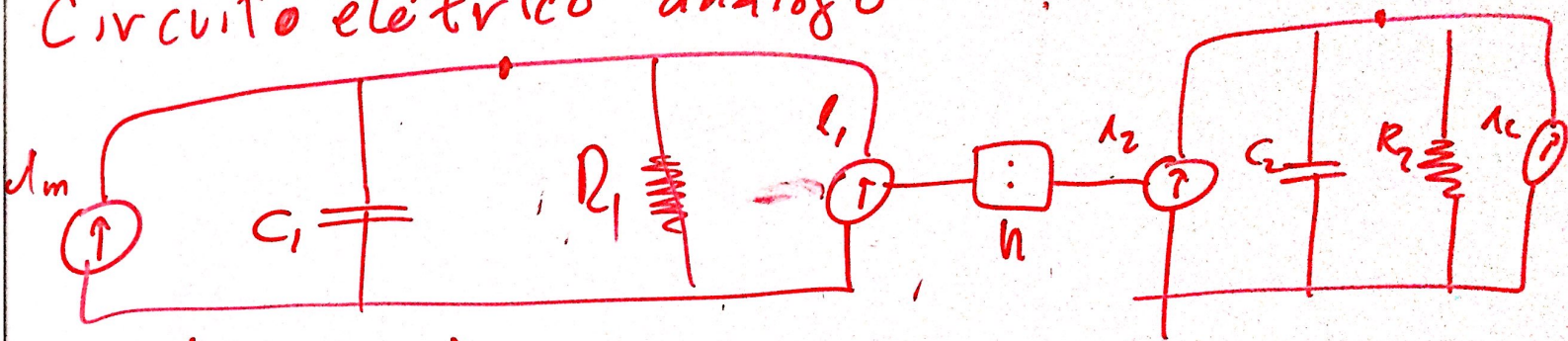


Circuito elétrico análogo



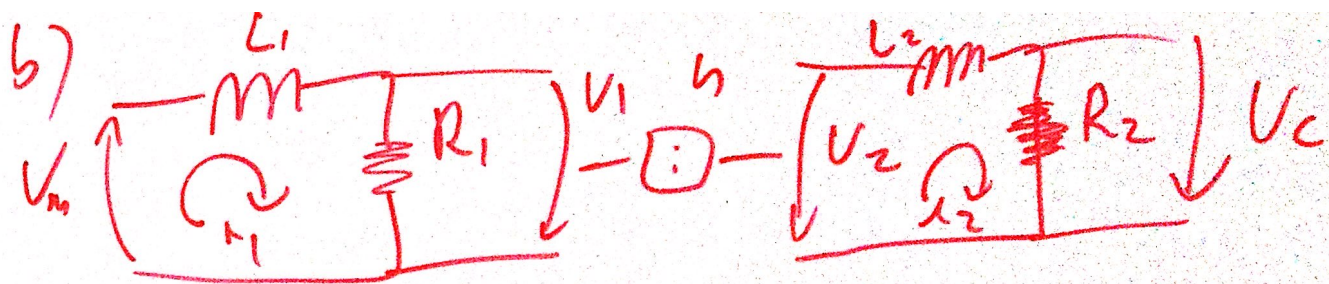
$$\begin{cases} \omega_1 (J_1 D + B_1) = T_m - T_1 \\ \omega_2 (J_2 D + B_2) = T_2 - T_c \end{cases}$$

↓

$$J_1 \ddot{\theta}_1 + B_1 \dot{\theta}_1 = T_m - T_1$$

$$J_2 \ddot{\theta}_2 + B_2 \dot{\theta}_2 = T_2 - T_c$$

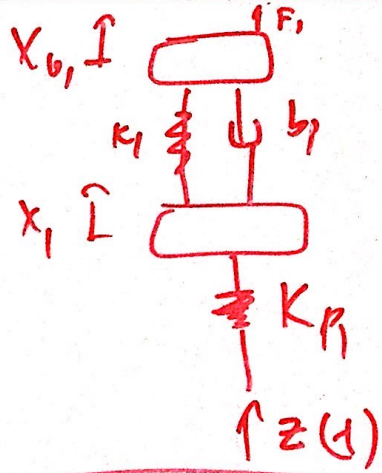
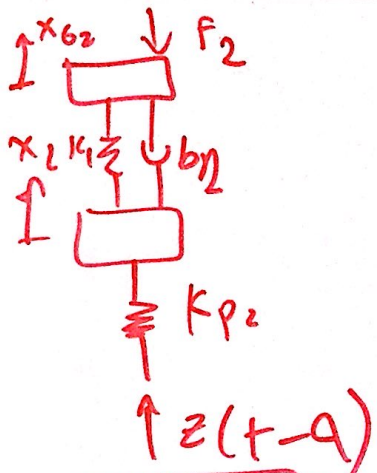
$$\rightarrow T_2 = h T_1 \quad \text{e} \quad \dot{\theta}_2 = \frac{\dot{\theta}_1}{h}$$



$$\begin{cases} L_1 D i_1 + R_1 i_1 = V_m - V_1 \\ L_2 D i_2 + R_2 i_2 = V_2 - V_c \end{cases}$$

↓

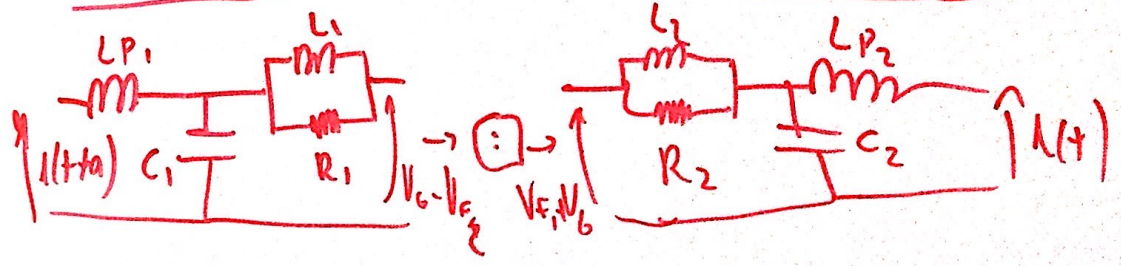
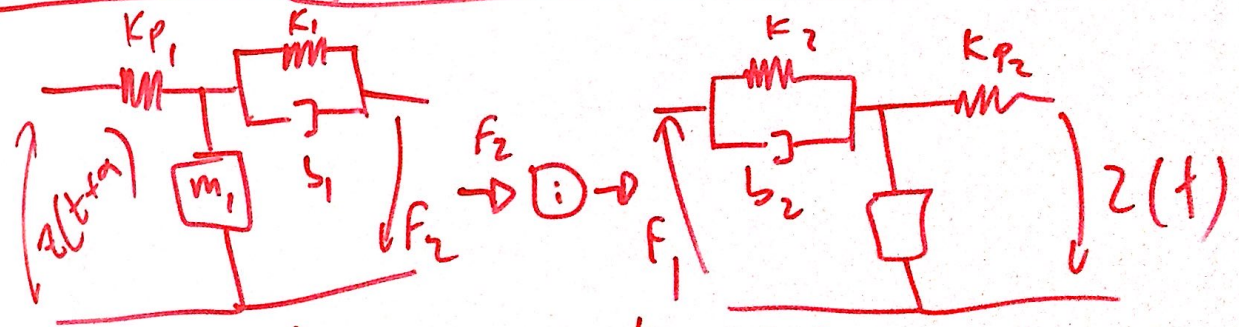
$$\begin{cases} J_1 \omega_1 + B_1 \omega_1 = T_m - T_1 \\ J_2 \omega_2 + B_2 \omega_2 = V_2 - V_c \end{cases}$$



$$F_2 l_2 = F_1 l_1$$

$$\frac{F_2}{F_1} = \frac{l_1}{l_2} = \eta$$

Sist. mecânico:



Lei das malhas:

$$\left\{ \begin{aligned} \lambda_1 \left(L_1 D + R_1 + \frac{1}{C_1 D} + \frac{1}{C_{p1} D} \right) + \frac{\lambda_2}{C_{p1} D} &= V_{f1} - V_G \\ \lambda_2 \left(L_2 D + R_2 + \frac{1}{C_2 D} + \frac{1}{C_{p2} D} \right) - \lambda_1 (1 + \tau a) \cdot \frac{1}{C_{p2} D} &= V_G - V_{f2} \end{aligned} \right.$$

Logo:

$$\left\{ \begin{aligned} m_1 \ddot{x}_1 + b_1 \dot{x}_1 + k_1 x_1 + k_{p1} x_1 - k_{p1} z_A - F_1 - M \ddot{x}_1 &= 0 \\ m_2 \ddot{x}_2 + b_2 \dot{x}_2 + k_2 x_2 + k_{p2} x_2 - k_{p2} z_B - F_2 - M \ddot{x}_2 &= 0 \end{aligned} \right.$$