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- Exercício de dia 20/10 -

Ex.: Determinar as funções de transferência

$$\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} \cdot u$$

Transformada de Laplace:

$$\begin{bmatrix} sX(s) - x(0) \\ sY(s) - y(0) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -100 & 0 \end{bmatrix} \begin{bmatrix} X(s) \\ Y(s) \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} \cdot U(s)$$

$$\begin{cases} sX(s) = \cancel{X(s)} \\ sY(s) = -100X(s) + 10U(s) \end{cases} \Rightarrow X(s) = \frac{Y(s)}{s} \quad (1)$$
$$(2)$$

Substituindo (1) em (2):

$$sY(s) = -100 \cdot \cancel{\frac{Y(s)}{s}} + 10 \cdot U(s)$$

~~$$s^2Y(s) = -100Y(s) + 10U(s)$$~~

$$\Rightarrow \left( s + \frac{100}{s} \right) Y(s) = 10U(s) \Rightarrow \left( \frac{s^2 + 100}{s} \right) Y(s) = 10U(s)$$

$$\Rightarrow Y(s) = \frac{10s}{s^2 + 100} \therefore X(s) = \frac{10U(s)}{s^2 + 100}$$

Função de transferência:

$$F \cdot T(x) = \frac{10}{s^2 + 100}$$

$$F \cdot T(y) = \frac{10}{s^2 + 100}$$

1.2 -  $\begin{bmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{bmatrix} = \begin{bmatrix} -1 & 4 & 0 \\ 5 & 2 & 0 \\ -1 & 0 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \cdot u$

→ Por domínio do tempo:

Solução homogênea

$$\begin{cases} \dot{x} = -x + 4y \\ \dot{y} = 5x + 2y \\ \dot{z} = -x - 3z \end{cases}$$

$$\Rightarrow \begin{bmatrix} A \cdot e^{\lambda t} \\ B \cdot x e^{\lambda t} \\ C \cdot z e^{\lambda t} \end{bmatrix} = \begin{bmatrix} -1 & 4 & 0 \\ 5 & 2 & 0 \\ -1 & 0 & -3 \end{bmatrix} \begin{bmatrix} A \cdot e^{\lambda t} \\ B \cdot e^{\lambda t} \\ C \cdot e^{\lambda t} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -1-\lambda & 4 & 0 \\ 5 & 2-\lambda & 0 \\ -1 & 0 & -3-\lambda \end{bmatrix} \begin{bmatrix} A \\ B \\ C \end{bmatrix} \cdot e^{\lambda t} = 0$$

$$\det \begin{vmatrix} -1-\lambda & 4 & 0 \\ 5 & 2-\lambda & 0 \\ -1 & 0 & -3-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (2-\lambda)(-3-\lambda)(-1-\lambda) - 5(-3-\lambda)4 - (2-\lambda)(-1)\cancel{-}0 = 0$$

$$\Rightarrow (-3-\lambda)[(2-\lambda)(-1-\lambda) - 20] = 0$$

~~$\therefore (-3-\lambda) = 0 \Rightarrow \lambda = -3$~~

$$\therefore (2-\lambda)(-1-\lambda) - 20 = 0 \Rightarrow -2 - 2\lambda + \lambda + \lambda^2 = 20$$

$$\Rightarrow \lambda^2 - \lambda - 22 = 0 \Rightarrow \lambda = \frac{-1 \pm \sqrt{1+88}}{2} = \frac{1 \pm \sqrt{89}}{2}$$

~~$\lambda_2 = \frac{1 - \sqrt{89}}{2}$~~

~~$\lambda_3 = \frac{1 + \sqrt{89}}{2}$~~

↳ Por Domínio da Freqüência:

Transformada de Laplace:

$$\begin{bmatrix} sX(s) - X(0) \\ sY(s) - Y(0) \\ sZ(s) - Z(0) \end{bmatrix} = \begin{bmatrix} -1 & 4 & 0 \\ 5 & 2 & 0 \\ -1 & 0 & -3 \end{bmatrix} \begin{bmatrix} X(s) \\ Y(s) \\ Z(s) \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \cdot U(s)$$

$$\begin{cases} sX(s) = -X(s) + 4Y(s) \\ sY(s) = 5X(s) + 2Y(s) + U(s) \\ sZ(s) = -X(s) - 3Z(s) \end{cases}$$

de (1):  $(s+1)X(s) = 4Y(s)$   
 $\Rightarrow X(s) = \frac{4Y(s)}{s+1}$  (4)

substituindo em (2):

$$sY(s) = \frac{20Y(s)}{s+1} + 2Y(s) + U(s)$$

$$\Rightarrow \left( s - \frac{20}{s+1} - 2 \right) Y(s) = U(s)$$

$$\Rightarrow \left( \frac{s^2 + s - 20 - 2s - 2}{s+1} \right) Y(s) = U(s)$$

$$\Rightarrow Y(s) = \frac{(s+1) \cdot U(s)}{s^2 - s - 22} \quad (5)$$

substituindo em (4):

$$X(s) = \frac{4U(s)}{s^2 - s - 22} \quad (6)$$

substituindo em (3):

$$sZ(s) = -\frac{4U(s)}{s^2 - s - 22} - 3Z(s)$$

$$\Rightarrow (s+3)Z(s) = -\frac{4U(s)}{s^2 - s - 22} \Rightarrow Z(s) = -\frac{4U(s)}{(s^2 - s - 22)(s+3)}$$

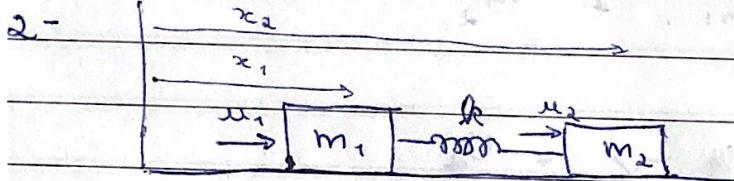
Função de Transferência:  $FT(s) = \frac{\frac{4}{s+1}}{(s^2-s-22)}$

Poles:

$$(s^2 - s - 22)(s + 3) = 0$$

$$\lambda_1 = -3, \quad \lambda_2 = \frac{1 - \sqrt{89}}{2}, \quad \lambda_3 = \frac{1 + \sqrt{89}}{2}$$

Percebe-se que os autovalores e os polos coincidem.



$$m_1 \ddot{x}_1 = u_1 + k(x_2 - x_1)$$

$$m_2 \ddot{x}_2 = u_2 - k(x_2 - x_1)$$

$$\begin{bmatrix} \dot{x}_1 \\ \ddot{x}_1 \\ \dot{x}_2 \\ \ddot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -\frac{k}{m_1} & 0 & \frac{k}{m_1} & 0 \\ 0 & 0 & 0 & 1 \\ \frac{k}{m_2} & 0 & -\frac{k}{m_2} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ \dot{x}_1 \\ x_2 \\ \dot{x}_2 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ \frac{1}{m_1} & 0 \\ 0 & 0 \\ 0 & \frac{1}{m_2} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

→ Para domínio do tempo:

$$\det \begin{vmatrix} -\lambda & 1 & 0 & 0 \\ -\frac{k}{m_1} & -\lambda & \frac{k}{m_1} & 0 \\ 0 & 0 & -\lambda & 1 \\ \frac{k}{m_2} & 0 & -\frac{k}{m_2} & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^4 + \frac{k^2}{m_1+m_2} = \frac{k^2}{m_1+m_2} = 0$$

$$\Rightarrow \lambda^4 = 0 \Rightarrow \lambda = 0$$

→ Para ilumínio da Freqüência:

$$\begin{bmatrix} \ddot{x}_1 - \dot{x}_1(0) \\ \ddot{x}_2 - \dot{x}_2(0) \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -\frac{k}{m_1} & 0 & \frac{k}{m_1} & 0 \\ 0 & 0 & 0 & 1 \\ \frac{k}{m_2} & 0 & -\frac{k}{m_2} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ \dot{x}_1 \\ x_2 \\ \dot{x}_2 \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{u_1}{m_1} \\ 0 \\ \frac{u_2}{m_2} \end{bmatrix}$$

$$\left\{ \begin{array}{l} \ddot{x}_1 = \dot{x}_1 \\ \ddot{x}_1 = -\frac{k}{m_1} x_1 + \frac{k}{m_1} x_2 + \frac{u_1}{m_2} \\ \ddot{x}_2 = \dot{x}_2 \\ \ddot{x}_2 = \frac{k}{m_2} x_1 - \frac{k}{m_2} x_2 + \frac{u_2}{m_1} \end{array} \right.$$

$$x_1 = \frac{-\frac{k}{m_2} \cdot \frac{u_1}{m_1} - \omega^2 \cdot \frac{u_1}{m_1} - \frac{k}{m_2} \cdot \frac{u_2}{m_1}}{\left(\frac{k}{m_1} + \frac{k}{m_2} + \omega^2\right) \omega^2}$$

$$\dot{x}_1 = \frac{-\frac{k}{m_2} \cdot \frac{u_1}{m_1} - \omega^2 \cdot \frac{u_1}{m_1} - \frac{k}{m_1} \cdot \frac{u_2}{m_2}}{\left(\frac{k}{m_1} + \frac{k}{m_2} + \omega^2\right) \omega}$$

$$x_2 = \frac{-\frac{k}{m_2} \cdot \frac{u_1}{m_1} - \frac{k}{m_1} \cdot \frac{u_2}{m_2} - \omega^2 \cdot \frac{u_2}{m_2}}{\left(\frac{k}{m_1} + \frac{k}{m_2} + \omega^2\right) \omega^2}$$

$$\dot{x}_2 = \frac{-\frac{k}{m_2} \cdot \frac{u_1}{m_1} - \frac{k}{m_1} \cdot \frac{u_2}{m_2} - \omega^2 \cdot \frac{u_2}{m_2}}{\left(\frac{k}{m_1} + \frac{k}{m_2} + \omega^2\right) \omega}$$

Pontos:  $s_1 = 0$ ,  $s_2 = 0$ ,  $s_3 = \sqrt{\frac{k}{m_1} + \frac{k}{m_2}}$  i,  $s_4 = -\sqrt{\frac{k}{m_1} + \frac{k}{m_2}}$  i

2.2 - O resultado é o mesmo do exercício anterior.

Isso porque somente realiza uma mudança de variável ao se usar o bárcentro e a distância das bolas como variáveis de estado.

$$x_F = \frac{x_1 + x_2}{2} \quad | \quad \delta = x_2 - x_1$$