

PME 3380 - Modelagem de Sistemas Dinâmicos

Exc 03/11

Gabriel Rodrigues Camargo - 10772460

① Pelos slides temos:

$$Y = \underbrace{(I + GH)^{-1} G}_{T} R \Rightarrow T = (I + GH)^{-1} G$$



Diagrama de blocos de FTMF

$$Z = HY \Rightarrow R - E = HY \Rightarrow R - G^{-1}Y = HY \Rightarrow R = (G^{-1} + H)Y \Rightarrow$$

$$\Rightarrow R = (I + HG)G^{-1}Y \Rightarrow (I + HG)^{-1}R = G^{-1}Y \Rightarrow Y = G(I + HG)^{-1}R \Rightarrow$$

$$\Rightarrow T = G(I + HG)^{-1}$$

Logo prova-se

$$G(I + HG)^{-1} = (I + GH)^{-1}G = G(I + L)^{-1}$$

Onde usa-se $L = HG$

② $Z = HY \Rightarrow Z - HGE = HG(R - Z) \Rightarrow HGR = (I + HG)Z \Rightarrow \boxed{(I + HG)^{-1}HG = ZR^{-1}}$

Também temos

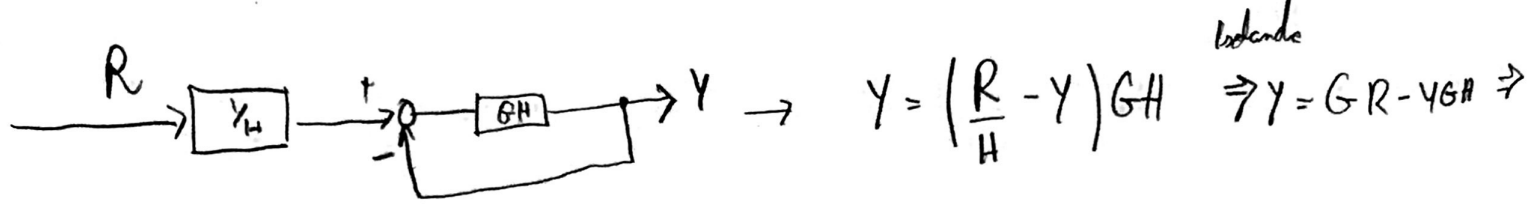
$$Y = GE \Rightarrow H^{-1}Z = G(R - Z) \Rightarrow GR = (H^{-1} + G)Z \Rightarrow GR = (I + GH)H^{-1}Z \Rightarrow$$

$$\Rightarrow \boxed{ZR^{-1} = H(I + GH)^{-1}G}$$

De mesma forma $L = HG$, logo

$$\frac{Z}{R} = \frac{L}{1+L} = \frac{GH}{1+GH} = \frac{HG}{1+HG} \Rightarrow Z = HY = HG(R - Z) \Rightarrow \frac{Z}{R} = \frac{HG}{1+HG}$$

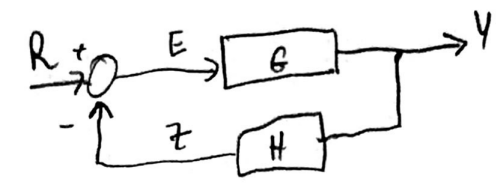
3



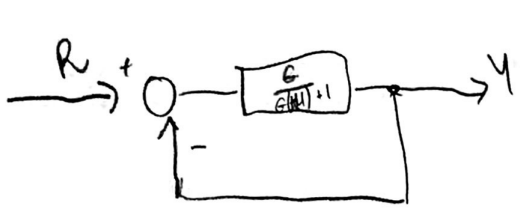
balando $\Rightarrow Y = \left(\frac{R}{H} - Y \right) GH \Rightarrow Y = GR - YGH \Rightarrow$

$\Rightarrow Y = \frac{GR}{1+GH}$

altern - de em bloco



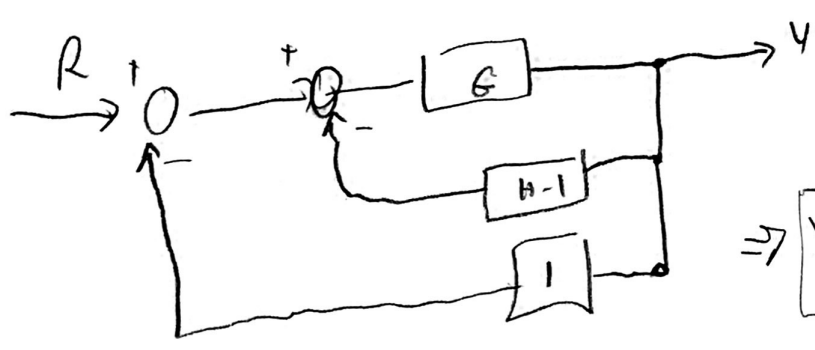
4



$Y = \left[\frac{G}{1+G(H-1)} \right] (R-Y)$ balando \Rightarrow

$\Rightarrow Y = \frac{GR}{1 + \frac{G}{1+G(H-1)}} \Rightarrow Y = \frac{GR}{G+1+G(H-1)} = \frac{GR}{1+GH} \Rightarrow Y = \frac{GR}{1+GH}$

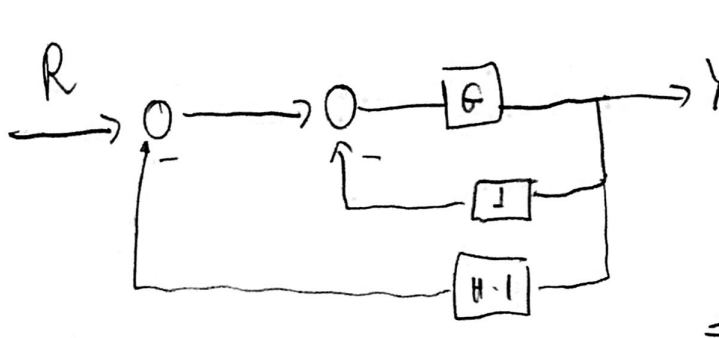
5



balando $\Rightarrow Y = [R - Y - Y(H-1)] G \Rightarrow$

$\Rightarrow Y = \frac{GR}{1+GH}$

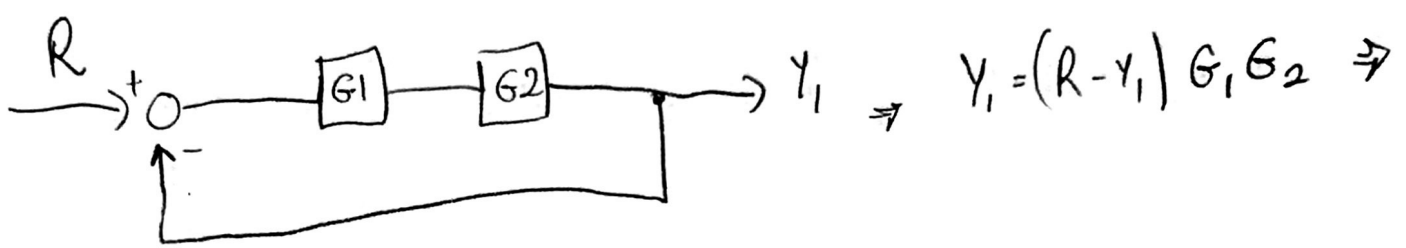
6



$\Rightarrow Y = [R - Y(H-1) - Y] G \Rightarrow$
 $\Rightarrow Y + GY + GY(H-1) = R \Rightarrow$

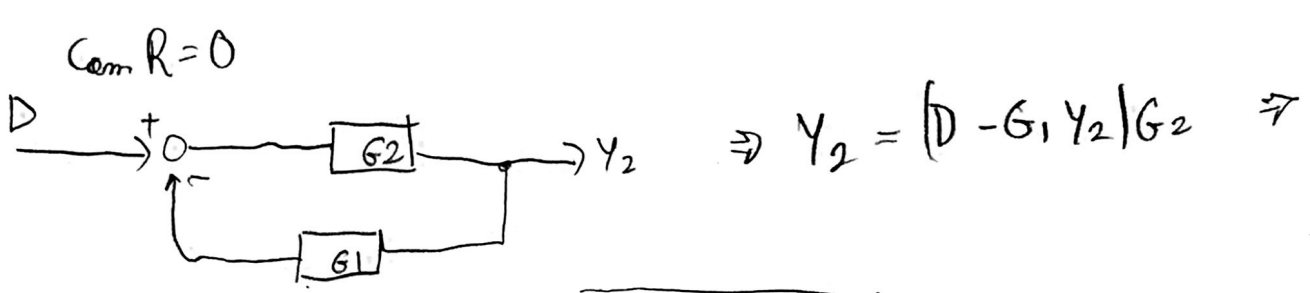
$\Rightarrow \frac{Y}{R} = \frac{G}{1+GH}$

7



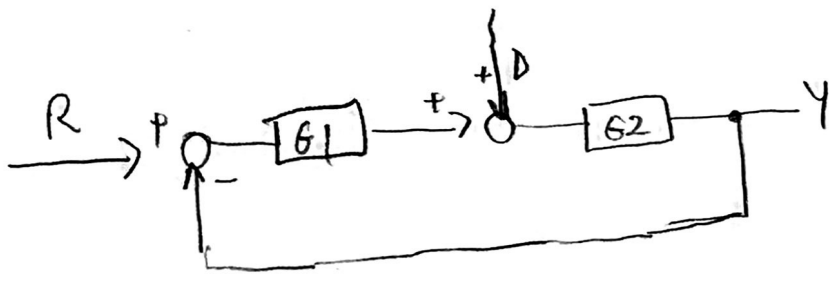
$\Rightarrow Y_1 = \frac{R G_1 G_2}{1 + G_1 G_2}$ em blocos: $R \rightarrow \boxed{\frac{G_1 G_2}{1 + G_1 G_2}} \rightarrow Y_1$

8



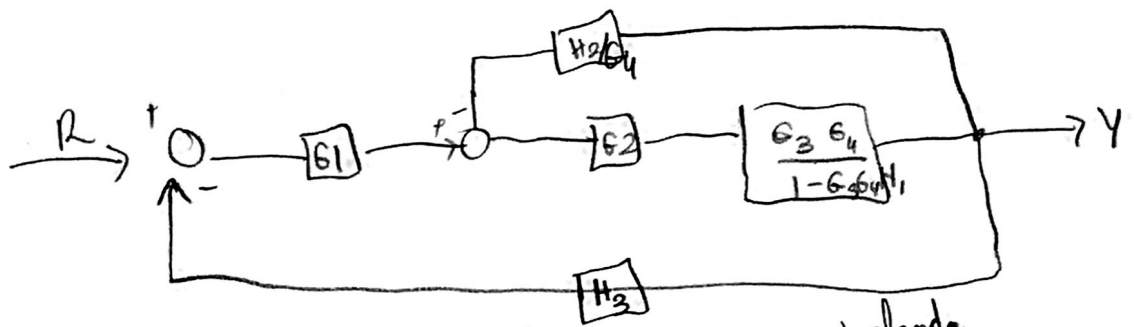
$\Rightarrow Y_2 (1 + G_1 G_2) = D G_2 \Rightarrow Y_2 = \frac{D G_2}{1 + G_1 G_2}$

9



$Y = [(R - Y)G_1 + D] G_2 \Rightarrow Y(1 + G_1 G_2) = (R G_1 + D) G_2 \Rightarrow Y = \frac{(R G_1 + D) G_2}{1 + G_1 G_2}$

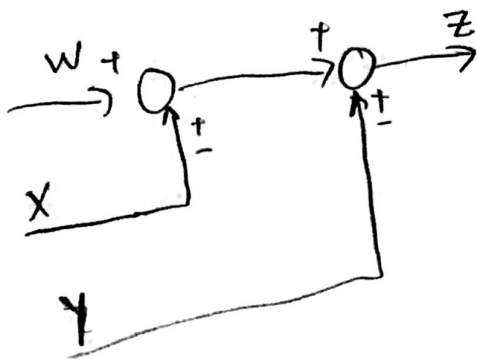
11



$Y = \left[(R - H_3 Y) G_1 - \frac{H_2 Y}{G_4} \right] \frac{G_2 G_3}{1 - G_3 G_4 H_1} \Rightarrow Y = \frac{G_1 G_2 G_3 G_4 R}{(1 - G_3 G_4 H_1 + G_1 G_2 G_3 G_4 H_3)}$ *balança*

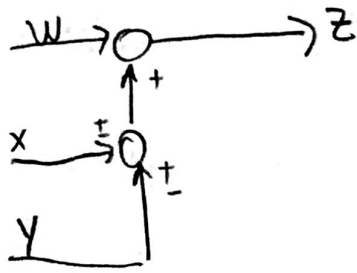
10

Blacas ignais!



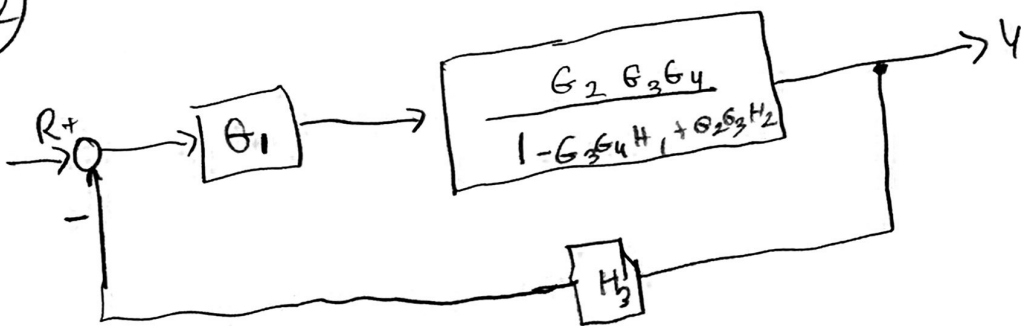
$$\Rightarrow Z = (W \pm X) \pm Y = W \pm X \pm Y$$

↕
⊖



$$\Rightarrow Z = (X \pm Y) + W = W \pm X \pm Y$$

12



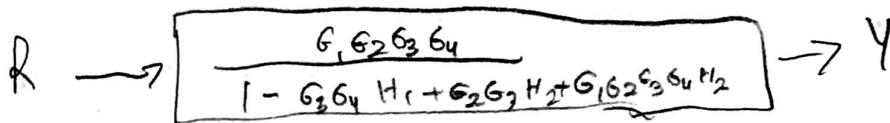
Logo

$$Y = \frac{G_2 G_3 G_4}{1 - G_3 G_4 H_1 + G_2 G_3 H_2} \left[G_1 (R - H_3 Y) \right]$$

↓ buscando

$$Y = \frac{G_1 G_2 G_3 G_4 R}{1 - G_3 G_4 H_1 + G_2 G_3 H_2 + G_1 G_2 G_3 G_4 H_3}$$

13



Logo

$$Y = \frac{G_1 G_2 G_3 G_4 R}{1 - G_3 G_4 H_1 + G_2 G_3 H_2 + G_1 G_2 G_3 G_4 H_2}$$