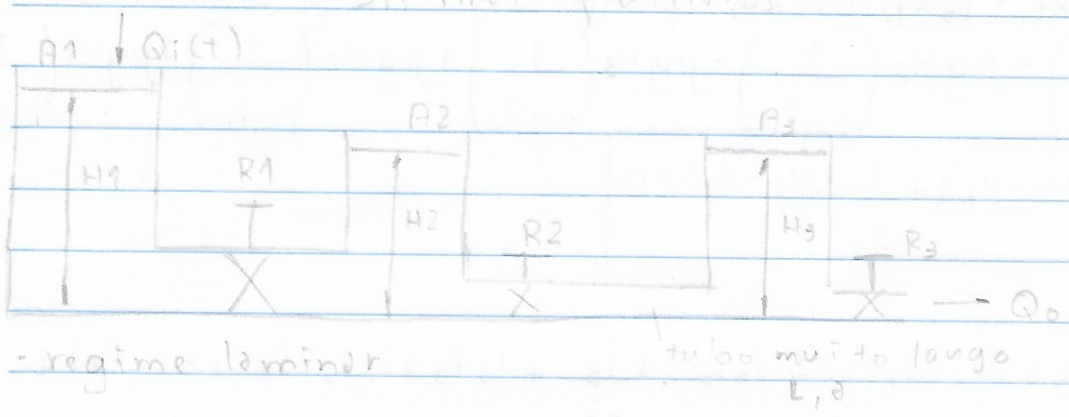
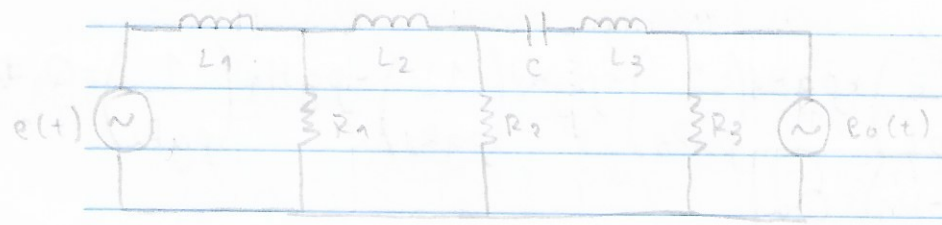


Victor Manoel Ferrsira Rosa da Costa 10772713

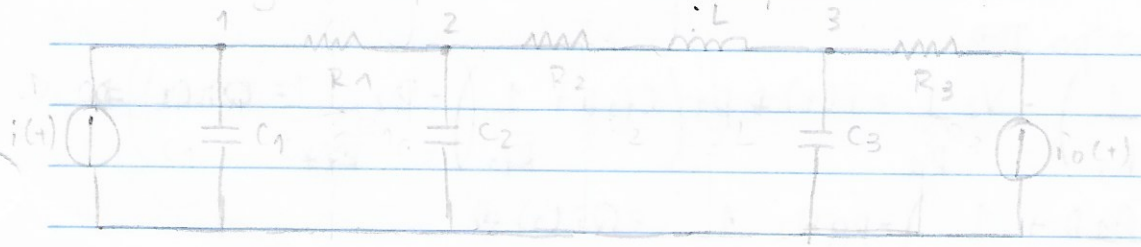
Sistemas fluidicos



2) Analogia tipo I $\rightarrow Q \rightarrow V$ $p \rightarrow i$



b) Analogia tipo II $\rightarrow Q \rightarrow i$ $p \rightarrow V$



c) Analogia tipo I \rightarrow

$$V_{L1} + V_{R1} = e(t) \Rightarrow i_1 L_1 D + i_1 R_1 - i_2 R_1 = e(t) \Rightarrow$$

$$\Rightarrow p_1 C_1 D + p_1 \bar{R}_1 - p_2 \bar{R}_1 = Q_i(t) \Rightarrow p g H_1 \left(\frac{A_1 D}{\rho g} \right) + p g H_1 \left(\frac{1}{\rho g R_1} \right) -$$

$$- p g H_2 \left(\frac{1}{\rho g R_1} \right) = Q_i(t) \Rightarrow \boxed{A_1 H_1 + \frac{1}{R_1} (H_1 - H_2) = Q_i(t)}$$



$$V_{L2} + V_{R2} + V_{R1} = 0 \Rightarrow \bar{i}_2 L_2 D + \bar{i}_2 R_2 - \bar{i}_3 R_2 + \bar{i}_2 R_1 - \bar{i}_1 R_1 = 0 \Rightarrow$$

$$\Rightarrow p_2 C_{f2} D + p_2 \bar{R}_{f2} - p_3 \bar{R}_{f2} + p_2 \bar{R}_{f1} - p_1 \bar{R}_{f1} = 0 \Rightarrow$$

$$\Rightarrow p g H_2 \left(\frac{A_2 D}{p g} \right) + p g H_2 \left(\frac{1}{p g R_2} \right) - p g H_3 \left(\frac{1}{p g R_2} \right) + p g H_2 \left(\frac{1}{p g R_1} \right) - p g H_1 \left(\frac{1}{p g R_1} \right) = 0 \Rightarrow$$

$$\Rightarrow \boxed{A_2 H_2 + \frac{1}{R_2} (H_2 - H_3) + \frac{1}{R_1} (H_2 - H_1) = 0}$$

$$V_{L3} + V_C + V_{R3} + V_{R2} = e_0(t) \Rightarrow \bar{i}_3 L_3 D + \bar{i}_3 \frac{C}{D} + \bar{i}_3 R_3 + \bar{i}_2 R_2 - \bar{i}_1 R_2 = e_0(t) \Rightarrow$$

$$\Rightarrow p_3 C_{f3} D + \frac{p_3}{L_3 D} + p_3 \bar{R}_{f3} + p_2 \bar{R}_{f2} - p_1 \bar{R}_{f2} = Q_0 \Rightarrow$$

$$\Rightarrow p g H_3 \left(\frac{A_3 D}{p g} \right) + p g H_3 \left(\frac{2}{p L} \right) + p g H_3 \left(\frac{1}{p g R_3} \right) + p g H_2 \left(\frac{1}{p g R_2} \right) - p g H_1 \left(\frac{1}{p g R_2} \right) = Q_0 \Rightarrow$$

$$\Rightarrow \boxed{A_3 H_3 + \frac{1}{R_3} H_3 + \frac{1}{R_2} (H_2 - H_1) = Q_0}$$

Analogia tipo II

$$V_1 \left(\frac{C_1 D + 1}{R_1} \right) - V_2 \frac{1}{R_1} = \bar{i}(t) \Rightarrow p_1 \left(\frac{C_{f1} D + 1}{\bar{R}_{f1}} \right) - p_2 \frac{1}{\bar{R}_{f1}} = Q \bar{i}(t) \Rightarrow$$

$$\Rightarrow p g H_1 \left(\frac{A_1 D + 1}{p g} \right) - p g H_2 \frac{1}{p g R_1} = Q \bar{i}(t) \Rightarrow$$

$$\Rightarrow \boxed{A_1 H_1 + \frac{1}{R_1} (H_1 - H_2) = Q \bar{i}(t)}$$

$$V_2 \left(\frac{C_2 D + 1}{R_2} + \frac{1}{R_1} + \frac{1}{L D} \right) - V_1 \frac{1}{R_1} - V_3 \left(\frac{1}{R_2} + \frac{1}{L D} \right) = 0 \Rightarrow$$

$$\Rightarrow p_2 \left(\frac{C_{f2} D + 1}{\bar{R}_{f2}} + \frac{1}{\bar{R}_{f1}} + \frac{1}{L D} \right) - p_1 \frac{1}{\bar{R}_{f1}} - p_3 \left(\frac{1}{\bar{R}_{f2}} + \frac{1}{L D} \right) = 0 \Rightarrow$$

$$\Rightarrow p g H_2 \left(\frac{A_2 D + 1}{p g} + \frac{1}{p g R_2} + \frac{1}{p g R_1} + \frac{1}{p L D} \right) - p g H_1 \frac{1}{p g R_1} - p g H_3 \left(\frac{1}{p g R_2} + \frac{1}{p L D} \right) = 0 \Rightarrow$$

$$\Rightarrow \left[\frac{A_2 H_2 + 1}{R_2} (H_2 - H_3) + \frac{1}{R_1} (H_2 - H_1) = 0 \right]$$

$$V_3 \left(C_3 D + \frac{1}{R_3} + \frac{1}{R_2} + \frac{1}{LD} \right) - V_2 \left(\frac{1}{R_2} + \frac{1}{LD} \right) = Q_0(t) \Rightarrow$$

$$\Rightarrow P_3 \left(C_3 D + \frac{1}{\bar{R}_3} + \frac{1}{\bar{R}_2} + \frac{1}{LD} \right) - P_2 \left(\frac{1}{\bar{R}_2} + \frac{1}{LD} \right) = Q_0 \Rightarrow$$

$$\Rightarrow \rho g H_3 \left(A_3 D + \frac{1}{\rho g R_3} + \frac{1}{\rho g R_2} + \frac{2}{\rho LD} \right) - \rho g H_2 \left(\frac{1}{\rho g R_2} + \frac{2}{\rho LD} \right) = Q_0 \Rightarrow$$

$$\Rightarrow \left[\frac{A_3 H_3 + 1}{R_3} H_3 + \frac{1}{R_2} (H_3 - H_2) = Q_0 \right]$$