

Exercício

⊕

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$$\text{II) } \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} u$$

↳ Transformada

$$\begin{bmatrix} sX_1 - x_1(0) \\ sX_2 - x_2(0) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} X + \begin{bmatrix} 0 \\ 10 \end{bmatrix} U$$

$$x_1(0) = x_2(0) = 0$$

$$\begin{bmatrix} sX_1 \\ sX_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} X + \begin{bmatrix} 0 \\ 10 \end{bmatrix} U$$

$$\begin{cases} sX_1 = X_2 & \text{I} \\ sX_2 = -100X_1 + 10U & \text{II} \end{cases}$$

↳ Saída = X_1 ; entrada = U I em II

$$s^2 X_1 = -100X_1 + 10U$$

$$\frac{X_1}{U} = \frac{10}{s^2 + 100}$$

Femmini

(2)



1.2) Determinando as saídas

$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \Rightarrow \begin{array}{l} Y_1 = X_2 \\ \underline{Y_2 = X_1} \end{array}$$

↳ Autovalores e eq. característica

$$\begin{vmatrix} -1-\lambda & 4 & 0 \\ 5 & 2-\lambda & 0 \\ -1 & 0 & -3-\lambda \end{vmatrix} \Rightarrow (-1-\lambda)(2-\lambda)(-3-\lambda) - 20(-3-\lambda) = 0$$

$\lambda = -3$

$$(-1-\lambda)(2-\lambda) - 20 = 0$$

$$\lambda = \frac{1 \pm \sqrt{89}}{2}$$

↳ Determinando as FTE

$$\begin{array}{l} sX_1 \\ sX_2 \\ sX_3 \end{array} = \begin{bmatrix} -1 & 4 & 0 \\ 5 & 2 & 0 \\ -1 & 0 & -3 \end{bmatrix} \begin{array}{l} X_1 \\ X_2 \\ X_3 \end{array} + \begin{array}{l} 0 \\ 1 \\ 0 \end{array} U$$

$$\begin{cases} sX_1 = -X_1 + 4X_2 & \textcircled{\text{I}} \\ sX_2 = 5X_1 + 2X_2 + U & \textcircled{\text{II}} \\ sX_3 = -X_1 - 3X_3 & \textcircled{\text{III}} \end{cases}$$

Feminina

(3)

↳ Por (I)

$$X_1 = \frac{4}{s+1} X_2 \quad \text{(IV)}$$

↳ (IV) em (II)

$$s X_2 = 5 \left(\frac{4}{s+1} \right) X_2 + 2 X_2 + U$$

$$s(s+1)X_2 = 20 X_2 + 2(s+1)X_2 + (s+1)U$$

$$G_1 = \frac{X_2}{U} = \frac{(s+1)}{(s+1)(s-2)-20} \quad \left| \begin{array}{l} \Rightarrow \text{zero} \Rightarrow s = -1 \\ \text{polos} \Rightarrow s = \frac{1 \pm \sqrt{89}}{2} \end{array} \right.$$

↳ (IV) em (II)

$$X_2 = \frac{s+1}{4} X_1$$

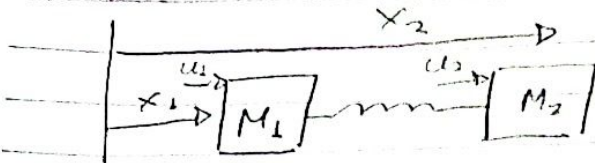
$$s \left(\frac{s+1}{4} \right) X_1 = 5 X_1 + 2 \left(\frac{s+1}{4} \right) X_1 + U$$

$$s(s+1)X_1 = 20X_1 + 2(s+1)X_1 + 4U$$

$$G_2 = \frac{X_1}{U} = \frac{4}{(s+1)(s-2)-20} \quad \left| \begin{array}{l} \Rightarrow \text{zero} = \{\emptyset\} \\ \text{polos} = s = \frac{1 \pm \sqrt{89}}{2} \end{array} \right.$$

Os polos são os autovalores de A

2.1)



$$\begin{cases} m_1 \ddot{x}_1 = u_1 + K(x_2 - x_1) \\ m_2 \ddot{x}_2 = u_2 - K(x_2 - x_1) \end{cases}$$

$$\begin{bmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -K/m_1 & K/m_1 \\ K/m_2 & -K/m_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1/m_1 & 0 \\ 0 & 1/m_2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

↳ Auto valores

$$\begin{vmatrix} -\lambda & 0 & 1 & 0 \\ 0 & -\lambda & 0 & 1 \\ -K/m_1 & K/m_1 & -\lambda & 0 \\ K/m_2 & -K/m_2 & 0 & -\lambda \end{vmatrix} = \lambda^4 + \frac{K^2}{m_1 m_2} + \lambda^2 K + \lambda^2 K$$

$$\lambda^4 + \left(\frac{K}{m_1} + \frac{K}{m_2} \right) \lambda^2 + \frac{K^2}{m_1 m_2} = 0$$

$$\lambda^2 = \frac{-\left(\frac{K}{m_1} + \frac{K}{m_2} \right) \pm \sqrt{\left(\frac{K}{m_1} + \frac{K}{m_2} \right)^2 - 4 \cdot \frac{K^2}{m_1 m_2}}}{2}$$

Resonância

5

↳ F.T

$$G = [C(sI - A)^{-1}B + D]$$

Peço matlab calcule-se

$$G_{11} = \frac{m_1 m_2 s (m_2 s^2 + 2k)}{F}$$

$$G_{12} = \frac{k m_1 m_2 s}{F}$$

$$G_{21} = \frac{k m_1 m_2 s^2}{F}$$

$$G_{22} = \frac{-(k^2 m_2 - k^2 m_1 + k m_1 m_2 s^2)}{F}$$

$$\text{Onde } F = 2k^2 m_2 - 2m_1 k^2 + k m_2^2 s^2 + 2m_1 k m_2 s^2 + m_1 m_2^2 s^4$$

Os resultados dos autovalores e polos ficaram iguais como se nota a seguir com o programa em matlab

Código do programa

```
1 - syms k m1 m2 s;
2
3 - A=[0 0 1 0; 0 0 0 1; -k/m1 k/m2 0 0; k/m2 -k/m2 0 0];
4 - B=[0 0; 0 0; 1/m1 0; 0 1/m2];
5 - C=[1 0 0 0; 0 0 0 1];
6
7 - G=C*inv(s*eye(4,4)-A)
8
9 - Polos=solve(2*k^2*m2 - 2*m1*k^2 + k*m2^2*s^2 + 2*m1*k*m2*s^2 + m1*m2^2*s^4==0)
10
11 - autovalores=eig(A)
```

Resultados

Polos =

```
-(-(2*k*m1 + k*m2 + k*(12*m1^2 - 4*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
-(-(2*k*m1 + k*m2 - k*(12*m1^2 - 4*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
(-(2*k*m1 + k*m2 + k*(12*m1^2 - 4*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
(-(2*k*m1 + k*m2 - k*(12*m1^2 - 4*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
```

autovalores =

```
-(-(k*m1 + k*m2 + k*(5*m1^2 - 2*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
-(-(k*m1 + k*m2 - k*(5*m1^2 - 2*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
(-(k*m1 + k*m2 + k*(5*m1^2 - 2*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
(-(k*m1 + k*m2 - k*(5*m1^2 - 2*m1*m2 + m2^2)^(1/2))/(2*m1*m2))^(1/2)
```

