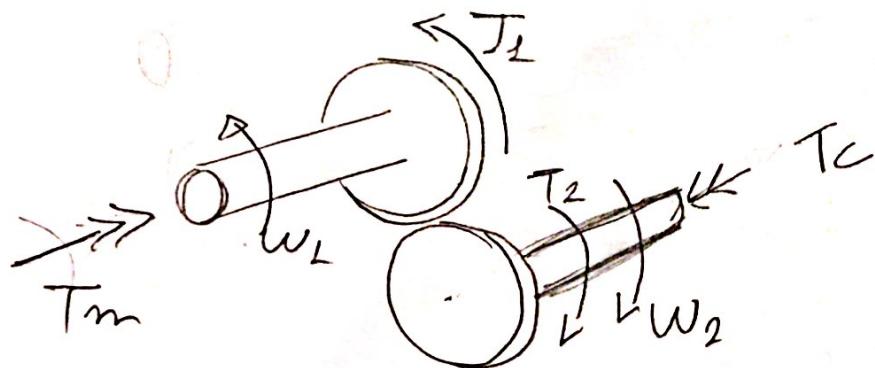


Jose Felipe Selia Refad -10333139

PME 3380 - Exercícios do dia 15/09.

### 1º Exercício



$$\begin{aligned} \cdot J_1 \cdot i\omega_1 + B_1 \omega_1 + T_1 &= T_m \\ \cdot J_2 \cdot \omega_2 + B_2 \omega_2 + T_c &= T_2 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\}$$

$\hookrightarrow \underline{T_2 = n T_1}$

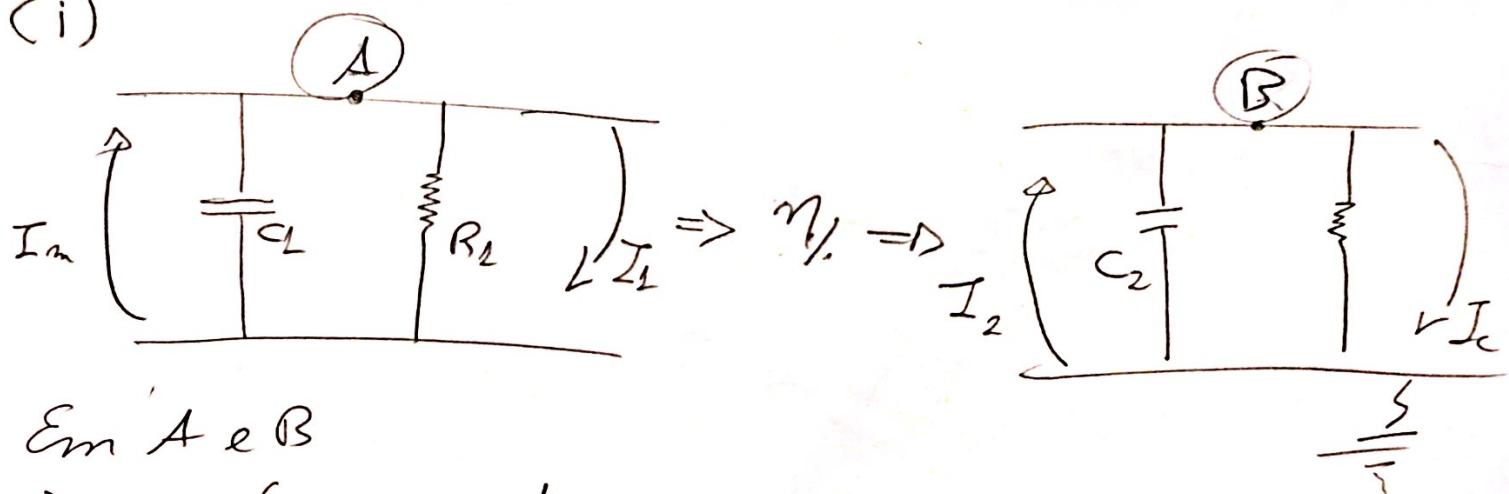
$$\begin{aligned} J_2 \omega_2 + B_2 \omega_2 + T_c &= n \cdot J_1 = n (T_m - J_1 i\omega_1 - B_1 \omega_1) \\ \underline{\underline{J_2 \omega_2 + B_2 \omega_2 + T_c = n(T_m - J_1 i\omega_1 - B_1 \omega_1)}} \end{aligned}$$

Por fim

$$\underline{\underline{(J_2 + n^2 J_1) \omega_2 + (B_2 + n^2 B_1) \omega_2 + T_c = n T_m}} //$$

Analogie do Tipo 2

(i)



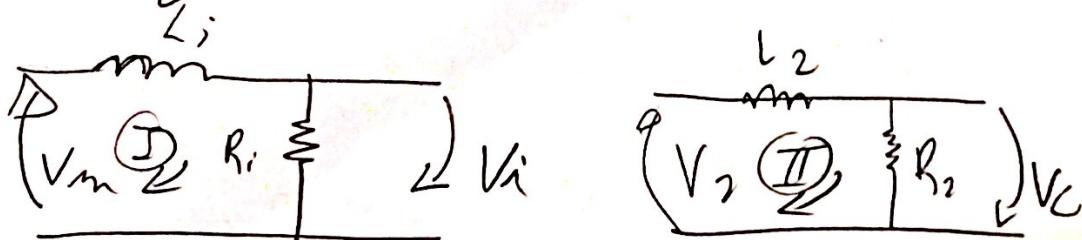
Em A e B

$$A) V_1 \cdot \left( C_2 D + \frac{1}{R_2} \right) = T_m - j_1 \quad \left. \right\}$$

$$B) V_2 \left( C_2 D + \frac{1}{R_2} \right) = j_2 - j_c \quad \left. \right\}$$

$$\begin{cases} J_1 \cdot \dot{\omega}_1 + B_1 \omega_1 = T_m - T_L \\ J_2 \cdot \dot{\omega}_2 + B_2 \omega_2 = T_2 - T_c \end{cases}$$

Analogie do Tipo 1



$$I: V_m - V_I = L_i D_i + R_i j_i \quad \left. \right\}$$

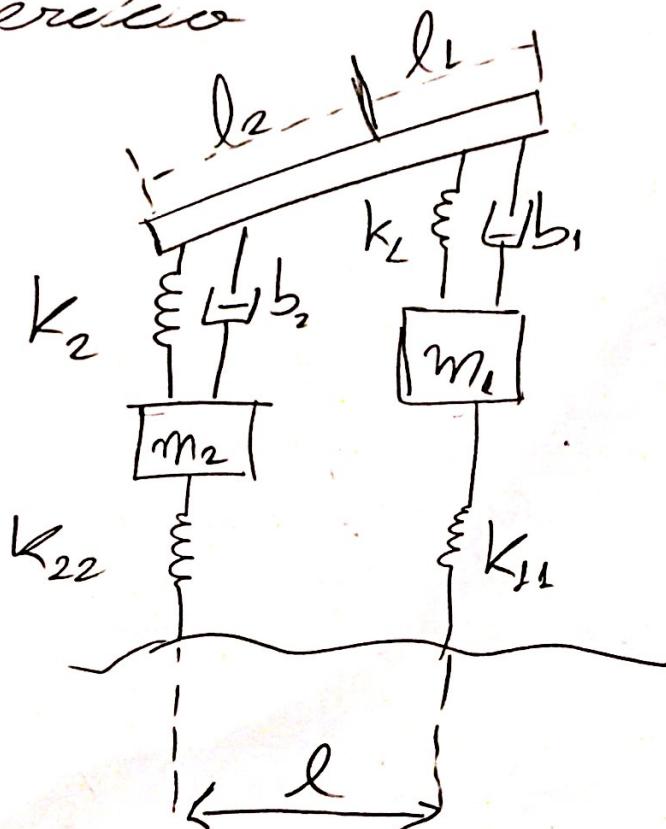
$$II: V_2 - V_C = L_2 D_2 j_2 + R_2 j_2 \quad \left. \right\}$$

$$\begin{cases} J_1 \cdot \dot{\omega}_1 + B_1 \omega_1 = T_m - T_L \\ J_2 \cdot \dot{\omega}_2 + B_2 \omega_2 = V_2 - V_C \end{cases}$$

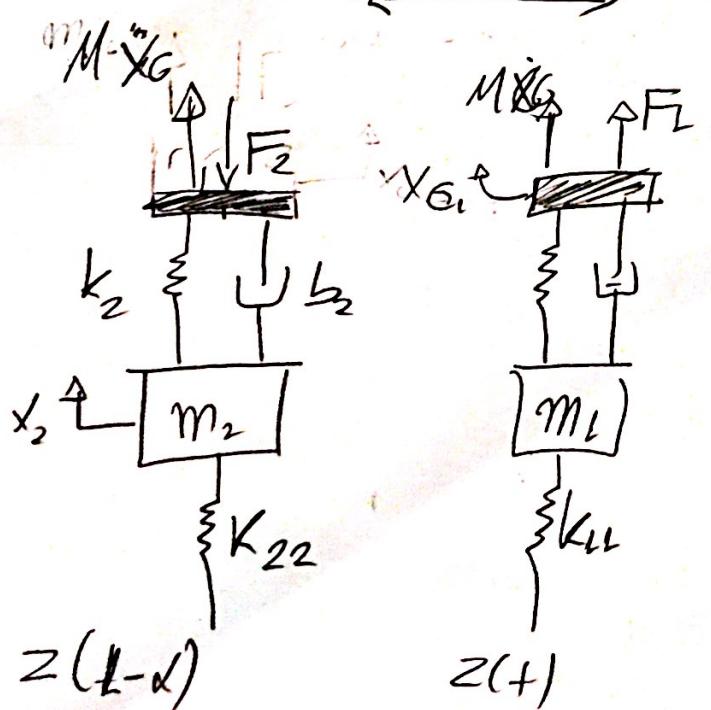
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PME3380 - Exercícios de 15/09

2º Exercício



Divida a figura ao lado em 2 sistemas, da esquerda com  $m_2$  e o do direito completo

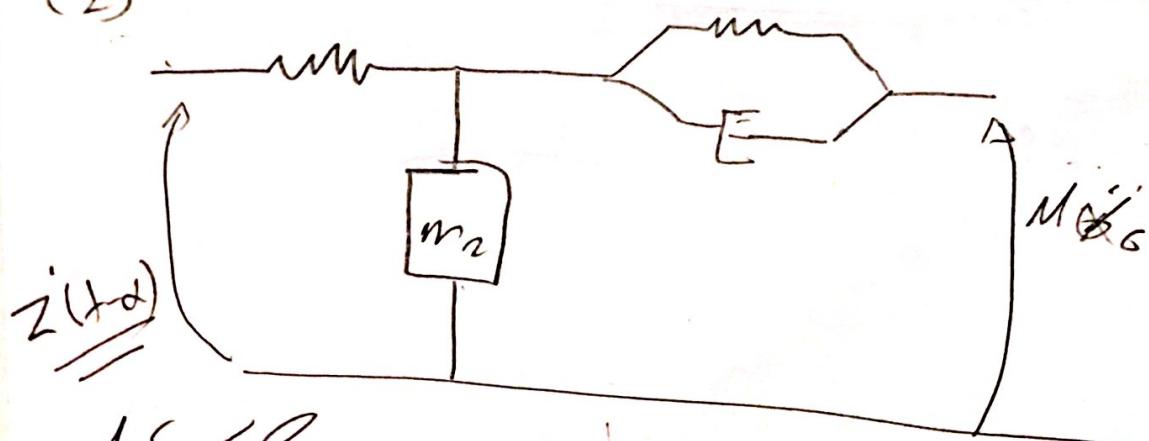


$$\frac{F_2 \cdot l_2}{l} = F_1 \cdot l_1$$
$$n = \frac{F_2}{F_1}$$

$z(l-x)$

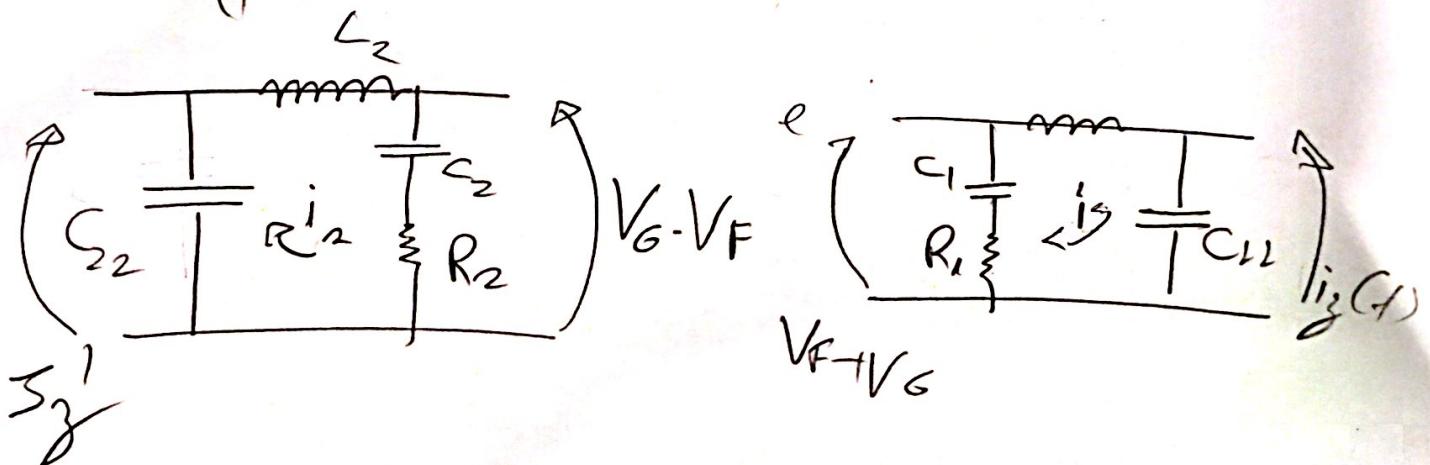
$z(+)$

(1)



Ainsi l'angle  $\rho \frac{1}{m_1}$

Dans cette forme



$$\textcircled{1} \quad V_{F_1} + V_G = i_2 \left( L_2 D + R_2 + \frac{1}{C_2 D} + \frac{1}{C_{P_1} D} \right) - i_3 \left( \frac{1}{C_{P_1} D} \right)$$

$$\textcircled{2} \quad V_G - V_{F_2} = i_2 \left( L_2 D + R_2 + \frac{1}{C_2 D} + \frac{1}{C_{P_2} D} \right) - i_3 (1-\alpha) \cdot \left( \frac{1}{C_{P_2} D} \right)$$

$$F_1 + M\ddot{x}_G = m_2 \ddot{x}_1 + b_1 \dot{x}_1 + K_1 x_1 + R_{J_1} x_1 - K_{J_2} \beta(1) \quad \swarrow$$

$$M\ddot{x}_G - F_2 = m_2 \ddot{x}_2 + b_2 \dot{x}_2 + K_2 x_2 + K_{J_2} x_2 - K_{J_1} \beta(1-\alpha) \quad \searrow$$