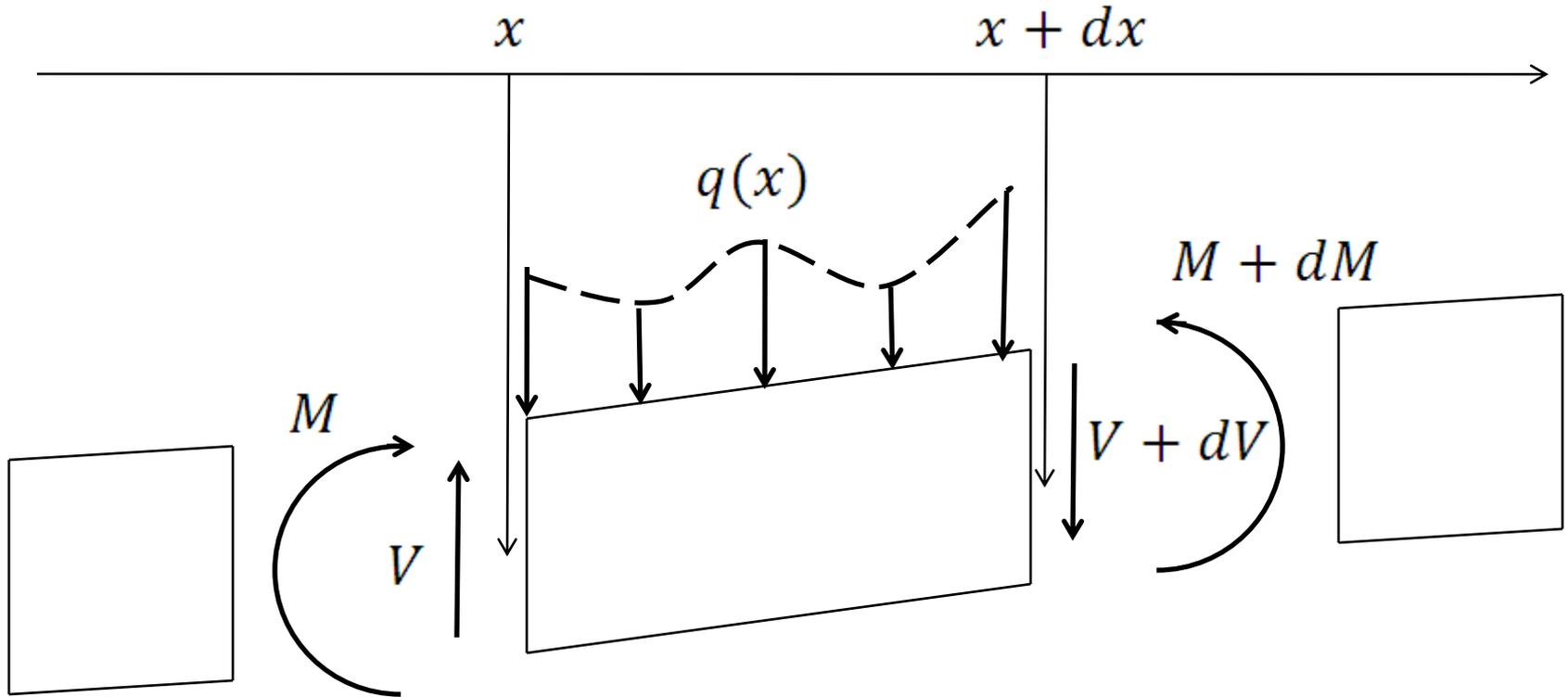
# Forças e torques em uma seção da placa



Forças:  $q(x)dx + dV = 0 \rightarrow \frac{dV}{dx} = -q$

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Forças:  $q(x)dx + dV = 0 \rightarrow \frac{dV}{dx} = -q$

Torques:  $dM = Vdx \rightarrow \frac{dM}{dx} = V \rightarrow \frac{d^2M}{dx^2} = \frac{dV}{dx}$

$$\frac{d^2M}{dx^2} = -q$$

# Elasticidade linear

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$$\begin{cases} \varepsilon_1 = \frac{1}{E}\sigma_1 - \frac{\nu}{E}\sigma_2 - \frac{\nu}{E}\sigma_3 \\ \varepsilon_2 = -\frac{\nu}{E}\sigma_1 + \frac{1}{E}\sigma_2 - \frac{\nu}{E}\sigma_3 \\ \varepsilon_3 = -\frac{\nu}{E}\sigma_1 - \frac{\nu}{E}\sigma_2 + \frac{1}{E}\sigma_3 \end{cases}$$

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$\varepsilon_1, \varepsilon_2, \varepsilon_3$

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$\varepsilon_1, \varepsilon_2, \varepsilon_3$       Deformações principais

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$E$

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$E$                       Módulo de elasticidade

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$\nu$

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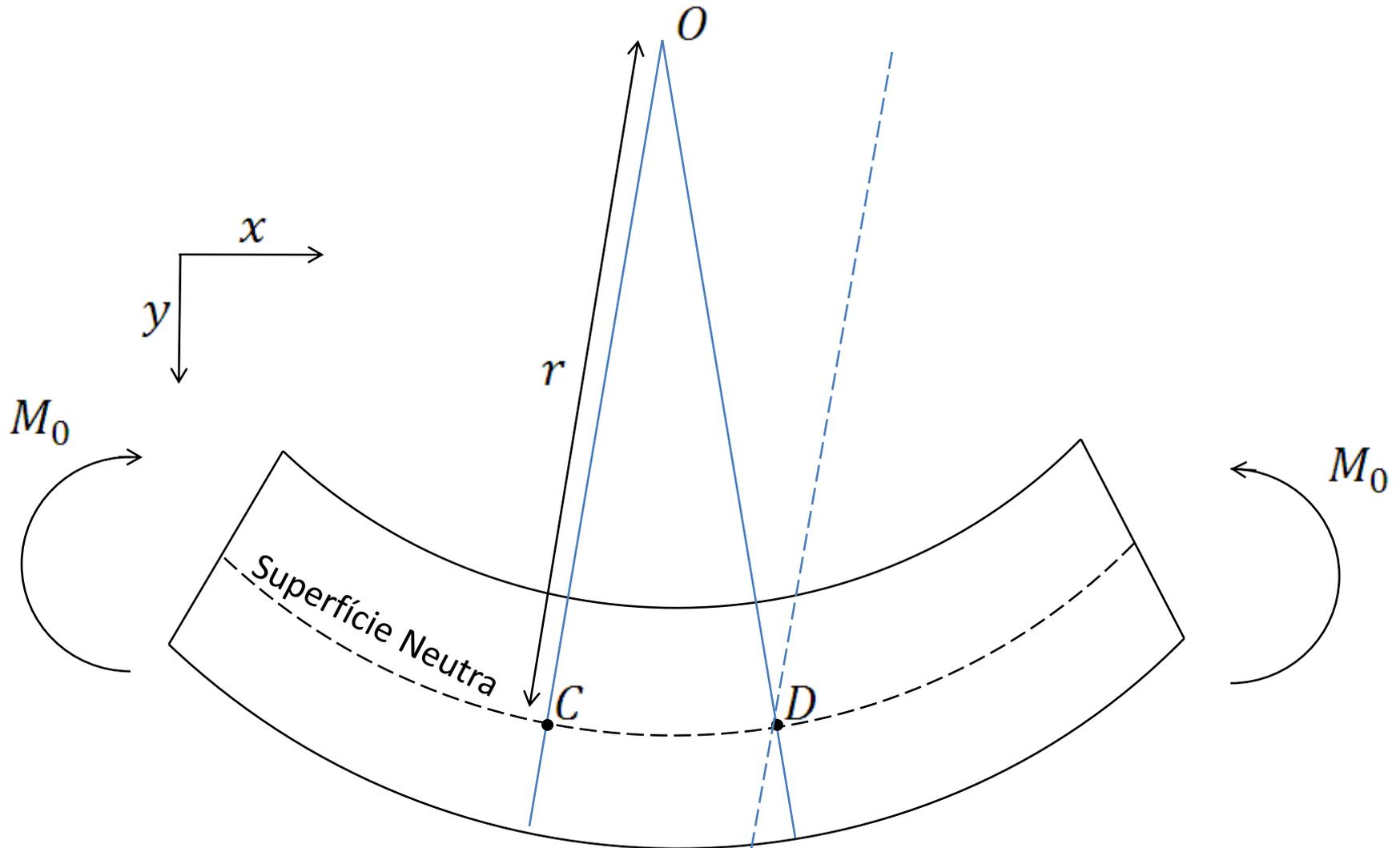
$\varepsilon_1, \varepsilon_2, \varepsilon_3$       Deformações principais

$\sigma_1, \sigma_2, \sigma_3$       Tensões principais

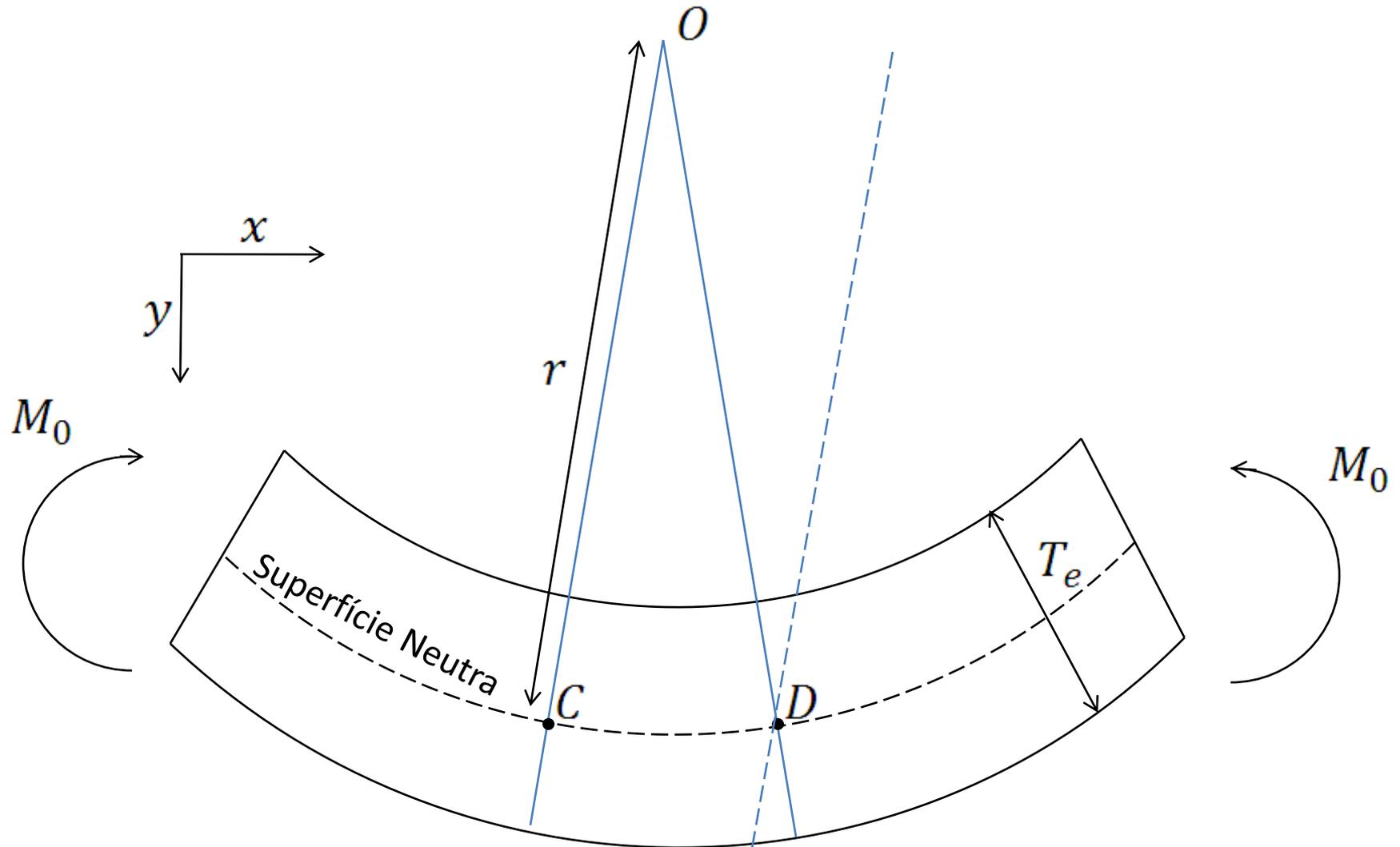
$E$                       Módulo de elasticidade

$\nu$                       Coeficiente de Poisson

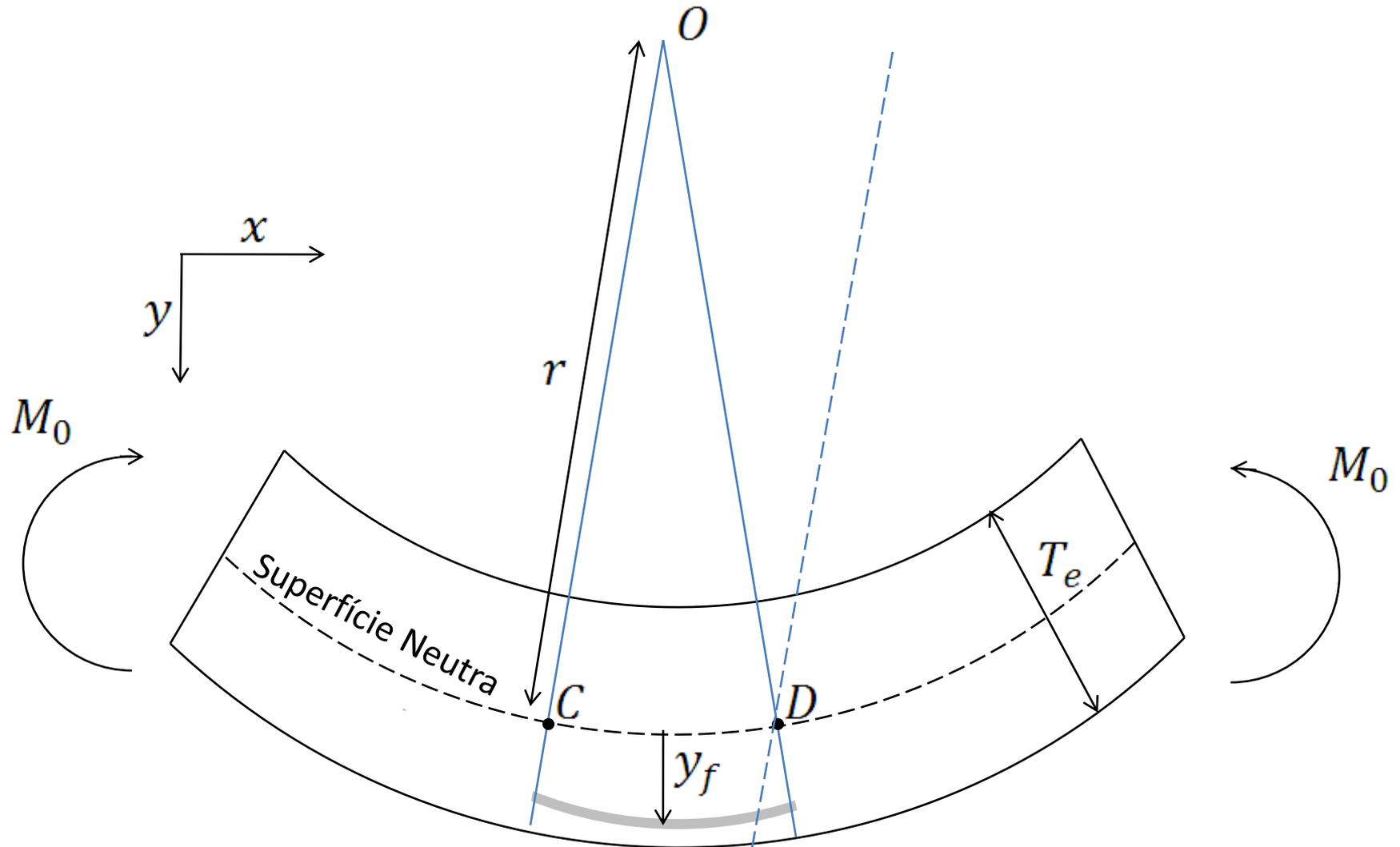
# Deformações no interior da placa



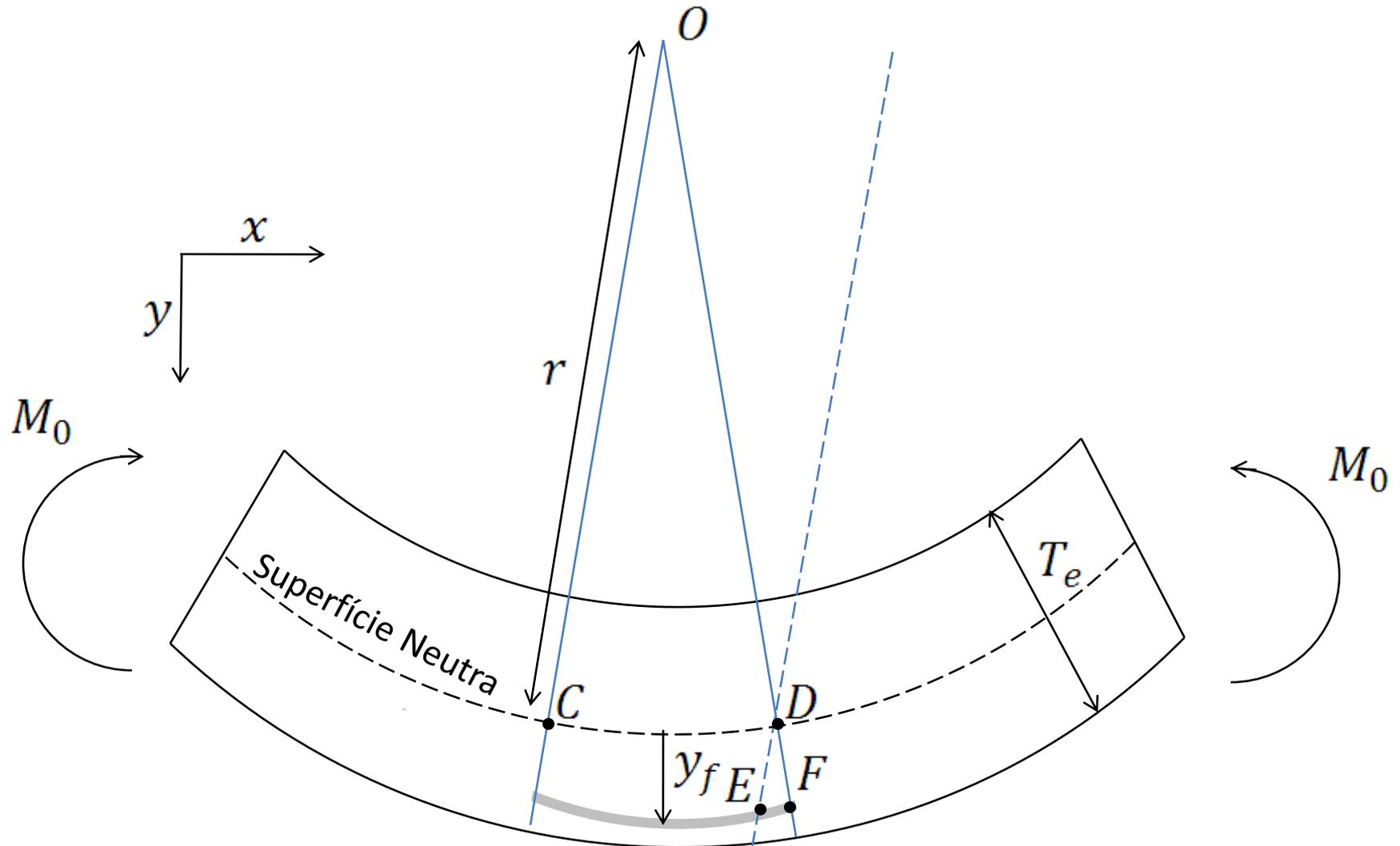
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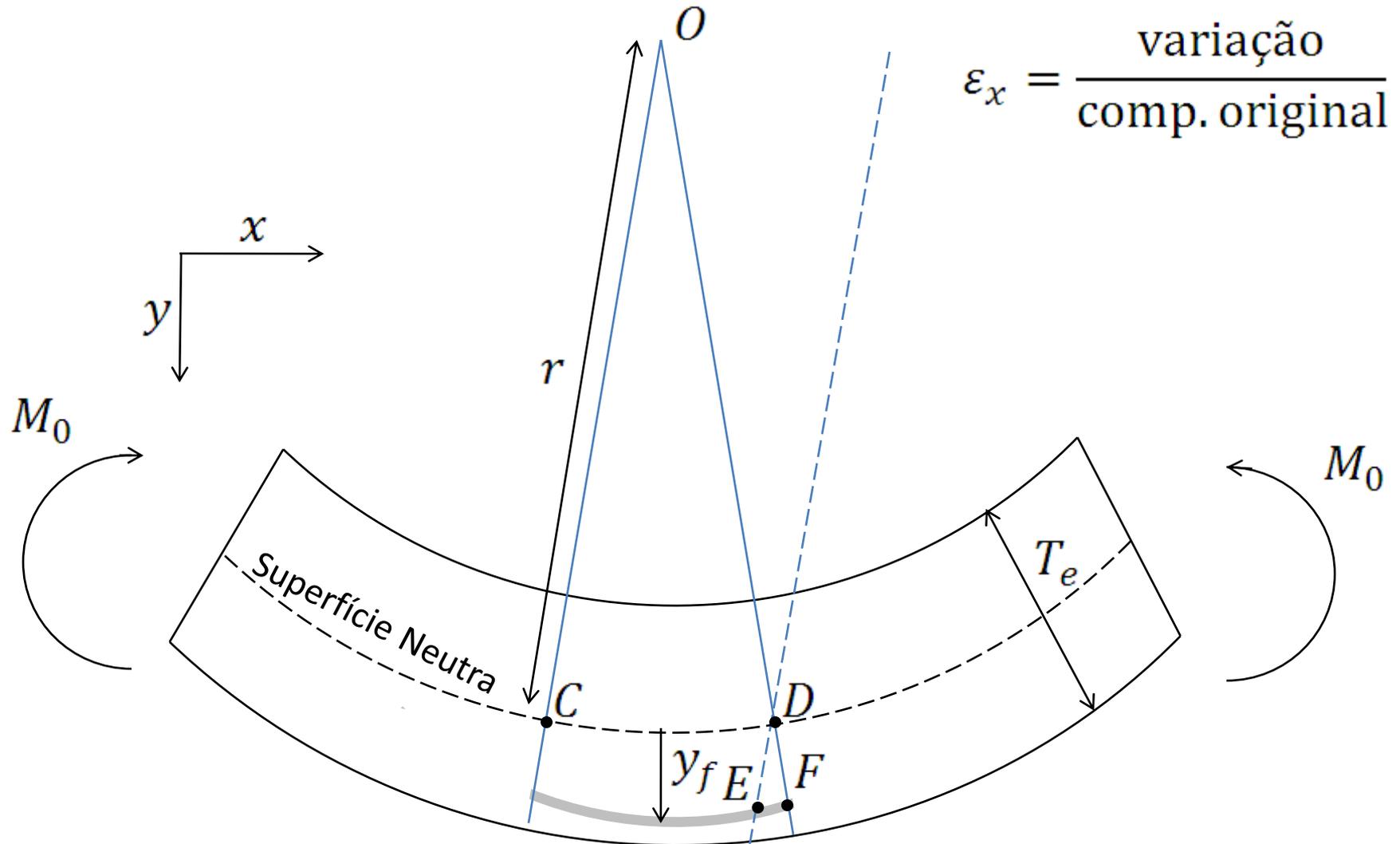
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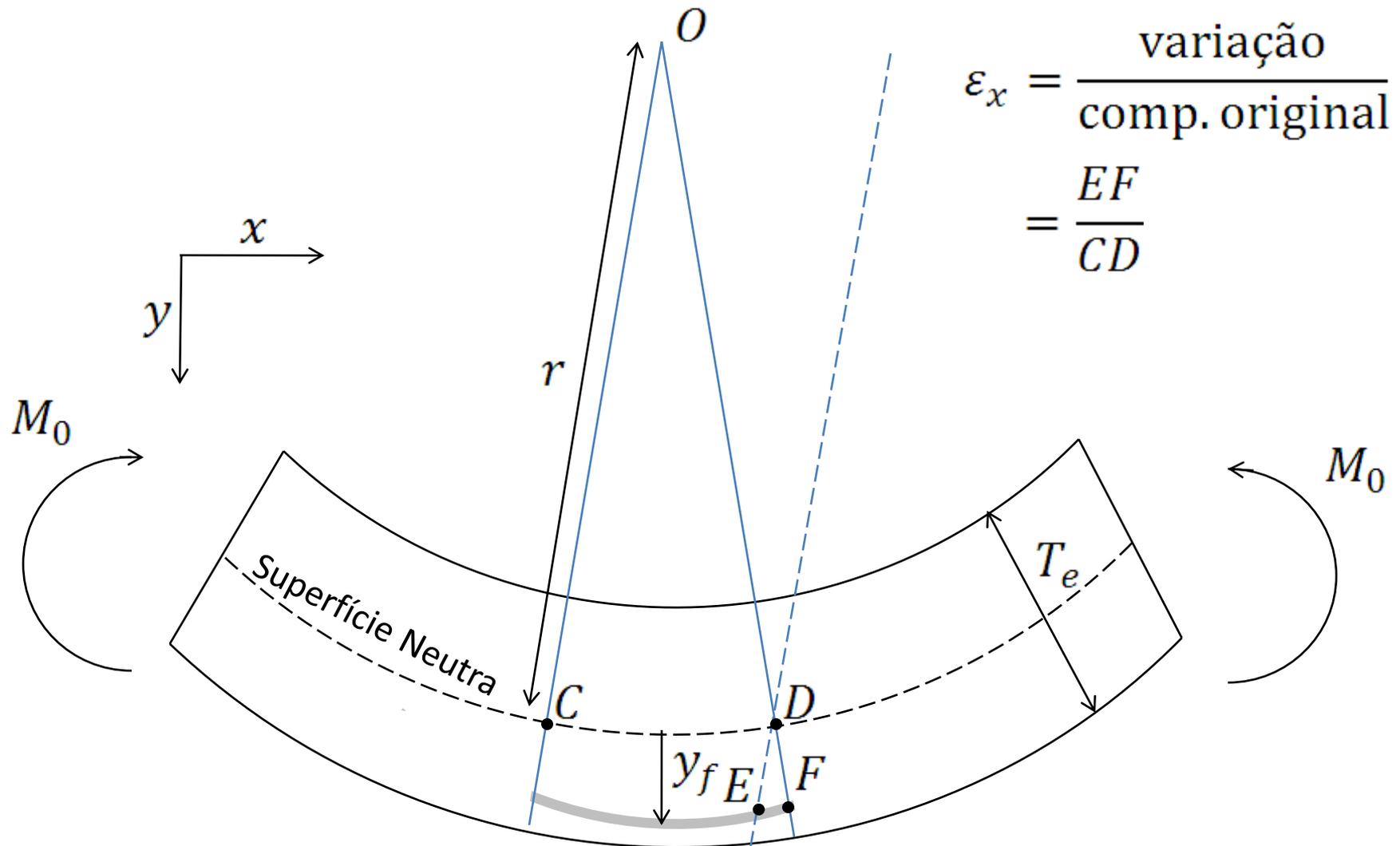
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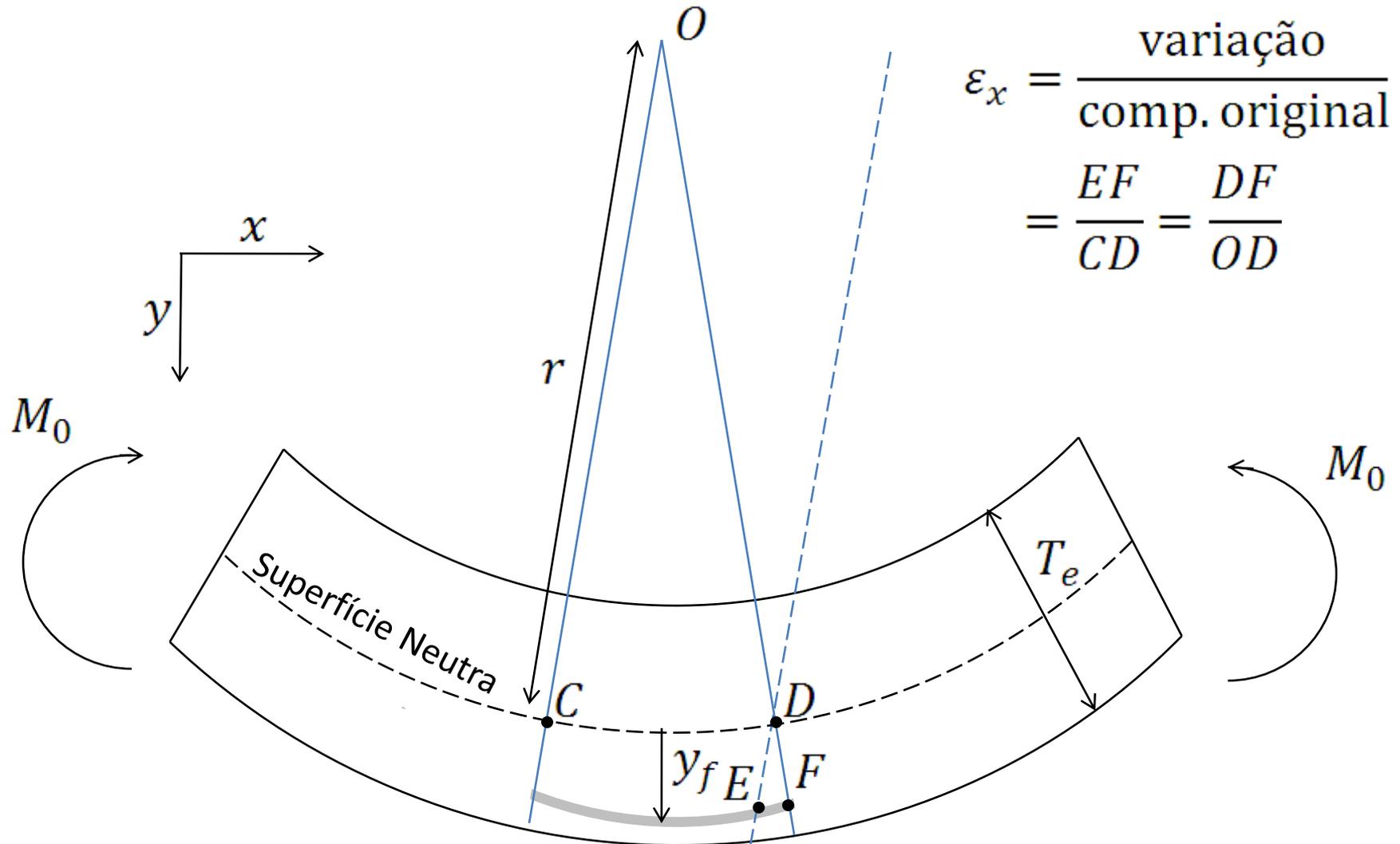
# Deformações no interior da placa



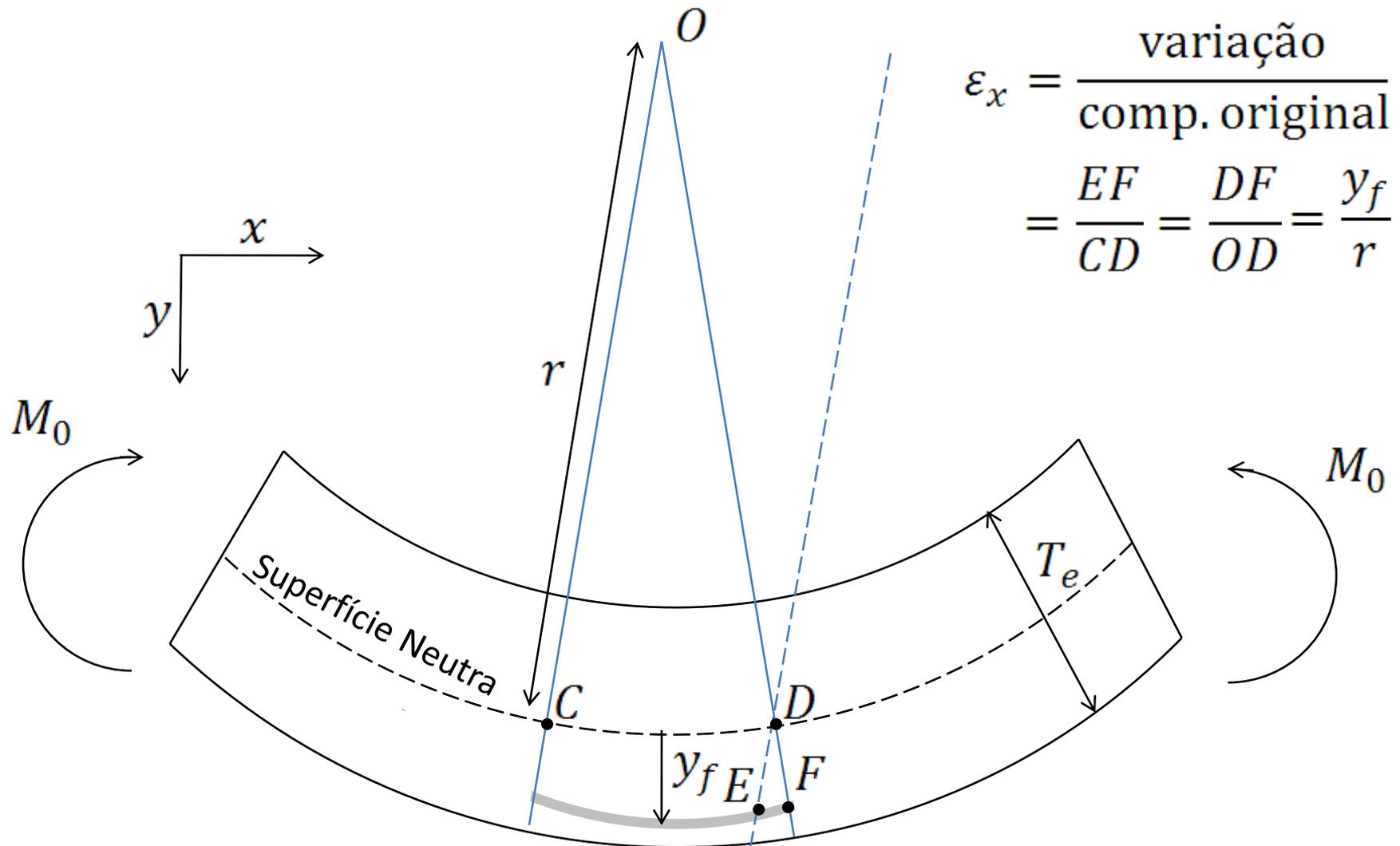
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# Tensões no interior da placa

Problema de flexura em 2D:

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$$\begin{cases} \varepsilon_x = \frac{1}{E} \sigma_x - \frac{\nu}{E} \sigma_y - \frac{\nu}{E} \sigma_z \\ \varepsilon_y = -\frac{\nu}{E} \sigma_x + \frac{1}{E} \sigma_y - \frac{\nu}{E} \sigma_z \\ \varepsilon_z = -\frac{\nu}{E} \sigma_x - \frac{\nu}{E} \sigma_y + \frac{1}{E} \sigma_z \end{cases}$$

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# Tensões no interior da placa

Problema de flexura em 2D:  $\varepsilon_z = 0$ ,  $\sigma_y = 0$

$$\left\{ \begin{array}{l} \varepsilon_x = \frac{1}{E} \sigma_x - \frac{\nu}{E} \sigma_y - \frac{\nu}{E} \sigma_z \\ \varepsilon_y = -\frac{\nu}{E} \sigma_x + \frac{1}{E} \sigma_y - \frac{\nu}{E} \sigma_z \\ \varepsilon_z = -\frac{\nu}{E} \sigma_x - \frac{\nu}{E} \sigma_y + \frac{1}{E} \sigma_z \end{array} \right. \rightarrow \left\{ \begin{array}{l} \varepsilon_x = \frac{1}{E} \sigma_x - \frac{\nu}{E} \sigma_z \\ \varepsilon_y = -\frac{\nu}{E} \sigma_x - \frac{\nu}{E} \sigma_z \\ 0 = -\frac{\nu}{E} \sigma_x + \frac{1}{E} \sigma_z \end{array} \right.$$

# Tensões no interior da placa

Problema de flexura em 2D:  $\varepsilon_z = 0$ ,  $\sigma_y = 0$

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# Tensões no interior da placa

Problema de flexura em 2D:  $\varepsilon_z = 0, \quad \sigma_y = 0$

$$\varepsilon_x = \frac{y_f}{r}$$

$$\begin{cases} \varepsilon_x = \frac{1}{E}\sigma_x - \frac{\nu}{E}\cancel{\sigma_y} - \frac{\nu}{E}\sigma_z \\ \varepsilon_y = -\frac{\nu}{E}\sigma_x + \frac{1}{E}\cancel{\sigma_y} - \frac{\nu}{E}\sigma_z \\ \cancel{\varepsilon_z} = -\frac{\nu}{E}\sigma_x - \frac{\nu}{E}\cancel{\sigma_y} + \frac{1}{E}\sigma_z \end{cases} \rightarrow \begin{cases} \varepsilon_x = \frac{1}{E}\sigma_x - \frac{\nu}{E}\sigma_z \\ \varepsilon_y = -\frac{\nu}{E}\sigma_x - \frac{\nu}{E}\sigma_z \\ 0 = -\frac{\nu}{E}\sigma_x + \frac{1}{E}\sigma_z \end{cases} \rightarrow \begin{cases} \sigma_x = \frac{E\varepsilon_x}{1-\nu^2} \\ \sigma_z = \frac{E\varepsilon_x\nu}{1-\nu^2} \end{cases}$$

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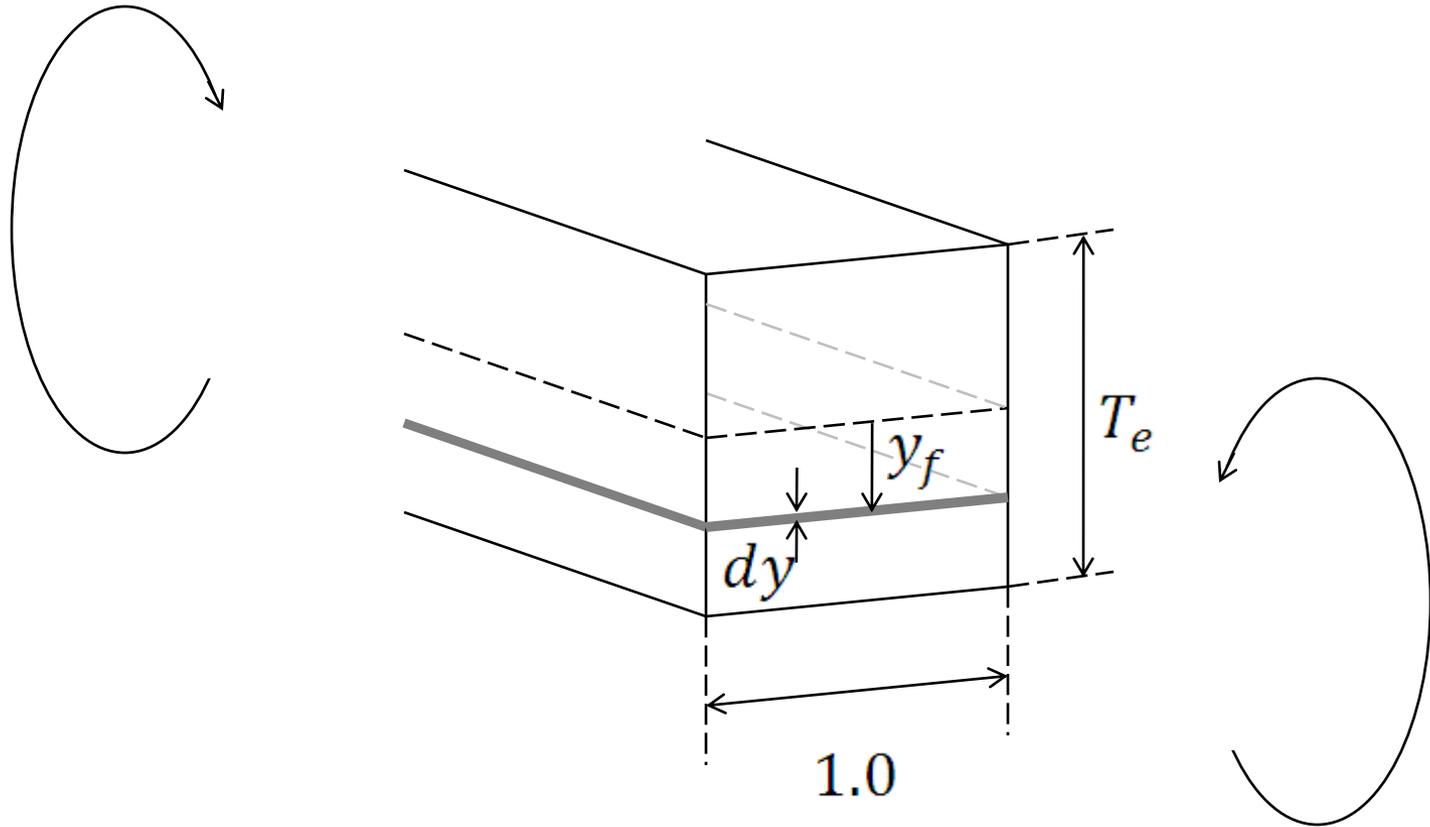
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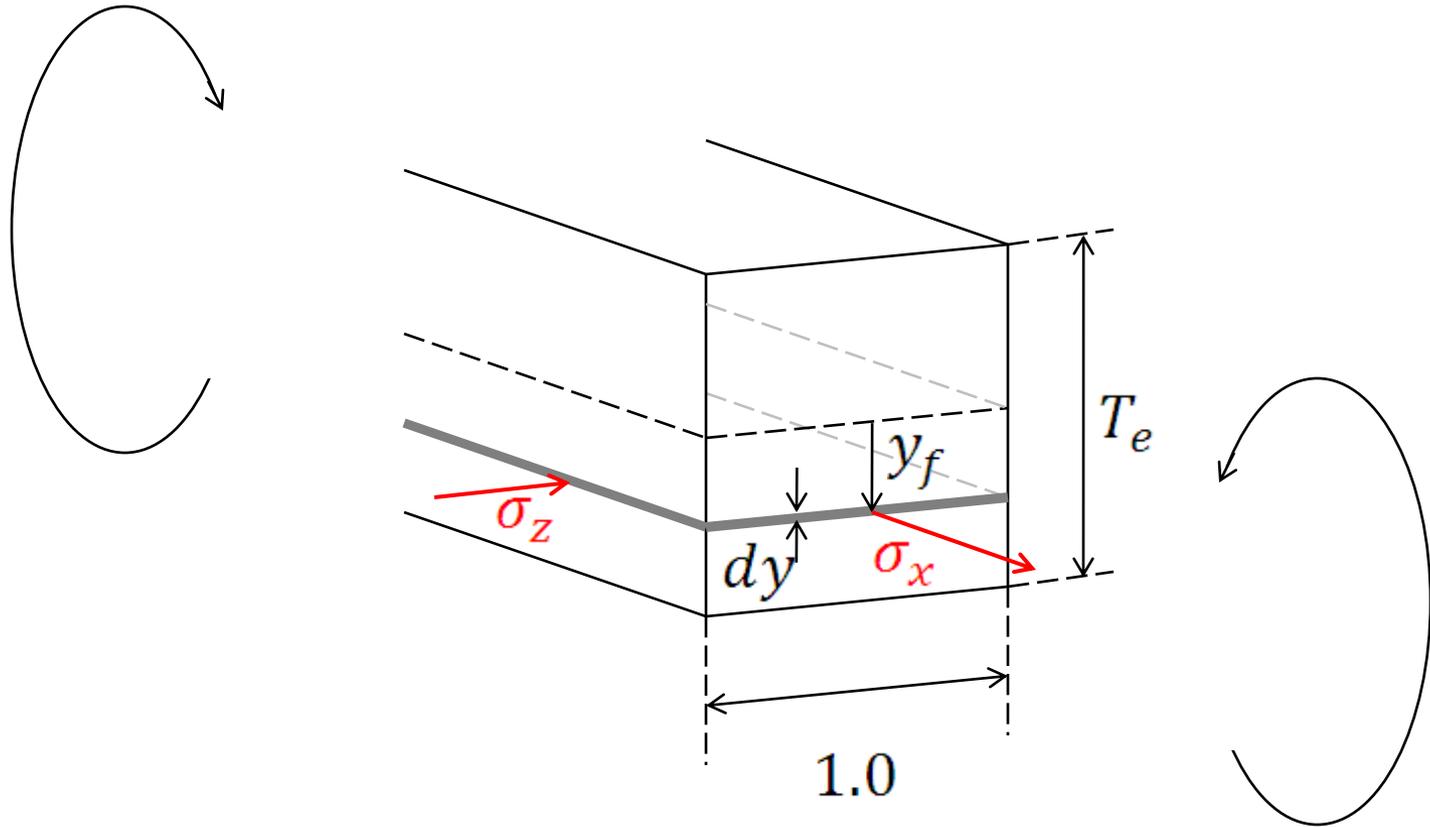
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$$\begin{cases} \sigma_x = \frac{E y_f}{r(1-\nu^2)} \\ \sigma_z = \frac{E y_f \nu}{r(1-\nu^2)} \end{cases}$$

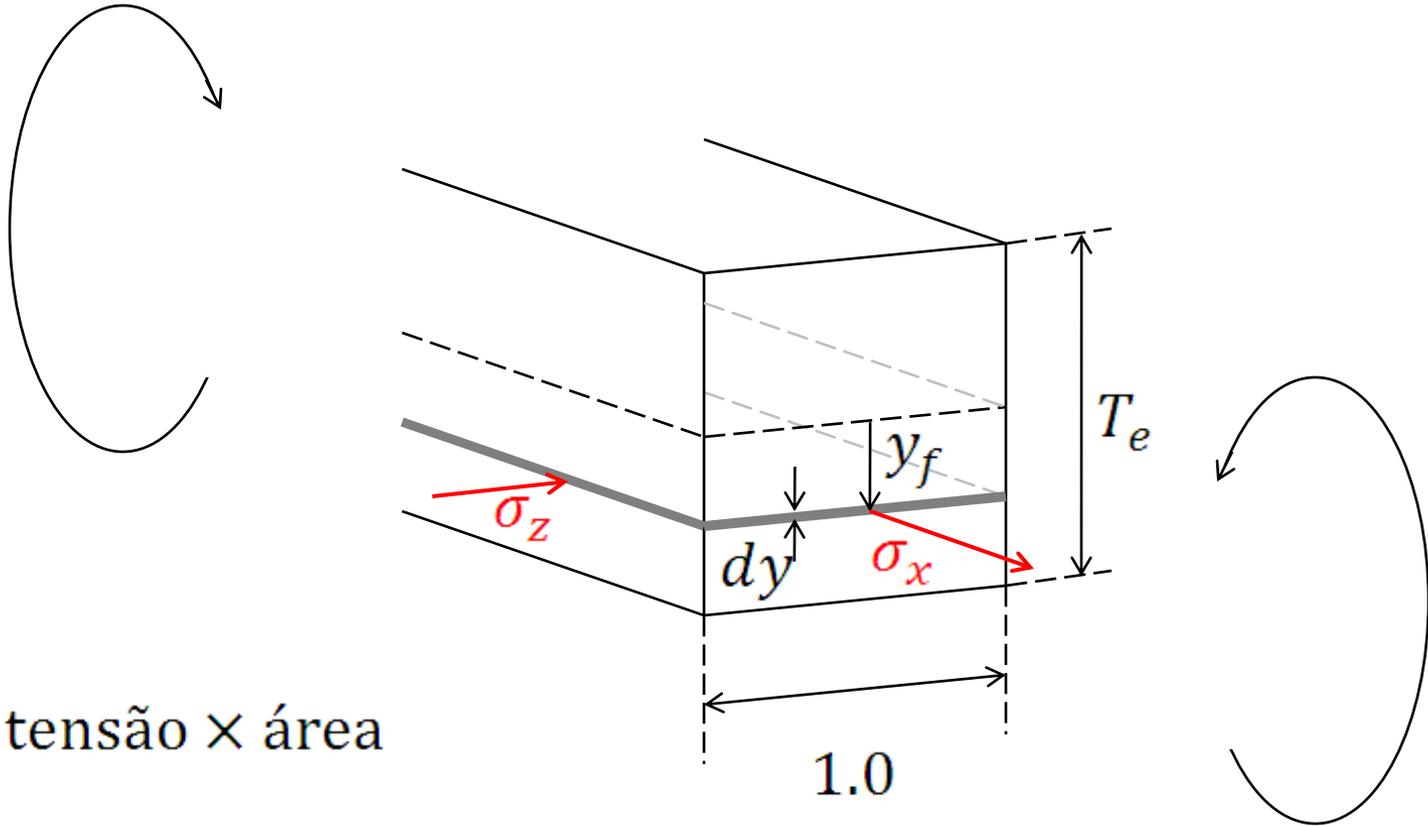
# Força cisalhante e Torque



# Força cisalhante e Torque

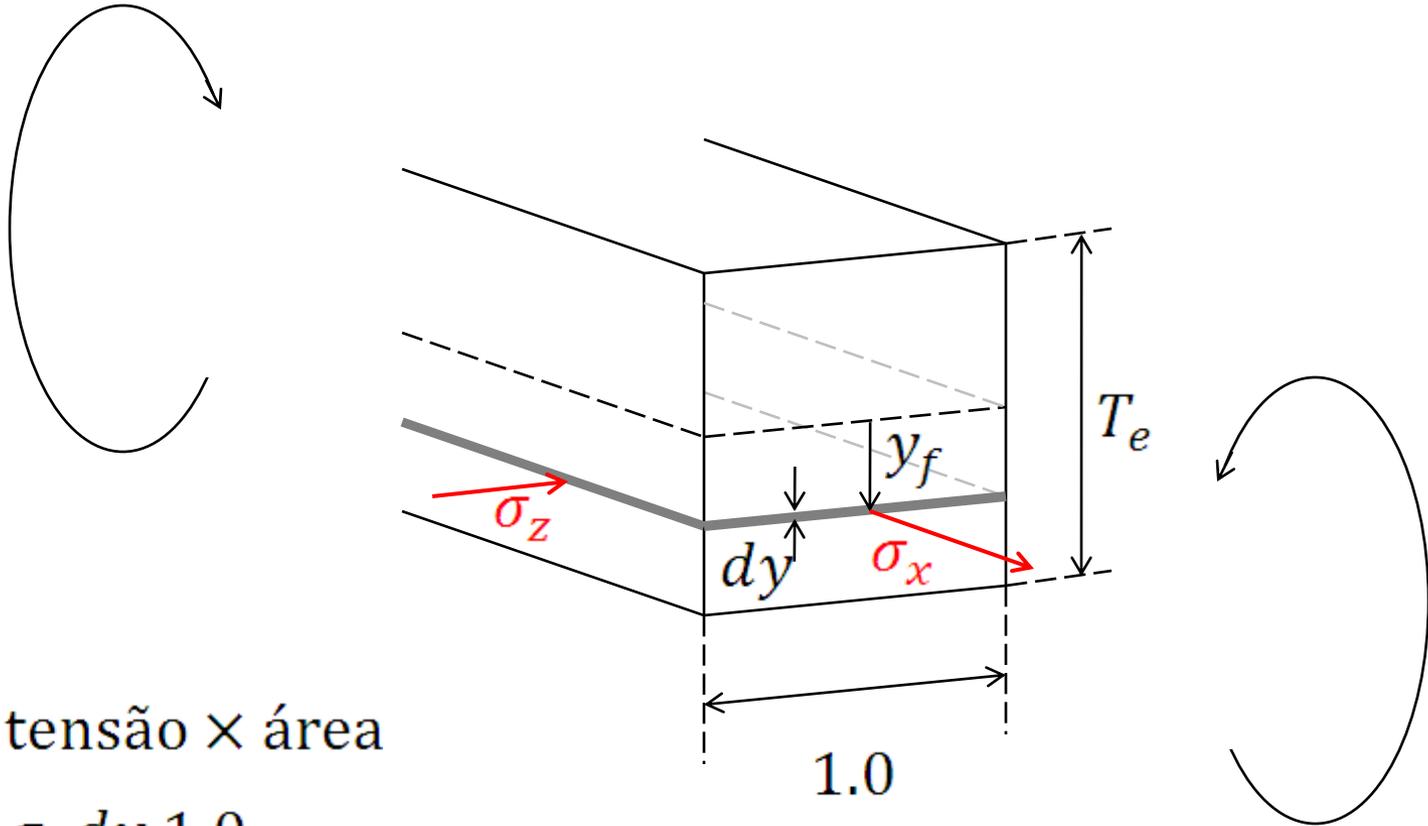


# Força cisalhante e Torque



força = tensão  $\times$  área

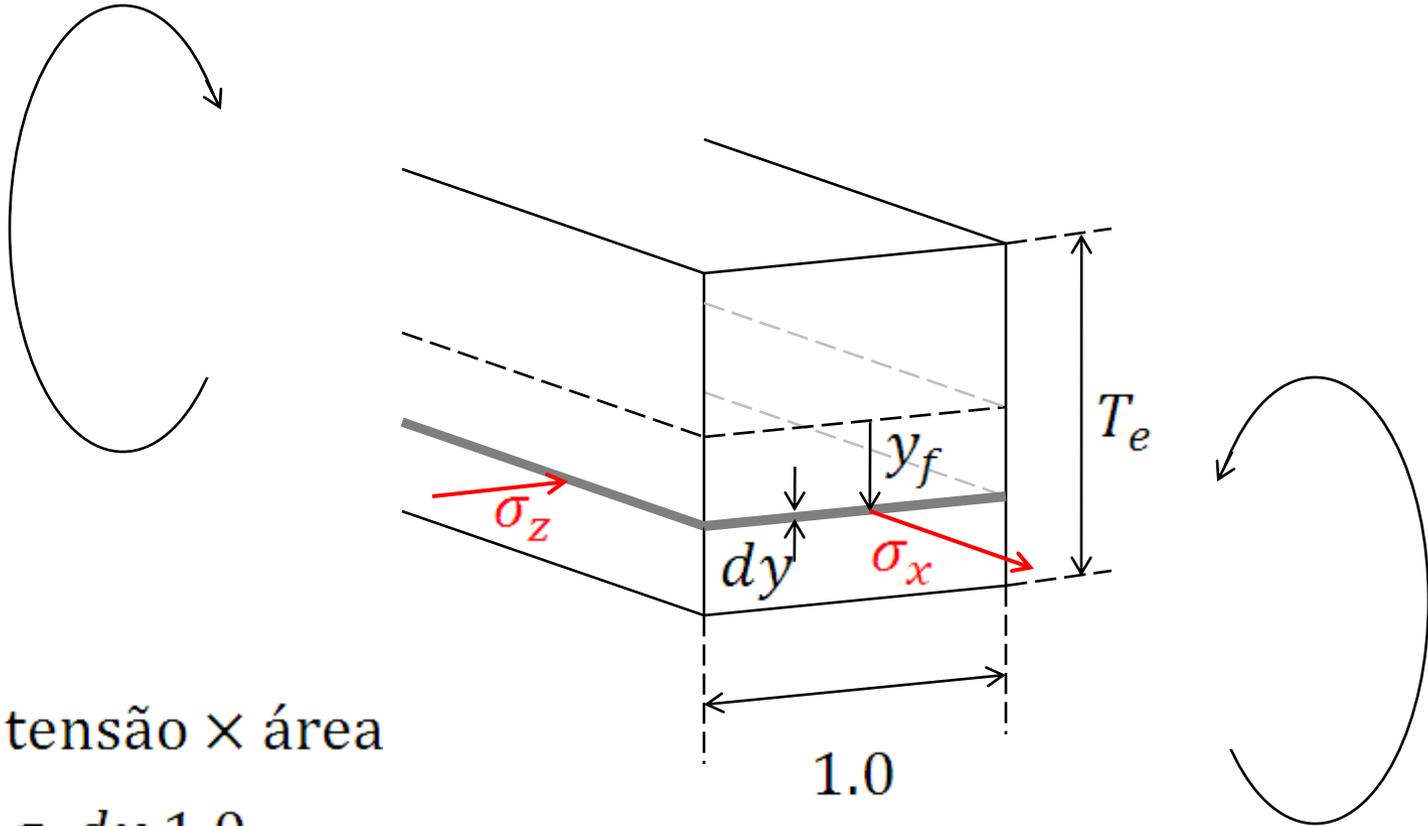
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$$dF = \sigma_x dy 1.0$$

# Força cisalhante e Torque

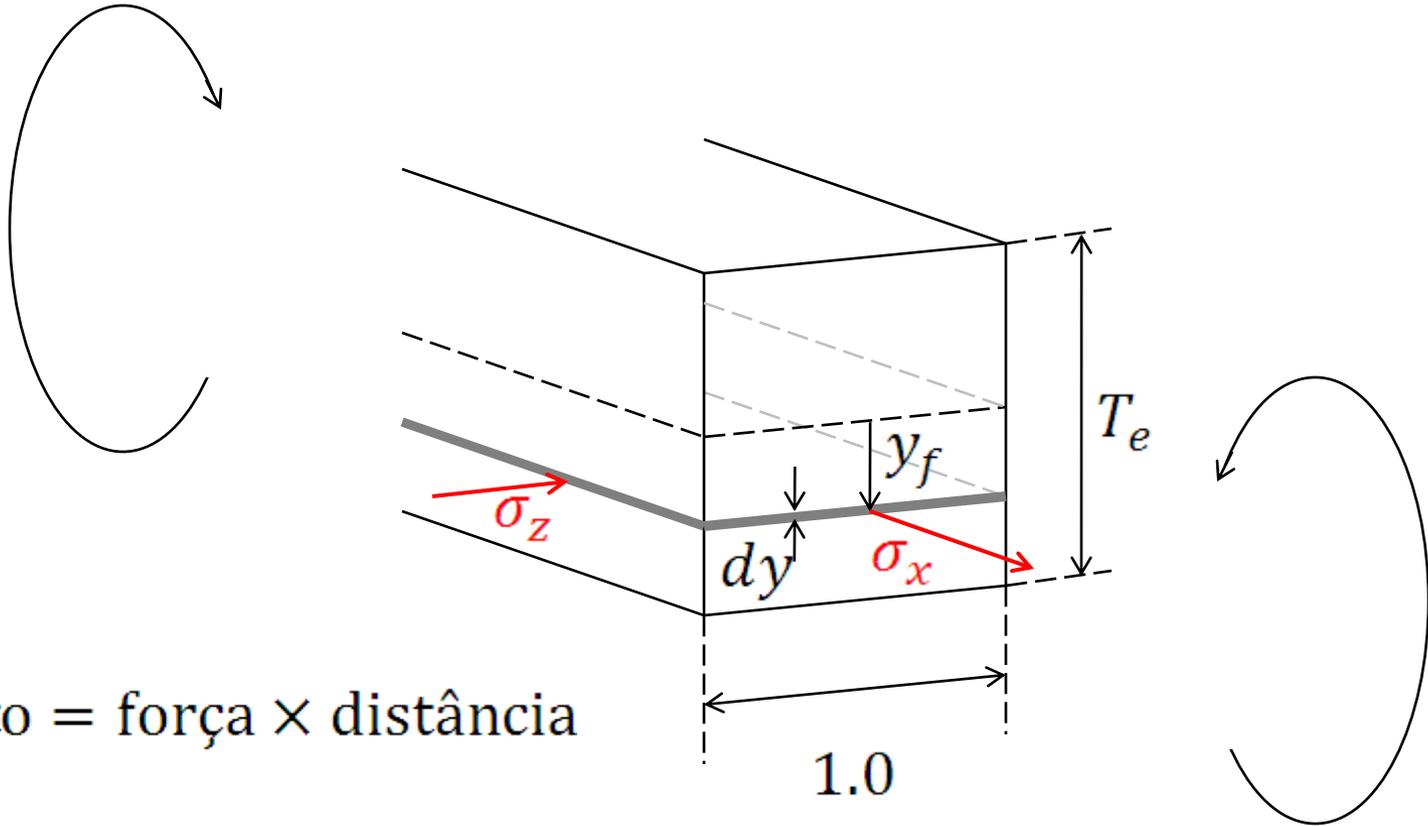


força = tensão  $\times$  área

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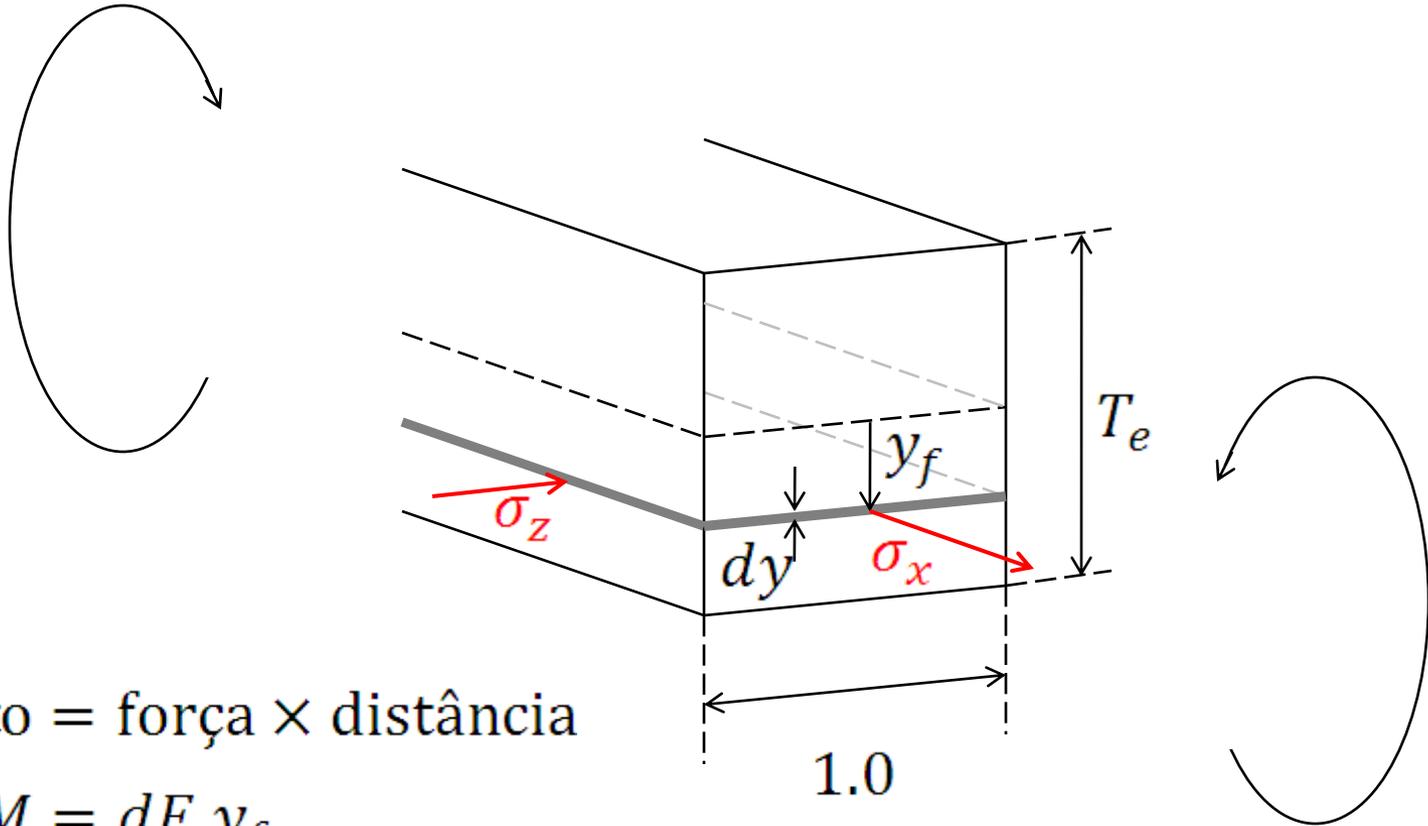
$$= \frac{E y_f}{r(1 - \nu^2)} dy$$

# Força cisalhante e Torque



momento = força  $\times$  distância

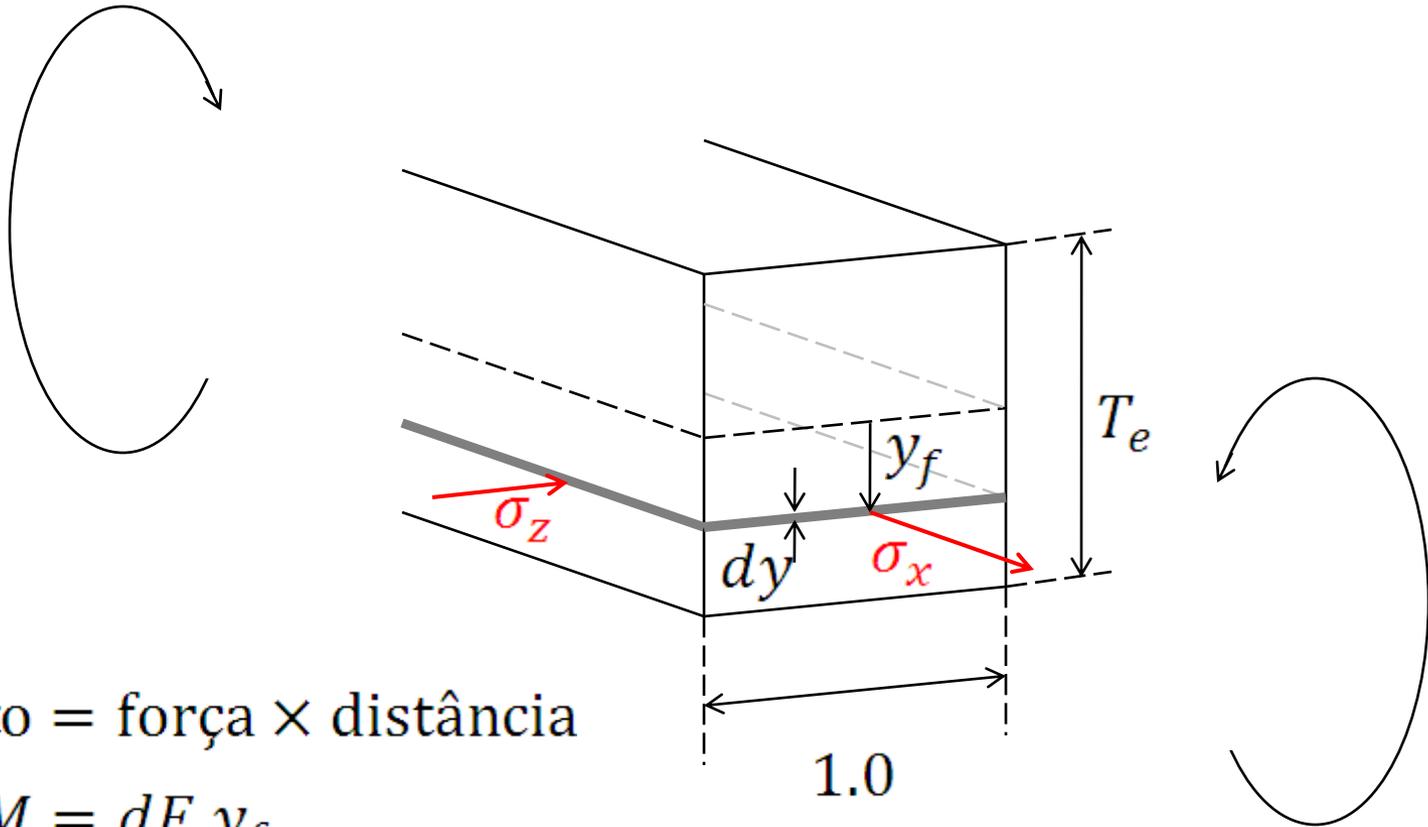
# Força cisalhante e Torque



momento = força  $\times$  distância

$$dM = dF y_f$$

# Força cisalhante e Torque



momento = força  $\times$  distância

$$dM = dF y_f$$

$$= \frac{E y_f^2}{r(1 - \nu^2)} dy$$

# Força cisalhante e Torque

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$$M = \int dM$$

# Força cisalhante e Torque

$$dM = \frac{E y_f^2}{r(1 - \nu^2)} dy$$

$$M = \int dM = \int_{-\frac{T_e}{2}}^{\frac{T_e}{2}} \frac{E y_f^2}{r(1 - \nu^2)} dy$$

# Força cisalhante e Torque

$$dM = \frac{E y_f^2}{r(1 - \nu^2)} dy$$

$$M = \int dM = \int_{-\frac{T_e}{2}}^{\frac{T_e}{2}} \frac{E y_f^2}{r(1 - \nu^2)} dy = \frac{E}{r(1 - \nu^2)} \left[ \frac{y^3}{3} \right]_{-\frac{T_e}{2}}^{\frac{T_e}{2}}$$

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$= D$   
Rigidez flexural

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$$dM = \frac{E y_f^2}{r(1 - \nu^2)} dy$$

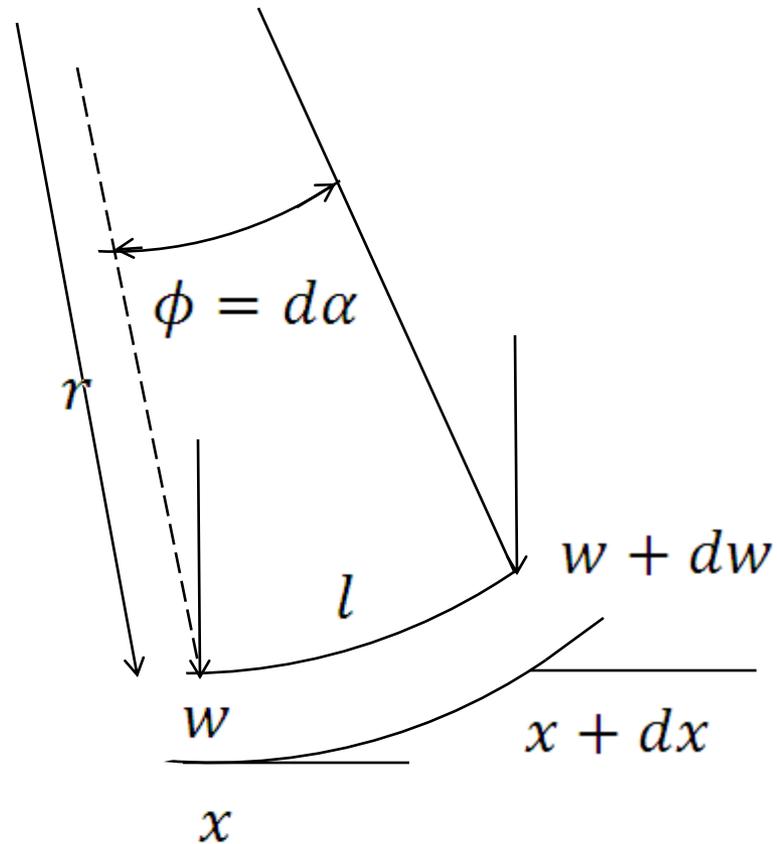
$$M = \int dM = \int_{-\frac{T_e}{2}}^{\frac{T_e}{2}} \frac{E y_f^2}{r(1 - \nu^2)} dy = \frac{E}{r(1 - \nu^2)} \left[ \frac{y^3}{3} \right]_{-\frac{T_e}{2}}^{\frac{T_e}{2}} = \frac{ET_e^3}{12(1 - \nu^2)} \cdot \frac{1}{r}$$

$$= D$$

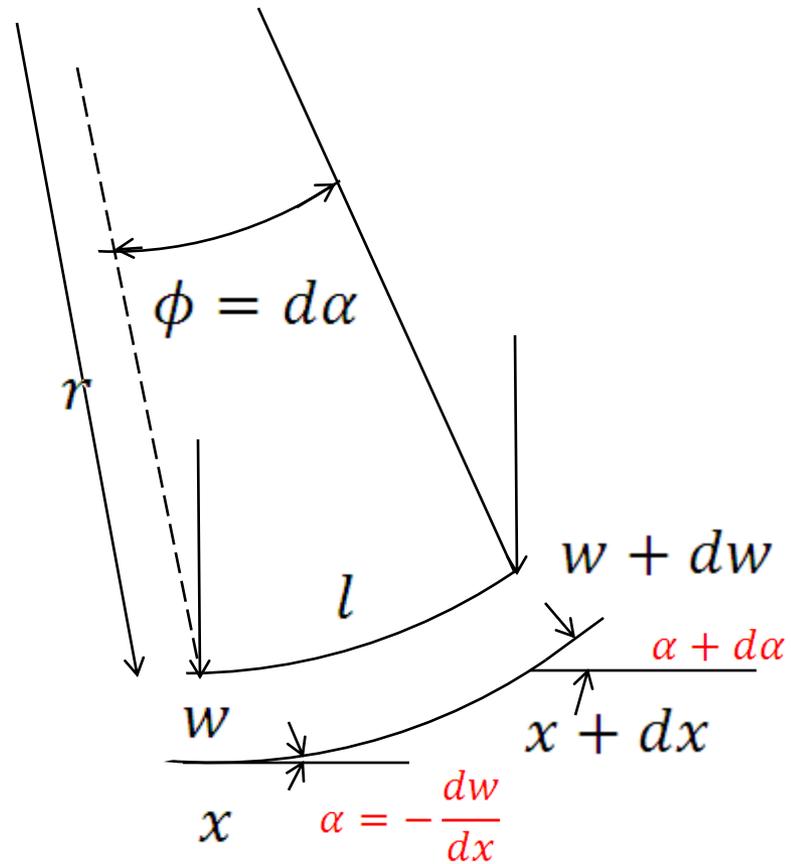
Rigidez flexural

$$M = \frac{D}{r}$$

# Determinação do raio de curvatura

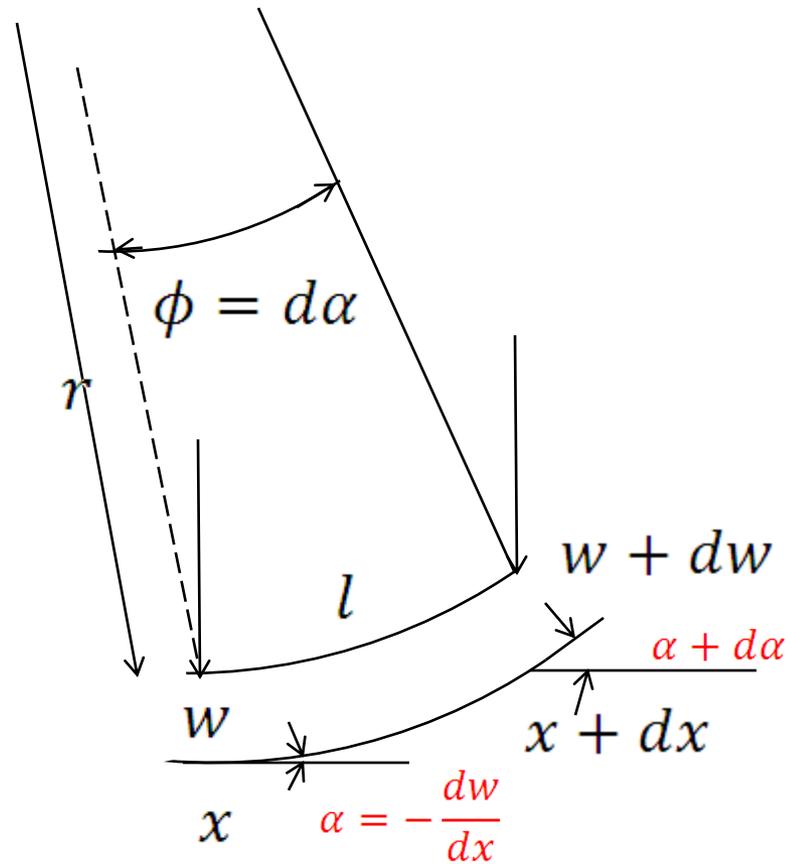


# Determinação do raio de curvatura



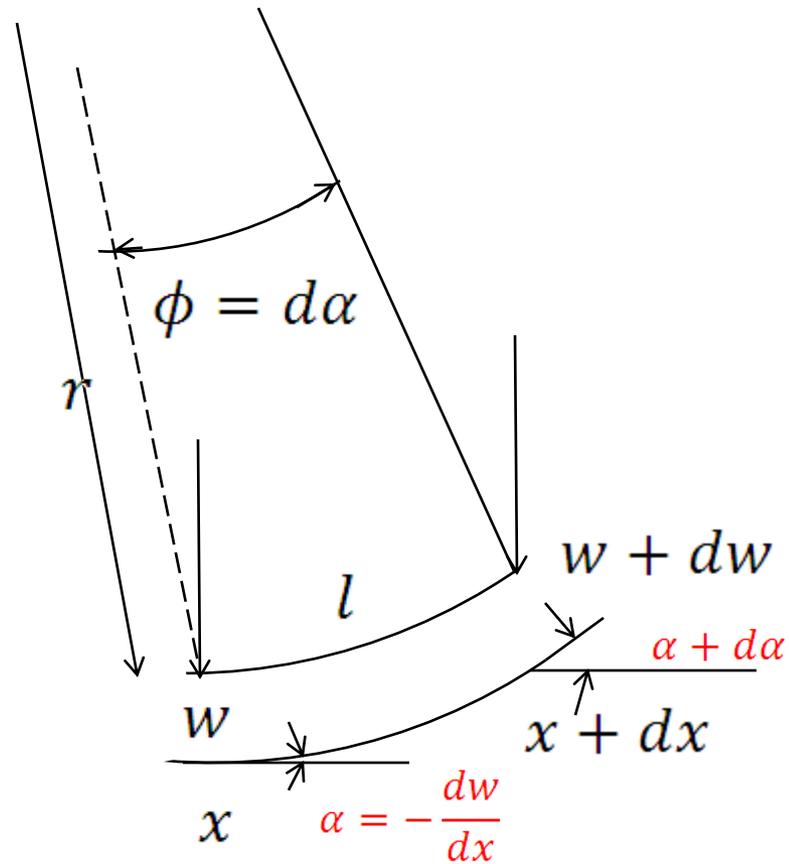
# Determinação do raio de curvatura

$$\phi = d\alpha$$



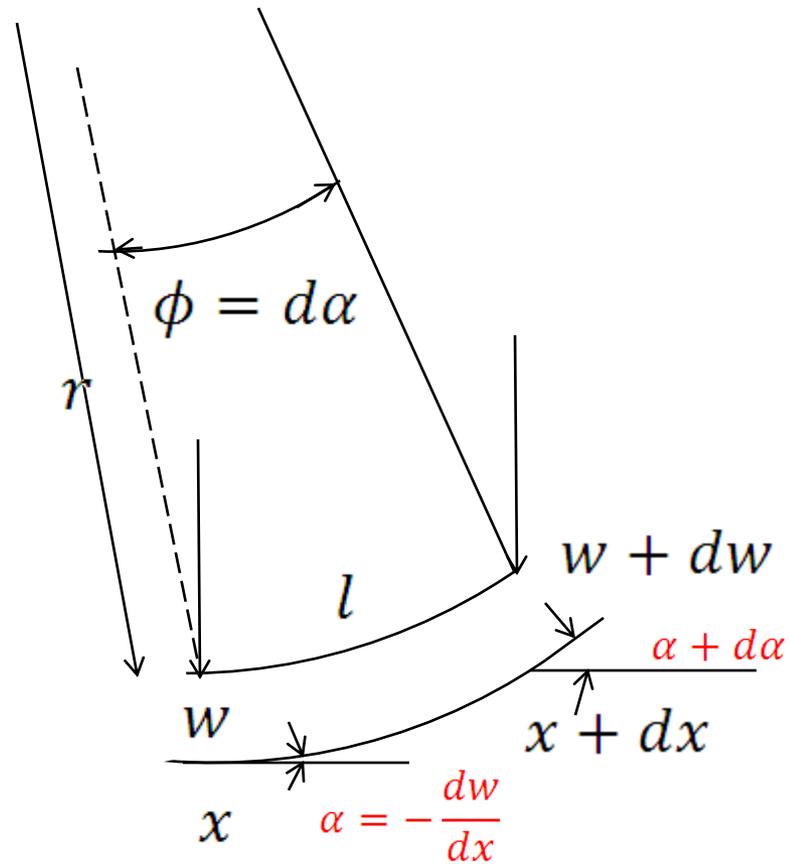
# Determinação do raio de curvatura

$$\phi = d\alpha = \frac{d\alpha}{dx} dx$$



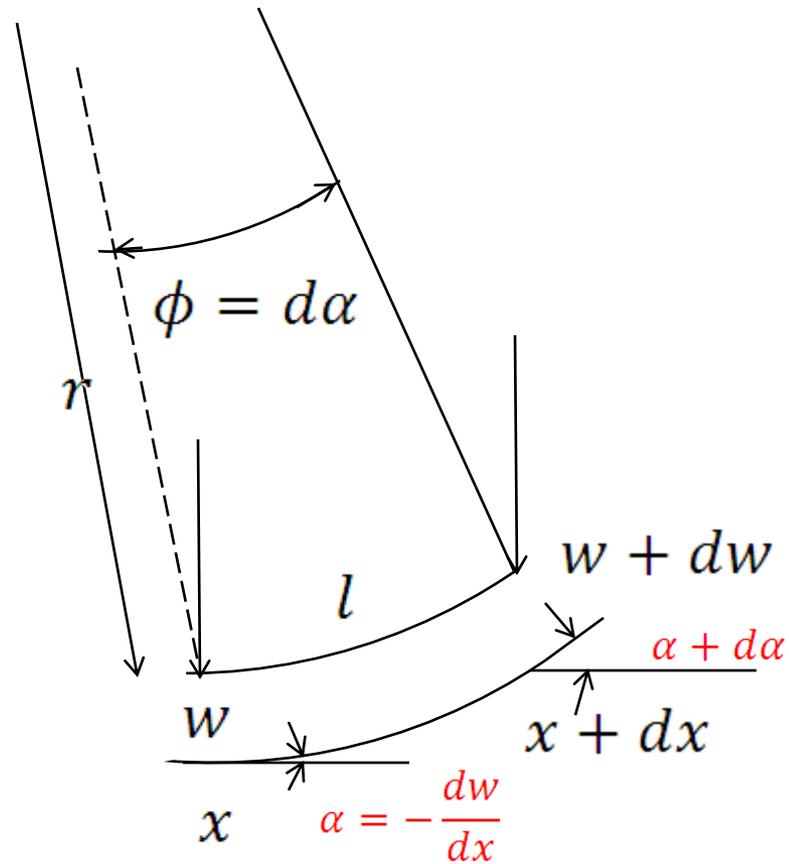
# Determinação do raio de curvatura

$$\phi = d\alpha = \frac{d\alpha}{dx} dx$$
$$= \frac{d}{dx} \left( -\frac{dw}{dx} \right) dx$$



# Determinação do raio de curvatura

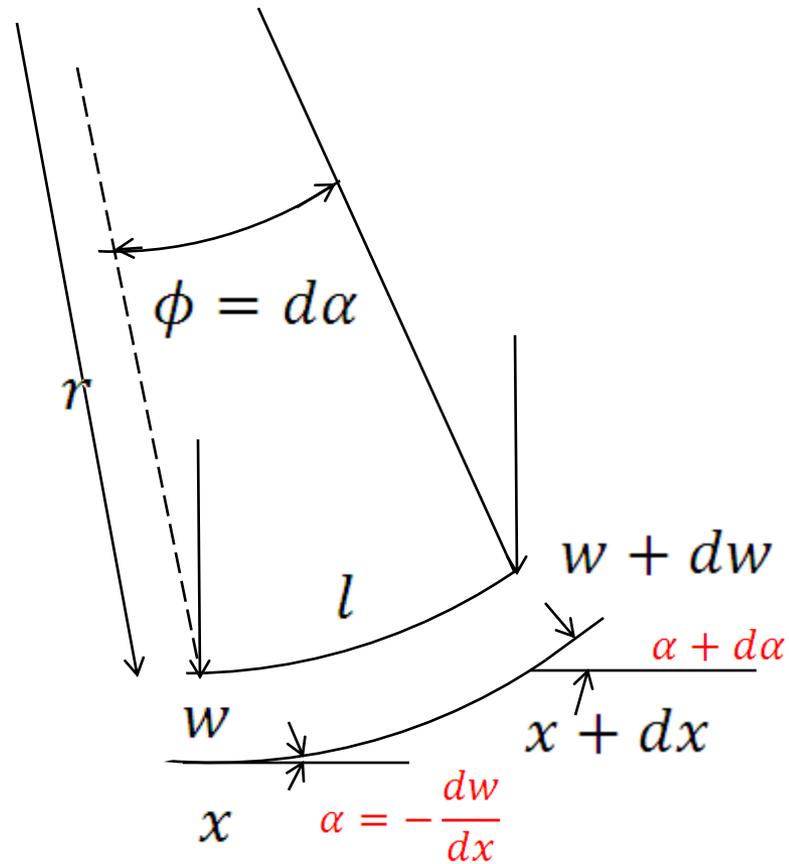
$$\begin{aligned}\phi &= d\alpha = \frac{d\alpha}{dx} dx \\ &= \frac{d}{dx} \left( -\frac{dw}{dx} \right) dx \\ &= -\frac{d^2w}{dx^2} dx\end{aligned}$$



# Determinação do raio de curvatura

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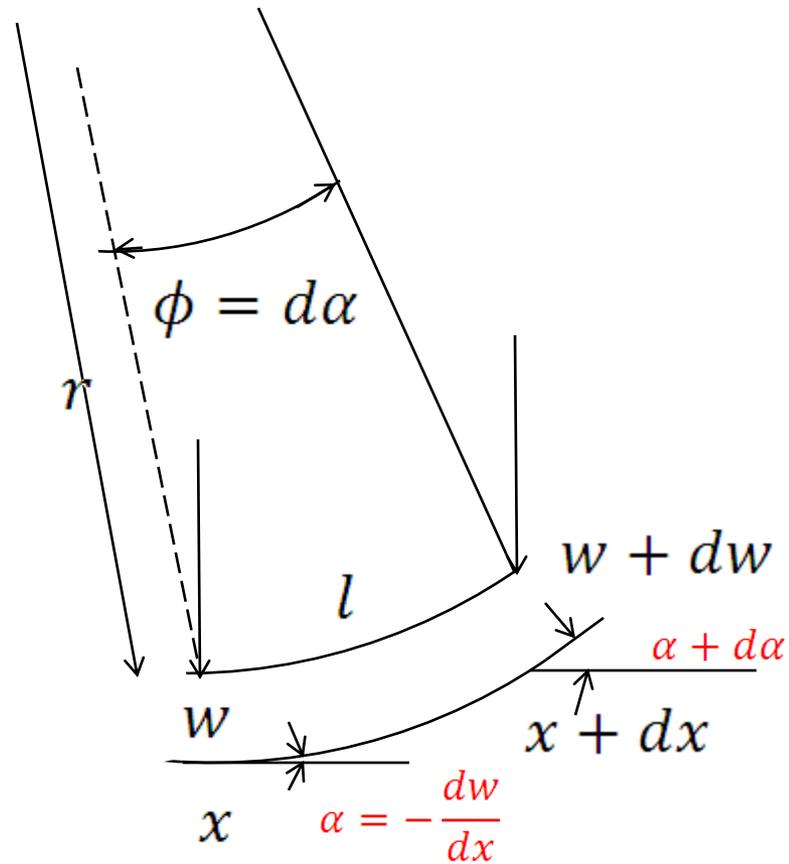
$$\frac{1}{r} = \frac{\phi}{l}$$



# Determinação do raio de curvatura

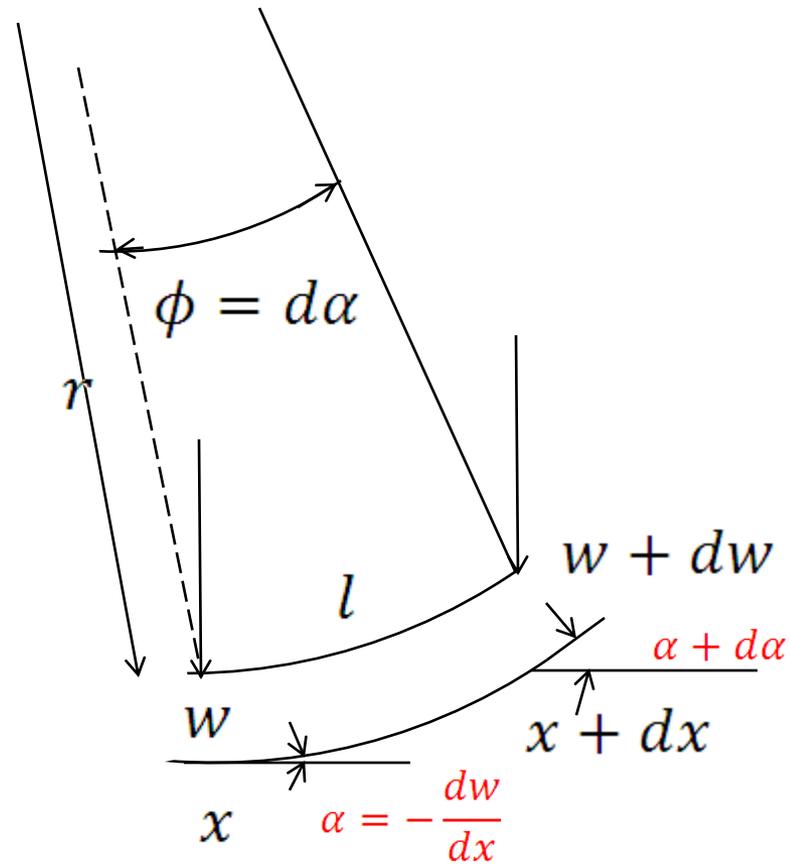
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$$\frac{1}{r} = \frac{\phi}{l} \approx \frac{\phi}{dx} = -\frac{d^2w}{dx^2}$$



# Determinação do raio de curvatura

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# Flexura de placa elástica fina

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$$\frac{d^2 M}{dx^2} = -q$$

$$M = \frac{D}{r}$$

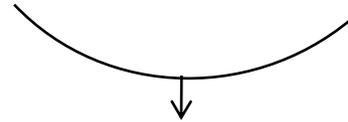
$$\frac{1}{r} \rightarrow -\frac{d^2 w}{dx^2}$$

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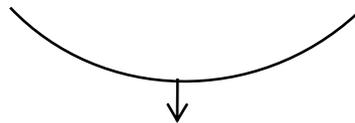


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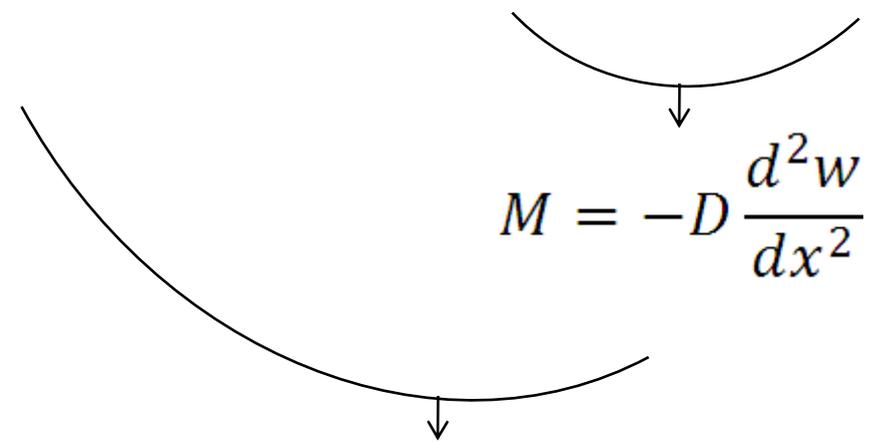
$$M = -D \frac{d^2 w}{dx^2}$$

# Flexura de placa elástica fina

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$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

# Aplicação para a litosfera

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

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$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

Superfície

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Crosta continental

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Manto litosférico continental

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Astenosfera

# Aplicação para a litosfera

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

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$\rho_c$

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$\rho_m$

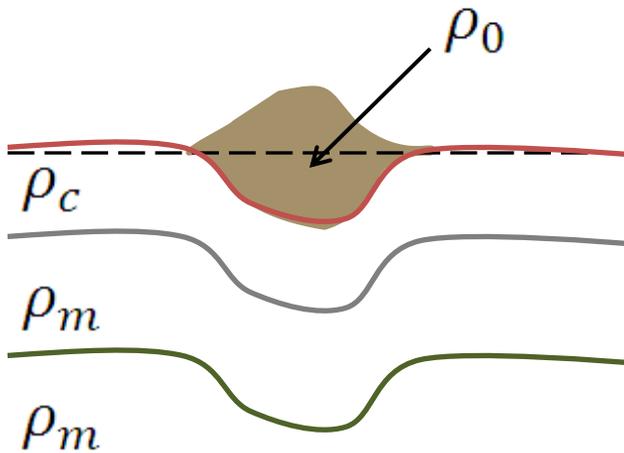
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$\rho_m$

# Aplicação para a litosfera

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

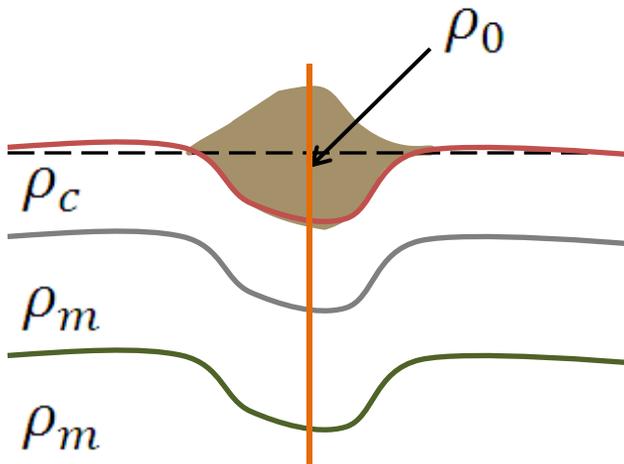
$q(x) = \text{carga} - \text{empuxo}$



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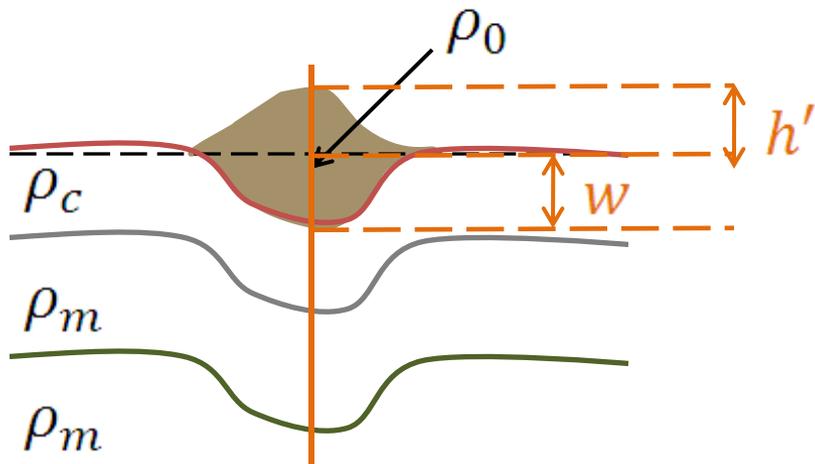
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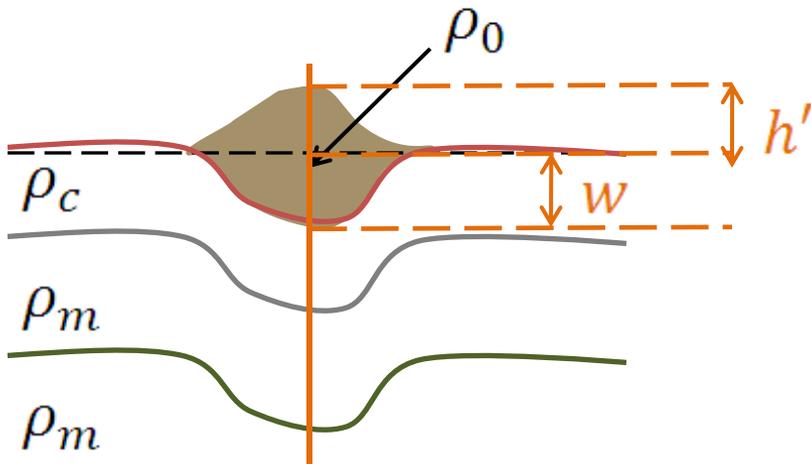


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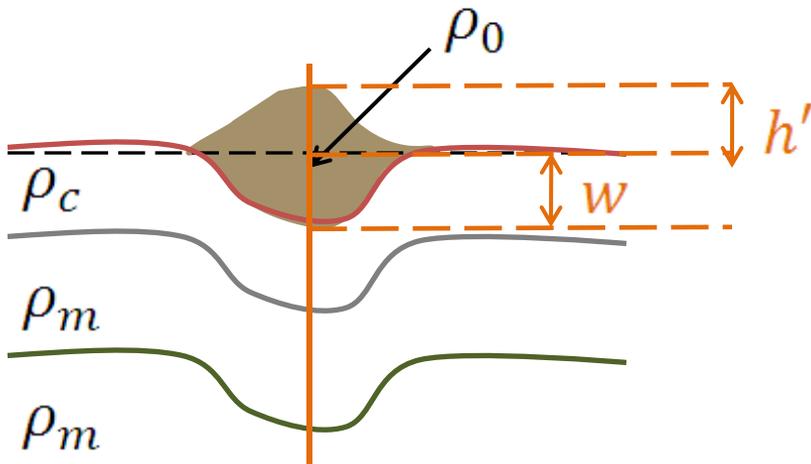


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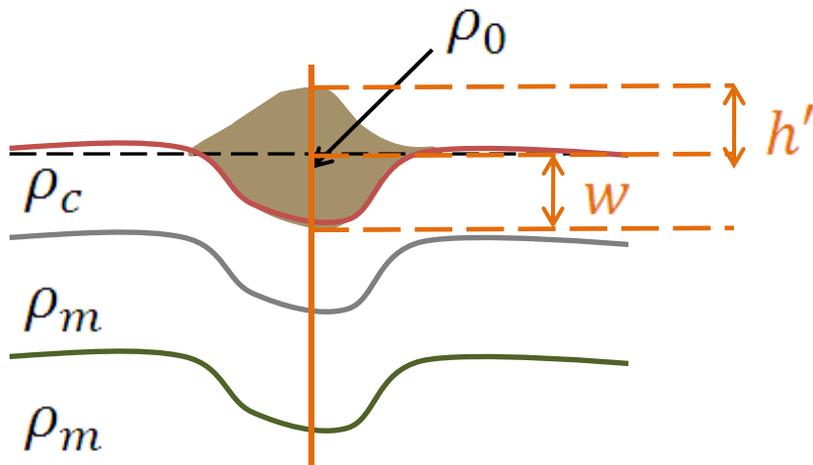


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$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = \rho_0 g h'$$

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Superfície

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Água

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Litosfera oceânica

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Astenosfera

# Aplicação para a litosfera

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

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$\rho_w$

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$\rho_m$

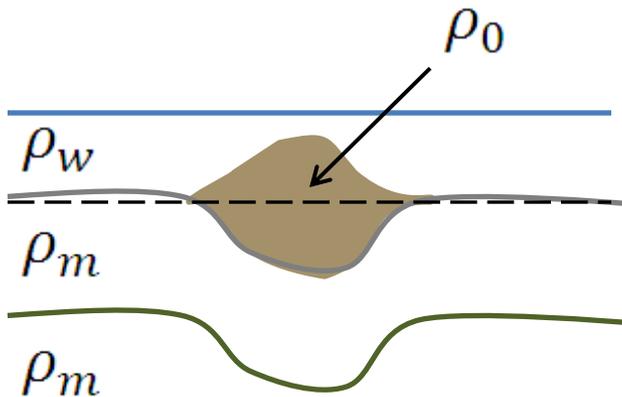
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$\rho_m$

# Aplicação para a litosfera

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) = q(x)$$

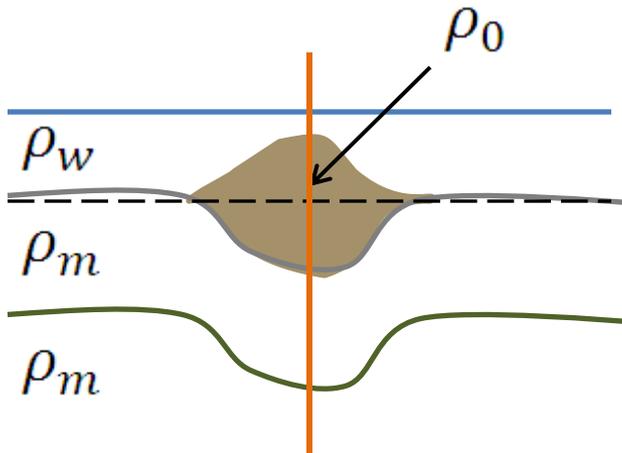
$q(x) = \text{car.} - \text{águas desloc.} - \text{empuxo}$



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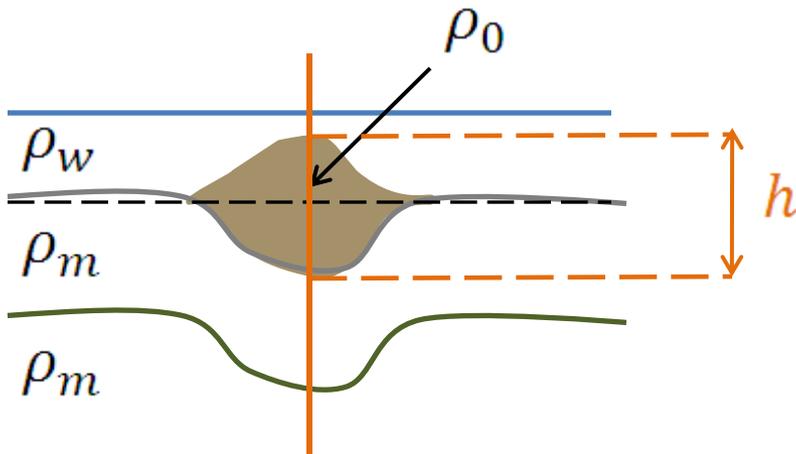
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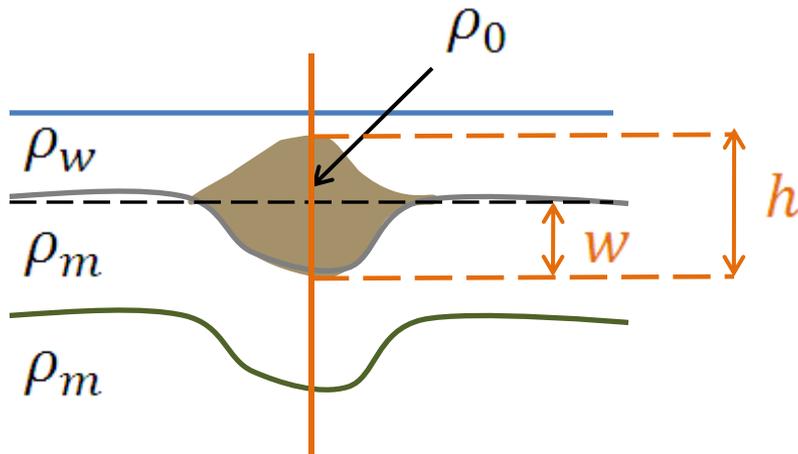
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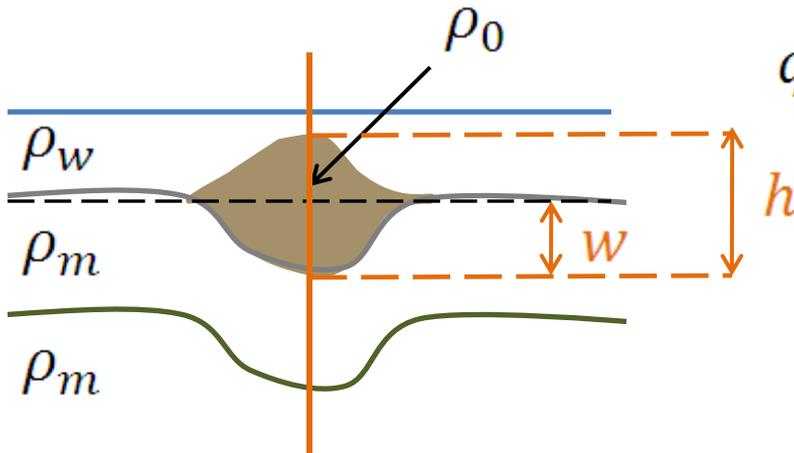


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$q(x)$  = car. – água desloc. – empuxo

$$q(x) = \rho_0 g h - \rho_w g (h - w) - \rho_m g w$$



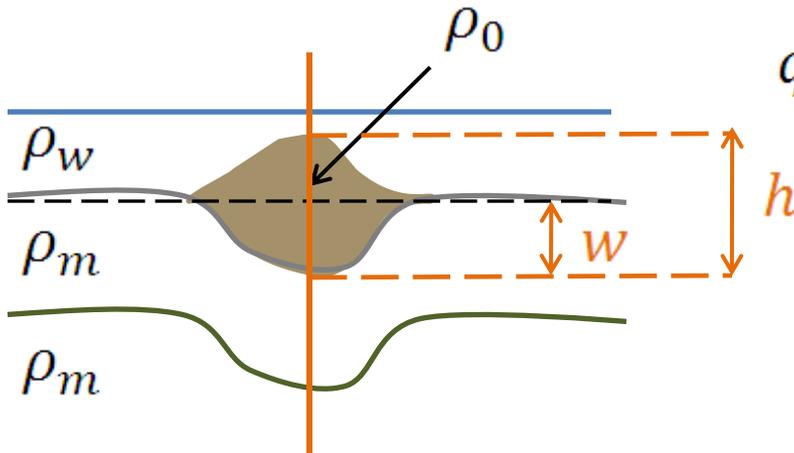
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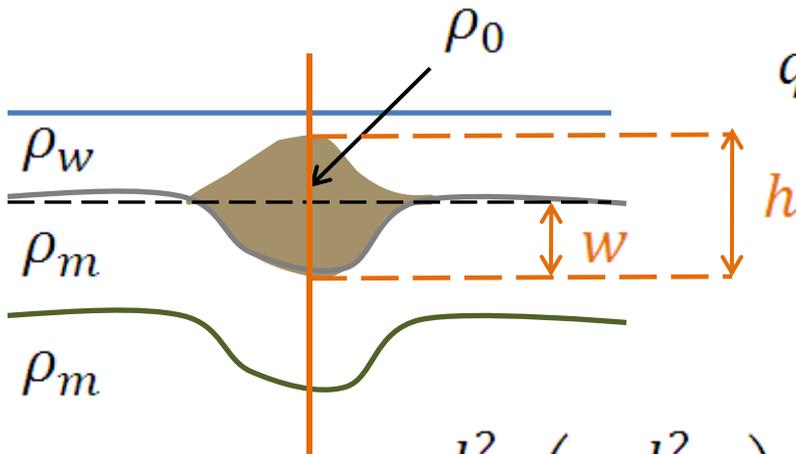
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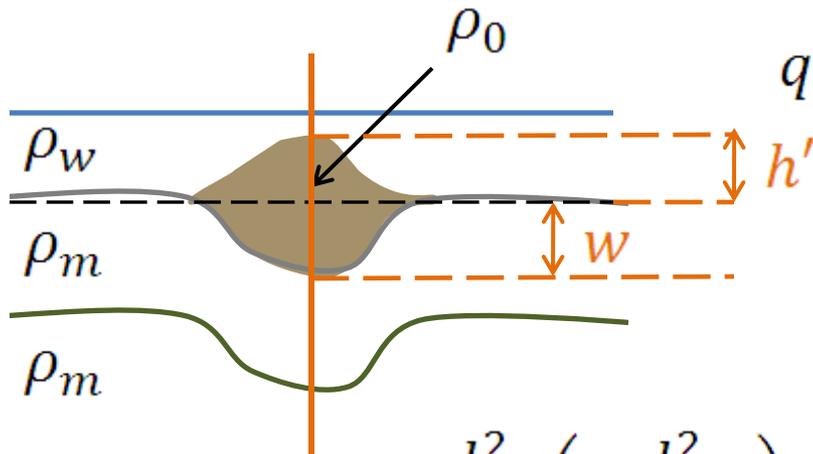
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$$\begin{aligned} q(x) &= \rho_0 g(h' + w) - \rho_w g h' - \rho_m g w \\ &= (\rho_0 - \rho_w) g h' - (\rho_m - \rho_0) g w \end{aligned}$$



$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_w) g h'$$

# Comparação

Caso continental:  $\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = \rho_0 g h'$

Caso oceânico I:  $\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_w) g w = (\rho_0 - \rho_w) g h$

Caso oceânico II:  $\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_w) g h'$

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$h$  Espessura total do carregamento

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$h$  Espessura total do carregamento

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria

# Comparação

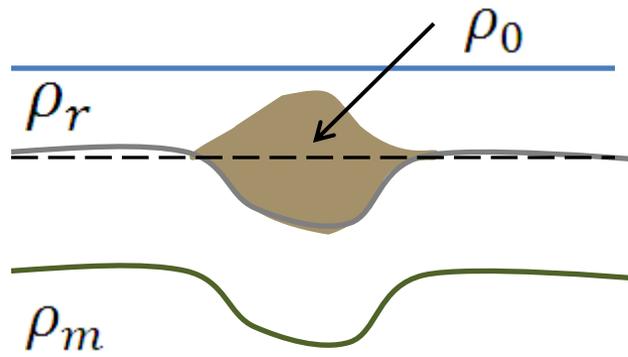
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# Comparação

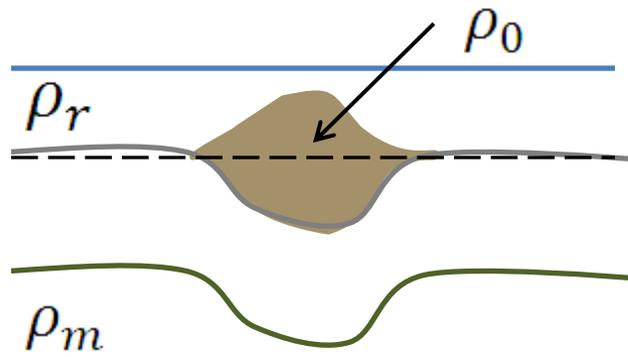
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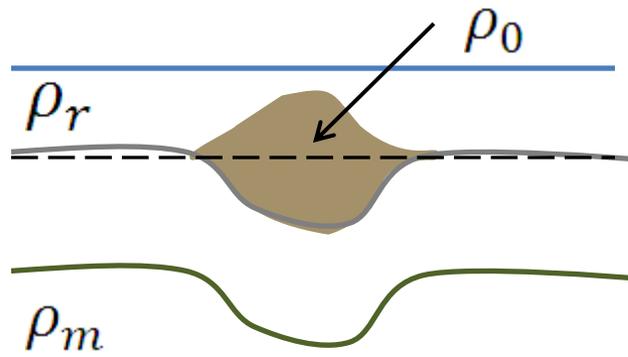
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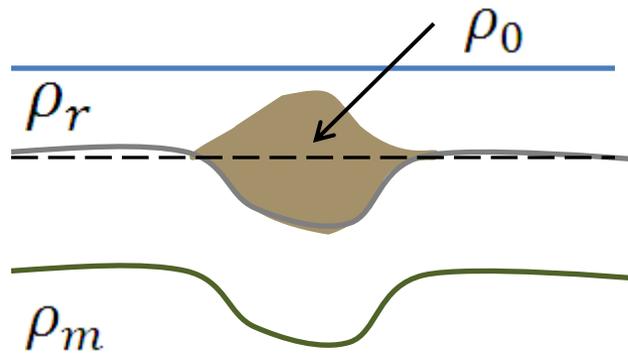
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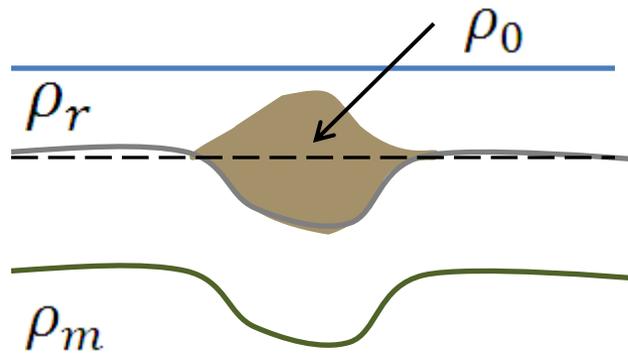
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# Comparação

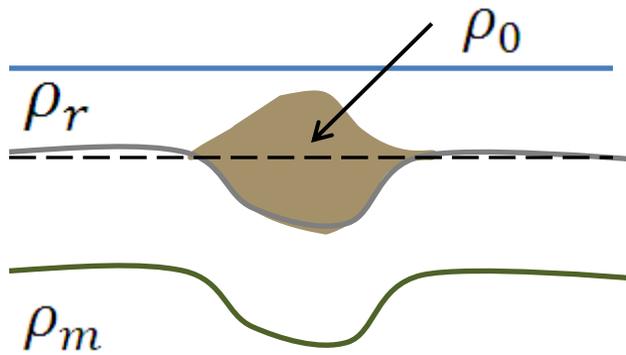
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$h$  Espessura total do carregamento

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria



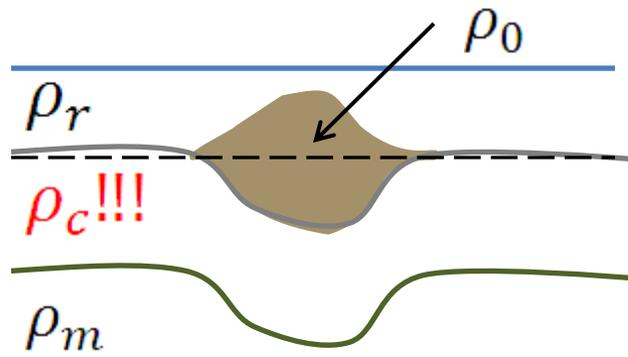
# Comparação

$h$  Espessura total do carregamento:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$



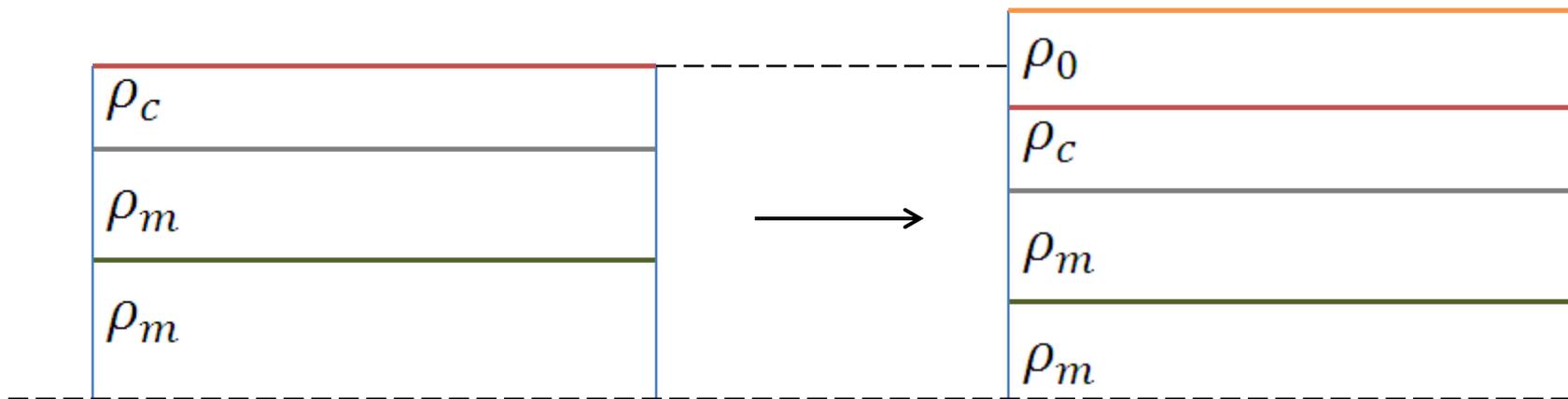
# Comparação

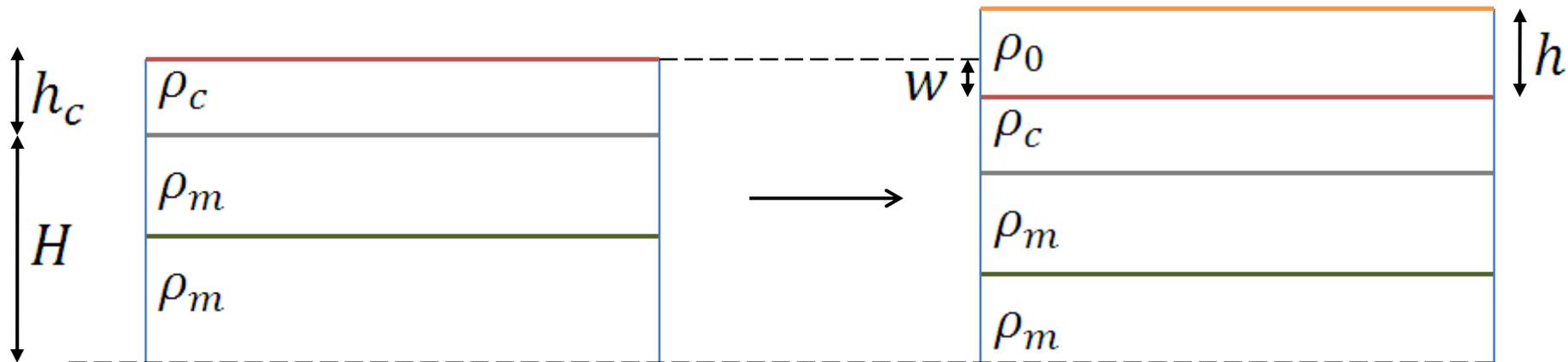
$h$  Espessura total do carregamento:

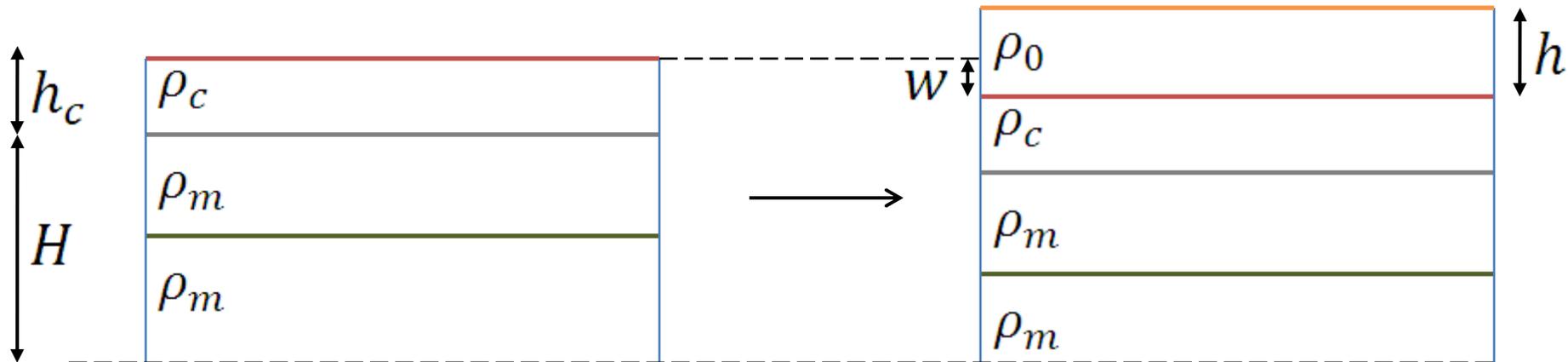
$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria:

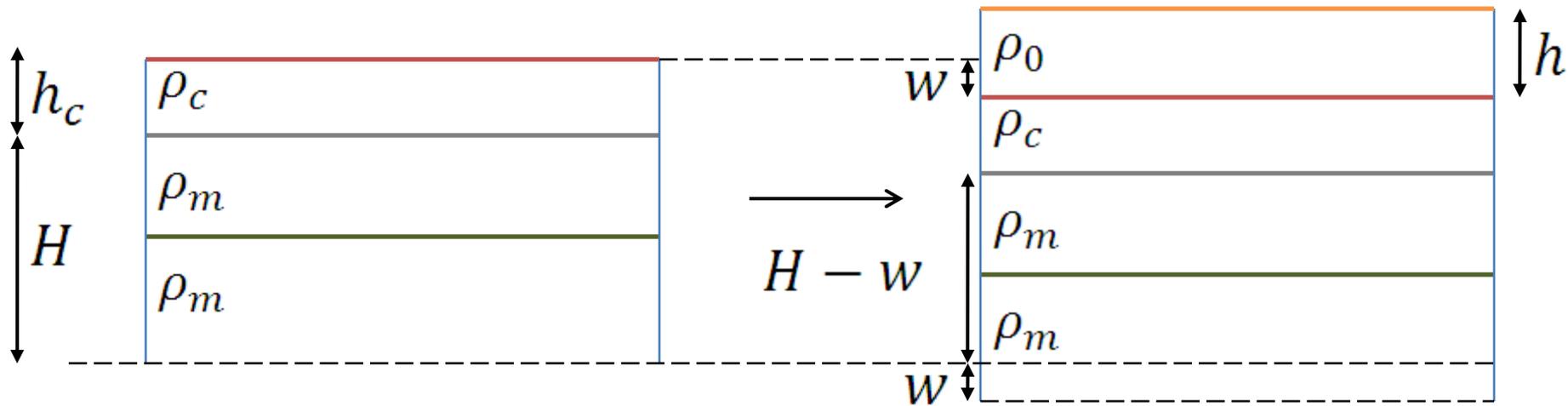
$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$



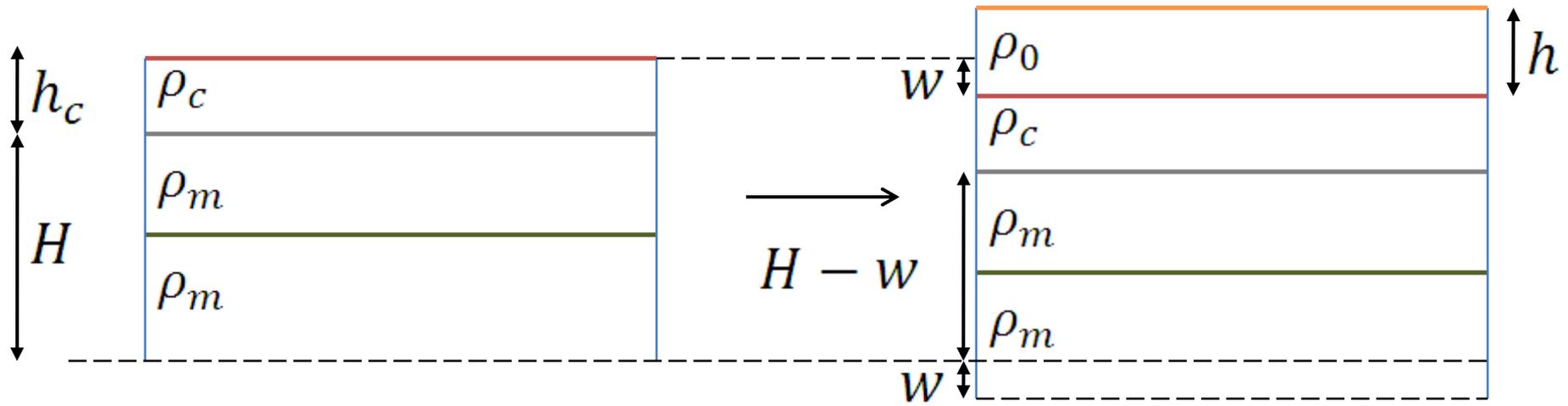




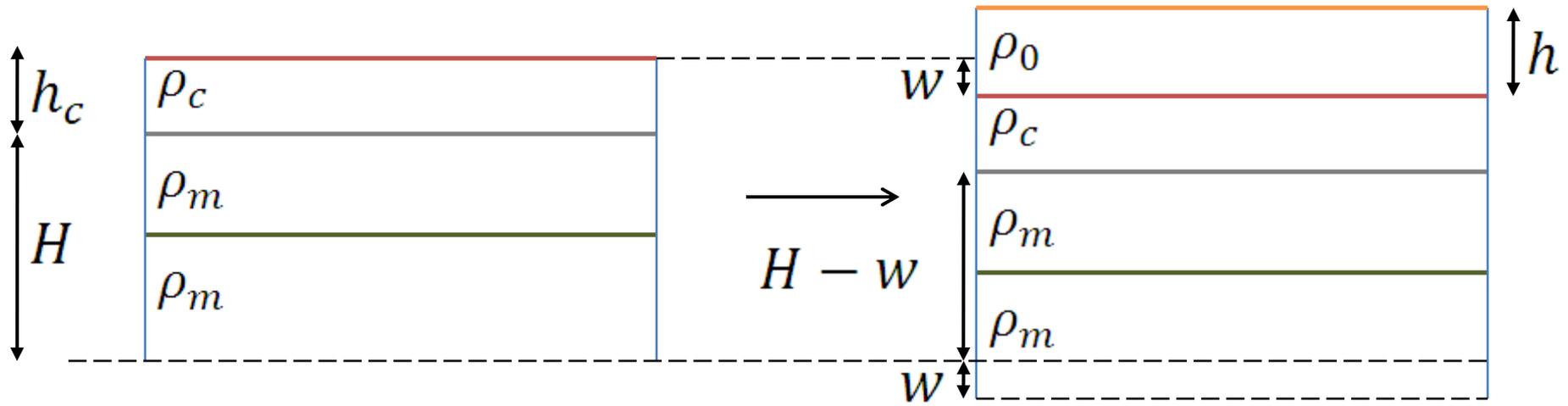
$$\rho_c g h_c + \rho_m g H =$$



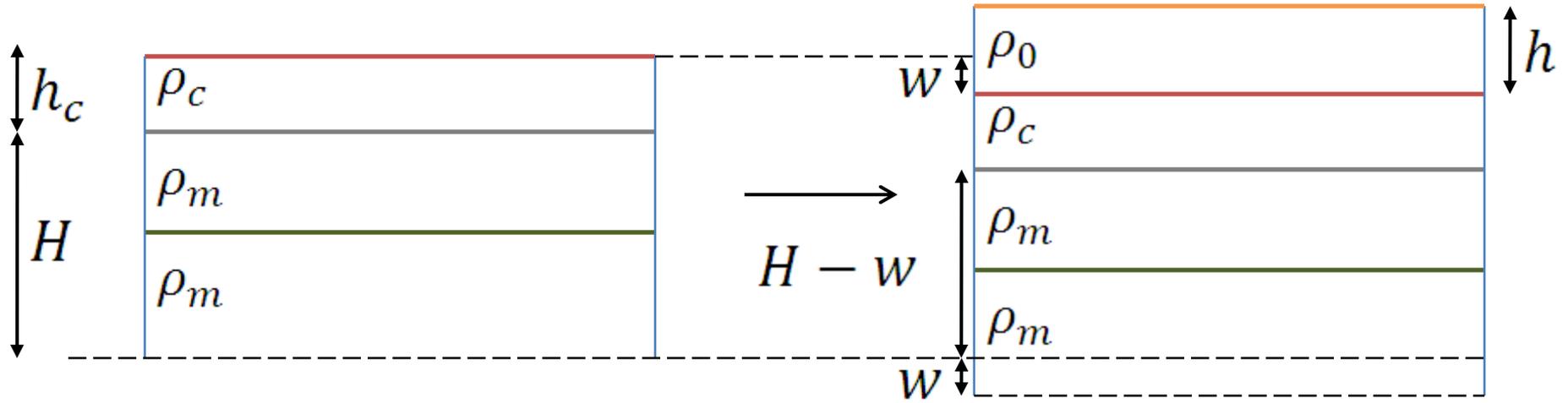
$$\rho_c g h_c + \rho_m g H = \rho_0 g h + \rho_c g h_c + \rho_m g (H - w)$$



$$\cancel{\rho_c g h_c} + \rho_m g H = \rho_0 g h + \cancel{\rho_c g h_c} + \rho_m g (H - w)$$

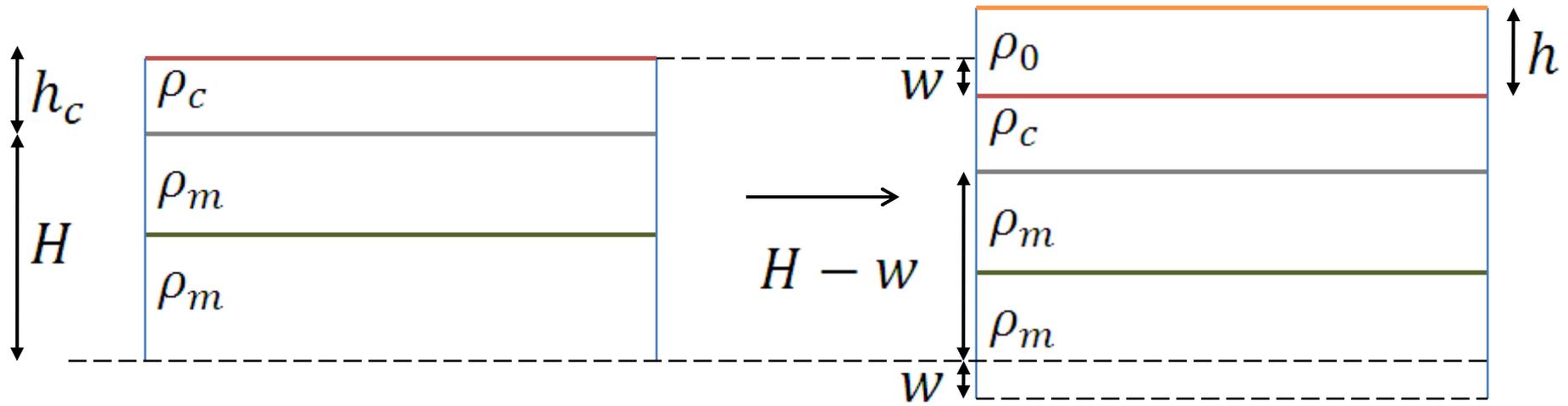


$$\cancel{\rho_c g h_c} + \cancel{\rho_m g H} = \rho_0 g h + \cancel{\rho_c g h_c} + \rho_m g (H - w)$$



$$\cancel{\rho_c g h_c} + \cancel{\rho_m g H} = \rho_0 g h + \cancel{\rho_c g h_c} + \rho_m g (H - w)$$

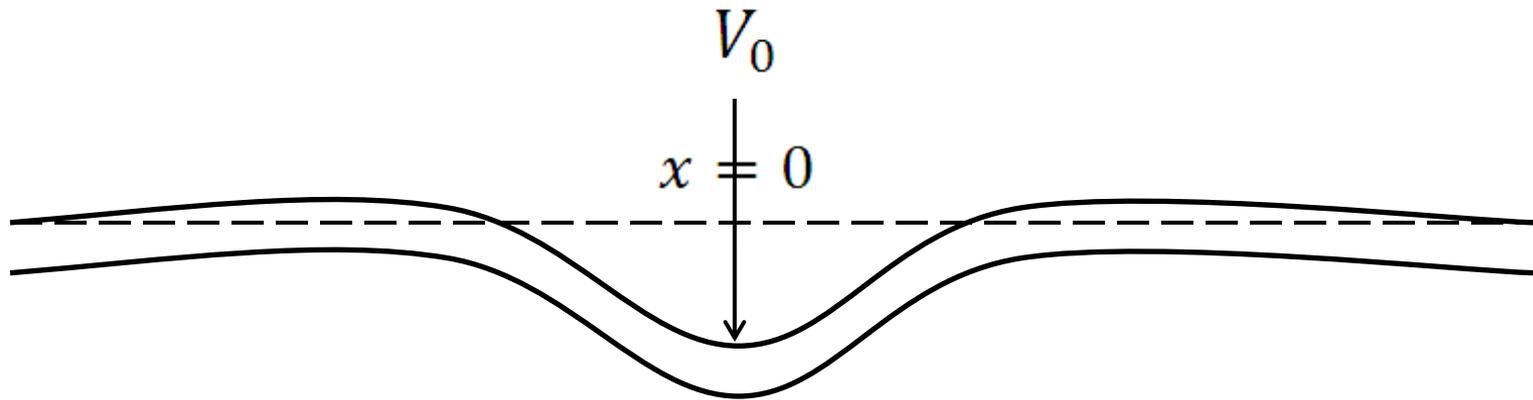
$$0 = \rho_0 g h - \rho_m g w$$



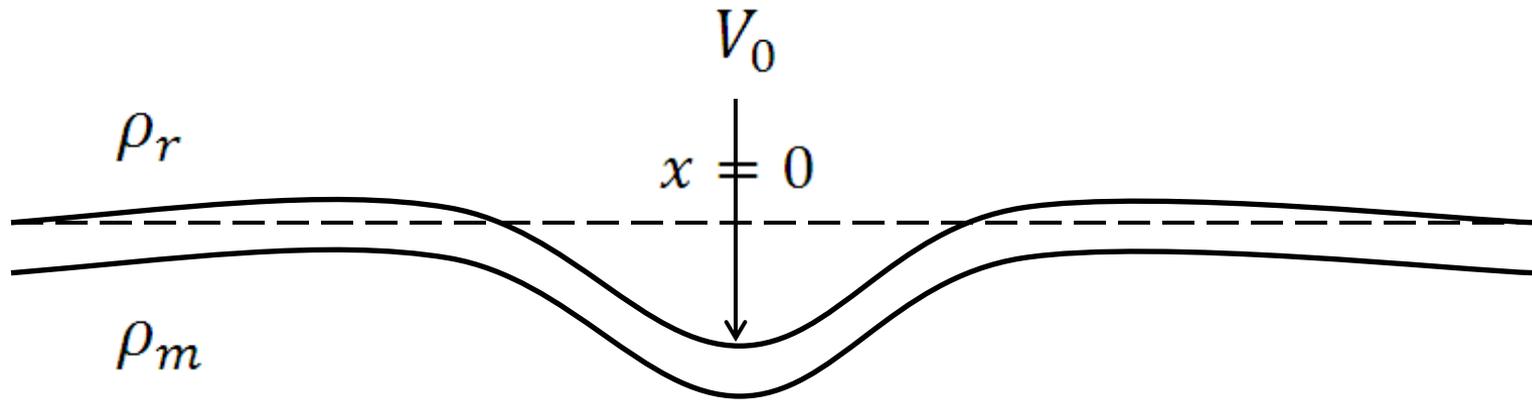
$$\cancel{\rho_c g h_c} + \cancel{\rho_m g H} = \rho_0 g h + \cancel{\rho_c g h_c} + \rho_m g (H - w)$$

$$0 = \rho_0 g h - \rho_m g w$$

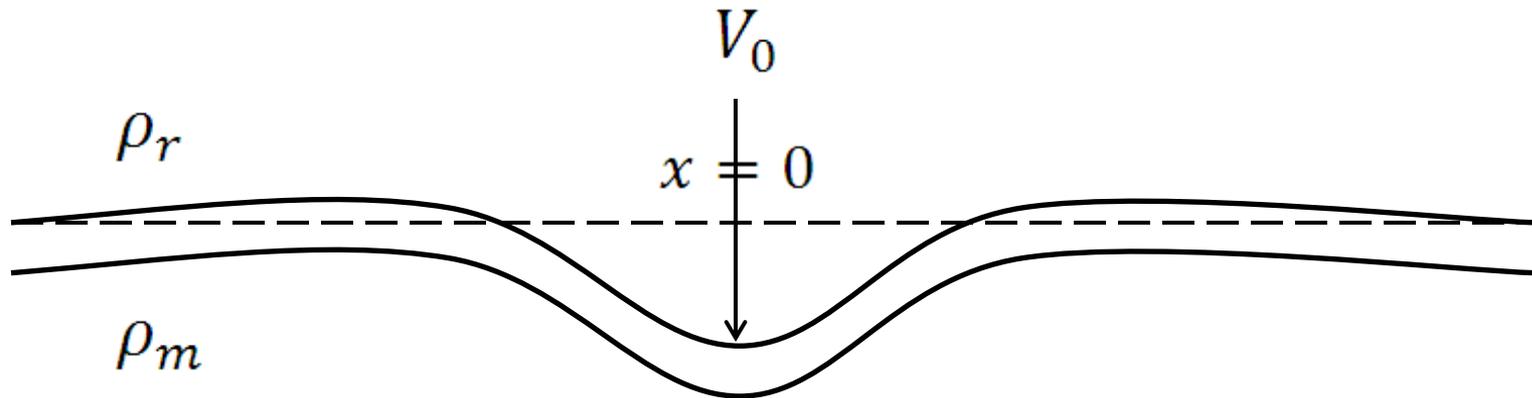
# Soluções Analíticas



# Soluções Analíticas



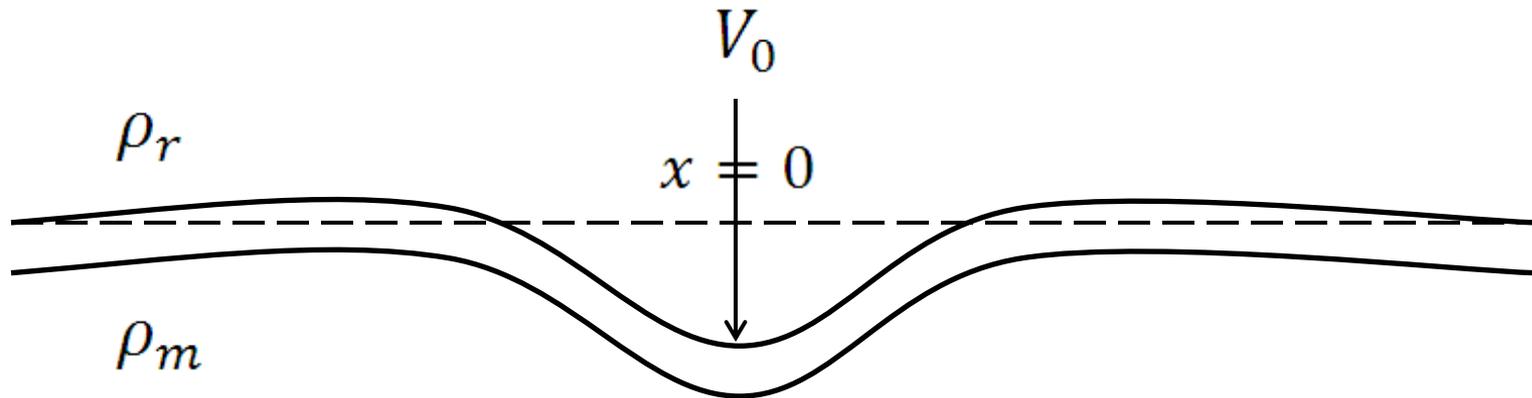
# Soluções Analíticas



Para  $x \neq 0$

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = 0$$

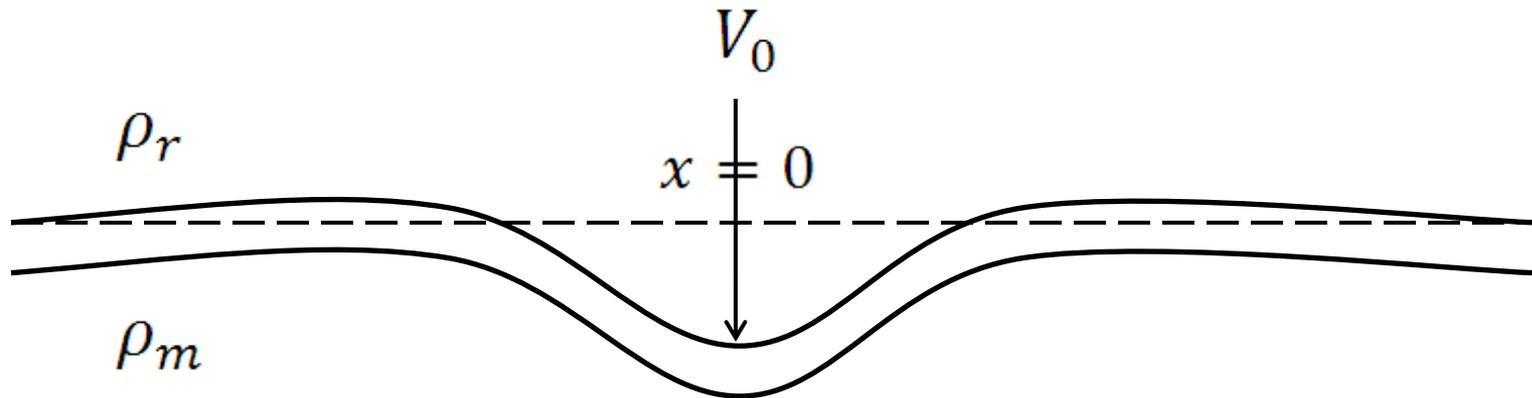
# Soluções Analíticas



Para  $x \neq 0$  
$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = 0$$

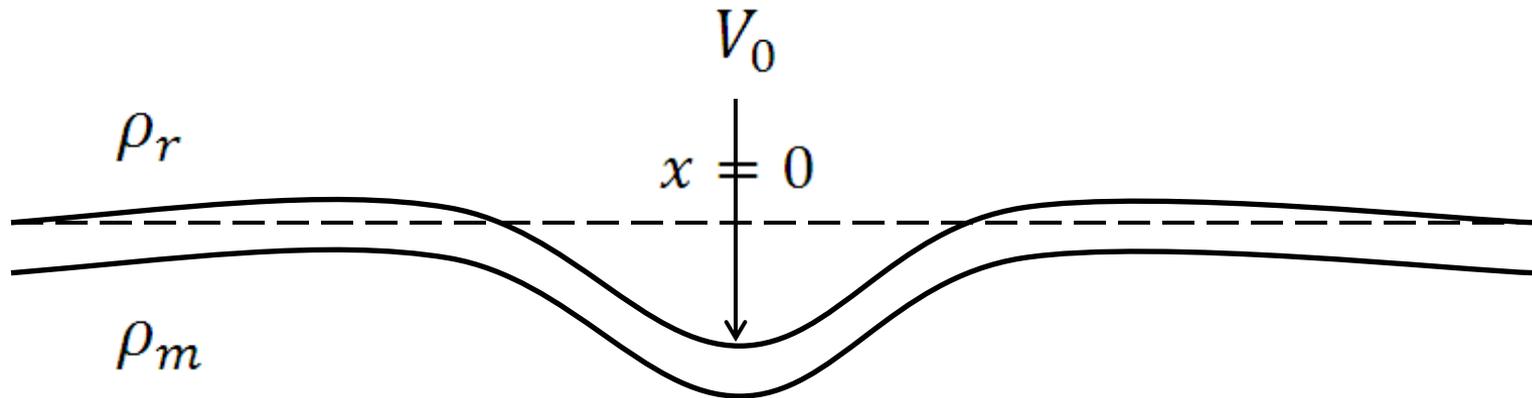
Para  $D$  constante 
$$D \frac{d^4 w}{dx^4} + (\rho_m - \rho_r) g w = 0$$

# Soluções Analíticas



$$D \frac{d^4 w}{dx^4} + (\rho_m - \rho_r) g w = 0$$

# Soluções Analíticas

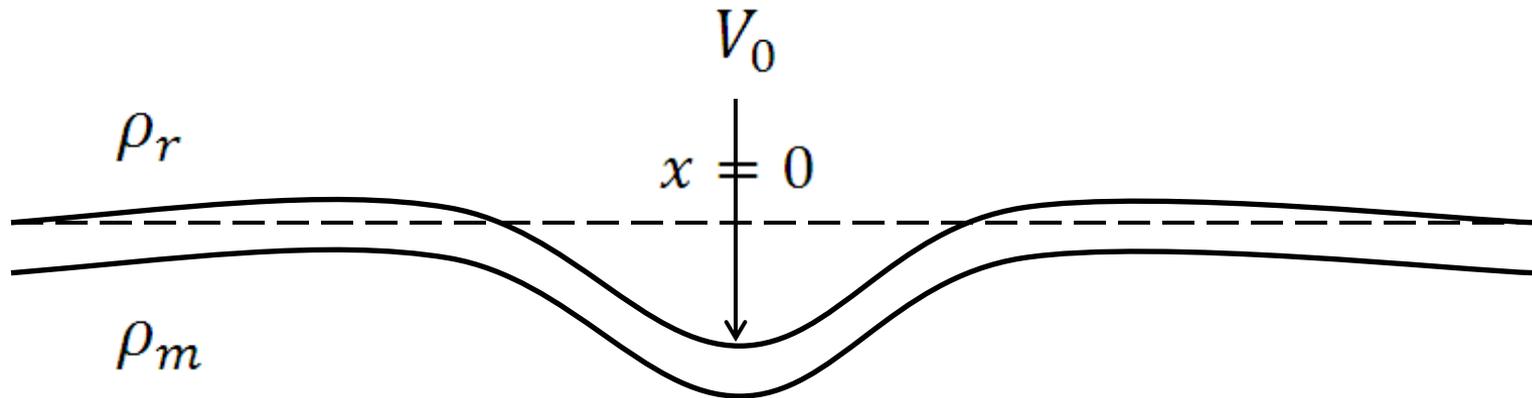


$$D \frac{d^4 w}{dx^4} + (\rho_m - \rho_r) g w = 0$$

$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

$$\lambda = \left[ \frac{(\rho_m - \rho_r) g}{4D} \right]^{1/4}$$

# Soluções Analíticas

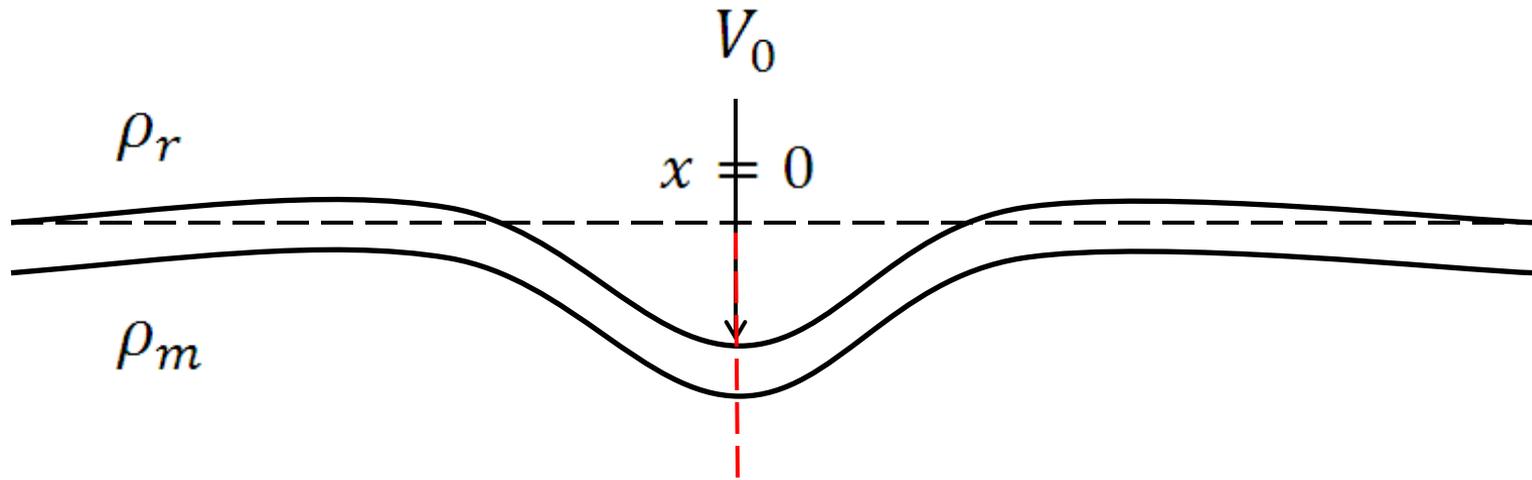


$$D \frac{d^4 w}{dx^4} + (\rho_m - \rho_r) g w = 0$$

$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

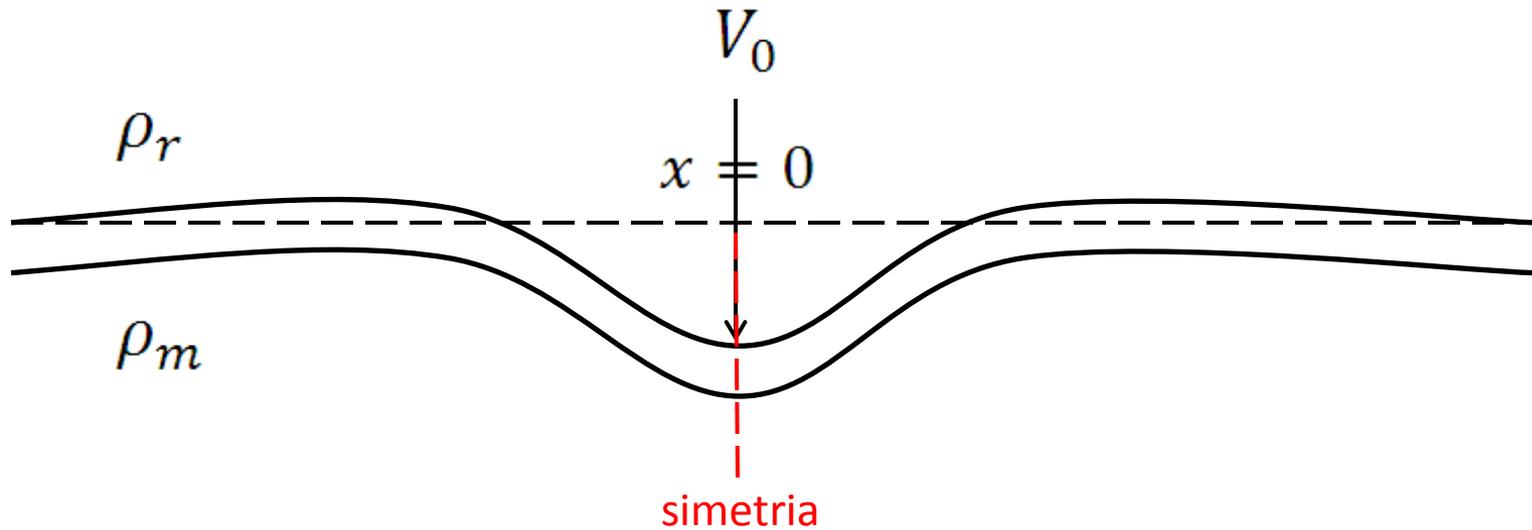
$$\lambda = \left[ \frac{(\rho_m - \rho_r) g}{4D} \right]^{1/4}$$

# Soluções Analíticas



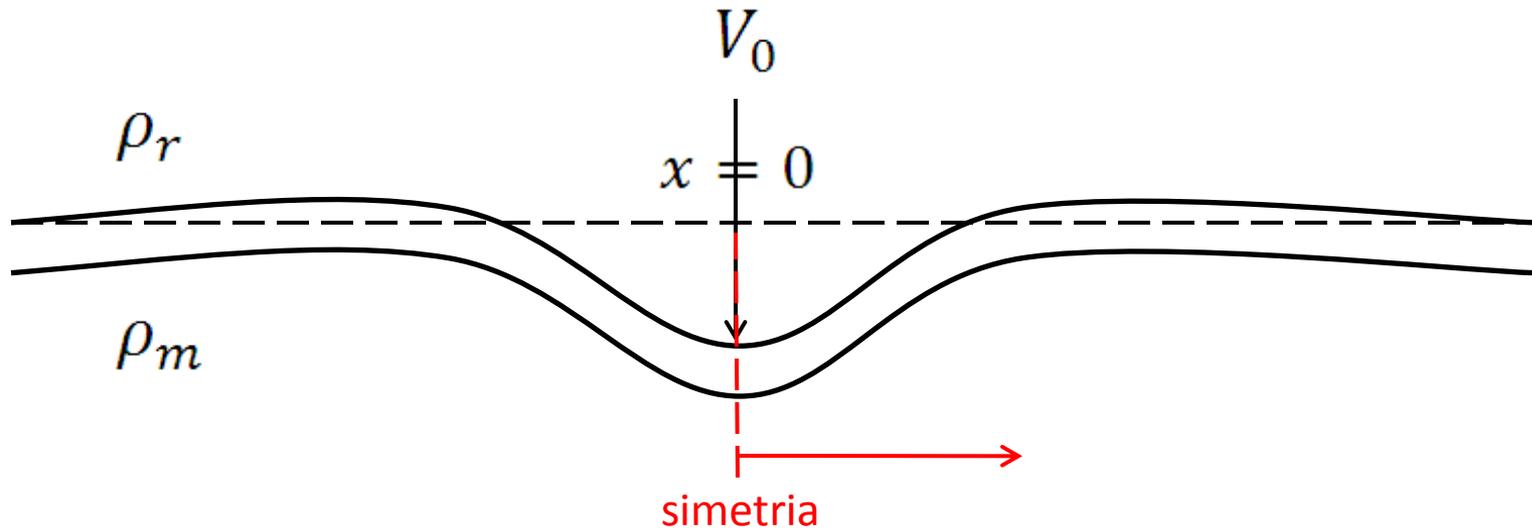
$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

# Soluções Analíticas



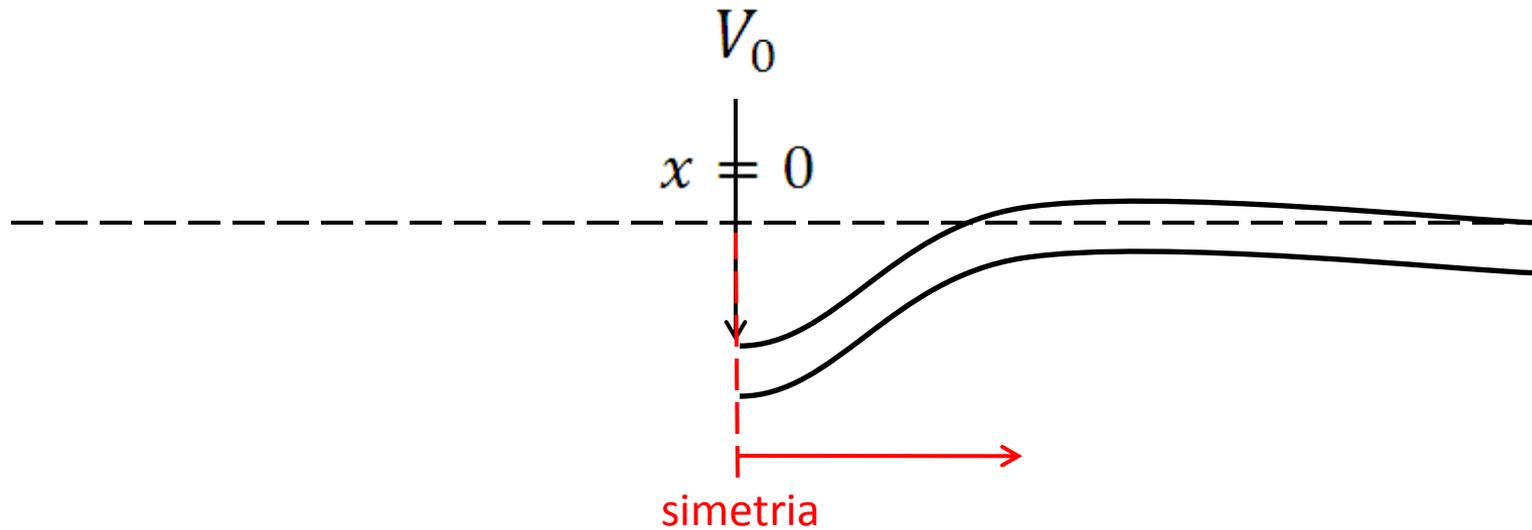
$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

# Soluções Analíticas



$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

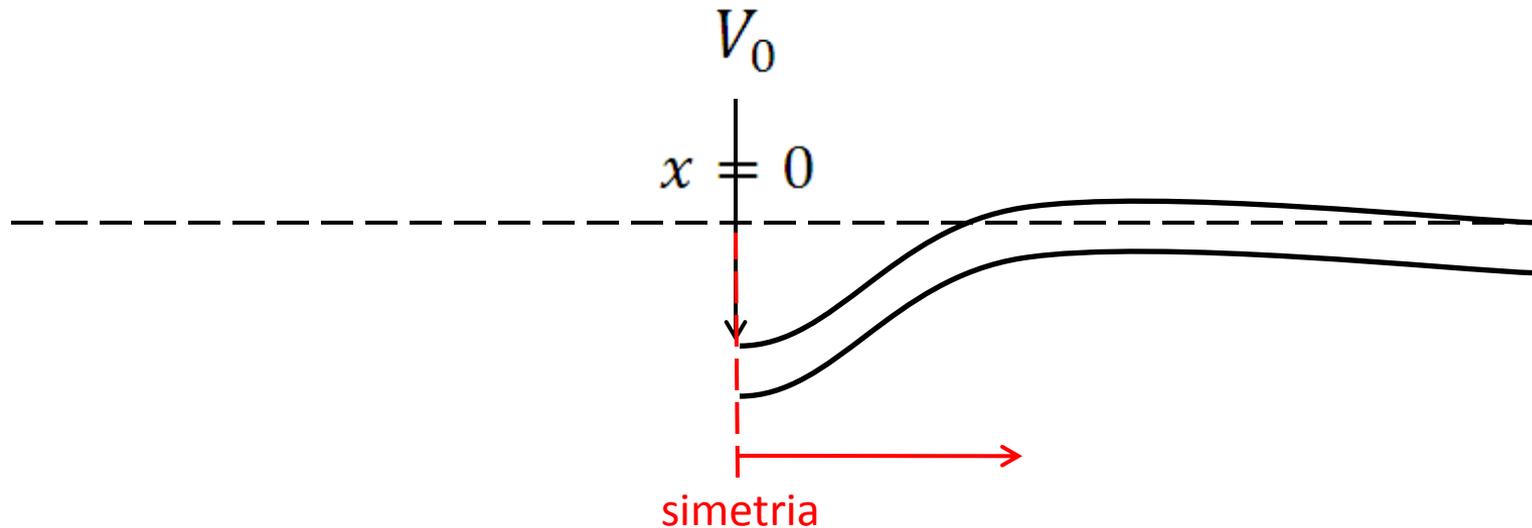
# Soluções Analíticas



$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

Para  $x \rightarrow +\infty$

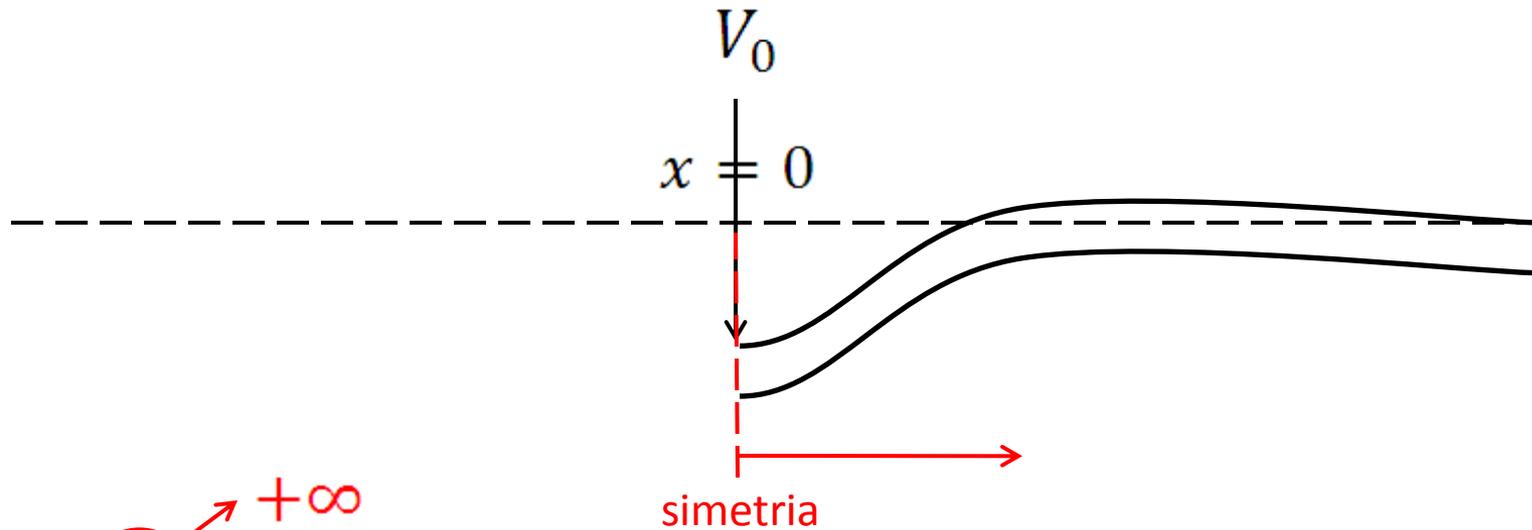
# Soluções Analíticas



$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

Para  $x \rightarrow +\infty$       $w \rightarrow 0$

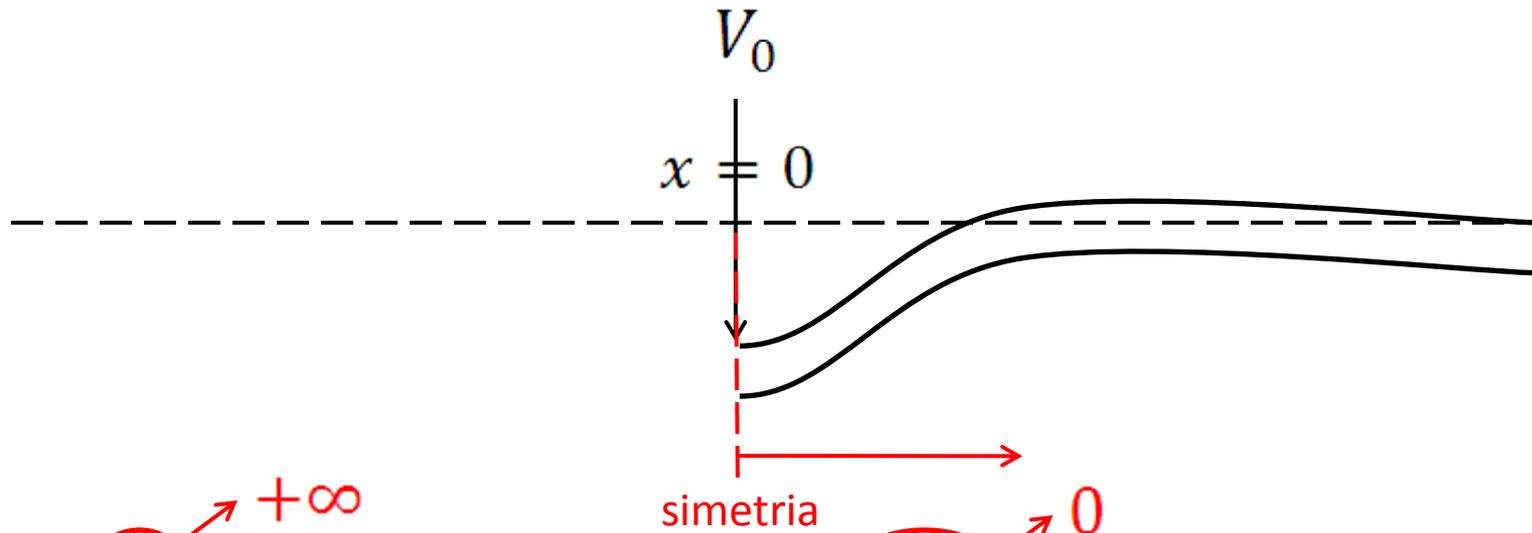
# Soluções Analíticas



$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

Para  $x \rightarrow +\infty$        $w \rightarrow 0$

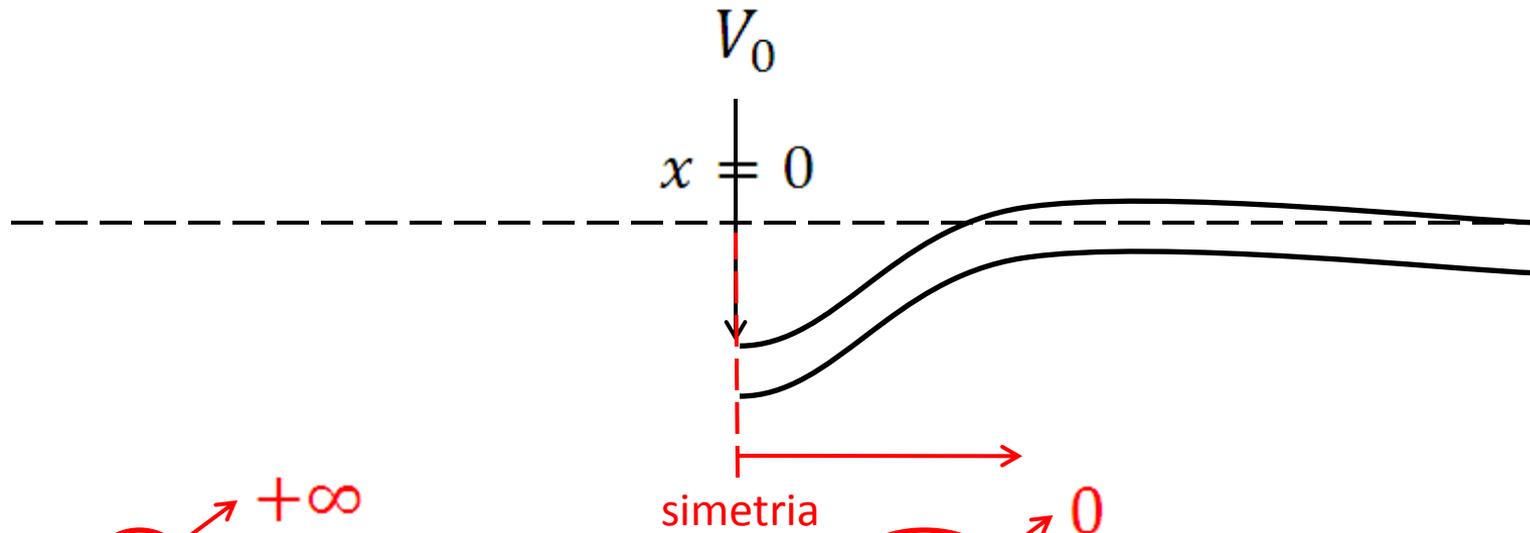
# Soluções Analíticas



$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

Para  $x \rightarrow +\infty$        $w \rightarrow 0$

# Soluções Analíticas

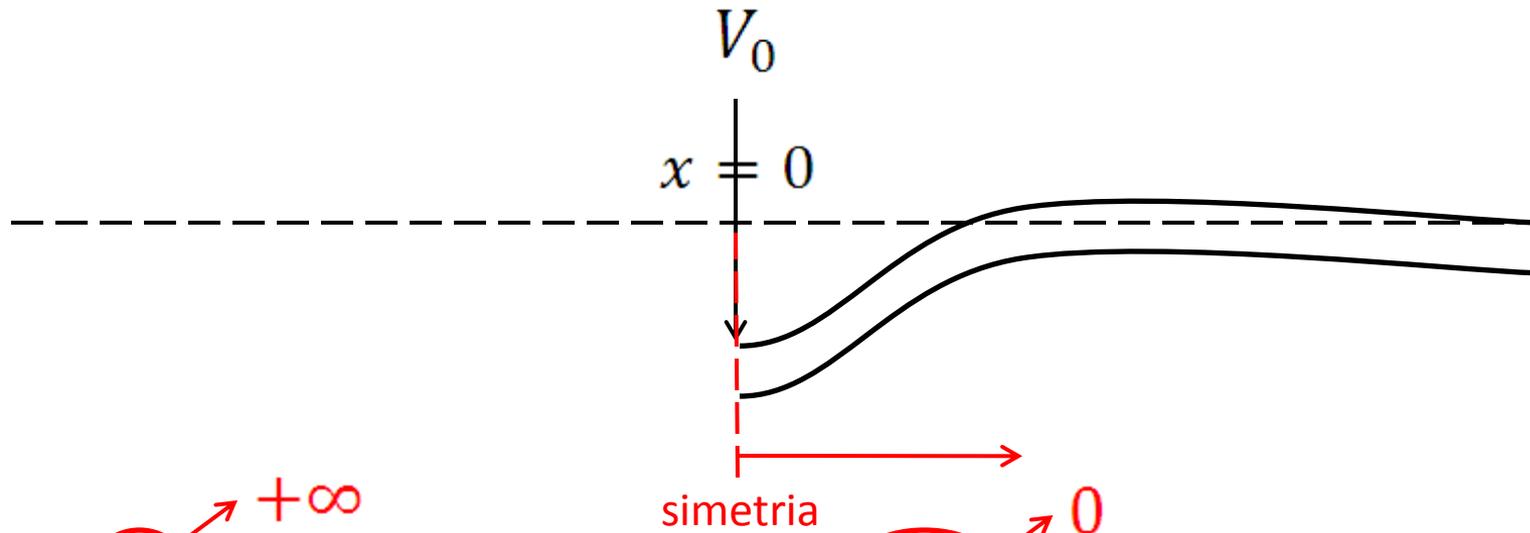


$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

Para  $x \rightarrow +\infty$        $w \rightarrow 0$

$$A_c = 0, B_c = 0$$

# Soluções Analíticas



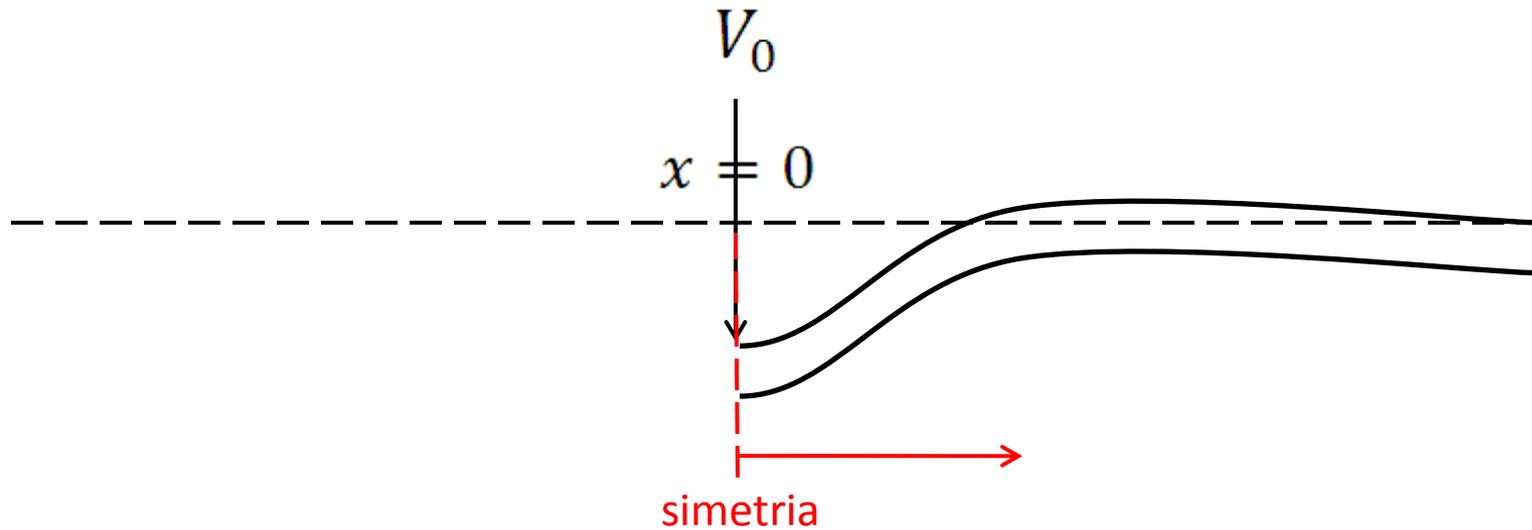
$$w = e^{\lambda x} (A_c \cos \lambda x + B_c \sin \lambda x) + e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

$$\text{Para } x \rightarrow +\infty \quad w \rightarrow 0$$

$$A_c = 0, B_c = 0$$

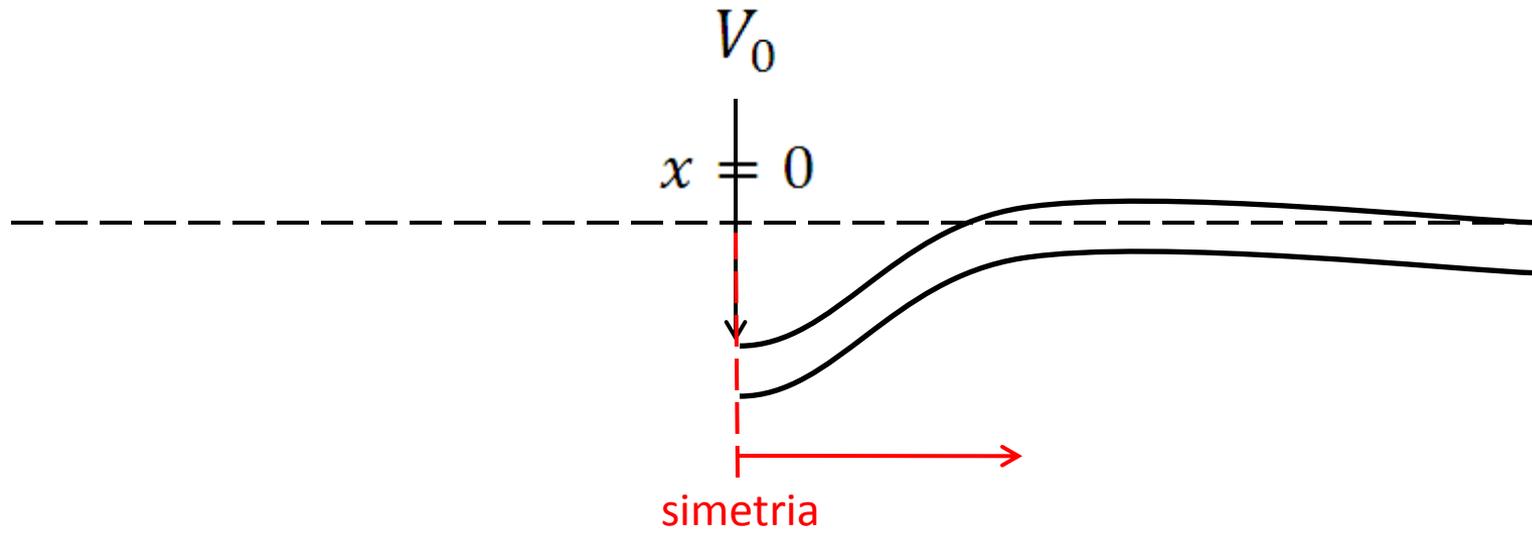
$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

# Soluções Analíticas



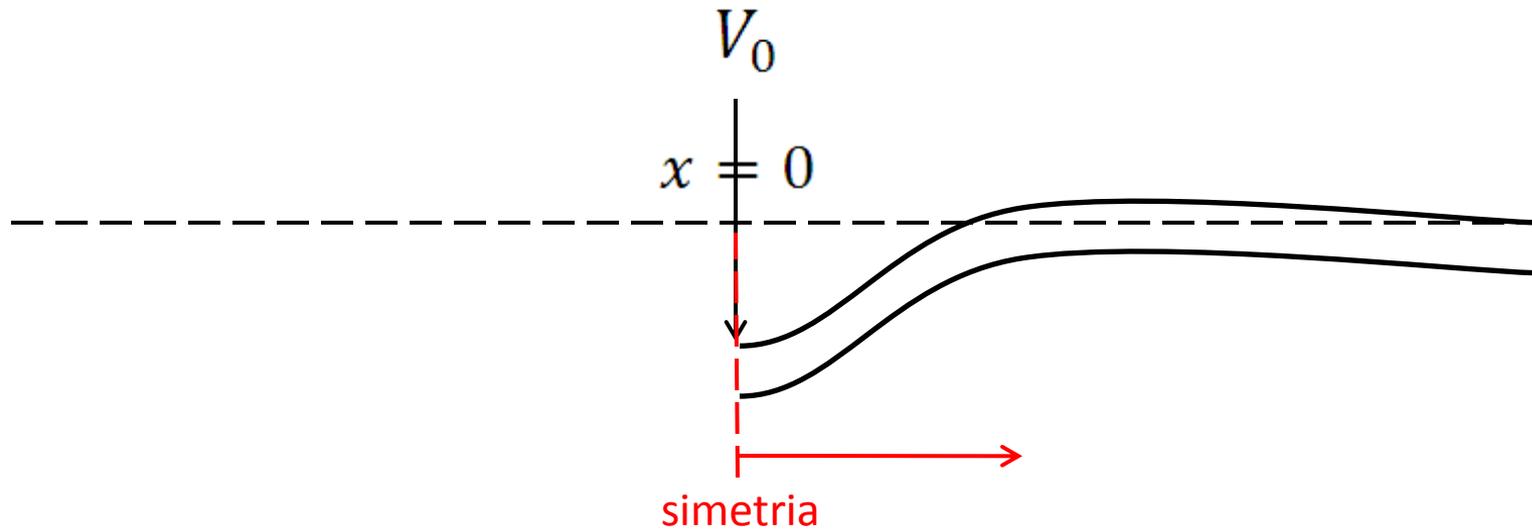
$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x)$$

# Soluções Analíticas



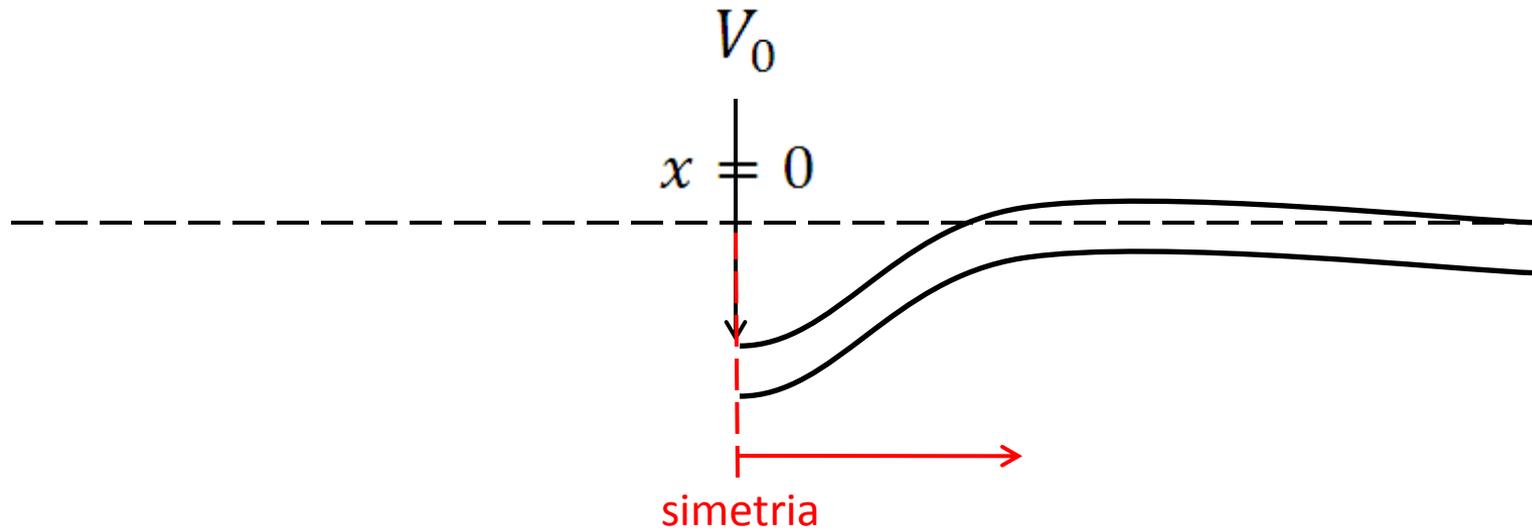
$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0$$

# Soluções Analíticas



$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

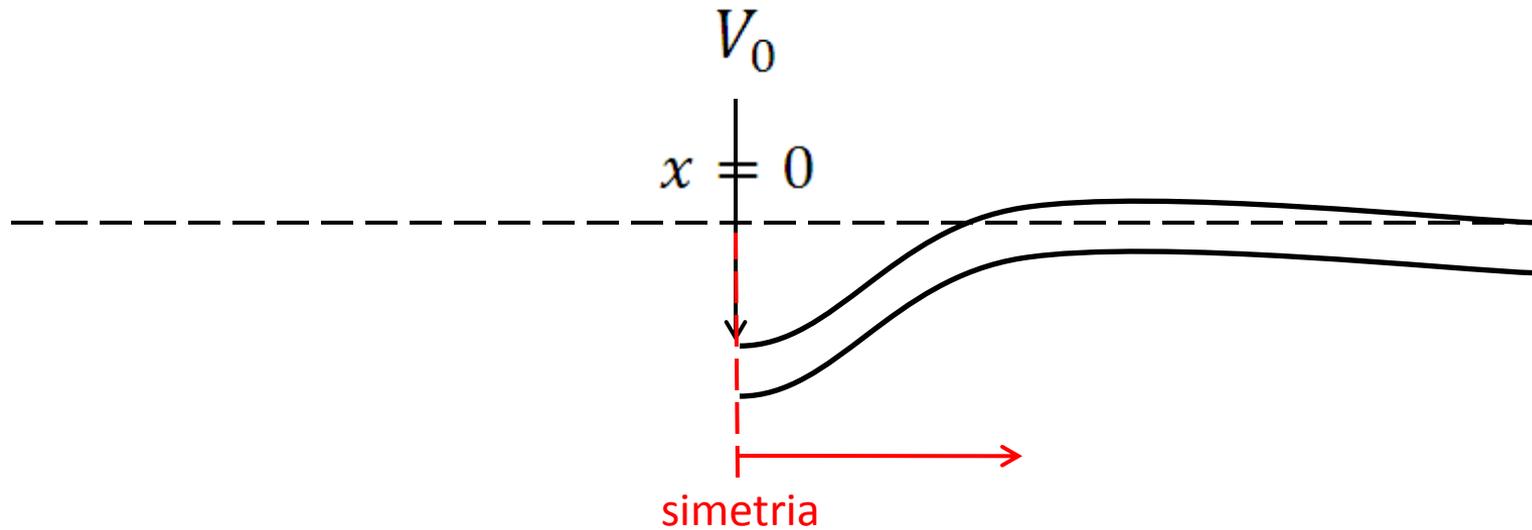
# Soluções Analíticas



$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

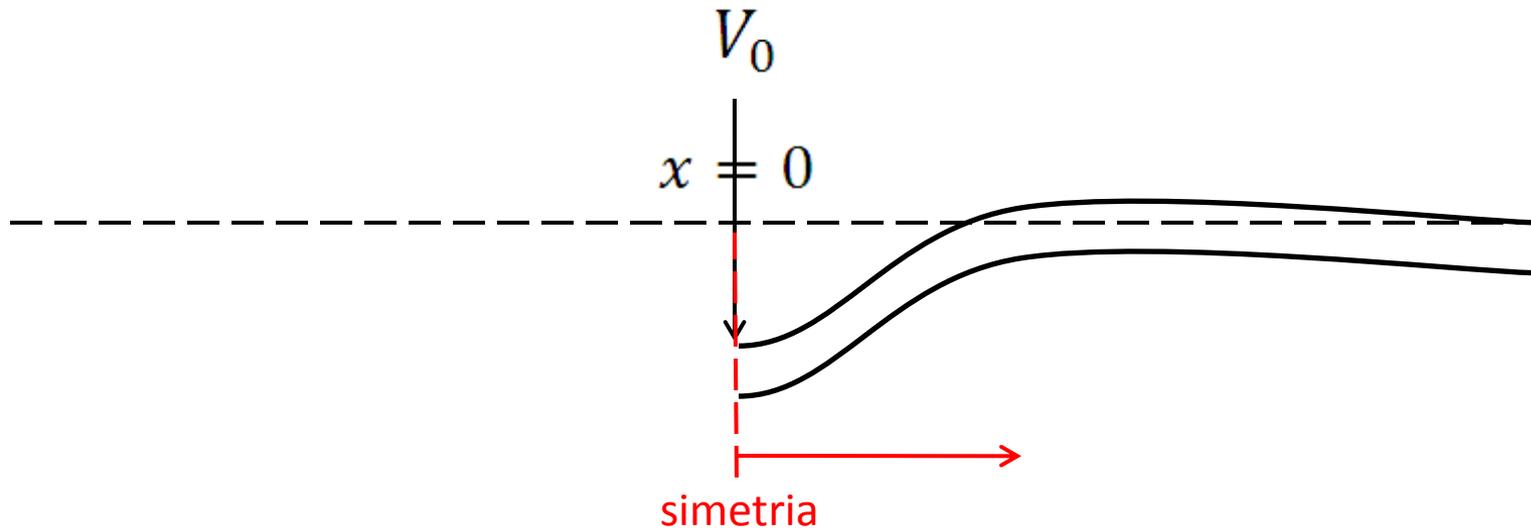
# Soluções Analíticas



$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

# Soluções Analíticas

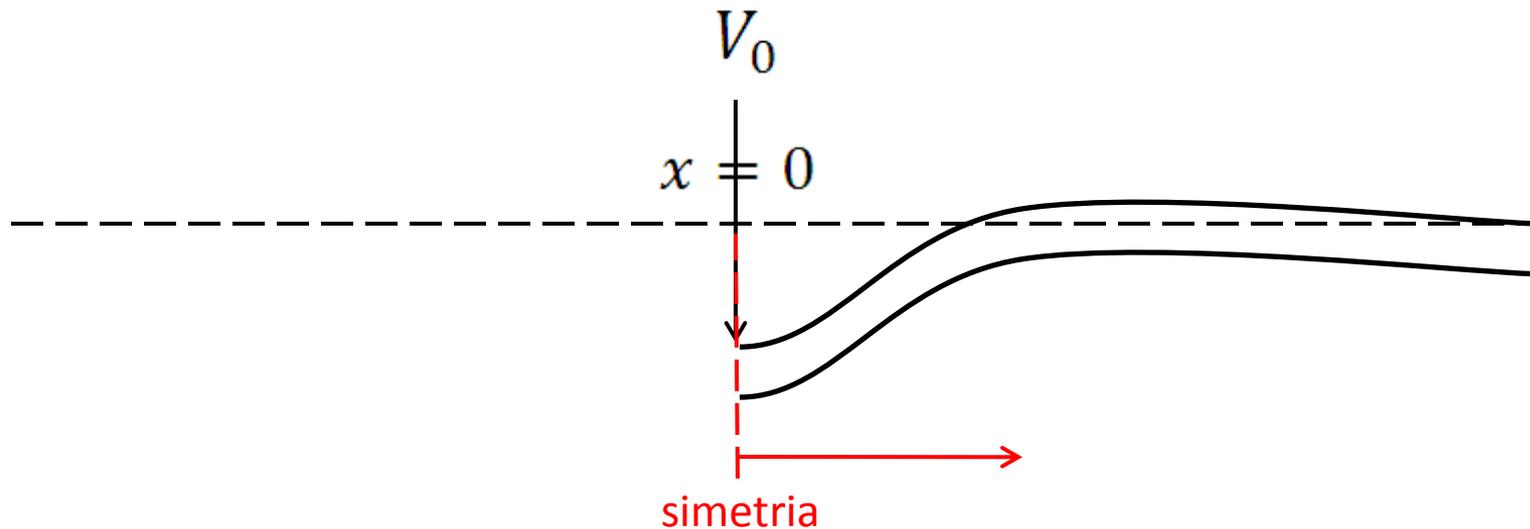


$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

1      0      0      1

# Soluções Analíticas

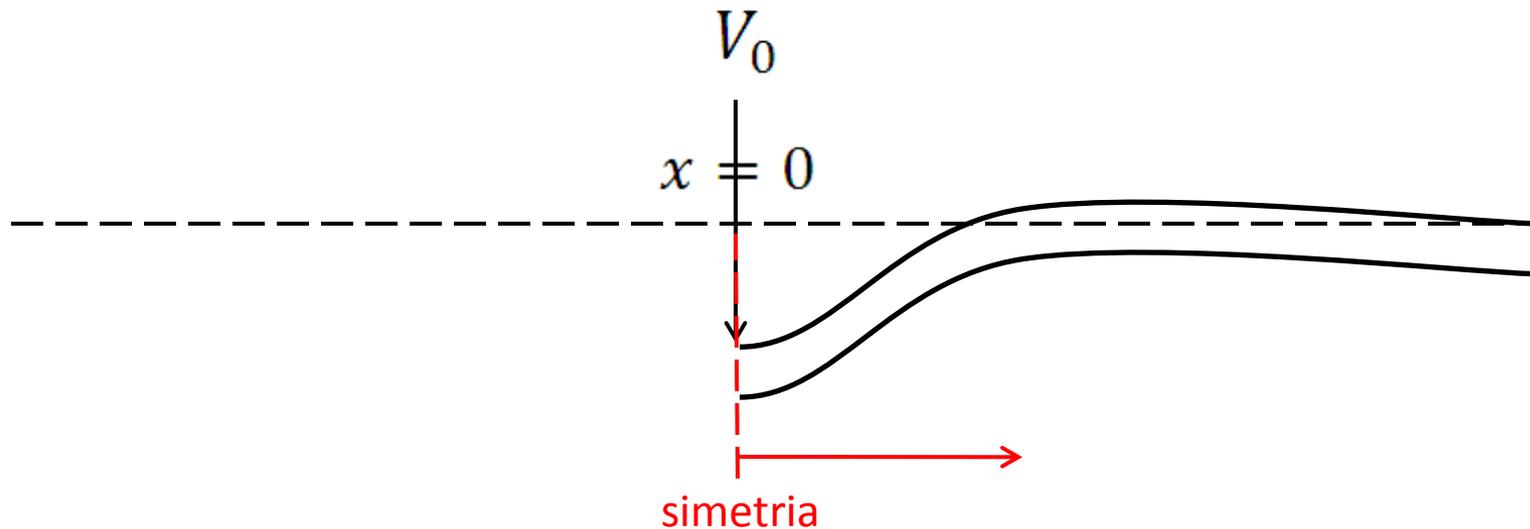


$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

Red arrows point from the terms in the derivative equation to the values 1 and 0, indicating the limits of the trigonometric functions as  $x \rightarrow 0$ .

# Soluções Analíticas



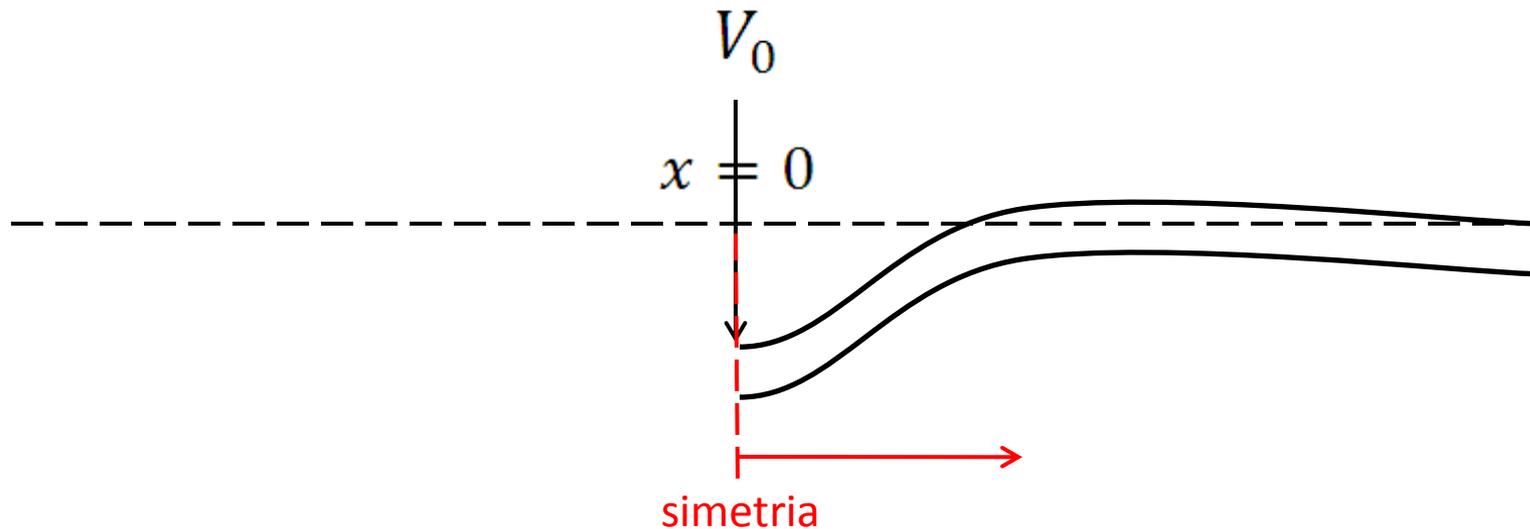
$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

Red arrows indicate the limits of the terms in the derivative equation as \$x \to 0\$: \$1\$ for \$\cos \lambda x\$, \$0\$ for \$\sin \lambda x\$, \$1\$ for \$\cos \lambda x\$, and \$0\$ for \$\sin \lambda x\$.

$$C_c(-\lambda) + D_c(\lambda) = 0$$

# Soluções Analíticas



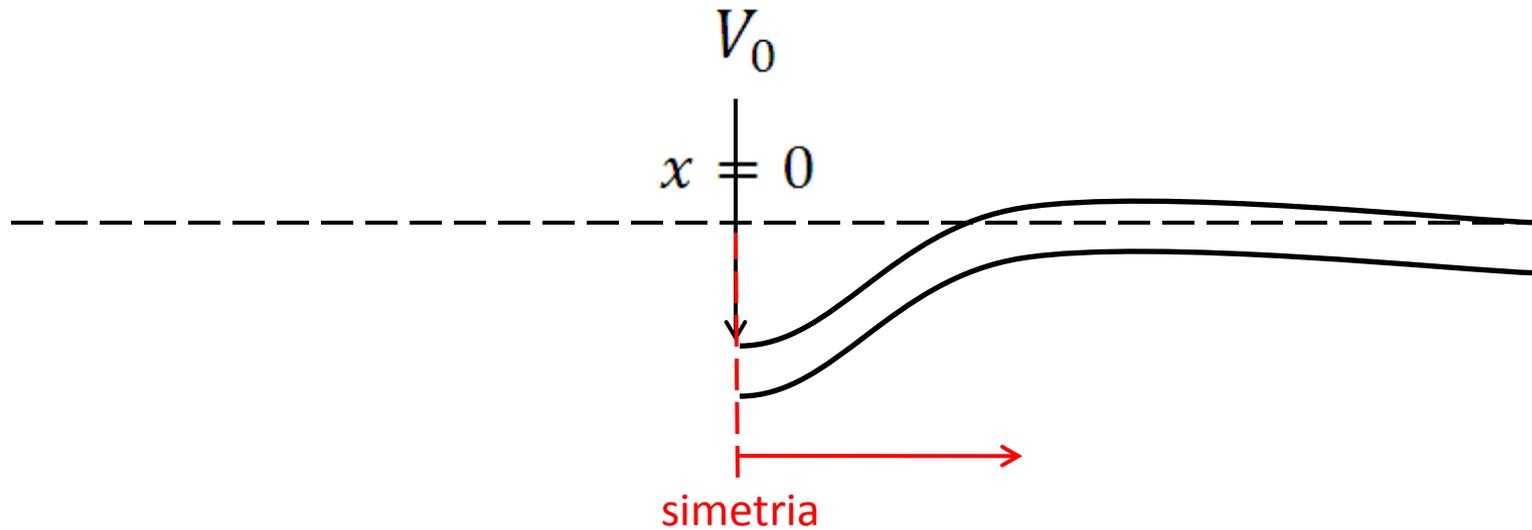
$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

Red arrows in the original image point to the terms in the derivative equation:  $\lambda$  (1),  $C_c$  (1),  $\cos \lambda x$  (1),  $D_c$  (1),  $\sin \lambda x$  (0),  $\lambda$  (1),  $e^{-\lambda x}$  (1),  $-C_c$  (1),  $\sin \lambda x$  (0),  $D_c$  (1),  $\cos \lambda x$  (1).

$$C_c(-\lambda) + D_c(\lambda) = 0 \rightarrow C_c = D_c$$

# Soluções Analíticas



$$w = e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) \quad \text{Para } x \rightarrow 0 \quad \frac{dw}{dx} \rightarrow 0$$

$$\frac{dw}{dx} = -\lambda e^{-\lambda x} (C_c \cos \lambda x + D_c \sin \lambda x) + \lambda e^{-\lambda x} (-C_c \sin \lambda x + D_c \cos \lambda x)$$

Red arrows point from the terms in the derivative equation to the values 1 and 0, indicating the limits of the trigonometric functions at \$x=0\$.

$$C_c(-\lambda) + D_c(\lambda) = 0 \rightarrow C_c = D_c \rightarrow w = e^{-\lambda x} D_c (\cos \lambda x + \sin \lambda x)$$

# Soluções Analíticas

$$w = e^{-\lambda x} D_c(\cos \lambda x + \sin \lambda x)$$

# Soluções Analíticas

$$w = e^{-\lambda x} D_c (\cos \lambda x + \sin \lambda x)$$

$$V_0 - 2(\rho_m - \rho_r)g \int_0^{\infty} w dx = 0$$

# Soluções Analíticas

$$w = e^{-\lambda x} D_c(\cos \lambda x + \sin \lambda x)$$

$$V_0 - 2(\rho_m - \rho_r)g \int_0^{\infty} w dx = 0 \rightarrow \int_0^{\infty} w dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

# Soluções Analíticas

$$w = e^{-\lambda x} D_c (\cos \lambda x + \sin \lambda x)$$

$$V_0 - 2(\rho_m - \rho_r)g \int_0^{\infty} w dx = 0 \rightarrow \int_0^{\infty} w dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

$$\rightarrow D_c \int_0^{\infty} e^{-\lambda x} (\cos \lambda x + \sin \lambda x) dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

# Soluções Analíticas

$$w = e^{-\lambda x} D_c (\cos \lambda x + \sin \lambda x)$$

$$V_0 - 2(\rho_m - \rho_r)g \int_0^{\infty} w dx = 0 \rightarrow \int_0^{\infty} w dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

$$\rightarrow D_c \int_0^{\infty} e^{-\lambda x} (\cos \lambda x + \sin \lambda x) dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

$$\rightarrow D_c \left[ -\frac{e^{-\lambda x}}{\lambda} \cos \lambda x \right] \Big|_0^{\infty} = \frac{V_0}{2(\rho_m - \rho_r)g}$$

# Soluções Analíticas

$$w = e^{-\lambda x} D_c (\cos \lambda x + \sin \lambda x)$$

$$V_0 - 2(\rho_m - \rho_r)g \int_0^{\infty} w dx = 0 \rightarrow \int_0^{\infty} w dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

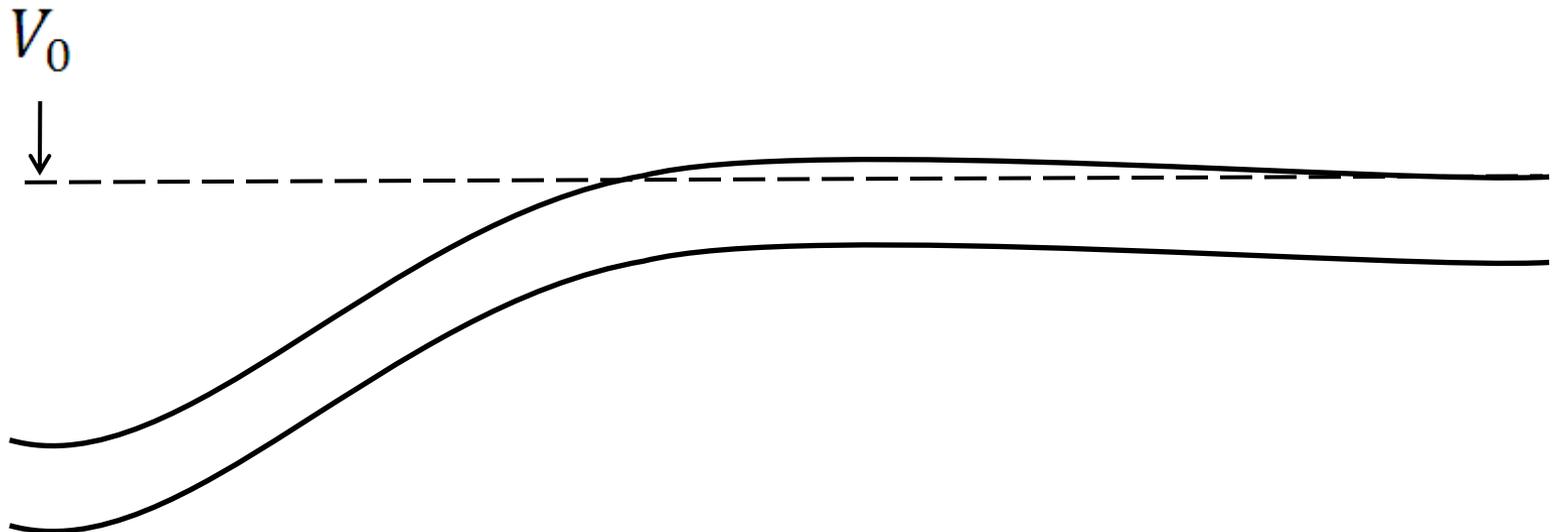
$$\rightarrow D_c \int_0^{\infty} e^{-\lambda x} (\cos \lambda x + \sin \lambda x) dx = \frac{V_0}{2(\rho_m - \rho_r)g}$$

$$\rightarrow D_c \left[ -\frac{e^{-\lambda x}}{\lambda} \cos \lambda x \right] \Big|_0^{\infty} = \frac{V_0}{2(\rho_m - \rho_r)g}$$

$$\rightarrow D_c \cdot \frac{1}{\lambda} = \frac{V_0}{2(\rho_m - \rho_r)g}$$

# Soluções Analíticas

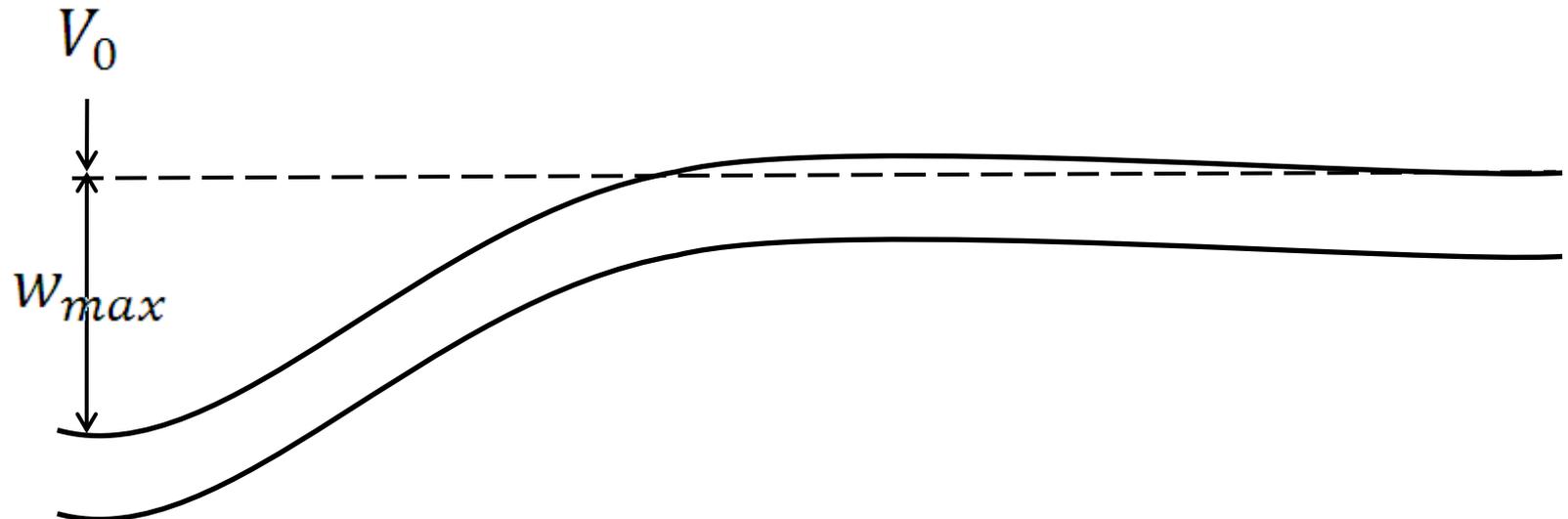
$$w = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g} e^{-\lambda x} (\cos \lambda x + \sin \lambda x)$$



# Soluções Analíticas

$$w = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g} e^{-\lambda x} (\cos \lambda x + \sin \lambda x)$$

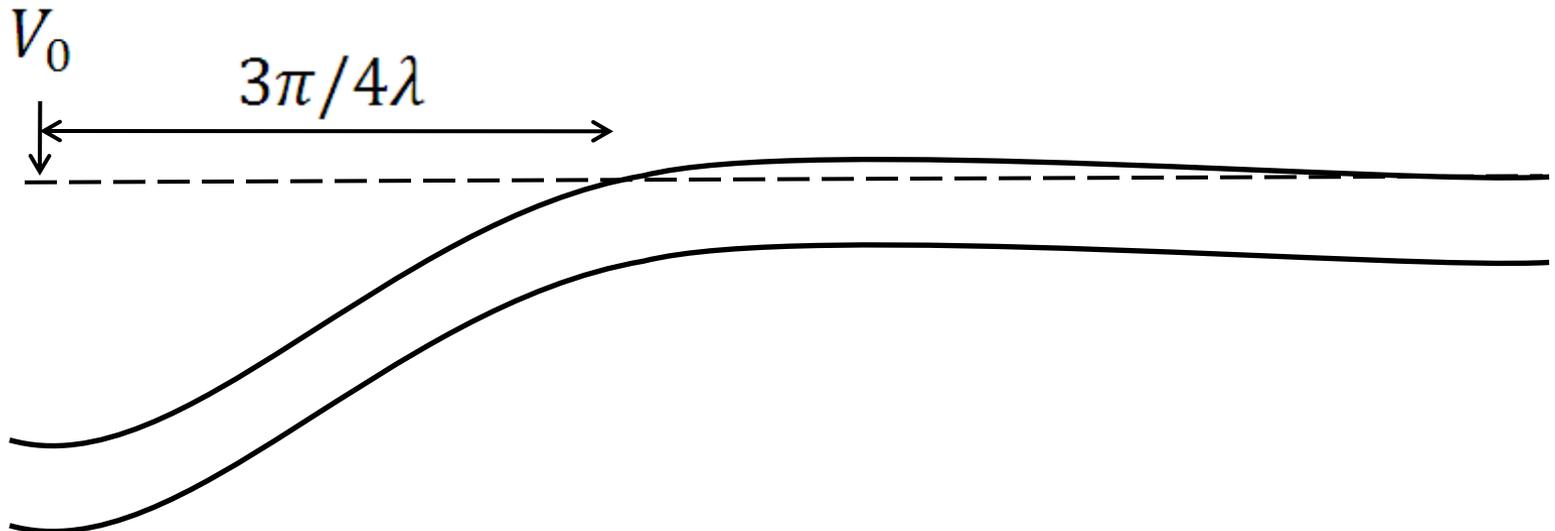
$$x = 0, \quad w = w_{max} = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g}$$



# Soluções Analíticas

$$w = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g} e^{-\lambda x} (\cos \lambda x + \sin \lambda x)$$

$$w = 0, \quad x = \frac{3\pi}{4\lambda}, \frac{7\pi}{4\lambda}, \dots$$

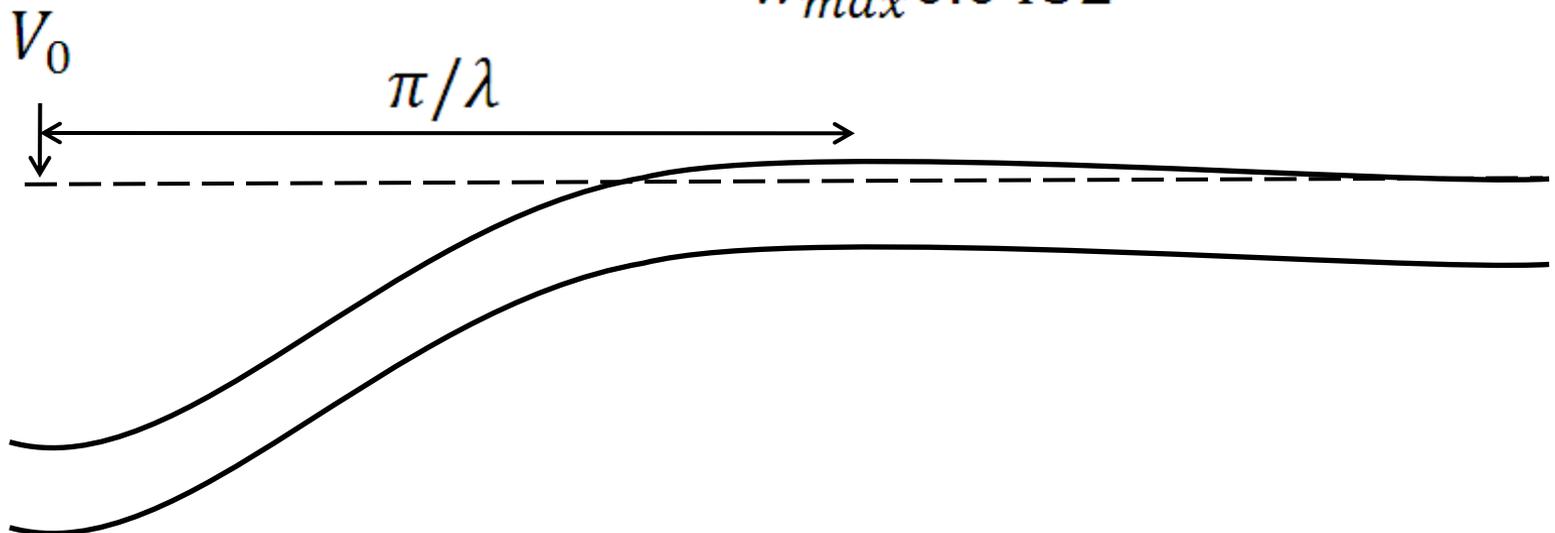


# Soluções Analíticas

$$w = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g} e^{-\lambda x} (\cos \lambda x + \sin \lambda x)$$

$$x = \frac{\pi}{\lambda}, \quad w_b = w_{max} e^{-\pi} (\cos \pi + \sin \pi)$$

$$\approx -w_{max} 0.0432$$



# Implementação

$$w = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g} e^{-\lambda x} (\cos \lambda x + \sin \lambda x)$$

$$\lambda = \left[ \frac{(\rho_m - \rho_r)g}{4D} \right]^{1/4}$$

$$D = \frac{ET_e^3}{12(1 - \nu^2)}$$

$$E = 1 \times 10^{11} \text{ N/m}^2$$

$$\nu = 0.25$$

$$g = 9.8 \text{ m/s}^2$$

$T_e$  e  $V_0$  variáveis

# Implementação

$$w = \frac{V_0 \lambda}{2(\rho_m - \rho_r)g} e^{-\lambda x} (\cos \lambda x + \sin \lambda x)$$

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$T_e$  e  $V_0$  variáveis