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1. $J_1 \dot{\omega}_1 + B_1 \omega_1 + T_1 = T_m$

$$J_2 \dot{\omega}_2 + B_2 \omega_2 + T_c = T_2 = n T_1$$

$$J_2 \dot{\omega}_2 + B_2 \omega_2 + T_c = n (T_m - J_1 \dot{\omega}_1 - B_1 \omega_1)$$

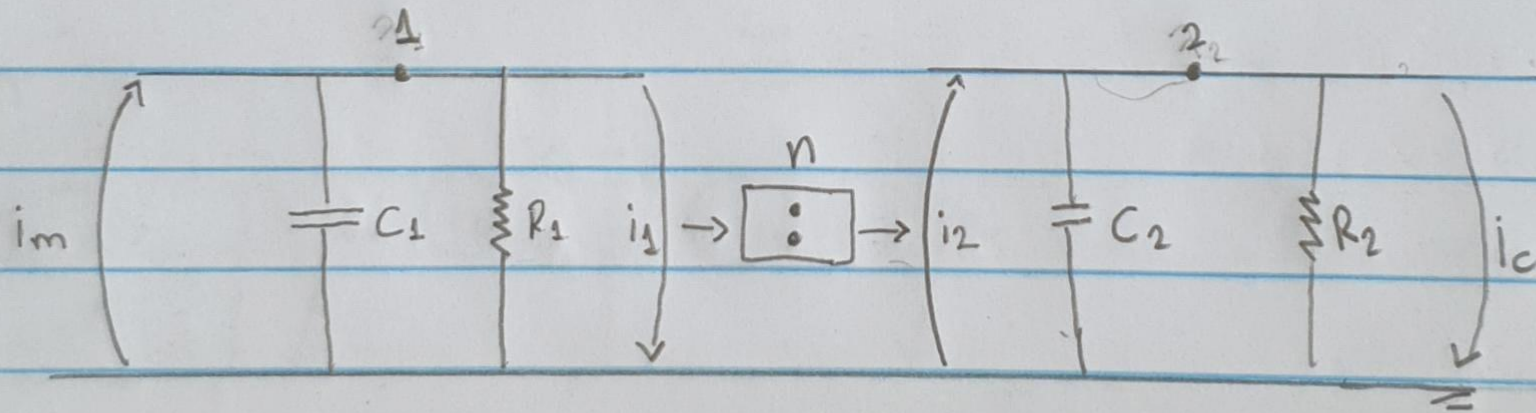
$$J_2 \dot{\omega}_2 + B_2 \omega_2 + T_c = n (T_m - J_1 n \dot{\omega}_2 - B_1 n \omega_2)$$

$$\dot{\omega}_2 (J_2 + n^2 J_1) + \omega_2 (B_2 + n^2 B_1) + T_c = n T_m$$

$J_{eq2} \dot{\omega}_2 + B_{eq2} \omega_2 + T_c = T_m \cdot n$

2.

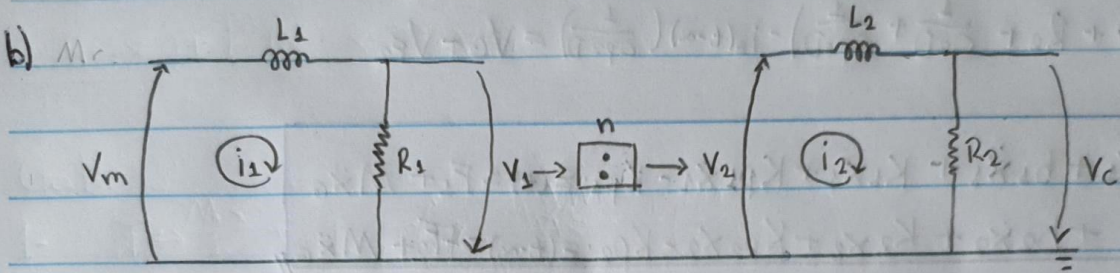
a)



No 1: $(C_1 D + \frac{1}{R_1}) V_1 = i_m - i_1$

No 2: $(C_2 D + \frac{1}{R_2}) V_2 = i_2 - i_c$

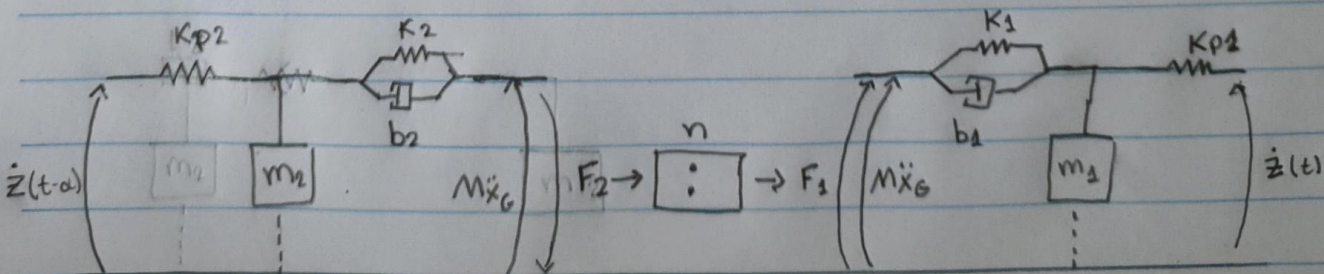
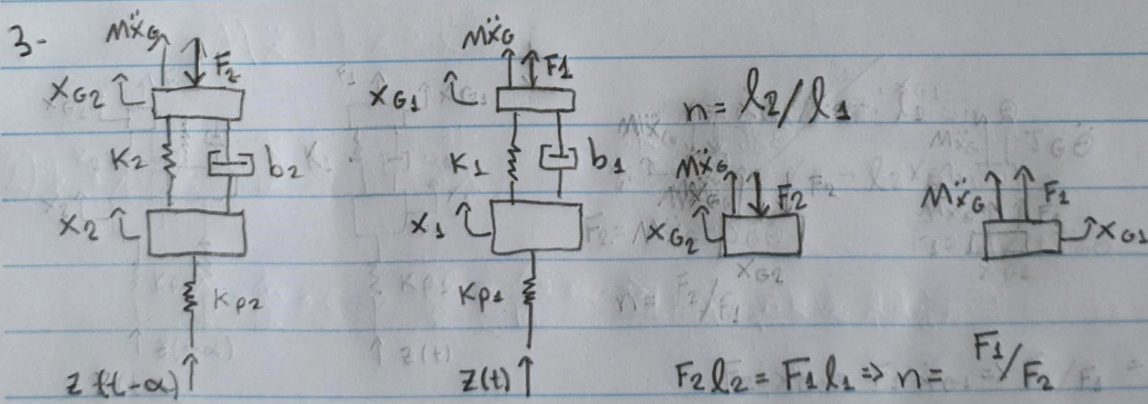
$$\begin{aligned} J_1 \dot{\omega}_1 + B_1 \omega_1 &= T_m - T_1 \\ J_2 \dot{\omega}_2 + B_2 \omega_2 &= T_2 - T_c \end{aligned}$$

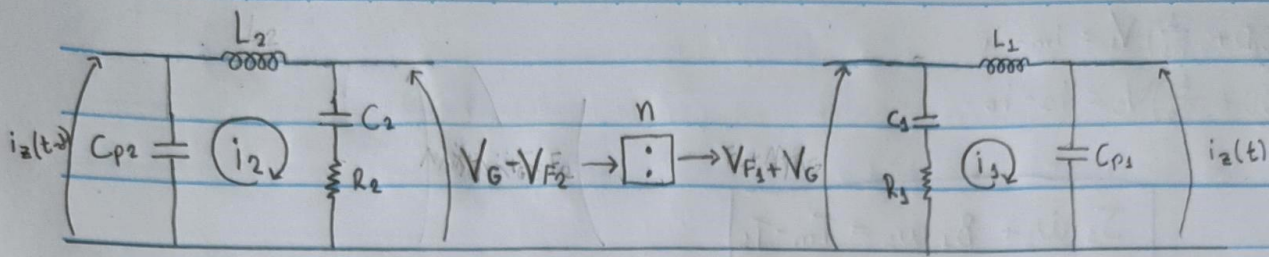


Malha 1: $L_1 D \cdot i_1 + R_1 i_1 = V_m - V_1$

Malha 2: $L_2 D \cdot i_2 + R_2 i_2 = V_2 - V_c$

$$\begin{aligned} J_1 \dot{\omega}_1 + B_1 \omega_1 &= T_m - T_1 \\ J_2 \dot{\omega}_2 + B_2 \omega_2 &= V_2 - V_c \end{aligned}$$





$$\text{Malha 1: } i_3(L_1 D + R_3 + \frac{1}{C_{p1} D} + \frac{1}{C_s D}) - i_2(t) \left(\frac{1}{C_{p1} D} \right) = V_{F3} + V_G$$

$$\text{Malha 2: } i_2(L_2 D + R_e + \frac{1}{C_2 D} + \frac{1}{C_{p2} D}) - i_2(t-\alpha) \left(\frac{1}{C_{p2} D} \right) = V_G - V_{F2}$$

$$\begin{aligned} m_1 \ddot{x}_1 + b_1 \dot{x}_1 + K_1 x_1 + K_{p1} x_1 - K_{p1} z(t) &= F_1 + M \ddot{x}_G \\ m_2 \ddot{x}_2 + b_2 \dot{x}_2 + K_2 x_2 + K_{p2} x_2 - K_{p2} z(t-\alpha) &= -F_2 + M \ddot{x}_G \end{aligned}$$