

Leonardo Zorzo de Oliveira

PME3380 - Modelagem de Sistemas Dinâmicos

1) Desenhe o diagrama, temos:

$$R - E = E \Rightarrow R - HY = E \Rightarrow R - E = HY \Rightarrow R - G^{-1}Y = HY$$

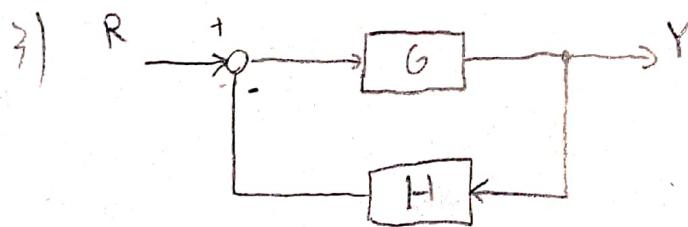
$$\Rightarrow R = (H + G^{-1})Y \Rightarrow R = (HG + I)G^{-1}Y \Rightarrow Y = G(HG + I)^{-1}R$$

Como $Y = TR$:

$$T = G(HG + I)^{-1} \Rightarrow T = G(I + HG)^{-1}$$

$$\therefore \boxed{G(I + HG)^{-1} = G(I + L)^{-1}}$$

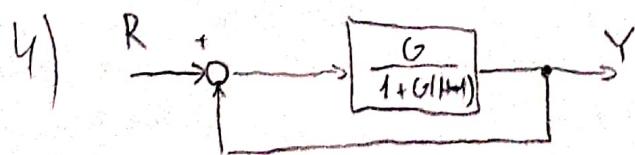
2)?



$$Y = GH \left(\frac{R}{H} - Y \right)$$

$$\Rightarrow Y = GR - GHY \Rightarrow Y(1+GH) = GR \Rightarrow$$

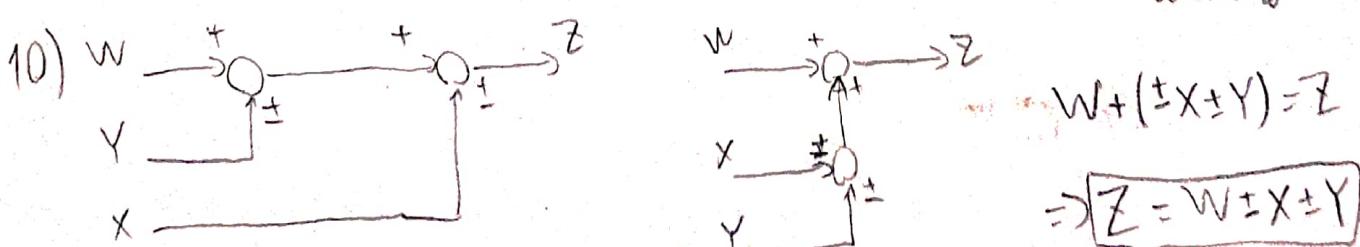
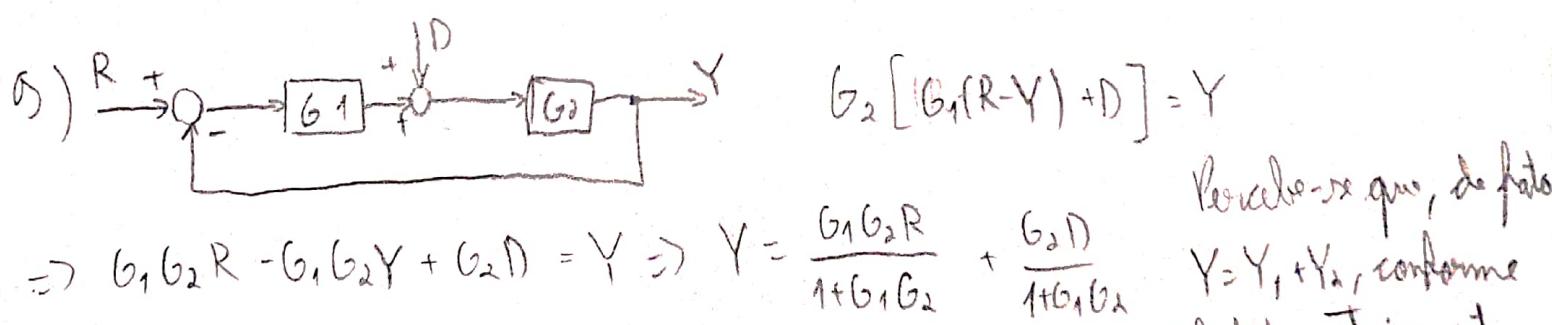
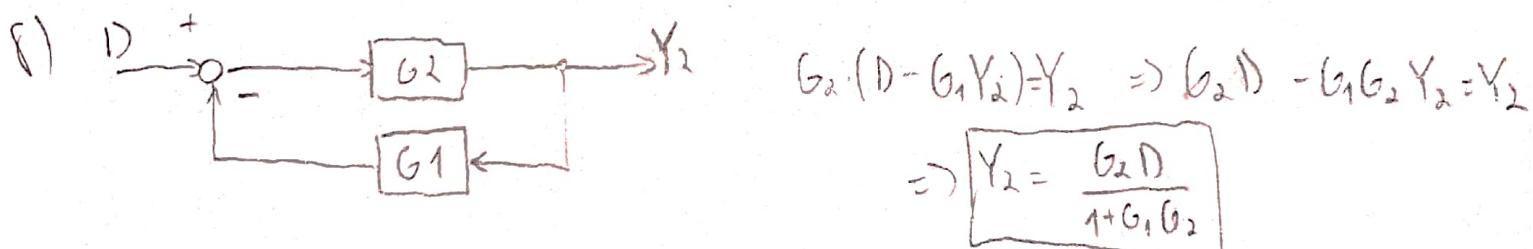
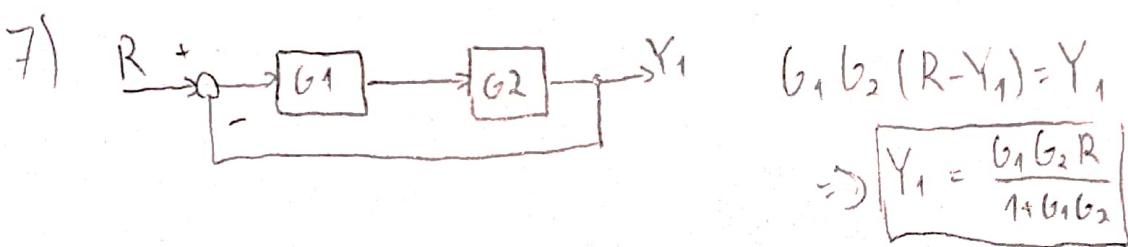
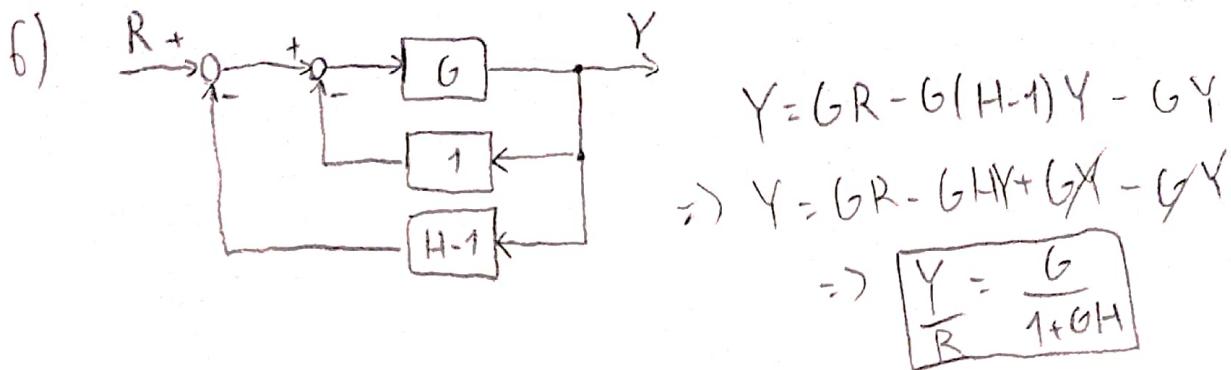
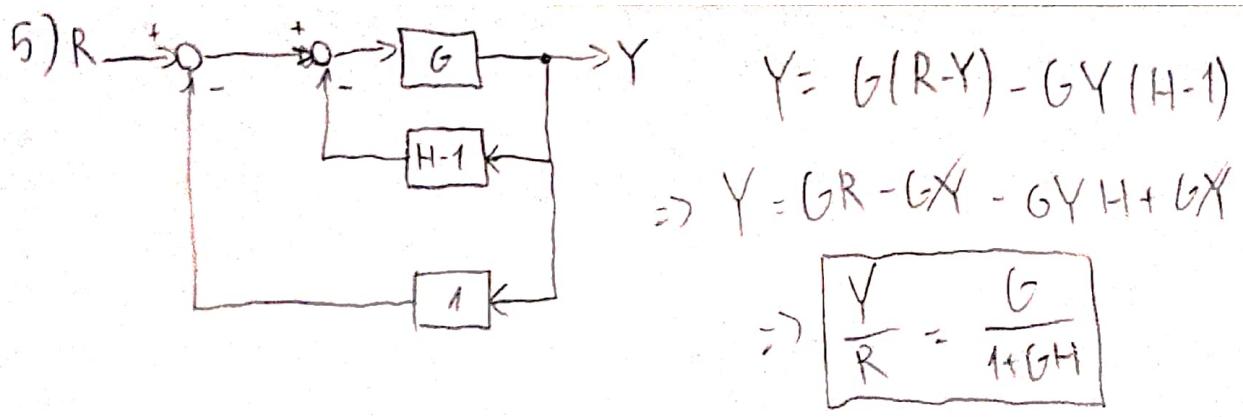
$$\boxed{\frac{Y}{R} = \frac{G}{1+GH}}$$



$$Y = (R - Y) \left(\frac{G}{1 + G(H + 1)} \right)$$

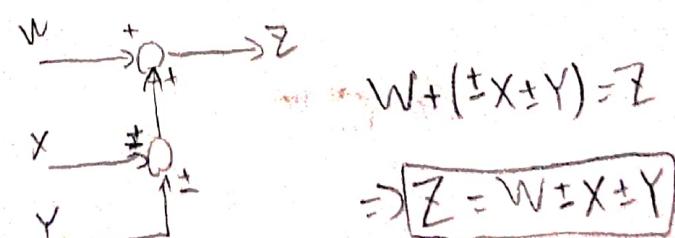
$$\Rightarrow Y \left(1 + \frac{G}{1 + G(H + 1)} \right) = \frac{RG}{1 + G(H + 1)} \Rightarrow Y = \frac{RG}{1 + G(H + 1)} \cdot \frac{1 + G(H + 1)}{1 + G(H + 1) + G} \Rightarrow$$

$$\boxed{\frac{Y}{R} = \frac{G}{1 + GH}}$$



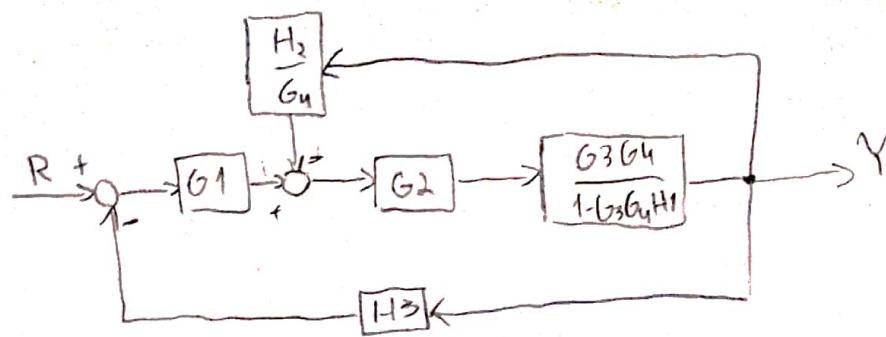
$$(W \pm Y) \pm X = Z$$

$$\Rightarrow \boxed{Z = W \pm X \pm Y}$$



✓

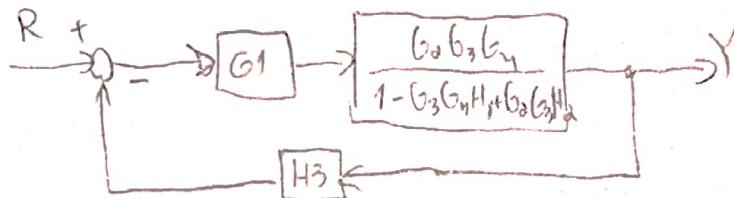
11)



$$\frac{G_3G_4}{1-G_3G_4H_1} \left\{ G_2 \left[G_1(R - H_3Y) - \frac{H_2}{G_4}Y \right] \right\} = Y$$

$$\Rightarrow \boxed{\frac{Y}{R} = \frac{G_1G_2G_3G_4}{1-G_3G_4H_1 + G_2G_3H_2 + G_1G_2G_3G_4H_3}}$$

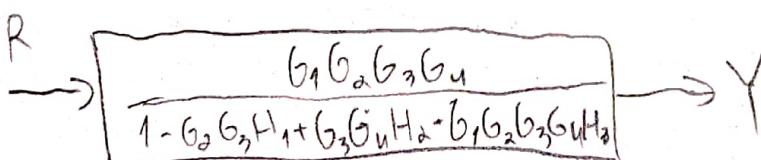
12)



$$\frac{G_2G_3G_4}{1-G_3G_4H_1 + G_2G_3H_2} \left[G_1 (R - H_3Y) \right] = Y$$

$$\Rightarrow \boxed{\frac{Y}{R} = \frac{G_1G_2G_3G_4}{1-G_2G_3H_1 + G_3G_4H_2 + G_1G_2G_3G_4H_3}}$$

13)



$$\frac{G_1G_2G_3G_4}{1-G_2G_3H_1 + G_3G_4H_2 + G_1G_2G_3G_4H_3} R = Y$$

$$\Rightarrow \boxed{\frac{Y}{R} = \frac{G_1G_2G_3G_4}{1-G_2G_3H_1 + G_3G_4H_2 + G_1G_2G_3G_4H_3}}$$