

1) $\dot{X} = AX + BU$

1.1) $\begin{bmatrix} \dot{X} \\ \dot{Y} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} U$

$\begin{bmatrix} sX(s) - X(0) \\ sY(s) - Y(0) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} U$

$Y = [1 \ 0] \begin{bmatrix} X \\ Y \end{bmatrix} = X \rightarrow \text{saída}$

$sX(s) = Y(s) + 0$
 $sY(s) = -100X(s) + 10U$
 $s^2X = -100X + 10U$
 $X(s^2 + 100) = 10U$
 $\frac{X}{U} = \frac{10U}{s^2 + 100} \Rightarrow FT$

* simulação última pg.

1.2)

$\begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \\ \dot{X}_3 \end{bmatrix} = \begin{bmatrix} -1 & 4 & 0 \\ 5 & 2 & 0 \\ -1 & 0 & -3 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 + 1 \\ X_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} U$; $Y = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix}$

$sX_1 = -X_1 + 4X_2$
 $sX_2 = 5X_1 + 2X_2 + U$
 $sX_3 = -X_1 - 3X_3$

$X_1 = 4X_2 / (s+1)$; $X_2 = X_1(s+1)/4$
 $sX_2 = \frac{20X_2 + 2X_2 + U}{s+1}$
 $(s - \frac{20}{s+1} - 2)X_2 = U \rightarrow \frac{X_2}{U} = \frac{s+1}{s^2 - s + 22}$

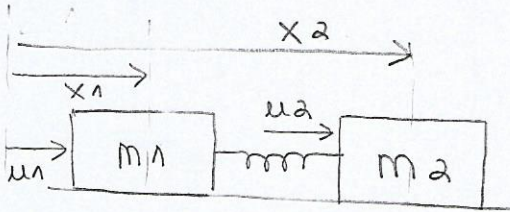
$\frac{X_2}{U} = \frac{X_1(s+1)}{4U} = \frac{s+1}{s^2 - s - 22} \rightarrow \frac{X_1}{U} = \frac{4}{s^2 - s - 22}$

Equação característica $\rightarrow (s^2 - s - 22)$
 zeros: $s = -1$;
 polos ($s^2 - s - 22 = 0$)
 $s = 5,217$; $s = -4,217$

2)

SISTEMA

$$\begin{cases} \ddot{x}_1 m_1 + k(x_1 - x_2) = \mu_1 \\ \ddot{x}_2 m_2 + k(x_2 - x_1) = \mu_2 \end{cases}$$



$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -k/m_1 & 0 & k/m_1 & 0 \\ 0 & 0 & 0 & 1 \\ k/m_2 & 0 & -k/m_2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_1 \\ x_2 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1/m_1 & 0 \\ 0 & 0 \\ 0 & 1/m_2 \end{bmatrix} \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$$

variáveis: x_1 e \dot{x}_2

$$\begin{bmatrix} r x_1 \\ r x_2 \\ r x_3 \\ r x_4 \end{bmatrix} = \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} + \begin{bmatrix} B \end{bmatrix} \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$$

$$r x_2 = -\frac{k}{m_1} x_1 + \frac{k x_3}{m_1} + \frac{\mu_1}{m_1} \rightarrow r^2 x_1 = -\frac{k x_1}{m_1} + \frac{k x_3}{m_1} + \frac{\mu_1}{m_1}$$

$$r x_1 = x_2$$

$$r x_3 = x_4$$

$$r x_4 = \frac{k}{m_2} x_1 - \frac{k x_3}{m_2} + \frac{\mu_2}{m_2}$$

$$r^2 x_3 = \frac{k}{m_2} x_1 - \frac{k x_3}{m_2} + \frac{\mu_2}{m_2}$$

$$\left(r^2 + \frac{k}{m_2}\right) x_3 = \frac{k}{m_2} x_1 + \frac{\mu_2}{m_2}$$

pólos: $r = 0; r = 0; r = \pm \sqrt{\frac{k}{m_1} + \frac{k}{m_2}}$

2.2)

baricentro $z_1 = \frac{m_2 x_2 + m_1 x_1}{(m_1 + m_2)}$

$$\Delta = z_2 = x_2 - x_1$$

$$\ddot{x}_1 m_1 + \ddot{x}_2 m_2 = \mu_1 + \mu_2$$

$$\ddot{z}_2 = \ddot{x}_2 - \ddot{x}_1$$

$$\ddot{z}_2 = \frac{\mu_2 - k z_2}{m_2} - \frac{\mu_1 + k z_2}{m_1}$$

$$\ddot{z}_1 = \frac{\mu_1 + \mu_2}{(m_1 + m_2)}$$

