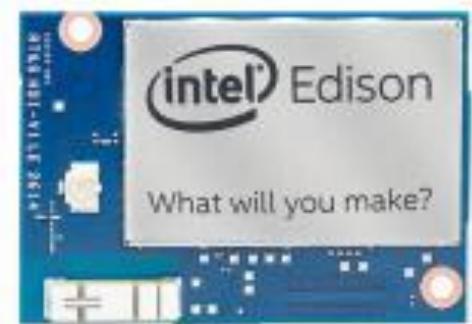




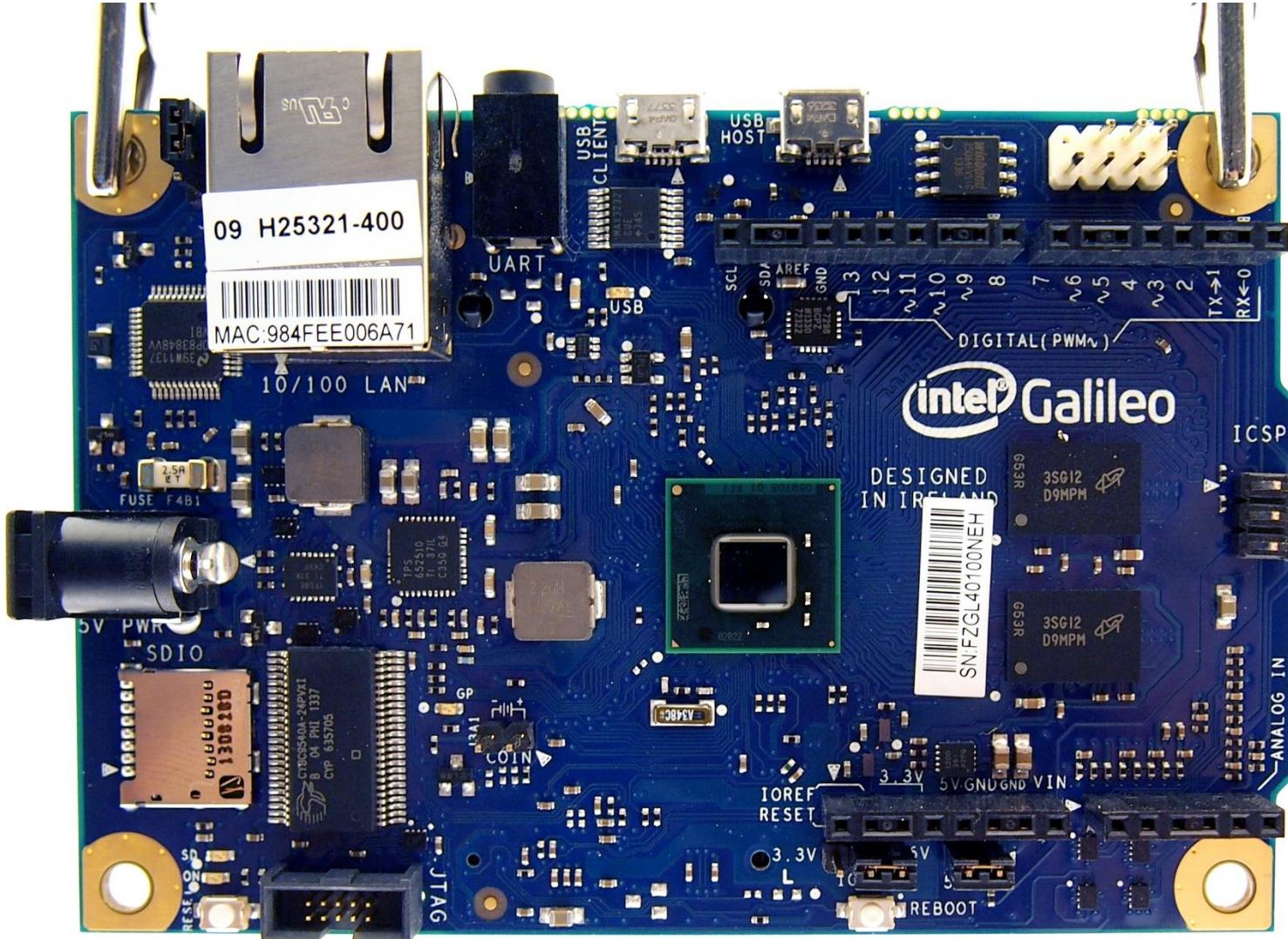
# Intel RoadShow



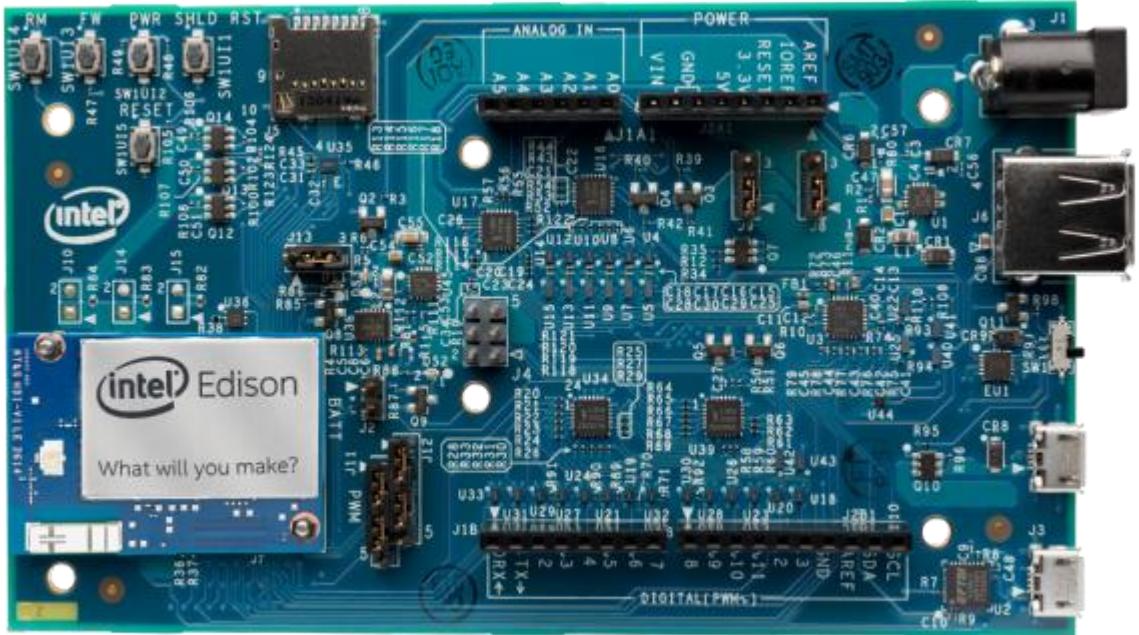
# Arduino



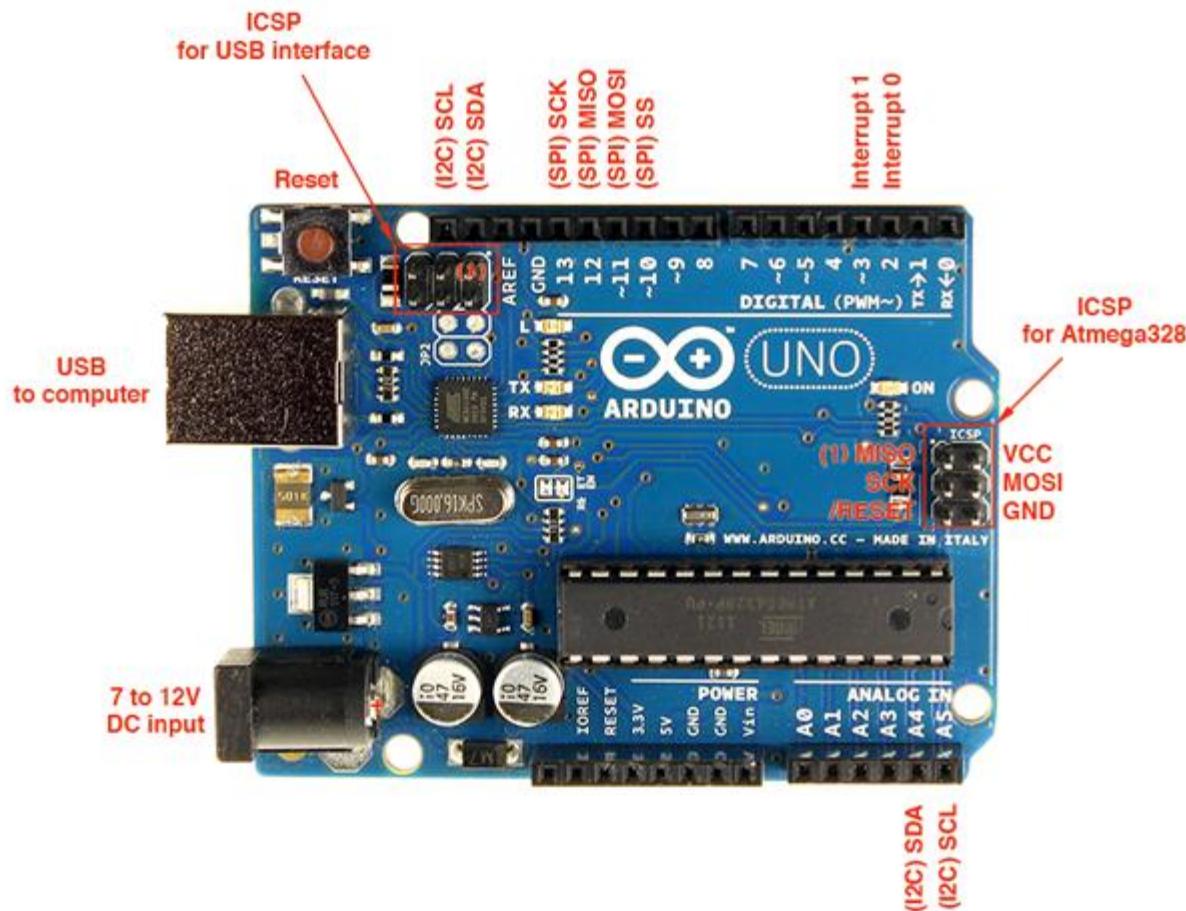
# Galileo



# Edison

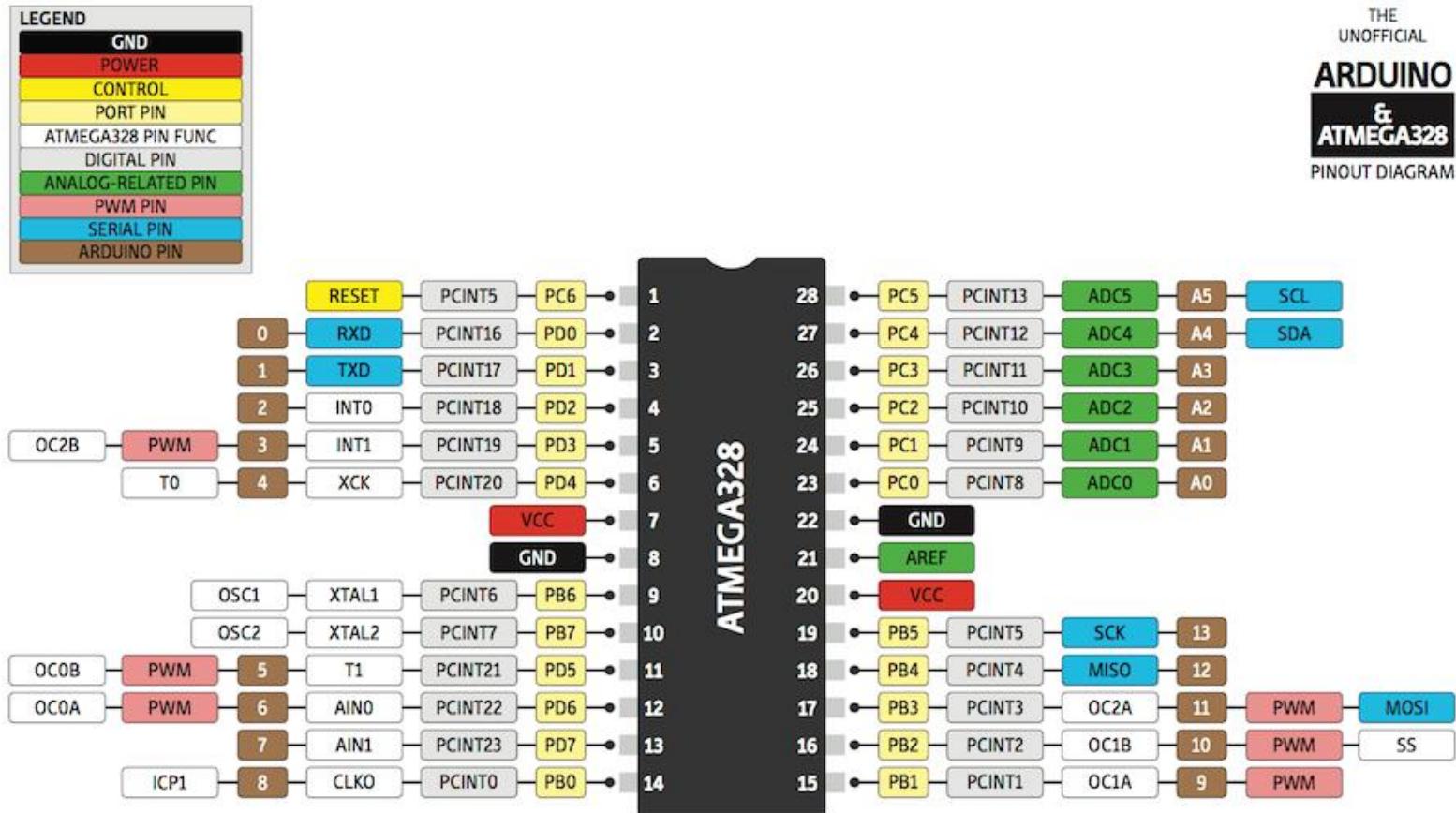


# Arduino

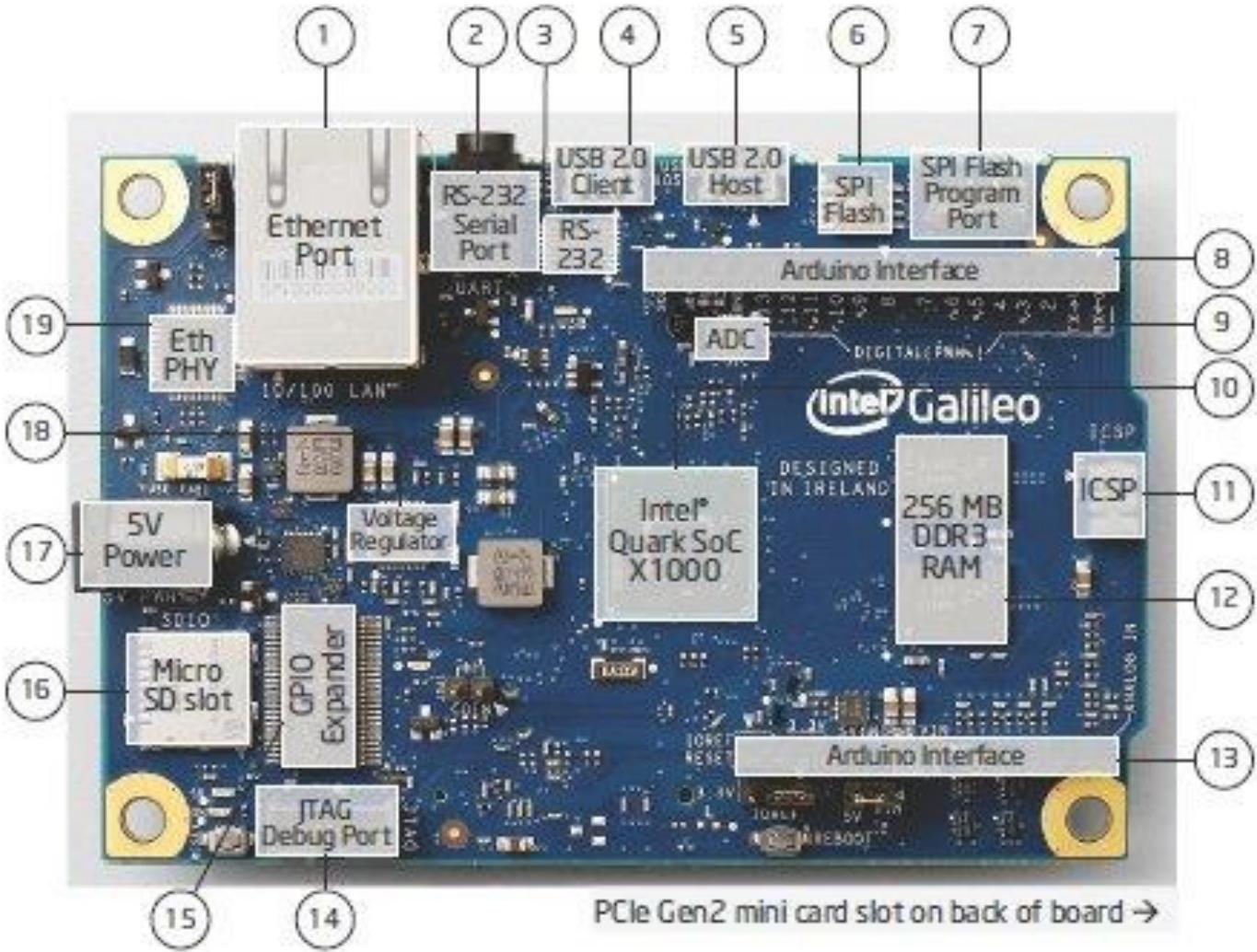


	<b>Arduino Uno</b>	<b>Intel Edison</b>
<b>Size</b>	7.6 x 1.9 x 6.4 cm	3.55 x 2.5 x .39 cm
<b>Memory</b>	0.002MB	1 GB
<b>GPIO</b>	14	40
<b>Clock Speed</b>	16 MHz	500 MHz
<b>On Board Network</b>	None	Dual-band (2.4 and 5 GHz) Wifi, Bluetooth 4.0
<b>Multitasking</b>	No	Yes
<b>Input voltage</b>	7 to 12 V	3.3 to 4.5 V
<b>Flash memory</b>	32KB	4 GB eMMC
<b>USB</b>	One, input only	One, peripherals OK
<b>Operating System</b>	None	Yocto Linux v1.6
<b>Integrated Development Environment</b>	Arduino IDE	Arduino IDE, Eclipse, Intel XDK

# Arduino



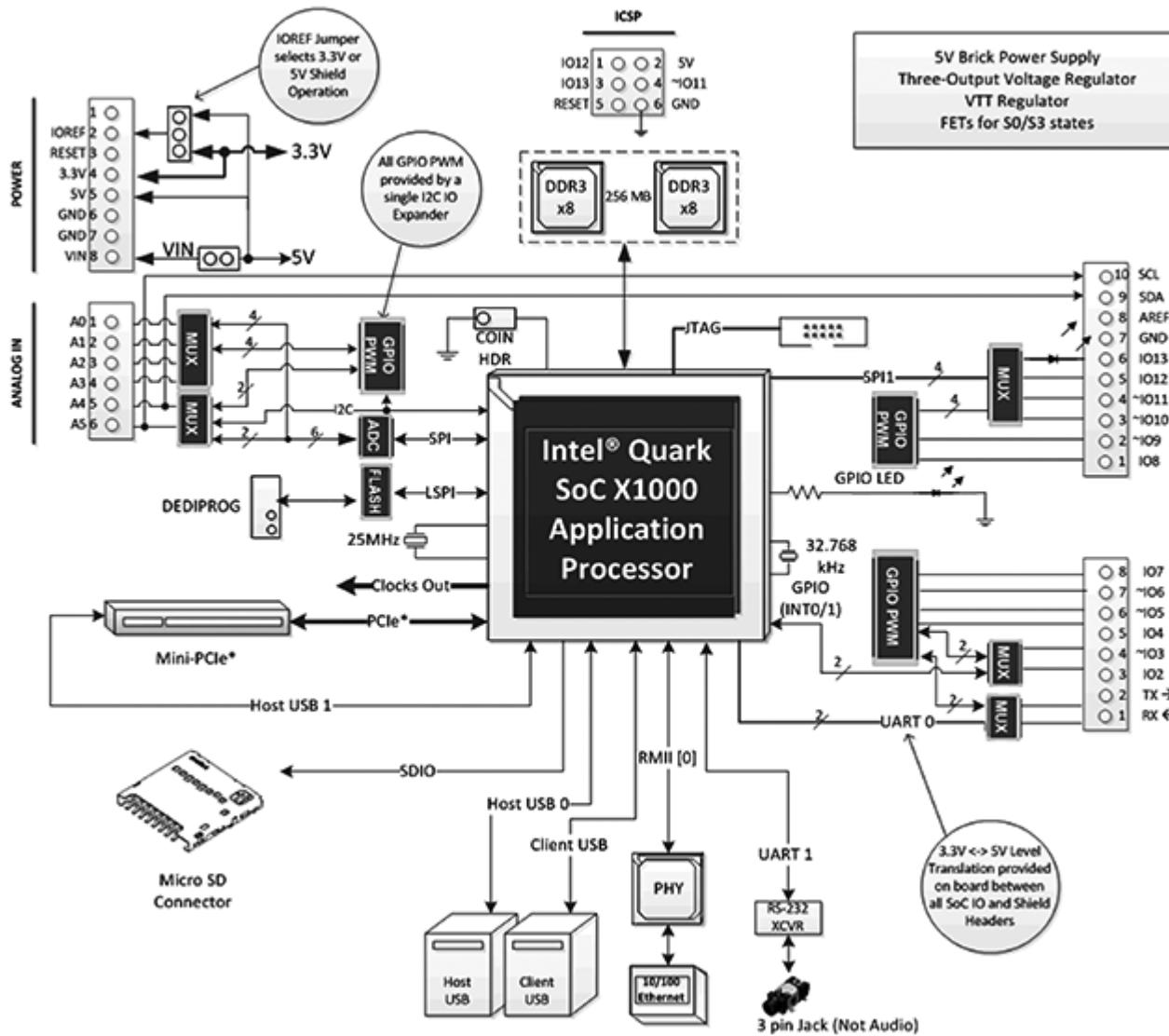
# Galileo



<b>Input Voltage (recommended)</b>	5V
<b>Input Voltage (limits)</b>	5V
<b>Digital I/O Pins</b>	14 (of which 6 provide PWM output)
<b>Analog Input Pins</b>	6
<b>Total DC Output Current on all I/O lines</b>	80 mA
<b>DC Current for 3.3V Pin</b>	800 mA
<b>DC Current for 5V Pin</b>	800 mA

# Galileo

Intel® Galileo Board Block Diagram



## Quark SoC X1000

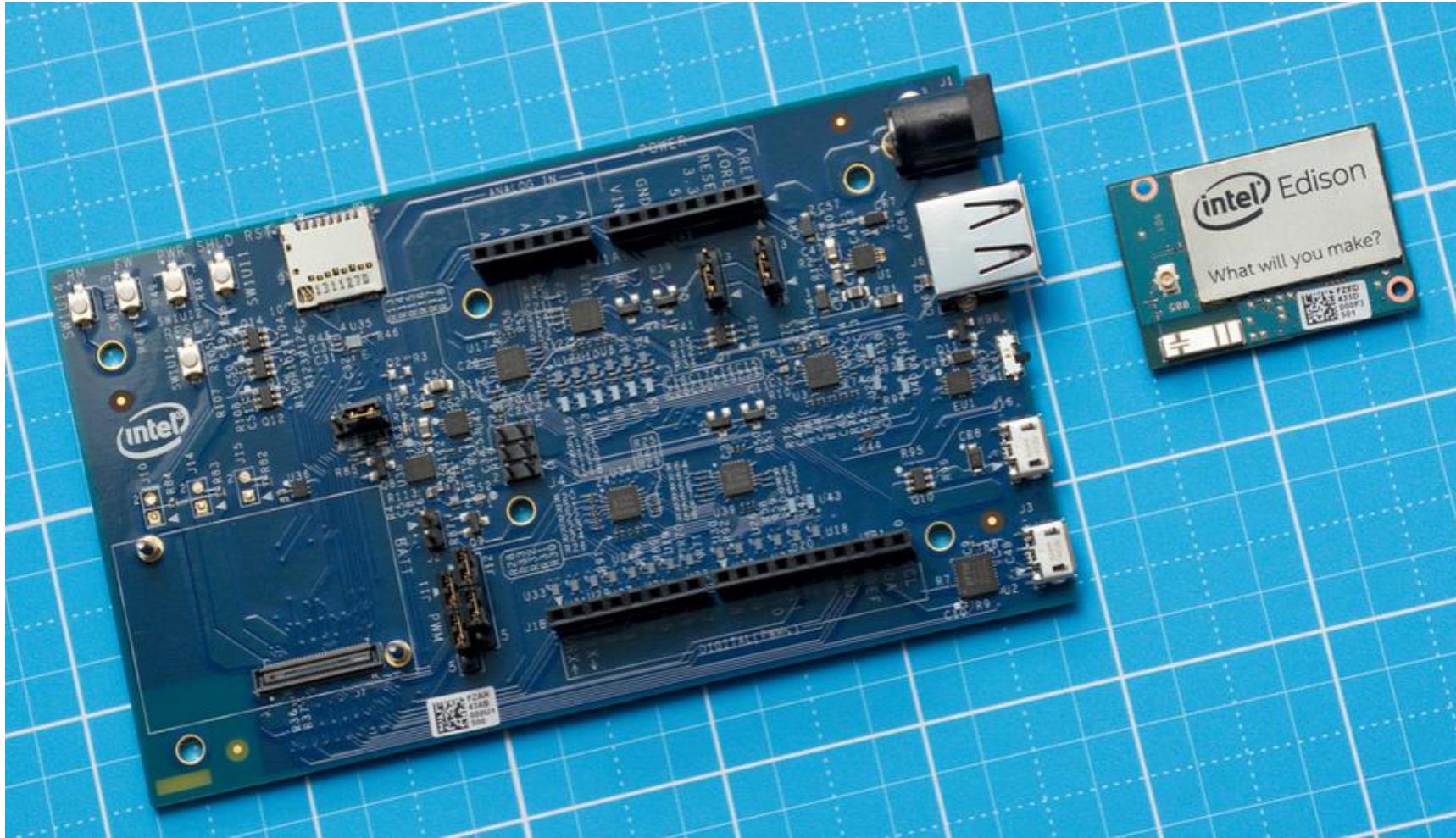
400 MHz 32-bit Intel®

®

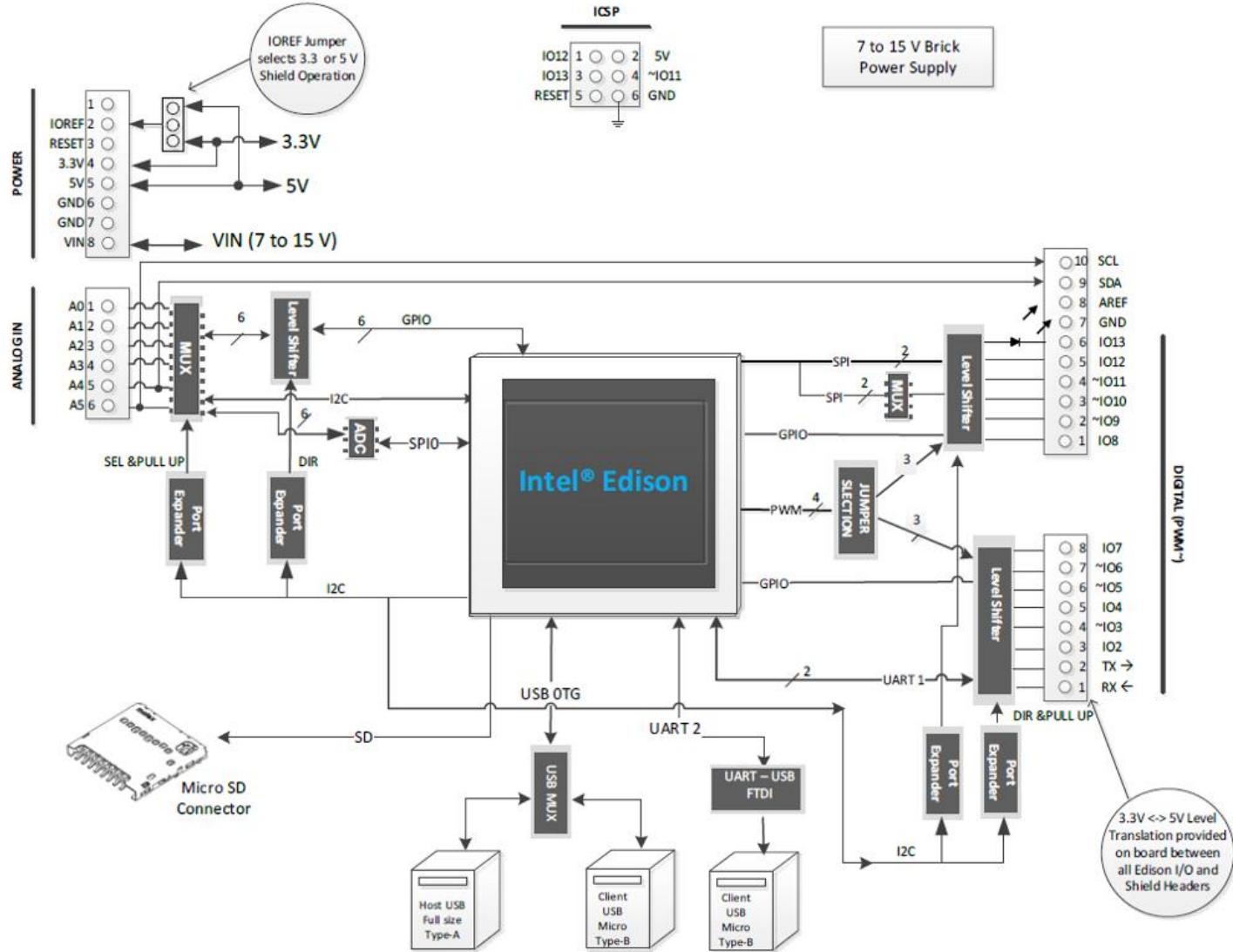
Pentium instruction set architecture (ISA)-compatible processor

- 16 KByte L1 cache
- 512 KBytes of on-die embedded SRAM
- Simple to program: Single thread, single core, constant speed
- ACPI compatible CPU sleep states supported

# Edison



# Edison



Microprocessador

Intel Atom de 500MHz com dois núcleos

Intel Quark de 100MHz

RAM

1Gb

Armazenamento Interno

eMMC de 4Gb

Wireless

Dual Band (2.4 e 5GHz) IEEE 802.11 a/b/g/n

Bluetooth

BT 4.0 + 2.1 EDR

USB 2.0

1 Controlador OTG

I/O

40 GPIOs que podem ser configuradas para

SD card: 1 Interface

UART: 2 controladores

I<sup>2</sup>C: 2 controladores

SPI: 1 controlador com 2 chip selects

I<sup>2</sup>S: 1 controlador

GPIO: 14 adicionais sendo que 4 tem capacidade de PWM

# AMBIENTE - SKETCH

Possui sua interface própria com inúmeros exemplos iniciais

Por motivo de ser código aberto, uma infinidade de exemplos podem ser adquiridos

Rápida implementação

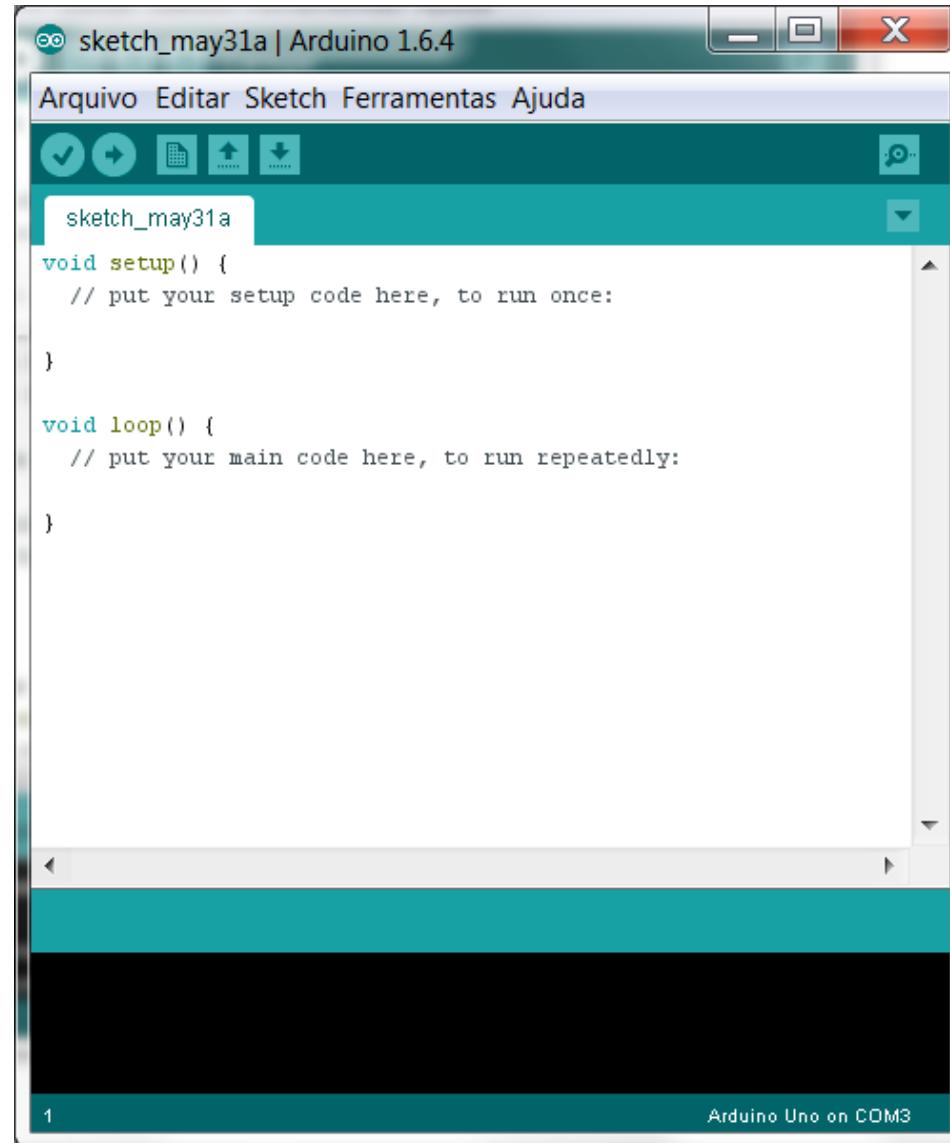
- Galileu
- Edison

Site oficial

<http://www.arduino.cc/>

Instalando o arduino

<http://www.arduino.cc/en/Guide/Windows>



The screenshot shows the Arduino IDE interface with the title bar "sketch\_may31a | Arduino 1.6.4". The menu bar includes "Arquivo", "Editar", "Sketch", "Ferramentas", and "Ajuda". Below the menu is a toolbar with icons for save, undo, redo, open, upload, and download. The main code editor window displays the following code:

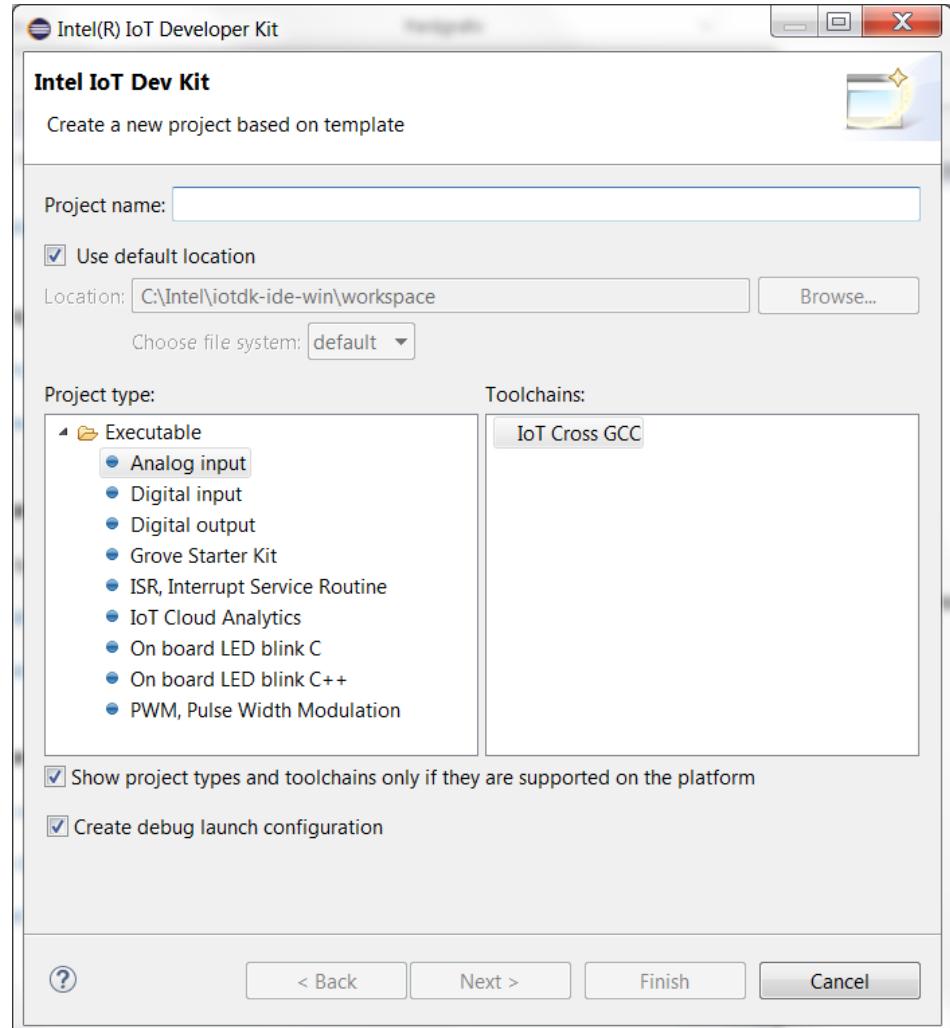
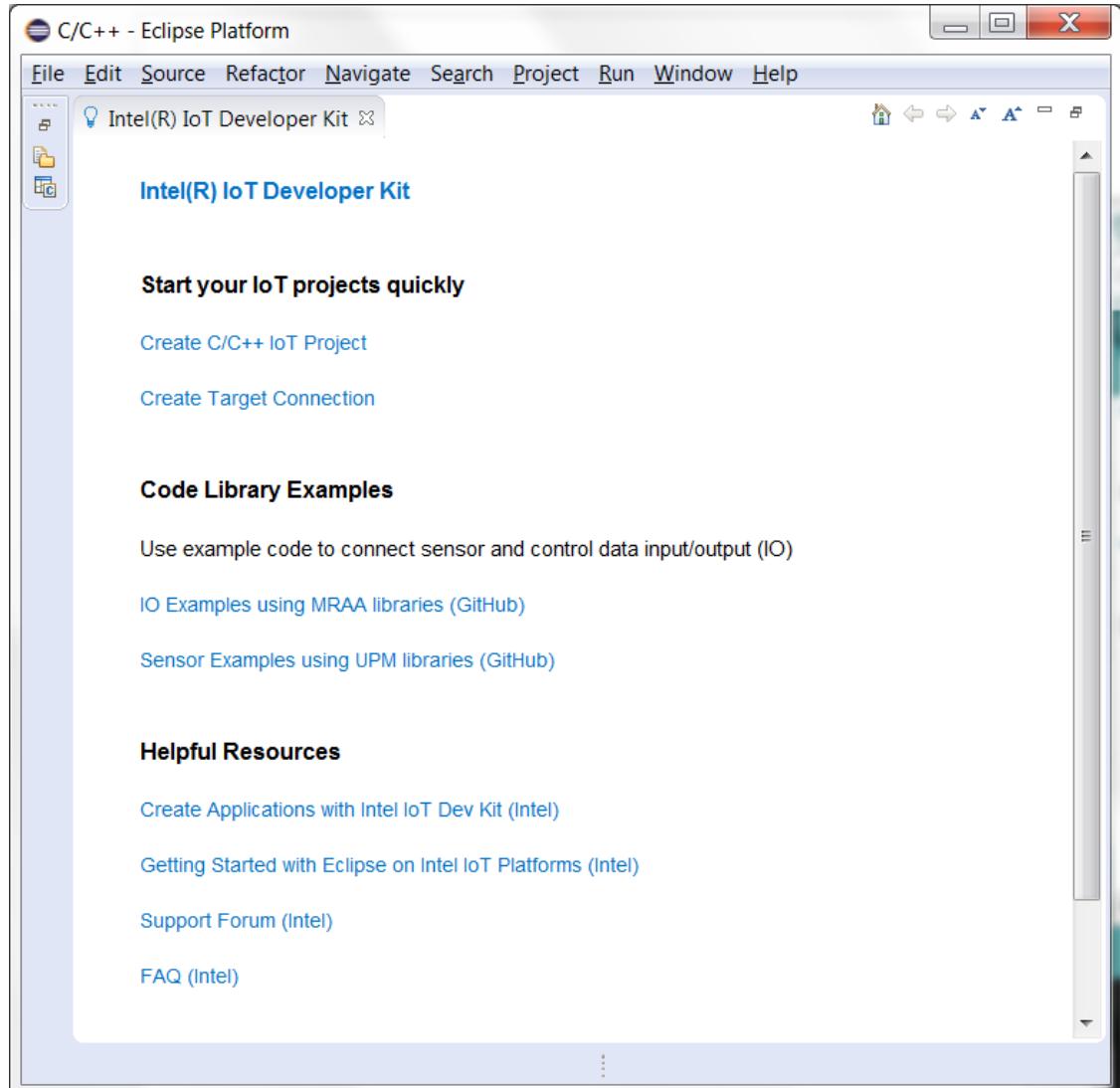
```
void setup() {
  // put your setup code here, to run once:
}

void loop() {
  // put your main code here, to run repeatedly:
}
```

The status bar at the bottom indicates "Arduino Uno on COM3".

# Plataforma Eclipse

## - Aplicações orientadas a IoT



```
25 #include <unistd.h>
26 #include <signal.h>
27 #include <iostream>
28 #include "adc121c021.h"
29 using namespace std;
30 int shouldRun = true;
31 void sig_handler(int signo)
32 {
33     if (signo == SIGINT)
34         shouldRun = false;
35 }
36 int main(int argc, char **argv)
37 {
38     signal(SIGINT, sig_handler);
39 //! [Interesting]
40     // Instantiate an ADC121C021 on I2C bus 0
41     upm::ADC121C021 *adc = new upm::ADC121C021(ADC121C021_I2C_BUS,
42                                               ADC121C021_DEFAULT_I2C_ADDR);
43     while (shouldRun)
44     {
45         uint16_t val = adc->value();
46         cout << "ADC value: " << val << " Volts = "
47             << adc->valueToVolts(val) << endl;
48         usleep(50000);
49     }
50 //! [Interesting]
51     cout << "Exiting..." << endl;
52     delete adc;
53     return 0;
54 }
```

# Programação C/C++

# Programação Javascript

```
27 +public class GpioRead6 {  
28 + static {  
29 +     try {  
30 +         System.loadLibrary("mraajava");  
31 +     } catch (UnsatisfiedLinkError e) {  
32 +         System.err.println(  
33 +             "Native code library failed to load. See the chapter on Dynamic Linking Problems in the SWIG Java documentation for help.\n" +  
34 +             e);  
35 +         System.exit(1);  
36 +     }  
37 + }  
38 + public static void main(String argv[]) {  
39 +     mraa.mraa.init();  
40 +     mraa.Gpio gpio_in = new mraa.Gpio(6);  
41 +     gpio_in.dir(mraa.Dir.DIR_IN);  
42 +     System.out.format("Gpio is %d\n", gpio_in.read());  
43 + }  
44 +}
```

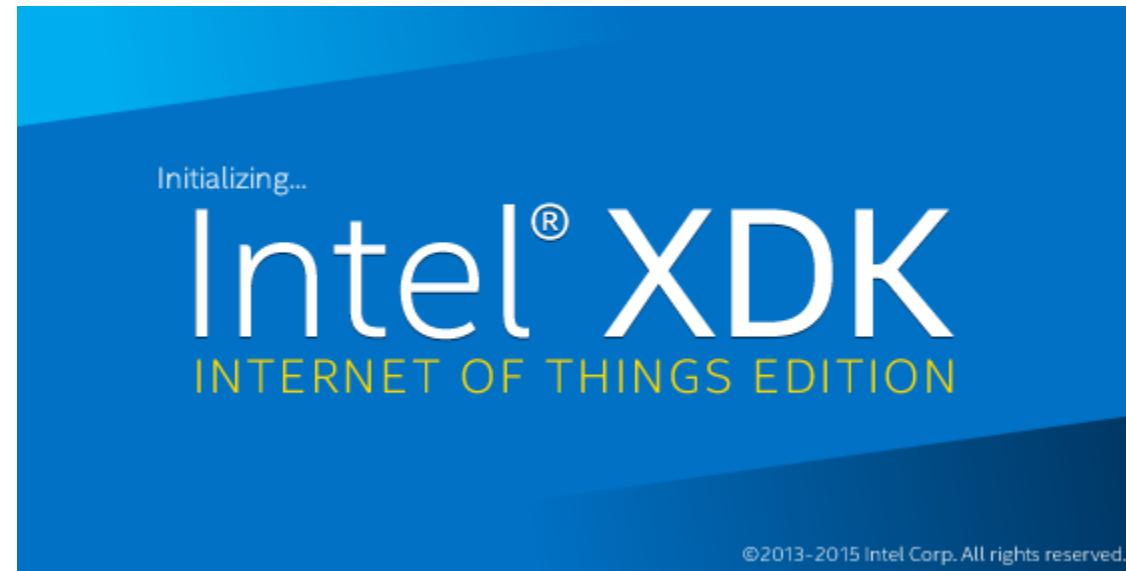
```
24 import time, sys, signal, atexit
25 import pyupm_a110x as upmA110x
27 # Instantiate a Hall Effect magnet sensor on digital pin D2
28 myHallEffectSensor = upmA110x.A110X(2)
31 ## Exit handlers ##
32 # This function stops python from printing a stacktrace when you hit control-C
33 def SIGINTHandler(signum, frame):
34     raise SystemExit
35
36 # This function lets you run code on exit, including functions from
myHallEffectSensor
37 def exitHandler():
38     print "Exiting"
39     sys.exit(0)
41 # Register exit handlers
42 atexit.register(exitHandler)
43 signal.signal(signal.SIGINT, SIGINTHandler)
56 while(1):
47     if (myHallEffectSensor.magnetDetected()):
48         print "Magnet (south polarity) detected."
49     else:
50         print "No magnet detected."
51     time.sleep(1)
```

# Programação Phyton

# AMBIENTE XDK

*“A Ferramenta de Desenvolvimento de Plataforma Cruzada HTML5 Intel® XDK oferece um fluxo de trabalho simplificado para permitir que os desenvolvedores projetem, depurem, criem e implantem com facilidade aplicativos de web híbridos em várias app stores e dispositivos de fator de forma.”*

INTEL – 2014 <https://software.intel.com/pt-br/html5/tools>



<https://software.intel.com/pt-br/intel-xdk>

**Intel® XDK IoT Edition**

**PROJECTS**

**START A NEW PROJECT**

**INTERNET OF THINGS EMBEDDED APPLICATION**

Templates

Import Your Node.js Project

**HTML5 COMPANION HYBRID MOBILE OR WEB APP**

+ Templates

+ Samples and Demos

Import Your HTML5 Code Base

**Internet of Things Node.js Projects**

Start your new project from the menu on the left, by choosing a template, sample or demo code base. There are Node.js, Standard HTML5 and HTML5 + Cordova code bases to choose from.

Write a board-embedded application which controls hardware. Use the Intel® XDK to install and test your control application on your maker board.

 Embed on maker boards

 Edison  Galileo

**Companion Hybrid Mobile and Web Apps**

**STANDARD HTML5 PROJECT**

Choose a template, sample or demo that uses Standard HTML5 APIs to create the most versatile project. Build your project as a packaged web app, host it on a server as an HTML5 web app or build it for distribution through popular mobile app stores.

 Desktops, smartphones & tablets

Web App Crosswalk Android iOS Windows Chrome OS Firefox OS Tizen

**HTML5 + CORDOVA PROJECT**

Develop your project specifically as a hybrid mobile app, using Standard HTML5 and Cordova APIs, for distribution through popular mobile app stores.

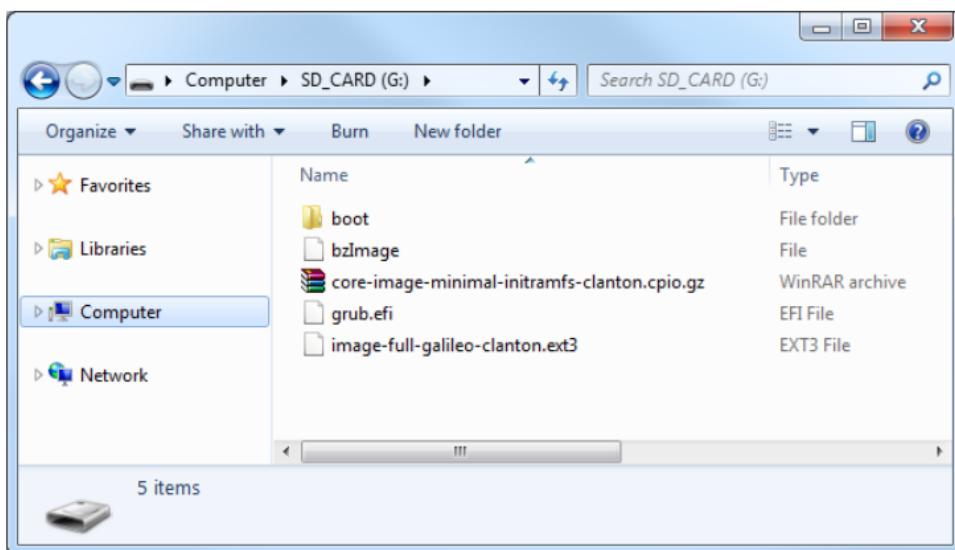
- Utilize data from device sensors, including GPS, accelerometer, compass and more.
- Access device hardware (Bluetooth, NFC, camera, etc.).
- Manage file storage and caching, and access databases like calendar and contacts.
- Explore third-party plugins to find an array of new features.

 OPEN AN INTEL® XDK PROJECT

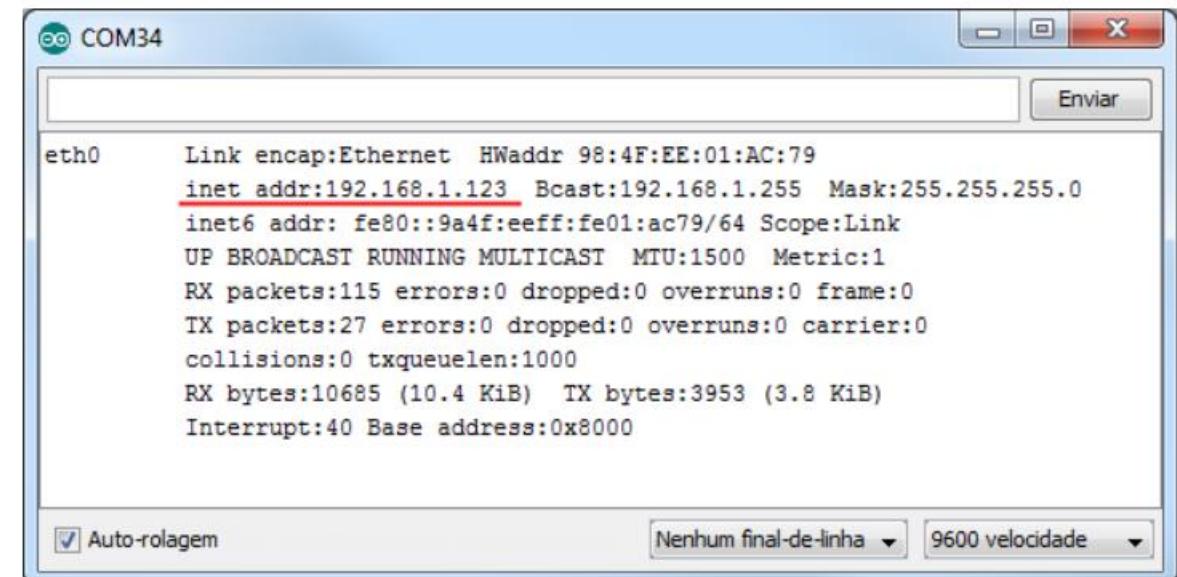
 Smartphones & tablets

# INICIALIZANDO - GALILEO LINUX

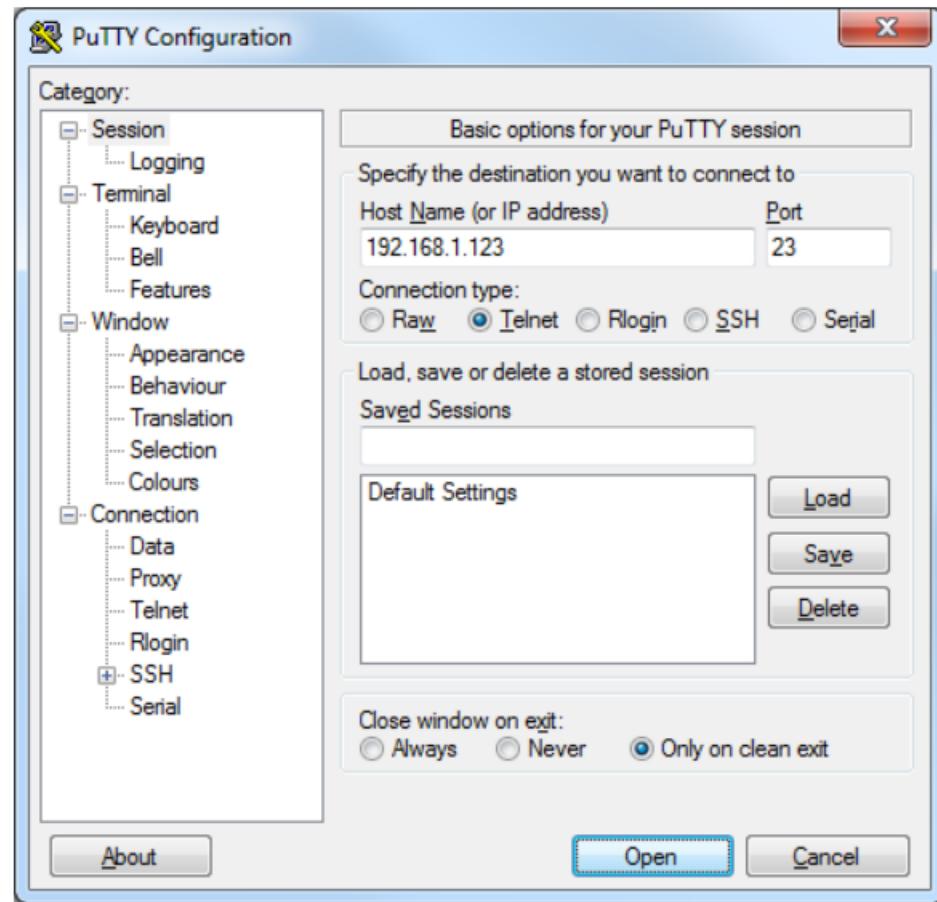
Software	File size	File type
SD-Card Linux Image	48 MB	.bz2



```
1 void setup()
2 {
3     system("telnetd -l /bin/sh");
4 }
5
6 void loop()
7 {
8     system("ifconfig eth0 > /dev/ttyGS0");
9     sleep(20);
10 }
```



# INICIALIZANDO - GALILEO LINUX



A PuTTY terminal window titled '192.168.1.123 - PuTTY' is shown. The session is connected to a host running 'Poky 9.0.2 (Yocto Project 1.4 Reference Distro) 1.4.2 clanton'. The terminal prompt is 'sh-4.2#'. The user runs several commands: 'ls' (listing directory contents), 'python' (running Python 2.7.3), and a Python script that prints the string 'FILIPEFLOP !'. The output shows the directory structure and the printed text.

```
Poky 9.0.2 (Yocto Project 1.4 Reference Distro) 1.4.2 clanton
sh-4.2# ls
bin      etc      lost+found  opt      sketch    usr
boot    home      media      proc      sys      var
dev     lib       mnt       sbin      tmp
sh-4.2# python
Python 2.7.3 (default, Oct 16 2014, 16:04:29)
[GCC 4.7.2] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> texto = "FILIPEFLOP !"
>>> print texto
FILIPEFLOP !
>>>
```

## INICIALIZANDO - GALILEO WIN 10

## Arquivos no Download:

	Nome do Arquivo	Tamanho do Arquivo	Baixar arquivo único
<input checked="" type="checkbox"/>	apply-BootMedia.cmd	20 KB	<a href="#">Baixar</a>

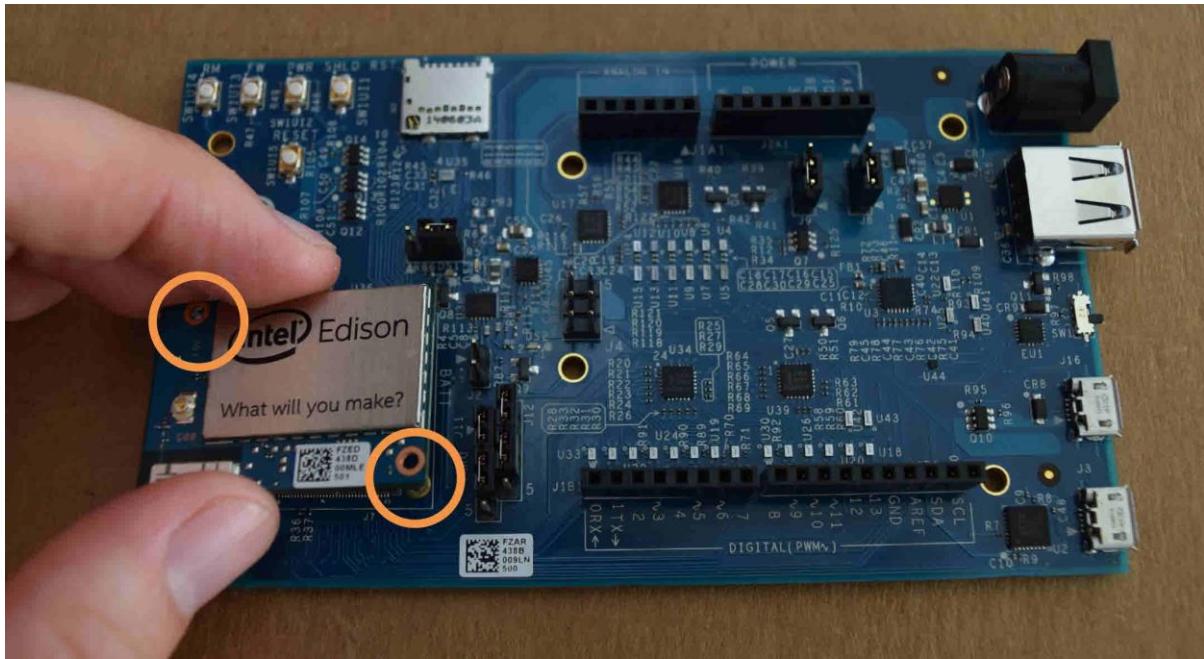
## Arquivos no Download:

	Nome do Arquivo	Tamanho do Arquivo	Baixar arquivo único
<input checked="" type="checkbox"/>	9600.16384.x86fre.winblue_rtm_iotbuild.150309-0310_galileo_v2.wim	166,77 MB	<a href="#">Baixar</a>

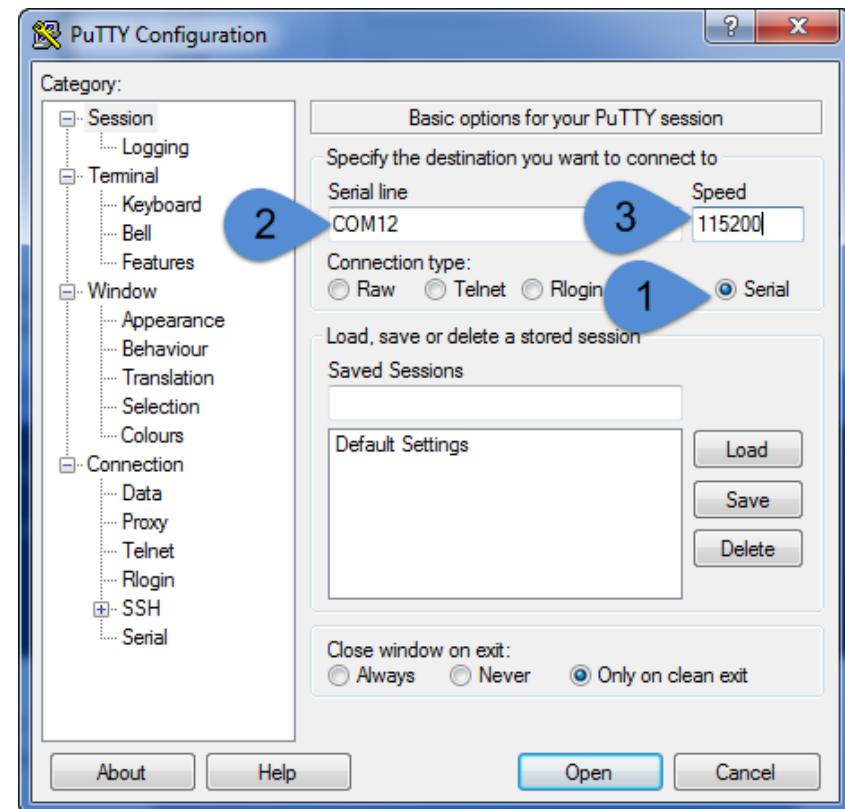
```
C:\apply-bootmedia.cmd -destination {YourSDCardDrive} -image {.wimFile downloaded above} -hostname mygalileo -password admin
```



## INICIALIZANDO – EDISON LINUX



## INICIALIZANDO – EDISON LINUX



A PuTTY terminal window titled 'COM8 - PuTTY'. The title bar has a small icon with a blue square and a yellow triangle. The window displays the text: 'Poky (Yocto Project Reference Distro) 1.6 Edison1 ttyMFD2' and 'Edison1 login:'. A green cursor is visible at the end of the line.

A PuTTY terminal window titled 'COM8 - PuTTY'. The title bar has a small icon with a blue square and a yellow triangle. The window displays the text: 'root@Edison1:~#'. A green cursor is visible at the end of the line.