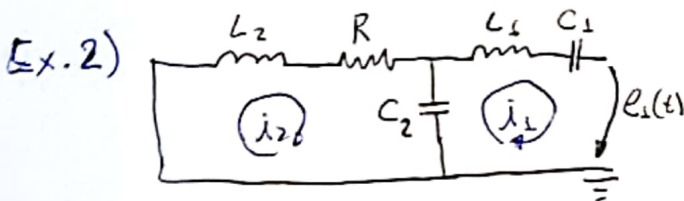


Malha 1: $0 = L_1 D i_1 + \frac{1}{C_1 D} i_1 + R_1 i_1 +$

$+\frac{1}{C_2 D} (i_1 - i_2) + R_2 (i_1 - i_2)$

Malha 2: $e(t) = L_2 D i_2 + \frac{1}{C_2 D} (i_2 - i_1) + R_2 (i_2 - i_1)$

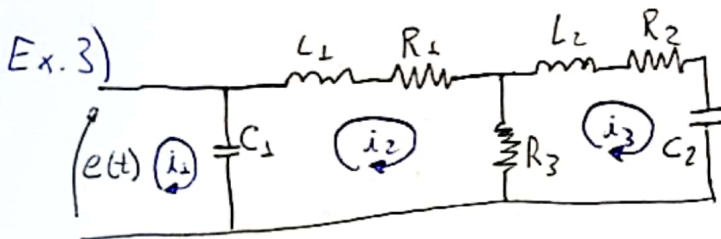
$M_1 \ddot{x}_1 + k_1 x_1 + b \dot{x}_1 + R_2 (x_1 - x_2) + b_2 (\dot{x}_1 - \dot{x}_2) = 0$
 $M_2 \ddot{x}_2 + k_2 (x_2 - x_1) + b_2 (\dot{x}_2 - \dot{x}_1) = f(t)$



Malha 1: $e_1(t) = L_1 D i_1 + \frac{1}{C_1 D} i_1 + (\frac{1}{C_2 D}) (i_1 - i_2)$

Malha 2: $0 = L_2 D i_2 + R i_2 + \frac{(i_2 - i_1)}{C_2 D}$

$M_1 \ddot{x}_1 + K_1 x_1 + K_2 (x_1 - x_2) = f_1(t)$
 $M_2 \ddot{x}_2 + b \dot{x}_2 + K_2 (x_2 - x_1) = 0$



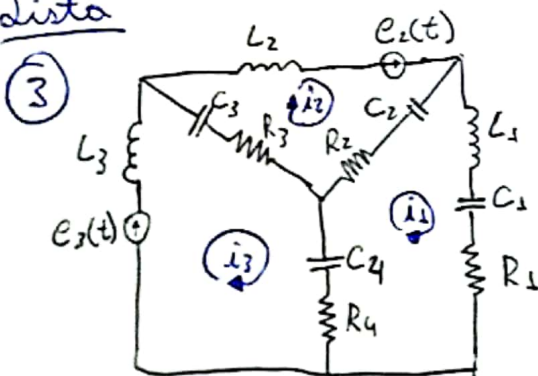
Malha 1: $e(t) = \frac{1}{C_1 D} i_1$

Malha 2: $0 = L_1 D i_2 + R_1 i_2 + R_3 (i_2 - i_3) + (\frac{1}{C_2 D}) (i_2 - i_1)$

Malha 3: $0 = L_2 D i_3 + R_2 i_3 + \frac{i_3}{C_2 D} + R_3 (i_3 - i_2)$

$K_1 \theta_1 = T$
 $J_1 \ddot{\theta}_2 + B_1 \dot{\theta}_2 + B_3 (\dot{\theta}_2 - \dot{\theta}_3) + K_1 (\theta_2 - \theta_1)$
 $J_2 \ddot{\theta}_3 + B_2 \dot{\theta}_3 + B_3 (\dot{\theta}_3 - \dot{\theta}_2) + K_2 \theta_3 = 0$

Sista



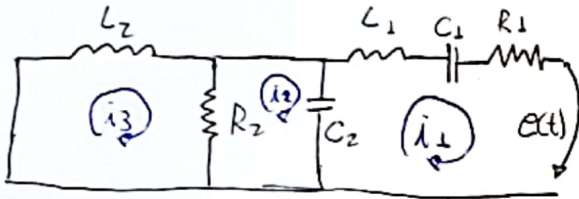
Malha 1: $L_1 D i_1 + \frac{1}{C_1 D} i_1 + R_1 i_1 + R_4 (i_1 - i_3) + (\frac{1}{C_2 D}) (i_1 - i_2) + R_2 (i_1 - i_2) + \frac{(i_1 - i_2)}{C_2 D} = 0$

Malha 2: $L_2 D i_2 + \frac{(i_2 - i_1)}{C_2 D} + R_2 (i_2 - i_1) + R_3 (i_2 - i_3) + \frac{(i_2 - i_3)}{C_3 D} = e_2(t)$

Malha 3: $L_3 D i_3 + \frac{(i_3 - i_2)}{C_3 D} + R_3 (i_3 - i_2) + \frac{(i_3 - i_1)}{C_4 D} + R_4 (i_3 - i_1) = e_3(t)$

$M_1 \ddot{x}_1 + K_1 x_1 + b_1 \dot{x}_1 + b_4 (x_1 - x_3) + K_4 (x_1 - x_3) + b_2 (\dot{x}_1 - \dot{x}_2) + K_2 (x_1 - x_2) = 0$
 $M_2 \ddot{x}_2 + K_2 (x_2 - x_1) + b_2 (\dot{x}_2 - \dot{x}_1) + b_3 (\dot{x}_2 - \dot{x}_3) + K_3 (x_2 - x_3) = f_2(t)$
 $M_3 \ddot{x}_3 + K_3 (x_3 - x_2) + b_3 (\dot{x}_3 - \dot{x}_2) + K_4 (x_3 - x_1) + b_4 (\dot{x}_3 - \dot{x}_1) = f_3(t)$

Ex. 6)



Malha 1: $e(t) = L_1 D i_1 + \frac{i_1}{C_1 D} + R_1 i_1 + \frac{(i_1 - i_2)}{C_2 D}$

Malha 2: $R_2 (i_2 - i_3) + \frac{(i_2 - i_1)}{C_2 D} = 0$

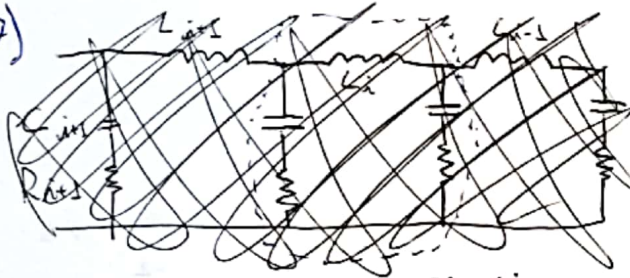
Malha 3: $L_2 D i_3 + R_2 (i_3 - i_2) = 0$

$M_1 \ddot{x}_1 + K_1 x_1 + b_1 \dot{x}_1 + K_2 (x_1 - x_2) = f(t)$

$M_2 \ddot{x}_3 + b_2 (\dot{x}_3 - \dot{x}_2) = 0$

$b_2 (\dot{x}_2 - \dot{x}_3) + K_2 (x_2 - x_1) = 0$

Ex. 7)

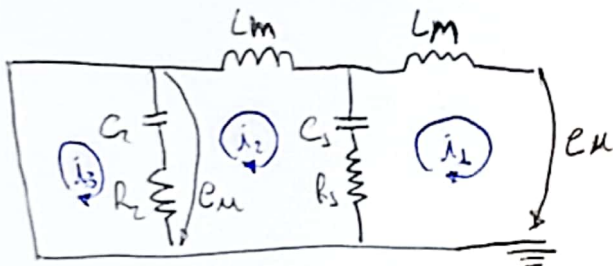


Malha 1: $i_2 (L_1 D) + (i_1 - i_2) \left(R_1 + \frac{1}{C_1 D} \right) = e_1(t)$

Malha 2: $i_n \left(L_n D + \frac{1}{C_{n-1} D} + R_{n-1} \right) - i_{n-1} \left(R_{n-1} + \frac{1}{C_{n-1} D} \right) = e_n(t)$

Malha i: $i_i L_i D + (R_i + R_{i-1}) i_i + \left(\frac{1}{C_i D} + \frac{1}{C_{i-1} D} \right) - i_{i+1} \left(\frac{1}{C_i D} + R_i \right) - i_{i-1} \left(R_i + \frac{1}{C_{i+1} D} \right) = e_i(t)$

Ex. 8) a)



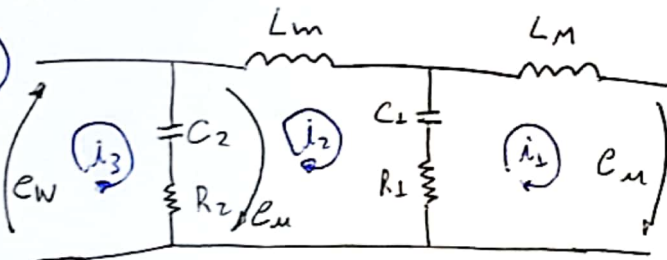
$$\begin{aligned}
 M\ddot{x}_1 + K_1(x_1 - x_2) + b_1(\dot{x}_1 - \dot{x}_2) &= U \\
 M\ddot{x}_2 + K_1(x_2 - x_1) + b_1(\dot{x}_2 - \dot{x}_1) + K_2(x_2 - w) + \\
 &+ b_2(\dot{x}_2 - \dot{w}) = -U \\
 K_2(w - x_2) + b_2(\dot{w} - \dot{x}_2) &= 0
 \end{aligned}$$

Malha 1: $Lm \dot{i}_1 + \frac{(i_1 - i_2)}{C_1 D} + R_1(i_1 - i_2) = e_u$

Malha 2: $Lm \dot{i}_2 + \frac{(i_2 - i_1)}{C_2 D} + R_1(i_2 - i_1) + \frac{(i_2 - i_3)}{C_2 D} + R_2(i_2 - i_3) = -e_u$

Malha 3: $\frac{(i_3 - i_2)}{C_2 D} + R_2(i_3 - i_2) = 0$

b)



$$\begin{aligned}
 M\ddot{x}_1 + K_1(x_1 - x_2) + b_1(\dot{x}_1 - \dot{x}_2) &= U \\
 M\ddot{x}_2 + K_1(x_2 - x_1) + b_1(\dot{x}_2 - \dot{x}_1) + K_2(x_2 - x_3) + \\
 &+ b_2(\dot{x}_2 - \dot{x}_3) = -U \\
 K_2(x_3 - x_2) + b_2(\dot{x}_3 - \dot{x}_2) &= W(t)
 \end{aligned}$$

Malha 1: $Lm \dot{i}_1 + \frac{(i_1 - i_2)}{C_1 D} + R_1(i_1 - i_2) = e_u$

Malha 2: $Lm \dot{i}_2 + \frac{(i_2 - i_1)}{C_2 D} + R_1(i_2 - i_1) + \frac{(i_2 - i_3)}{C_2 D} + R_2(i_2 - i_3) = -e_u$

Malha 3: $\frac{(i_3 - i_2)}{C_2 D} + R_2(i_3 - i_2) = e_w$