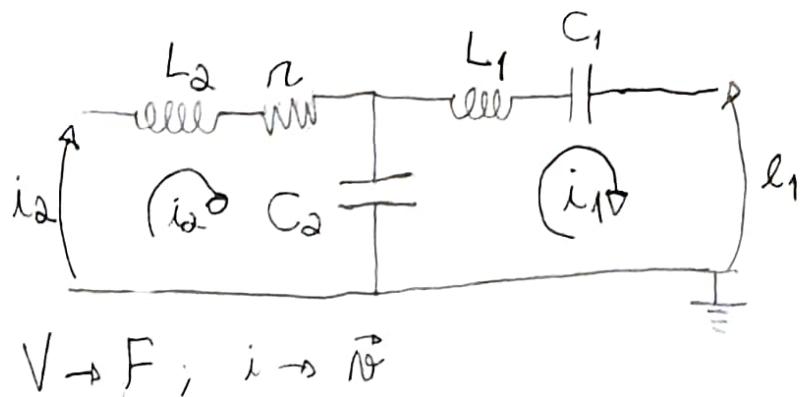
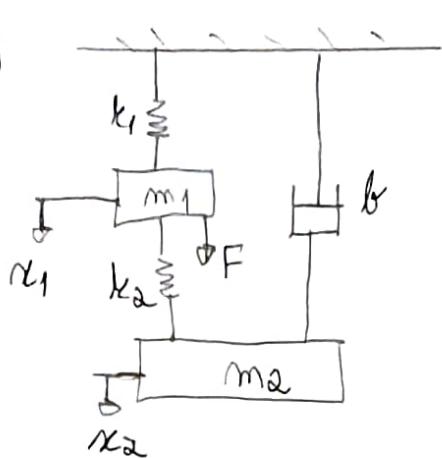


2)



$$\nabla \rightarrow F; i \rightarrow \vec{N}$$

•) Malla 1:  $\frac{(i_1 - i_2)}{C_2 \cdot D} + L_1 \cdot D \cdot i_1 + \frac{i_1}{C_1 \cdot D} = l_1$

$$\Rightarrow (\text{N}_1 - \text{N}_2) \cdot \frac{k_2}{D} + m_1 \cdot \text{N}_1 \cdot D + \text{N}_1 \cdot \frac{k_1}{D} = F$$

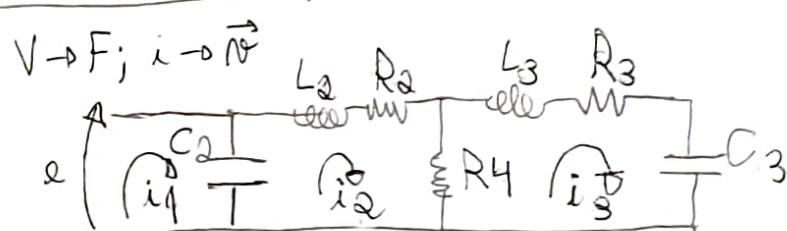
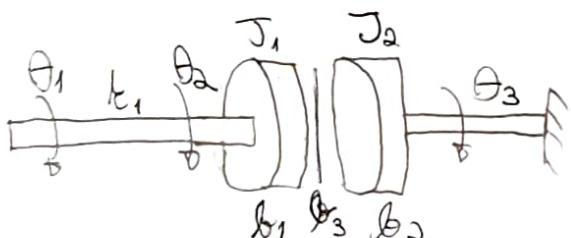
$$\Rightarrow (\ddot{x}_1 - \ddot{x}_2) \cdot k_2 + m_1 \cdot \ddot{x}_1 + x_1 \cdot k_1 = F$$

•) Malla 2:  $L_2 \cdot D \cdot i_2 + R \cdot i_2 + \frac{(i_2 - i_1)}{C_2 \cdot D} = 0$

$$\Rightarrow m_2 \cdot \text{N}_2 \cdot D + b \cdot \text{N}_2 + \frac{(\text{N}_2 - \text{N}_1)}{D} \cdot k_2 = 0$$

$$\Rightarrow m_2 \cdot \ddot{x}_2 + b \cdot \dot{x}_2 + (x_2 - x_1) \cdot k_2 = 0$$

3)



•) Malla 1:  $\ell - \frac{(i_1 - i_2)}{C_2 \cdot D} = 0 \Rightarrow F - \frac{(\text{N}_1 - \text{N}_2)}{D} \cdot k_1 = 0 \Rightarrow (x_1 - x_2) / k_1 = F$

o) Malla 2:

$$\frac{(i_2 - i_1)}{C_2 \cdot D} + L_2 \cdot D \cdot i_2 + R_2 \cdot i_2 + (i_2 - i_3) \cdot R_4 = 0$$

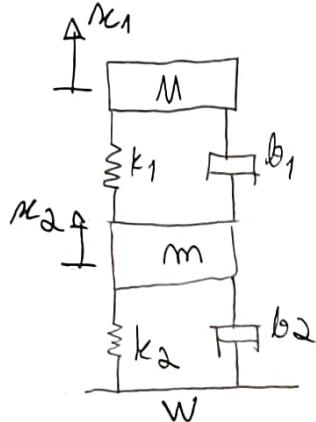
$$\Rightarrow (x_2 - x_1) \cdot k_1 + m_1 \ddot{x}_1 + b_1 \cdot \dot{x}_1 + (\theta_1 - \theta_2) \cdot b_3 = 0$$

o) Malla 3:

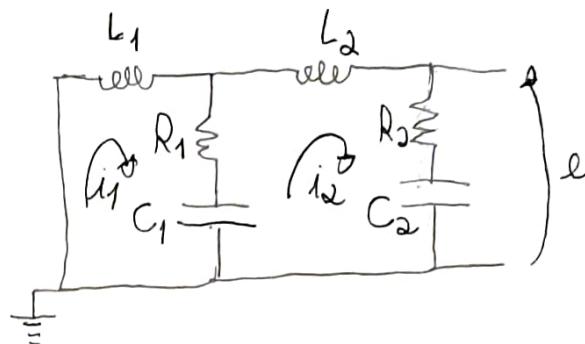
$$(i_3 - i_2) \cdot R_4 + i_3 \cdot D \cdot L_3 + R_3 \cdot i_3 + \frac{i_3}{C_3 \cdot D} = 0$$

$$\Rightarrow (\theta_2 - \theta_1) \cdot b_3 + m_2 \ddot{x}_2 + b_2 \cdot \dot{x}_2 + k_2 \cdot x_2 = 0$$

g)



$F \rightarrow V$   
 $\vec{v} \rightarrow i$



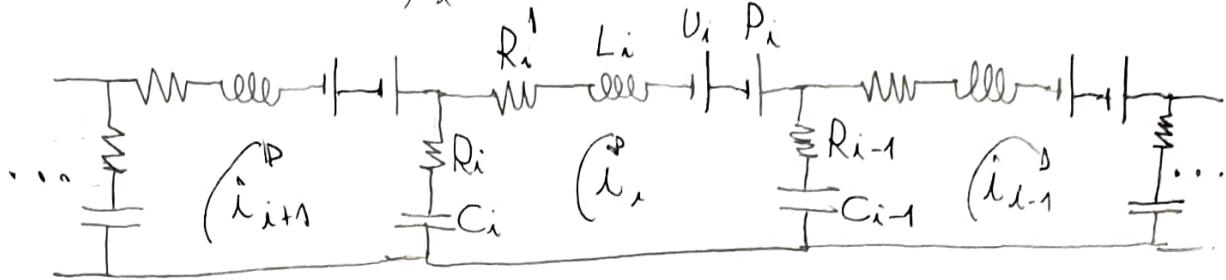
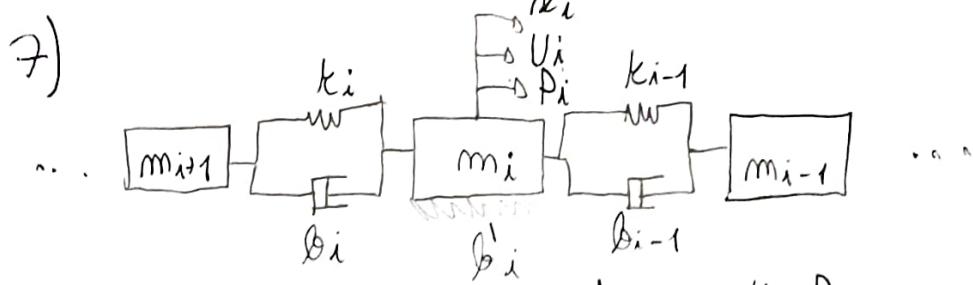
a) o) Malla 1:  $i_1 \cdot L_1 \cdot D + (i_1 - i_2) \cdot \left( R_1 + \frac{1}{C_1 \cdot D} \right) = 0$

$$\Rightarrow m_1 \ddot{x}_1 + (\theta_1 - \theta_2) b_1 + (x_1 - x_2) k_1 = 0$$

o) Malla 2:  $i_2 \cdot L_2 \cdot D + (i_2 - i_1) \cdot \left( R_2 + \frac{1}{C_2 \cdot D} \right) + (i_2 - i_1) \cdot \left( R_1 + \frac{1}{C_1 \cdot D} \right) = 0$

$$\Rightarrow m_2 \ddot{x}_2 + (\theta_2 - \theta_1) (b_2 + b_1) + (x_2 - x_1) (k_1 + k_2) = 0$$

b)  $\Rightarrow m_2 \ddot{x}_2 + b_2 \ddot{x}_2 + k_2 x_2 + (x_2 - x_1) b_1 + (x_2 - x_1) k_1 = W$

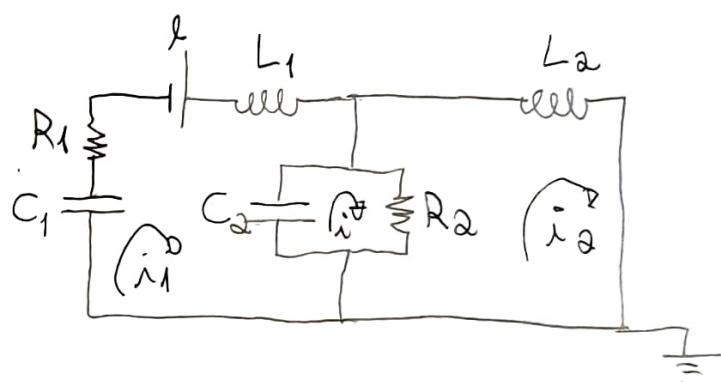
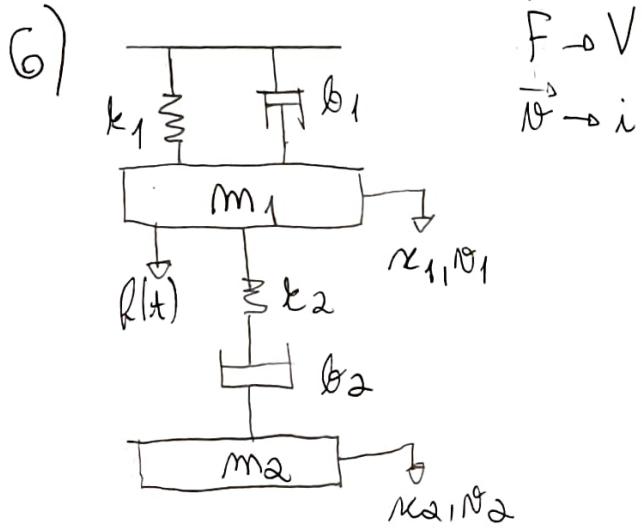


•) Malla  $i$ :

$$i_i \cdot R'_i + L_i D_i \cdot i_i - U_i - P_i + (i_i - i_{i-1}) \cdot \left( R_{i-1} + \frac{1}{C_{i-1} \cdot D} \right)$$

$$+ (i_i - i_{i+1}) \cdot \left( R_i + \frac{1}{C_i \cdot D} \right) = 0$$

$$\Rightarrow \dot{x}_i \cdot b'_i + m_i \cdot \ddot{x}_i + (\dot{x}_i - \dot{x}_{i-1}) \cdot b_{i-1} + (x_i - x_{i-1}) \cdot k_{i-1} + \\ (\dot{x}_i - \dot{x}_{i+1}) \cdot b_i + (x_i - x_{i+1}) \cdot k_i = U_i + m \cdot g \cdot \text{rent}$$



• Malla "i":

$$(i - i_2) \cdot R_2 + (i - i_1) \cdot \frac{1}{C_2 \cdot D} = 0$$

$$\Rightarrow (\dot{x} - \dot{x}_2) \cdot b_2 + (x - x_1) \cdot k_2 = 0$$

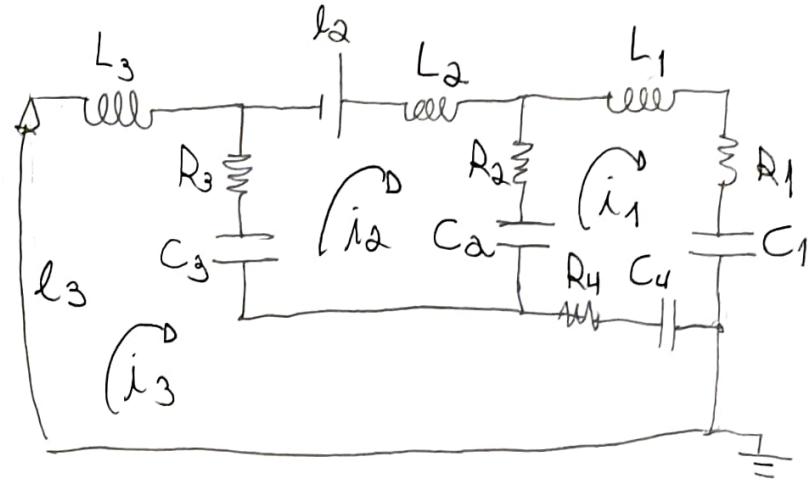
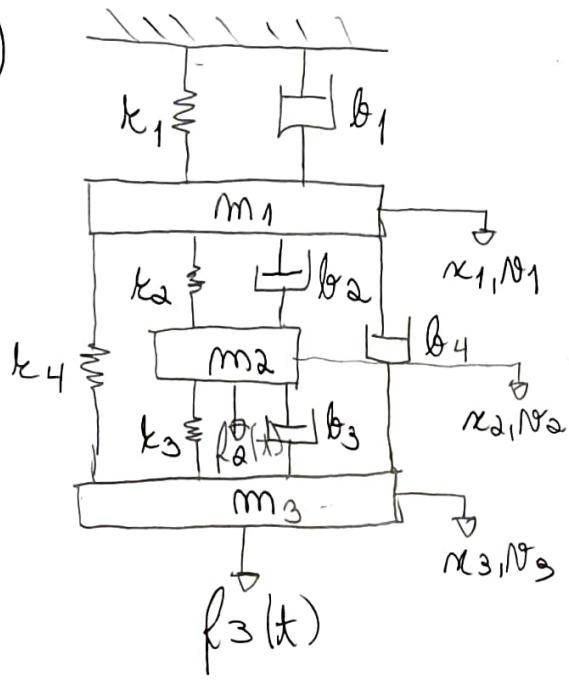
$$\bullet \text{Malla 1: } i_1 \cdot \frac{1}{D \cdot C_1} + i_1 \cdot R_1 + L_1 \cdot D \cdot i_1 + (i_1 - i) \cdot \frac{1}{C_0 \cdot D} = e$$

$$\Rightarrow m_1 \ddot{x}_1 + b_1 \dot{x}_1 + k_1 x_1 + (x_1 - x) k_2 = f(t)$$

$$\bullet \text{Malla 2: } i_2 \cdot L_2 \cdot D + (i_2 - i) \cdot R_2 = 0$$

$$\Rightarrow m_2 \ddot{x}_2 + (\dot{x}_2 - \dot{x}) \cdot b_2 = 0$$

3)



$$\bullet \text{Malla 1: } i_1 \left( L_1 \cdot D + R_1 + \frac{1}{C_1 \cdot D} \right) + (i_1 - i_3) \cdot \left( \frac{1}{C_4 \cdot D} + R_4 \right) + (i_1 - i_3) \cdot (R_2 + \frac{1}{C_2 \cdot D}) = 0$$

$$\Rightarrow m_1 \ddot{x}_1 + b_1 \dot{x}_1 + k_1 x_1 + (x_1 - x_3) b_4 + (\dot{x}_1 - \dot{x}_2) b_2 + (x_1 - x_3) k_4 + (x_1 - x_2) k_2 = 0$$

$$\bullet \text{Malla 2: } L_2 \cdot D \cdot i_2 + (i_2 - i_1) \cdot \left( \frac{1}{C_2 \cdot D} + R_2 \right) + (i_2 - i_3) \cdot \left( \frac{1}{C_3 \cdot D} + R_3 \right) = e_2$$

$$\Rightarrow m_2 \ddot{x}_2 + (\dot{x}_2 - \dot{x}_1) b_2 + (x_2 - x_1) k_2 + (\dot{x}_2 - \dot{x}_3) b_3 + (x_2 - x_3) k_3 = f_2(t)$$

$$\bullet \text{Malla 3: } L_3 \cdot D \cdot i_3 + (i_3 - i_2) \cdot \left( \frac{1}{C_3 \cdot D} + R_3 \right) + (i_3 - i_1) \cdot \left( \frac{1}{C_4 \cdot D} + R_4 \right) = e_3$$

$$\Rightarrow m_3 \ddot{x}_3 + (\dot{x}_3 - \dot{x}_2) b_3 + (x_3 - x_2) k_3 + (\dot{x}_3 - \dot{x}_1) b_4 + (x_3 - x_1) k_4 = f_3(t)$$