



PMR 5020 Modelagem do Projeto de Sistemas

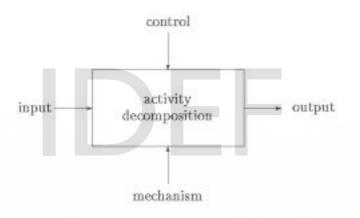
Aula 8: Paradigmas e métodos formais especificação de projeto

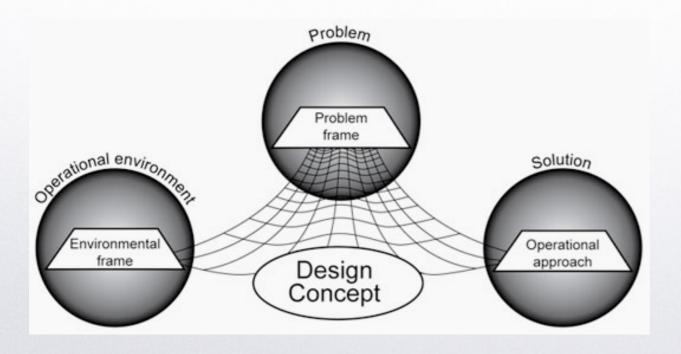


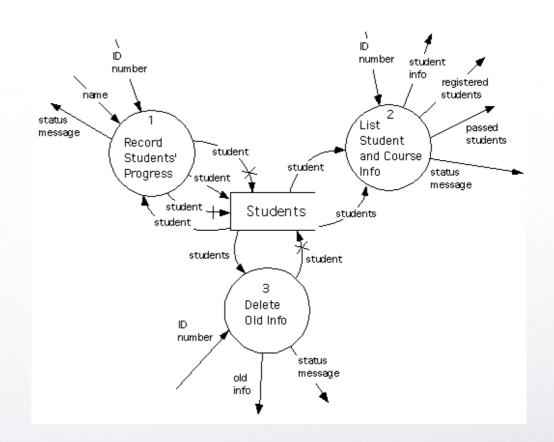




O primeiro paradigma







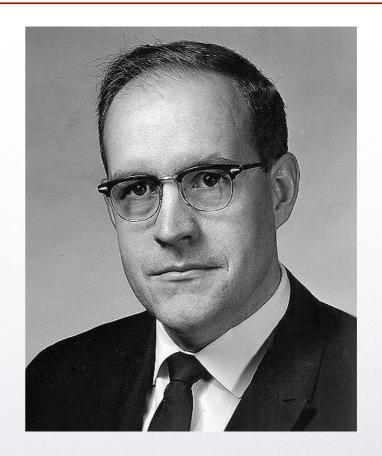






On February 19, 1985, Fred Brooks was one of three former IBM employees to receive the first National Technology Medal from U.S. President Ronald Reagan. Brooks, <u>Erich Bloch</u> and <u>Bob O. Evans</u> were recognized for their contributions to the development of the IBM System/360, which helped to revolutionize the data processing industry.

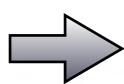
"The hardest single part of building a software system is deciding precisely what to build. No other part of the conceptual work is as difficult as establishing the detailed technical requirements: No other part of the work so cripples the resulting system if done wrong. No other part is as difficult to rectify later. "







state-transition methods



No.	Attribute	Values
1	paradigm	state machine, algebra, process algebra, trace
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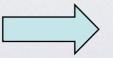




Modelagem Estado-Transição

- Estados e transições são noções distintas e intercaladas (no sentido de que estados são adjacentes a transições e vice-versa);
- Ambos, estados e transições são entidades distribuídas;
- A extensão das mudanças de causadas por uma transição é restrita ao escopo da mudança de estado (afeta portanto somente aos estados que antecedem e sucedem a transição);
- Uma transição (distribuída) t está habilitada em um estado (distribuído) s <u>sse</u> todas as componentes de t estiverem habilitadas e puderem ocorrer;

Sistema de Estados Finitos



Modelagem Estado-Transição







(State) - Transition Systems: A Logic definition

DEFINITION 13.1 (Transition System) A transition system is a tuple $\mathbb{S} = (S, In, T, \mathcal{X}, dom, L)$, where

- (1) S is a finite non-empty set, called the set of states of S.
- (2) $In \subseteq S$ is a non-empty set of states, called the set of *initial states* of S.
- (3) $T \subseteq S \times S$ is a set of pairs of states, called the *transition relation* of S.
- (4) \mathcal{X} is a finite set of state variables.
- (5) dom is a mapping from \mathcal{X} such that for each state variable $x \in \mathcal{X}$, dom(x) is a non-empty set, called the domain for x.
- (6) L is a function, called the *labeling function* of S. It will be explained later.

The transition system is said to be *finite-state* if for every state variable x, the domain dom(x) for this variable is finite.







Automation is allays defined for a partially ordered sequence of events (or actions) we call "process". Therefore if we are dealing with automated service design we should be aware of the processes this service generates to verify it.







Properties of systems

- safety: "the system never reaches a bad state"; in each state holds P
 - deadlock freedom
 - mutual exclusion etc.
- liveness: "there is progress in the system"; X occurs infinitely often
- fairness; once X has occurred, Y will occur in n steps
 - sent messages are eventually received
 - each request is served
- self-stabilisation: "the system recovers from a failure in a finite number of steps"







Representing time

Most properties on the previous slide can be formulated by combining two operations:

- finally in the future
- globally in the future

It must be chosen whether the present belongs to the future. Time can be described in several ways:

- global time or local time for each party
- linear or branching
- discrete or continuous

The time may be associated with the occurrences of events or with the state of the system at each moment.







Representing time: fixing the choices

- We use a discrete global time that is tied to the occurrences of events.
- The present belongs to the future.
- We mostly observe the states as a function of time, not the events.

One thing is difficult to solve: should the time be linear or branching?

LTL (linear temporal logic): the behaviour is a collection of infinite transition sequences

CTL (computational tree logic): the behaviour is an infinite transition tree

Each logic can express properties that cannot be represented in the other logic. The union of LTL and CTL, CTL* is even more *expressive*: it can express some properties that are beyond the power of both CTL and LTL.







Linear temporal logic LTL

- The state propositions or formulae (Φ : $p \in \Phi$ if p) map system states to truth values.
- The formulae $Fma(\Phi) \supset \Phi$ include state propositions and
 - the false proposition $\bot \in Fma(\Phi)$
 - implication: if $a \in Fma(\Phi)$ and $b \in Fma(\Phi)$ then $a \to b \in Fma(\Phi)$, and
 - the connective "globally": if $a \in Fma(\Phi)$ then $\Box a \in Fma(\Phi)$.

Other connectives can be expressed using these:

$$\neg a \Leftrightarrow a \to \bot \qquad \Diamond a \Leftrightarrow \neg \Box \neg a
a \lor b \Leftrightarrow (\neg a) \to b \qquad \top \Leftrightarrow \neg \bot
a \land b \Leftrightarrow \neg (a \to \neg b)$$

This is just one way of defining LTL and its basic connectives.



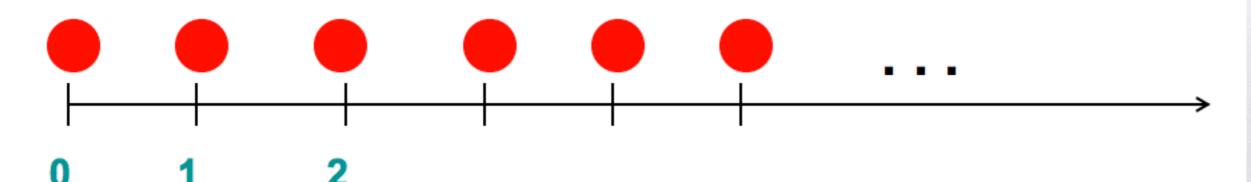




Globally (Always) p: G p

G p is true for a computation path if p holds at all states (points of time) along the path

Suppose G p holds along the path below starting at s₀





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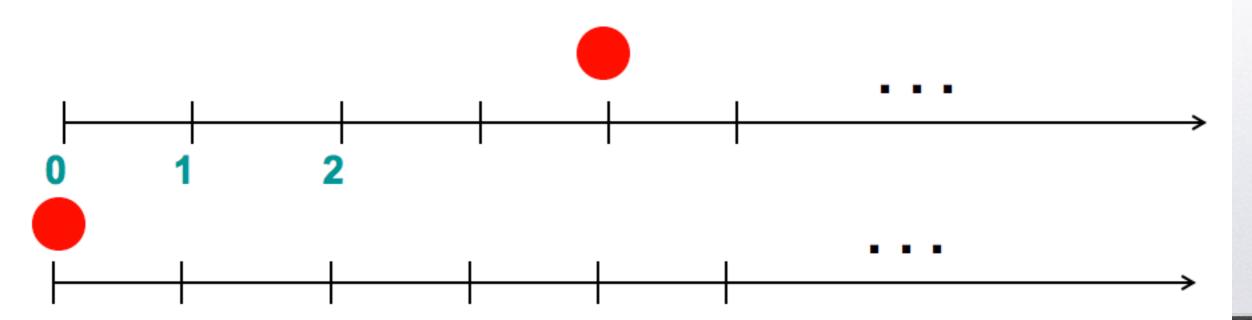




Eventually p: F p

 F p is true for a path if p holds at some state along that path

Does F p holds for the following examples?





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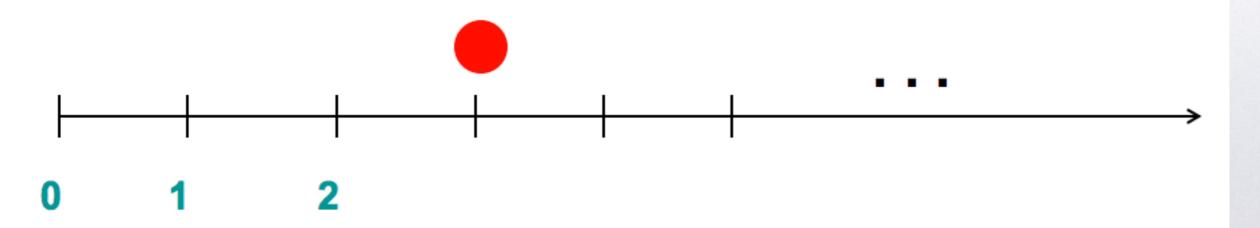




Next p: X p

 X p is true along a path starting in state s_i (suffix of the main path) if p holds in the next state s_{i+1}

Suppose X p holds along the path starting at state s₂









Notation

 Sometimes you'll see alternative notation in the literature:

G 🗆

F ◊

X °



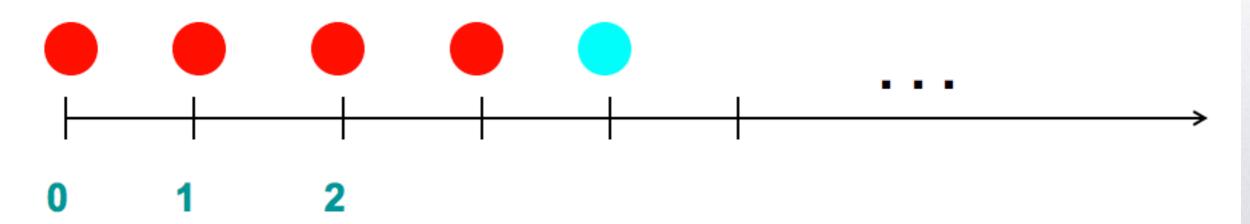




p Until q: p U q

- p U q is true along a path starting at s if
 - q is true in some state reachable from s
 - p is true in all states from s until q holds

Suppose p U q holds for the path below

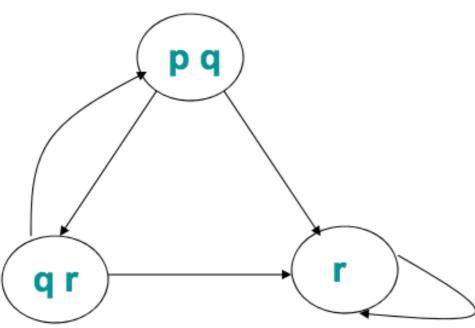




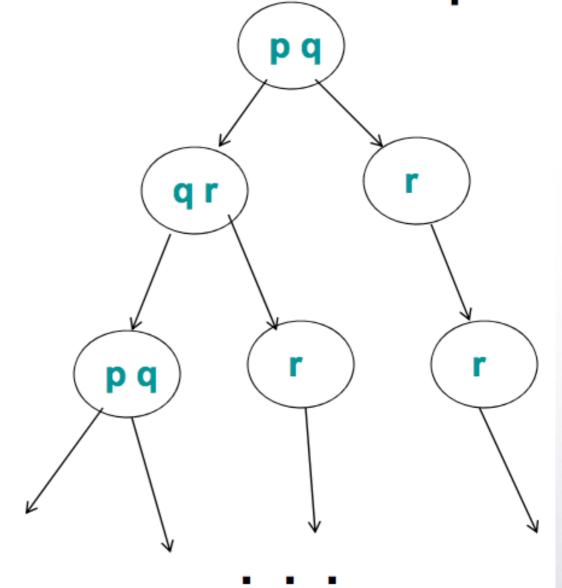




Labelled State Transition Graph



"Kripke structure"



Infinite Computation Tree







As a restriction let us now take a finite-state transition system where |S|=1, that is, where there is one and only one initial state and each transition does not depend on the previous state-transition history. These *dynamic systems* constitutes a special class of systems very important to engineering and theoretical computer science which we can call *machines* or *automaton*.





Modelagem baseada em autômatos

Def.] Um autômato finito é definido pela n-upla (Q, Σ , Q₀, R, T) onde,

Q é um conjunto de estados, Q ≠ Ø

• Σ é um conjunto finto de letras (eventos)

Q₀ é o estado inicial

 R é um conjunto de estados definidos como estados finais (ou de saída)

 T: Q X ∑ → Q, é um mapeamento de Q X ∑ em Q que denota as condições e o efeito para a ocorrência de uma transição.

O conjunto de eventos característicos de um sistema (autômato) está associado a uma linguagem formal determinada por seus processos aceitáveis.



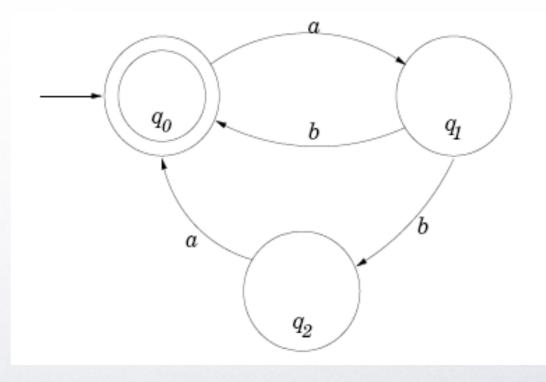




Um exemplo simples

Example: Consider the finite automaton M in Figure 1. In this case,

- $-Q = \{q0, q1, q2\}$
- -§ = {a, b}
- q1 = R(q0, a), q2 = R(q1, b), q0 = R(q2, a), q0 = R(q1, b) (note that R is not a function)
- Init = q0 (indicated by the straight arrow in Figure 1)
- F = q0 (indicated by a double circle in Figure 1)
- $-L(M) = {^2}$, ab, aba, abab, abaaba, . . .} = $((ab)^{x}(aba)^{x})^{x} \mu \S^{x}$
- non-deterministic









Redes de Petri



Tese de doutorado de Carl Adam Petri sobre comunicação entre autômatos, Kommunication mit Automaten, apresentada em 1962 no Schriften des Institutes Instrumentelle Matematik, Bonn.



Modelagem distribuída estado-transição





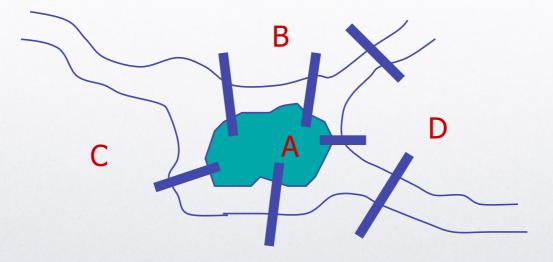


Teoria de Grafos: a base formal

O primeiro artigo sobre teoria de Grafos foi apresentado por Euler, onde o problema das pontes de Konisberg foi proposto.

L. Euler, 'Solutio Problematis Ad geometriam Situs Pertinentis', Commenrarii Academiae Sciencitiarum Imperialis Petropolitanae 8 (1736), pp. 128-140.

O teor do artigo consistia em mostrar que existe uma classe de problemas que pode ser formalizado por relações de adjacência e de forma independente dos aspectos geométricos.





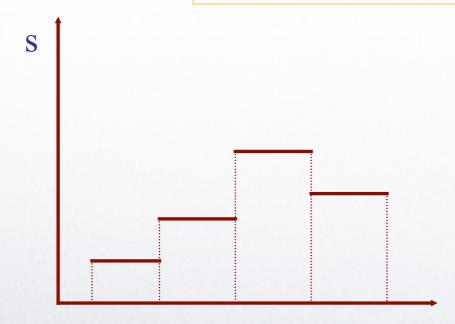
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Sistemas Discretos: a Inspiração

Eventos causam uma mudança instantânea no estado



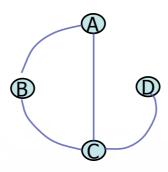


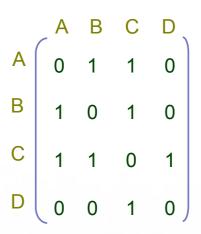




Representação de Grafos no computador

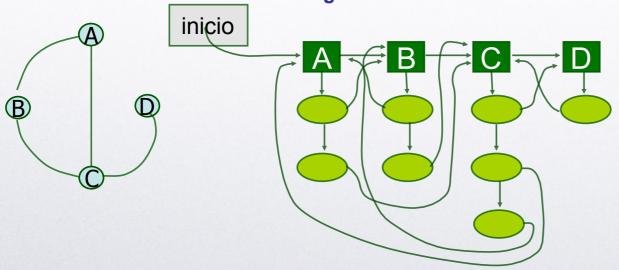
Grafos podem ser representados em duas estruturas de dados básicas: a matriz de incidência e o vetor adjacências





Vetor de adjacências

Uma representação pictórica desta estrutura de dados é mostrada a seguir.





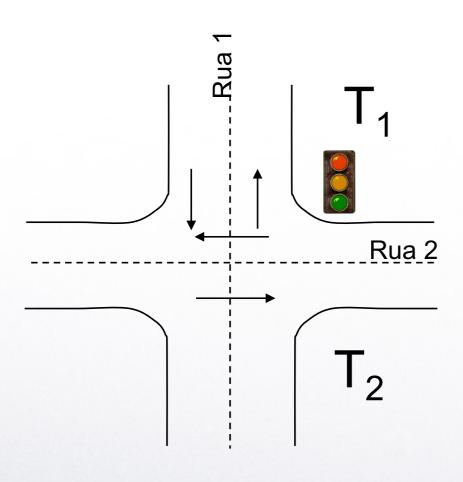


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Um exemplo realístico: semáforo em "dois tempos"



O Semáforo em dois tempos corresponde a um sistema simples com dois <u>estados</u>: aberto para a Rua 1 e aberto para a Rua 2. Tem ainda a restrição expressa pela seguinte expressão: ou o semáforo está aberto para a Rua 1 OU está aberto para a Rua 2

aberto R1		aberto R2	aberto R1 OU R2	
	V	V	F	
	V	F	V	
	F	V	V	
	F	F	F	

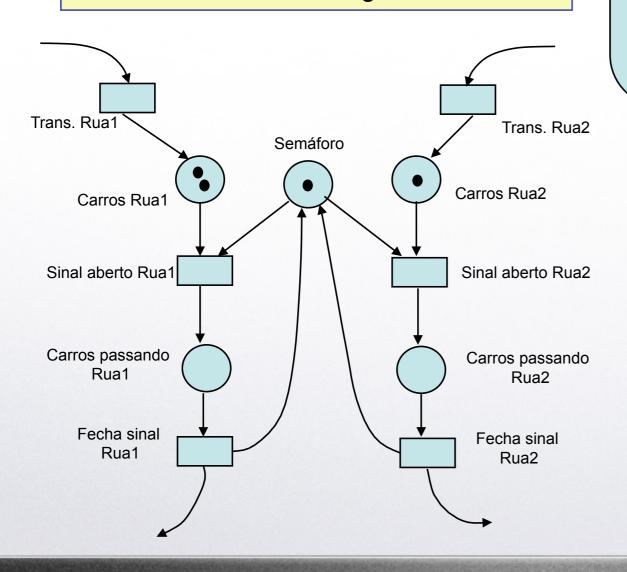






Redes de Petri

As redes de Petri se tornaram uma representação formal poderosa, esquemática e genérica, com um apelo visual, para a representação de sistemas discretos em geral.



Elementos constituintes lugar arco orientado

transição

Representação de estado

- conceito de marcação
- estado distribuído

Condição de disparo (estrita)

- pré-codições marcadas
- capacidade nas pós-condições

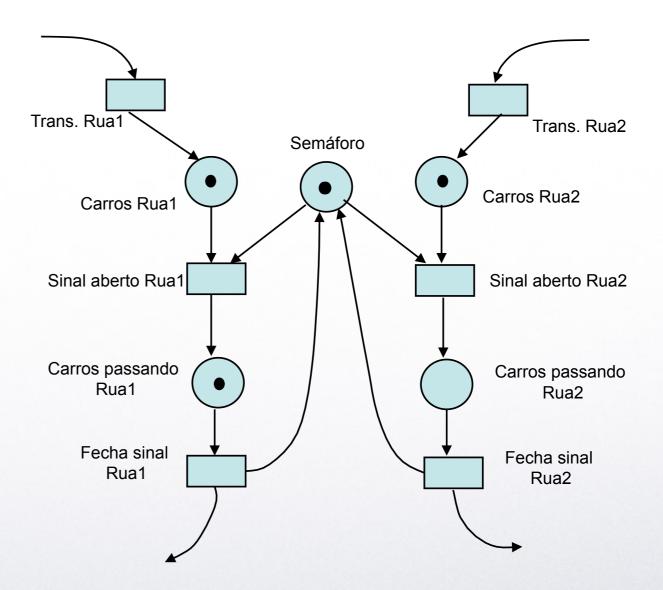


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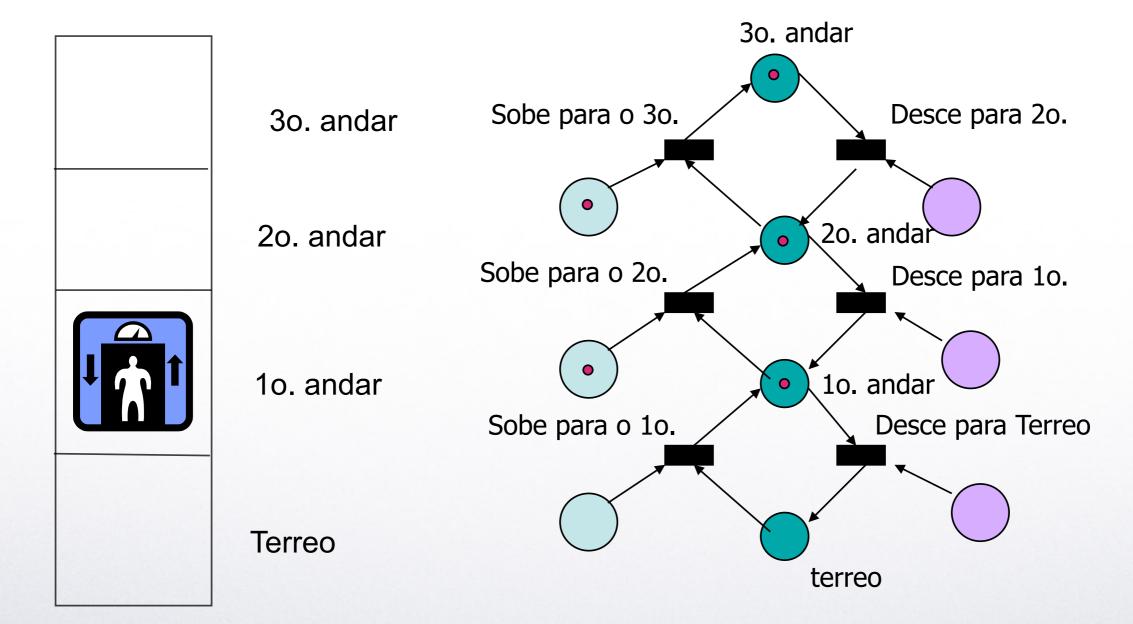
é um sistema capaz de identificar as transições habilitadas e implementar as respectivas mudanças de estado corretamente. Isto pode ser feito de forma heurística mas, é recommendável que seja feito de maneira formal.









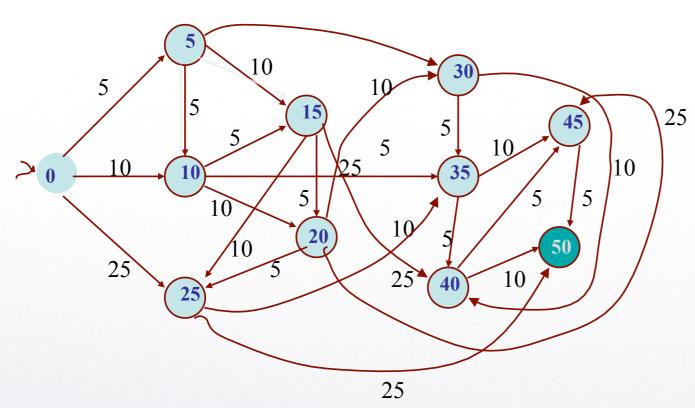








Um outro exemplo: serving machine



Uma máquina de vender refrigerantes trabalha com moedas como estímulo (evento), onde estas podem ser de \$5, \$10 e \$25, e o refrigerante custa R\$0,50







Jornalismo de Redes de Petri

Podemos então introduzir os conceitos elementares para se definir uma rede, ou melhor o que passaremos a chamar de rede elementar.

Def.] Uma rede N é um grafo bipartido, não-nulo, direcionado, representado pela n-upla (S, T; F), onde a relação de incidência F, aqui chamada de relação de fluxo é tal que $F \subseteq (SXT) \cup (TXS)$.

Se a rede N não possui laços, esta é dita pura. Se além disso a rede é simples, isto é, se não possui duas arestas distintas com os mesmos extremos – mesmo que estes não sejam coincidentes – então a rede é dita simples.

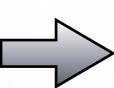
www.informatik.uni-gamburg.de/TGI/PetriNets/







object-orientation



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Objects

Uma coisa visível e tangível com forma relativamente estável; uma coisa que pode ser percebida intelectualmente; uma coisa para qual o pensamento ou ação pode ser direcionada.

Randon College Dictionary

Um objeto tem identidade, estado e comportamento

Grady Booch

Um objeto é uma unidade de modularidade estrutural e comportamental que tem propriedades

R. Buhr







Genesis dos objetos

Os objetos têm duas origens praticamente paralelas:

• estrutural: frames, Marvin Minsky, MIT, 1975

• programação : Simula 67







Objetos e programação



1966 Montagem da Simula 67: introdução do conceito de "information hiding" e encapsulamento.



1980 Aparecimento do Smalltalk 80 de Adele Goldberg







Features	Abstract	Inheritance	Dynamic	Extensive
X	Data	Support	Binding	Library
Languages	Types			
Simula	yes	yes	yes	no
CLU	yes	no	yes	no
Ada	yes	no	no	yes
Smalltalk	yes	yes	yes	yes
ObjectiveC	yes	yes	yes	yes
C++	yes	yes	yes	yes
CLOS	yes	yes	yes	no
Obj.Pascal	yes	yes	yes	no
Beta	yes	yes	yes	no
Eiffel	yes	yes	yes	yes
Actor	yes	yes	yes	no
Java	yes	yes	yes	yes







Conceitos Originais

Tipos abstratos de dados – David Parnas

Nome

Estrutura de dados da fila

Insert(x, Fila)

Retira(x, Fila)

Disciplina FIFO







Classificação: o conceito principal

Reutilização de software Reutilização de designs

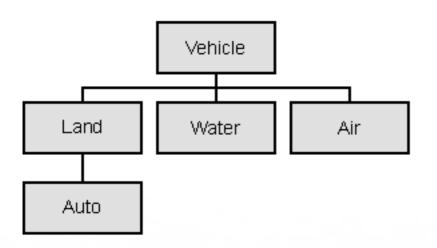


Classificação: Charles Darwin

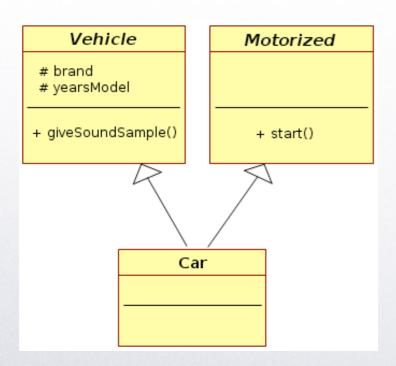
Espécie Família Grupo Instância







A herança simples deriva diretamente do conceito de classificação. Neste caso cada elemento ou instância de objeto tem um e somente um ancestral.



Na herança múltipla uma mesma instância pode herdar propriedades de "pais" distintos de forma composicional. Naturalmente esta implementação, mesmo em linguagens de programação é mais complexa.

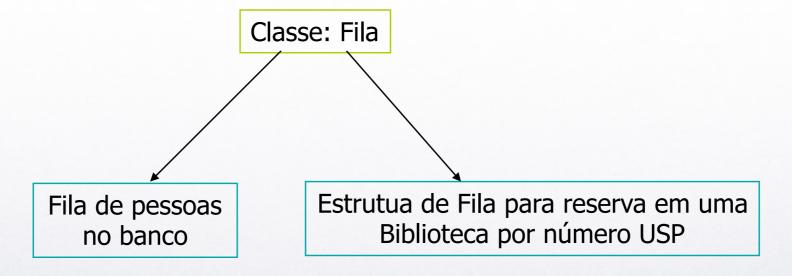






Um exemplo simples

Objetos e suas propriedades : herança (simples e múltipla), polimorfismo e Vinculação dinâmica





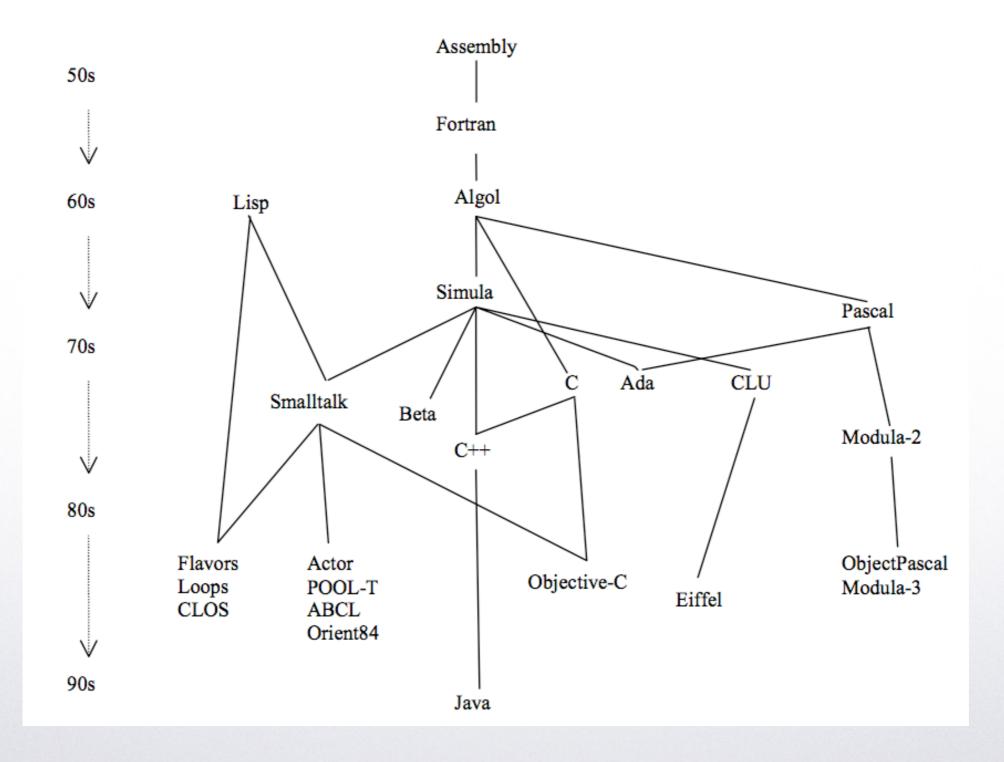




dynamic binding - The property of <u>object-oriented programming</u> languages where the code executed to perform a given operation is determined at <u>run time</u> from the <u>class</u> of the operand(s) (the receiver of the message). There may be several different classes of objects which can receive a given message. An expression may denote an object which may have more than one possible class and that class can only be determined at run time. New classes may be created that can receive a particular message, without changing (or recompiling) the code which sends the message. A class may be created that can receive any set of existing messages.













Object Oriented Design

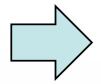
- o sistema é composto por um conjunto de objetos
- o estado do sistema é dado pelos atributos de todas as instâncias de objeto
- uma transição no sistema se dá através de mensagens que por sua vez dispara um ou mais métodos.







A abordagem de objetos



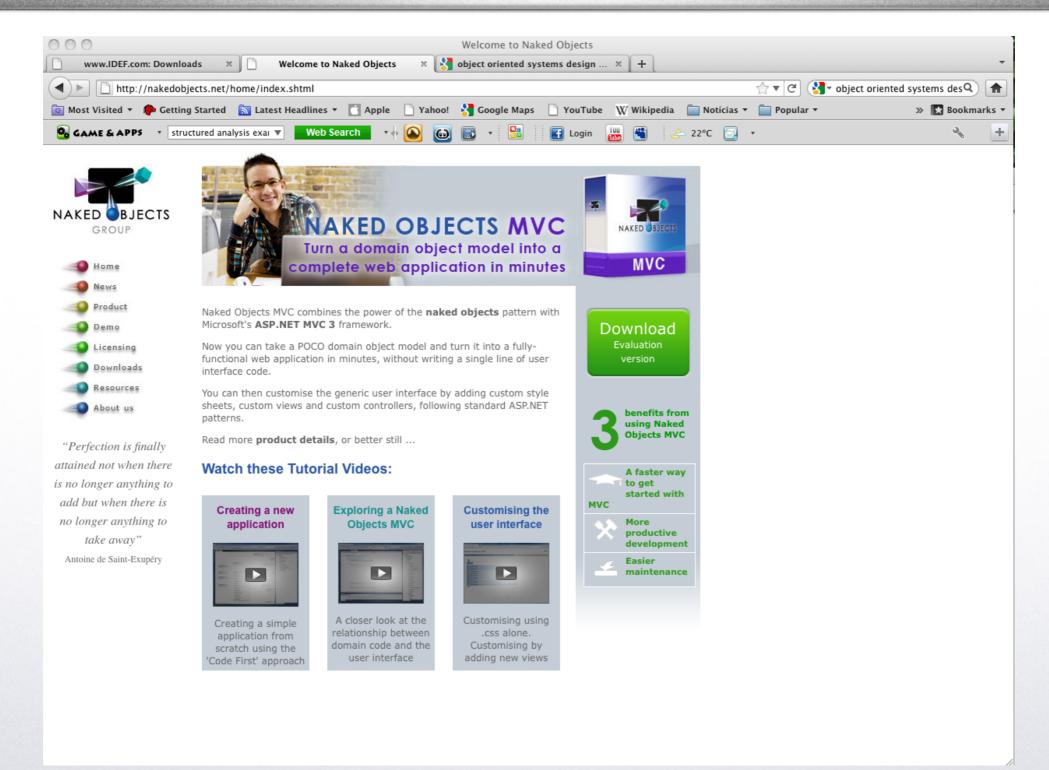
Completeza comportamental

- separation of concerns
- encapsulation
- classification
- inheritance (single and multiple)
- polymorphism











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Behaviorally Complete Objects

– or –

Back to the Roots

- An Object models the (complete) behavior of the thing it represents
- An Object
 - knows something
 - →Properties and associations
 - → Fields
 - does something
 - →Methods









Voltando ao design orientado a objetos

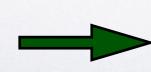
- 1. Understand and define the context and the modes of use of the system
- 2. Design the system architecture
- 3. Identify the principal objects in the system
- 4. Develop design models
- 5. Specify object interfaces







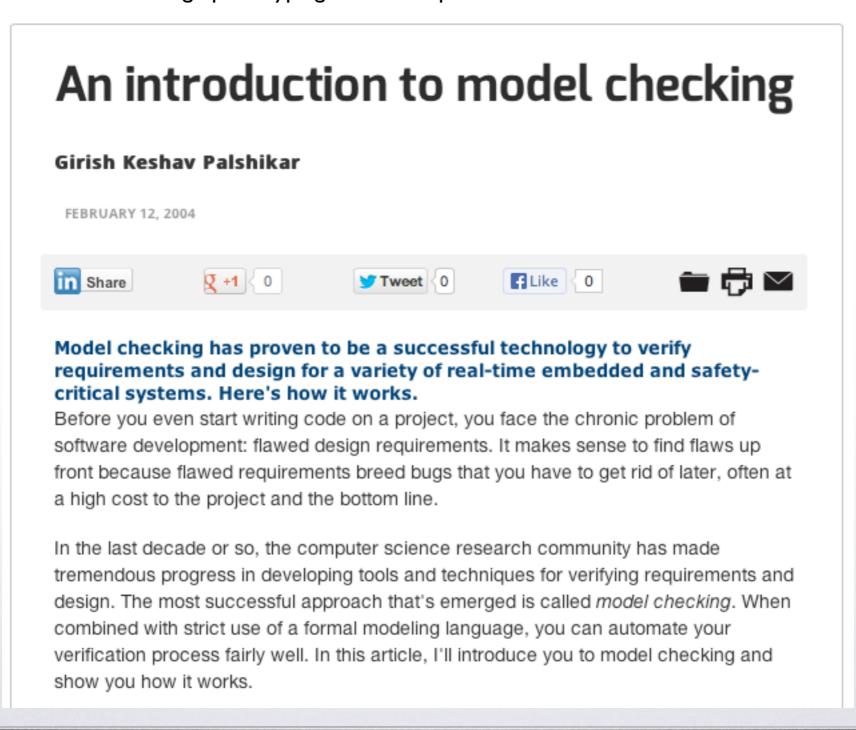
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http://www.embedded.com/design/prototyping-and-development/4024929/An-introduction-to-model-checking









Hypothesis

- Model checking is an algorithmic approach to analysis of finite-state systems
- Model checking has been originally developed for analysis of hardware designs and communication protocols
- Model checking algorithms and tools have to be tuned to be applicable to analysis of software

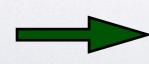
Natasha Sharygina Lecturer







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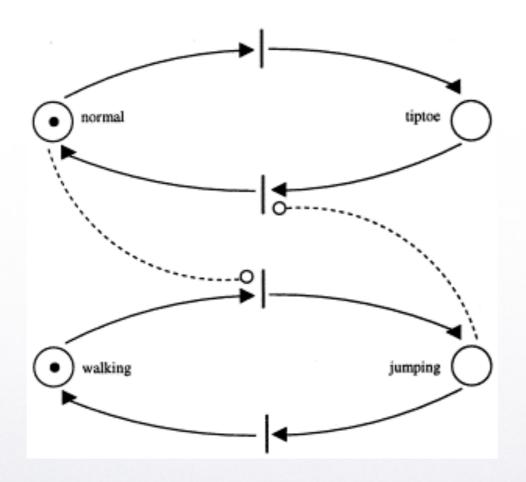








Event inhibition





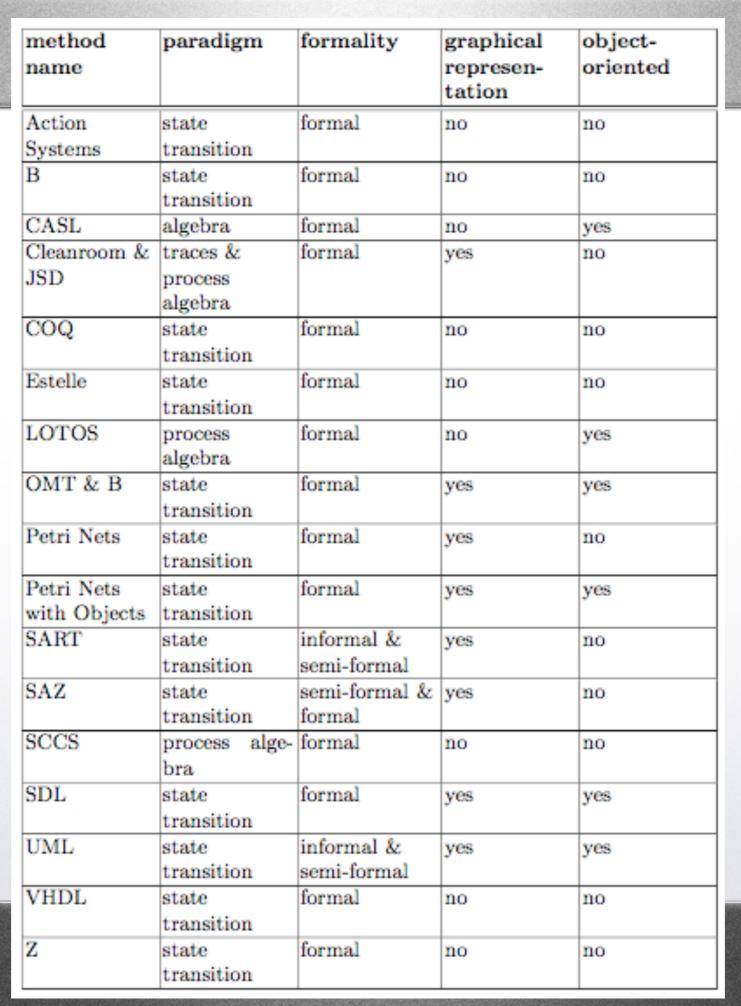




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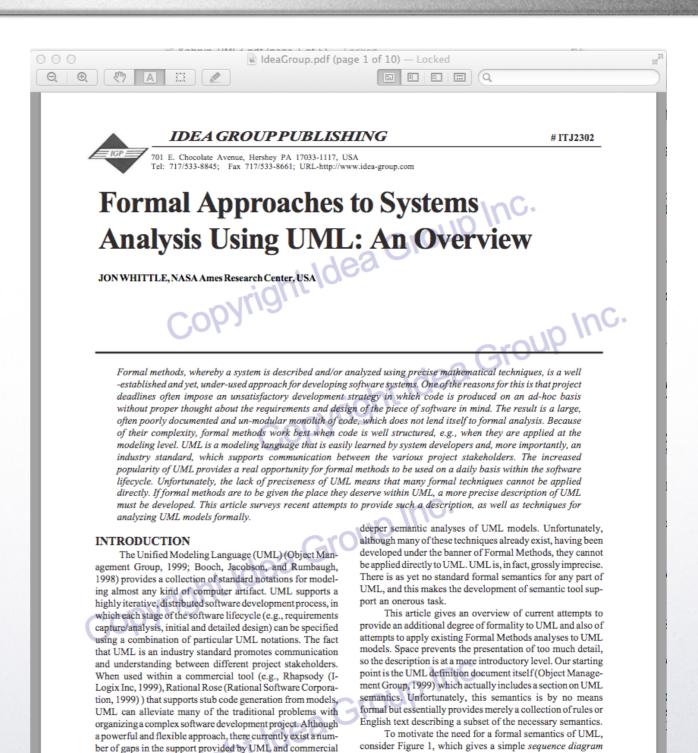


method	concurrency	executability	usage of	non-
name			variables	determinism
Action	no	yes	yes	yes
Systems				
В	no	yes	yes	yes
CASL	no	yes	yes	no
Cleanroom &	no	yes	yes	yes
JSD				
COQ	no	yes	yes	yes
Estelle	yes	yes	yes	no
LOTOS	yes	yes	yes	yes
OMT & B	no	yes	yes	yes
Petri Nets	yes	yes	no	yes
Petri Nets	yes	yes	yes	yes
with Objects				
SART	yes	no	no	yes
SAZ	no	yes	yes	yes
SCCS	yes	yes	yes	yes
SDL	yes	yes	no	yes
UML	yes	no	no	no
VHDL	yes	yes	yes	no
Z	no	yes	yes	yes





Leitura da Semana



describing a trace in an automated teller machine (ATM).

Sequence diagrams, derived in part from their close neighbor



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Escola Politécnica da USP 55

tools. First and foremost, the consistency checks provided by

current tools are limited to very simple syntactic checks, such





Leitura da Semana



1. INTRODUCTION

for object-oriented methodologies.

Over the past three decades, several software development methodologies have appeared. Such methodologies address some or all phases of the software life cycle ranging from requirements to maintenance. These methodologies have often been developed in response to new ideas about how to cope with the inherent complexity of software systems. Due to the increasing popularity of object-oriented programming, in the last twenty years, research on object-oriented methodologies has become a growing field of in-

velopment, in the 1990s, demand for object-oriented software sys-

tems increased dramatically; consequently, several methodologies

have been proposed to support software development based on that

paradigm. Also presented are a survey and a classification scheme

There has also been an explosive growth in the number of software systems described as object-oriented. Object-orientation has already been applied to various areas such as programming languages, office information systems, system simulation and artificial intelligence. Some important features of present software The notion of "object" naturally plays a central role in objectsystems include:

- Complexity: the internal architecture of current software systems is complex, often including concurrency and parallelism. Abstraction in terms of object-oriented concepts is a technique that helps to deal with complexity. Abstraction involves a selective examination of certain aspects of an application. It has the goal of isolating those aspects that are important for an understanding of the application, and also suppressing those aspects that are irrelevant. Forming abstractions of an application in terms of classes and objects is one of the fundamental tenets of the object-oriented paradigm.
- Friendliness: this is a paramount requirement for software systems in general. Iconic interfaces provide a user-friendly

duction of additional components that may themselves be reused in future software developments. Taking components created by others is better than creating new ones. If a good library of reusable components exists, browsing components to identify opportunities for reuse should take precedence over writing new ones from scratch. Inheritance is an objectoriented mechanism that boosts software reusability.

The rapid development of this paradigm during the past ten years has important reasons, among which are: better modeling of realworld applications as well as the possibility of software reuse during the development of a software system. The idea of reusability within an object-oriented approach is attractive because it is not just a matter of reusing the code of a subroutine, but it also encompasses the reuse of any commonality expressed in class hierarchies. The inheritance mechanism encourages reusability within an object-oriented approach (rather than reinvention!) by permitting a class to be used in a modified form when a sub-class is derived from it [1, 2, 3, 4].

2. THE BACKGROUND OF THE OBJECT-ORIENTED APPROACH

oriented software systems, but this concept has not appeared in the object-oriented paradigm. In fact, it could be said that the objectoriented paradigm was not invented but actually evolved by improving already existing practices. The term "object" emerged almost independently in various branches of computer science. Some areas that influenced the object-oriented paradigm include: system simulation, operating systems, data abstraction and artificial intelligence. Appearing almost simultaneously in the early 1970s, these computer science branches cope with the complexity of software in such a way that objects represent abstract components of a software system. For instance, some notions of "object" that emerged from these research fields are:

Classes of objects used to simulate real-world applications, in ula [5]. In this language the execution of



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