

$$\begin{cases} \ddot{x} = (u_1 + u_2)/M \\ \ddot{\delta} = -kM\delta + \frac{u_1}{M_1} - \frac{u_2}{M_2} \end{cases}$$

$$\begin{cases} (2) M\ddot{x} + b(\dot{x} - \dot{y}) + k_1(x - y) = 0 \\ m\ddot{y} - b(\dot{x} - \dot{y}) - k_1(x - y) - k_2(y - z) = 0 \end{cases}$$

$$\begin{aligned} z &= [\bar{x} \quad \delta \quad \dot{x} \quad \dot{\delta}]^T \\ \dot{z} &= [\dot{\bar{x}} \quad \dot{\delta} \quad \ddot{x} \quad \ddot{\delta}]^T \end{aligned}$$

$$\begin{aligned} \dot{X} &= [x \quad y \quad \dot{x} \quad \dot{y}]^T & \dot{X} &= AX + Bz \\ \begin{bmatrix} \dot{x} \\ \dot{y} \\ \ddot{x} \\ \ddot{y} \end{bmatrix} &= \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -k_1/M & k_1/M & -b/M & b/M \\ k_1/m & -\frac{k_1 - k_2}{m} & b/m & -b/m \end{bmatrix} \begin{bmatrix} x \\ y \\ \dot{x} \\ \dot{y} \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ k_2/m \end{bmatrix} z \end{aligned}$$

$$\begin{aligned} \begin{bmatrix} \ddot{x} \\ \ddot{\delta} \\ \dot{x} \\ \dot{\delta} \end{bmatrix} &= \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & -kM/M_1M_2 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ \delta \\ \dot{x} \\ \dot{\delta} \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ M_1/M_2 \\ M_1 - 1/M_2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \\ &= A \quad B \end{aligned}$$

$$\begin{cases} (3) m\ddot{y} + b(\dot{y} - \dot{x}) + k(y - x) = 0 \\ M\ddot{x} - b(\dot{y} - \dot{x}) - k(\dot{y} - \dot{x}) = u \end{cases}$$

$$y = [x_1 \quad x_2]^T$$

$$X = [x \quad y \quad \dot{x} \quad \dot{y}]^T \quad \dot{X} = AX + B \rightarrow u$$

$$\begin{aligned} \begin{bmatrix} \ddot{x} \\ \delta \end{bmatrix} &= \begin{bmatrix} M_1/M \\ 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} &= \begin{bmatrix} M \\ -1 \end{bmatrix}^{-1} \begin{bmatrix} \bar{x} \\ \delta \end{bmatrix} \\ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} &= \begin{bmatrix} M_2/M \\ M_1/M \end{bmatrix} \begin{bmatrix} \bar{x} \\ \delta \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \begin{bmatrix} \dot{x} \\ \dot{y} \\ \ddot{x} \\ \ddot{y} \end{bmatrix} &= \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -k/M & k/M & -b/M & b/M \\ k/m & -k/m & b/m & -b/m \end{bmatrix} \begin{bmatrix} x \\ y \\ \dot{x} \\ \dot{y} \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1/m \end{bmatrix} u(t) \end{aligned}$$

$$\begin{bmatrix} 1/M & 0 & 0 \\ 1/M & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \bar{x} \\ \delta \\ \dot{\bar{x}} \\ \dot{\delta} \end{bmatrix} \quad C \quad z$$

$$\begin{aligned} (4) \quad m_1 \ddot{x}_1 - b_1(\dot{x}_G - \dot{x}_1 + \dot{\theta}) - k_1(x_G - x_1 + l\theta) + k(x_1 - z) &= 0 \\ m_2 \ddot{x}_2 - b_2(\dot{x}_G - \dot{x}_2 - \dot{\theta}) - k_2(x_G - x_2 - l\theta) + k(x_2 - z) &= 0 \\ M\ddot{x}_G + b_1(\dot{x}_G - \dot{x}_1 + \dot{\theta}) + b_2(\dot{x}_G - \dot{x}_2 - \dot{\theta}) + & \\ + k_1(x_G - x_1 + l\theta) + k_2(x_G - x_2 - l\theta) &= 0 \\ J_G \ddot{\theta} + b_1 l(\dot{x}_G - \dot{x}_1 + \dot{\theta}) - b_2 l(\dot{x}_G - \dot{x}_2 - \dot{\theta}) + & \\ + k_1 l(x_G - x_1 + l\theta) - k_2 l(x_G - x_2 - l\theta) &= 0 \end{aligned}$$

$$\bar{x} = [x_1 \quad x_2 \quad x_G \quad \theta]^T \Rightarrow \dot{X} = [X \quad \dot{X}]^T$$

$$\dot{X} = AX + BU, \text{ com } U = [z(t), z(t-d)]^T$$

$$A = \begin{bmatrix} O_{4 \times 4} & I_{4 \times 4} \\ \bar{A}_{4 \times 4} & \bar{\bar{A}}_{4 \times 4} \end{bmatrix} \quad B = \begin{bmatrix} O_{2 \times 1} \\ k \\ k \end{bmatrix}$$

$$\textcircled{6} \quad m\ddot{x} = mg - kI^2/x^2 \\ LI + RI = V$$

$$\bar{A} = \begin{bmatrix} \frac{-k_1+k}{m_1} & k_1/m_1 & k_{1l}/m_1 & \\ & \frac{-k_2+k}{m_2} & k_2/m_2 & -k_{2l}/m_2 \\ k_1/M & k_2/M & -\frac{k_1+k_2}{M} & l\frac{k_2-k_1}{M} \\ k_{1l}/J & -k_{2l}/J & l\frac{k_2-k_1}{J} & -l^2\frac{k_2+k_1}{J} \end{bmatrix}$$

$$\ddot{x} = 2i_0 I - 2i_0^2 x \\ m x_0^2 \quad m x_0^3 \\ j = (-R/L)I + V/L$$

$$X = \begin{bmatrix} x & \dot{x} & I \end{bmatrix}$$

$$\dot{X} = AX + BV$$

$$\bar{\bar{A}} = \begin{bmatrix} -b_1/m_1 & b_1/m_1 & b_{1l}/m_1 & \\ & -b_2/m_2 & b_2/m_2 & -b_{2l}/m_2 \\ b_1/M & M & -\frac{b_1+b_2}{M} & -l\frac{b_1-b_2}{M} \\ b_{1l}/J & -b_{2l}/J & l\frac{b_1-b_2}{J} & l^2\frac{b_1-b_2}{J} \end{bmatrix}$$

$$A = \begin{bmatrix} & & 1 \\ -2i_0^2/mx_0^3 & & \\ & 2i_0/mx_0^2 & \\ & & -R/L \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 0 \\ 1/L \end{bmatrix}$$

Obs:  $\bar{A}$  e  $\bar{\bar{A}}$  são, na representação (M, CK),  $M^{-1}K$  e  $M^{-1}C$ , respectivamente

$$Y = CX + DV \quad C = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad D = O_{3 \times 1}$$

$$\textcircled{5} \quad \begin{cases} (M+m)\ddot{x} + ml\ddot{\theta} = u & \leftarrow \ddot{\theta} = \dots \\ J\ddot{\theta} + ml\ddot{x} - mlq\theta = 0 & \ddot{x} = \dots \end{cases}$$

$$\ddot{x} = \frac{J[(m+M)+1]\theta - J u}{m^2 l^2 - (m+M)J} \quad \frac{ml^2 - (m+M)J}{m^2 l^2 - (m+M)J}$$

$$\ddot{\theta} = \frac{-mlq(m+M)\theta + ml u}{m^2 l^2 - (m+M)J} \quad \frac{ml^2 - (m+M)J}{m^2 l^2 - (m+M)J}$$

Escreveremos  $\ddot{x} = c_1 \theta + d_1 u$   
 $\ddot{\theta} = c_2 \theta + d_2 u$

$$X = \begin{bmatrix} x & \theta & \dot{x} & \dot{\theta} \end{bmatrix}^T \quad \dot{X} = AX + Bu$$

$$A = \begin{bmatrix} O_{2 \times 2} & I_{2 \times 2} \\ 0 & c_1 & 0 \\ 0 & c_2 & 2 \times 2 \end{bmatrix} \quad B = \begin{bmatrix} O_{2 \times 1} \\ d_1 \\ d_2 \end{bmatrix}$$