

↳ Lagrange

$$T = \frac{m \dot{x}^2}{2}$$

$$L = T - V$$

$$V = \frac{Lq^2}{2}$$

$$R = \frac{b \dot{x}^2}{2} + \frac{R \dot{q}^2}{2}$$

$$f = lB \dot{q}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) = m \ddot{x}$$

$$\frac{\partial L}{\partial x} = 0$$

$$\frac{\partial R}{\partial \dot{x}} = b \dot{x}$$

$$m \ddot{x} + b \dot{x} = lB \dot{q}$$

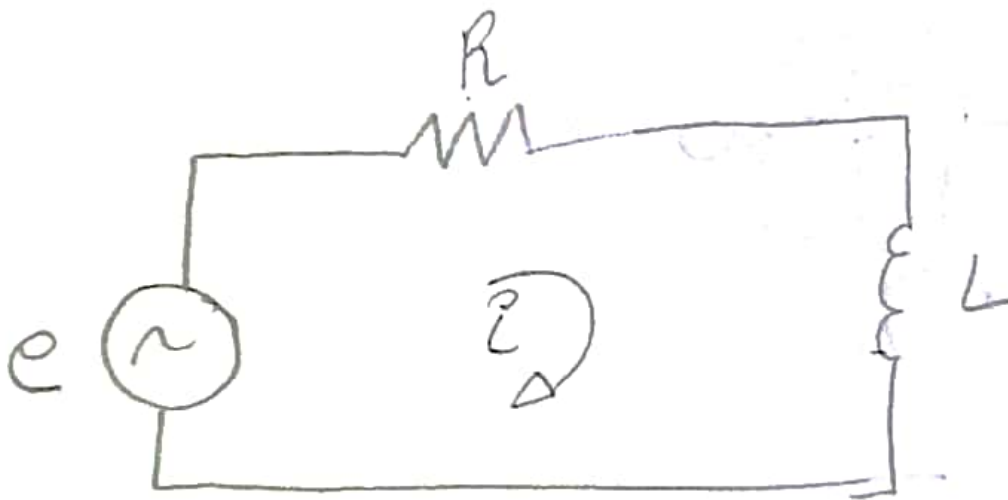
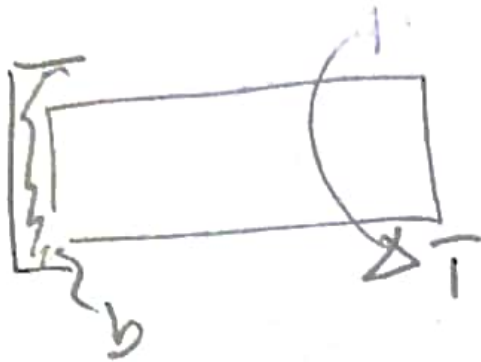
$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0$$

$$\frac{\partial L}{\partial q} = -Lq$$

$$\frac{\partial R}{\partial \dot{q}} = R \dot{q}$$

$$Lq + R \dot{q} = u_a - lB \dot{x}$$

2



$$L(\dot{I} + LD) = e$$

$$J\ddot{\Theta} + B\dot{\Theta} = T$$