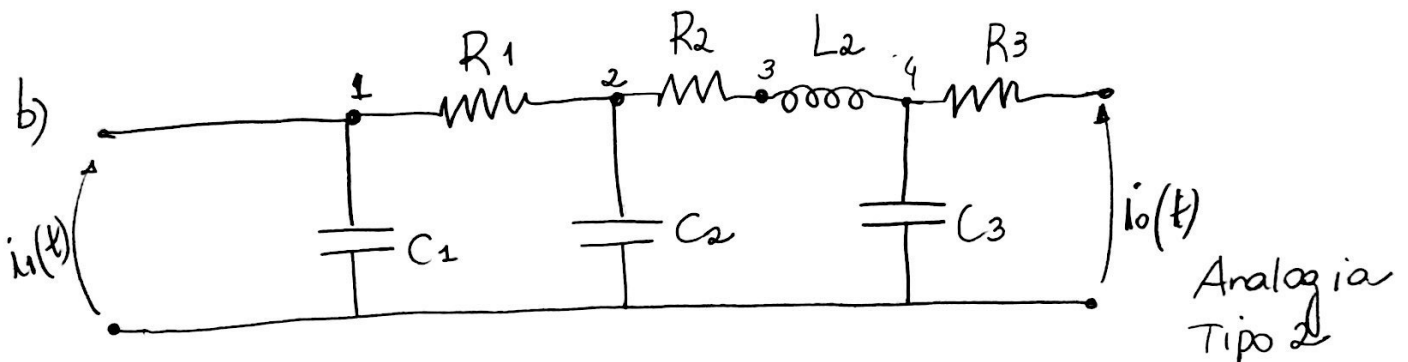
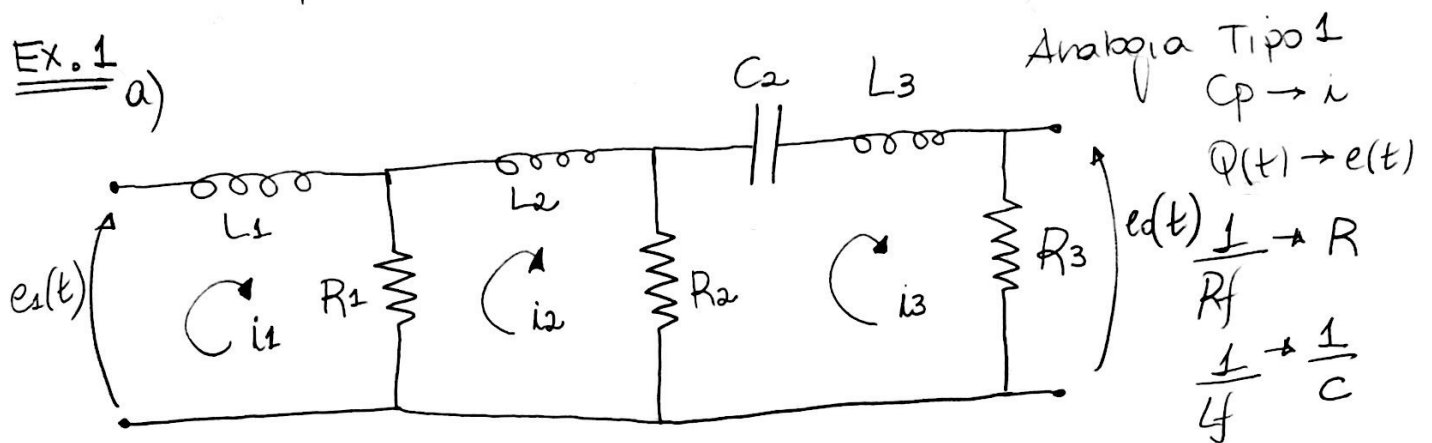


Ex. 1 a)



c) • Analógia Tipo 1:

$$(1): e_1(t) = (R_1 + L_1 D) i_1 - R_1 i_2$$

$$(2): 0 = (R_1 + L_2 D + R_2) i_2 - R_1 i_1 - R_2 i_3$$

$$(3): e_2(t) = (R_2 + \frac{1}{C_2 D} + L_3 D + R_3) i_3 - R_2 i_2$$

$$(1) \rightarrow Q_1(t) = h_1 A + \frac{1}{R_{f1}} (h_1' - h_2')$$

$$(2) \rightarrow 0 = h_2 A + \frac{1}{R_{f1}} (h_2' - h_1') + \frac{1}{R_{f2}} (h_2' - h_3')$$

$$(3) \rightarrow Q_2(t) = h_3 A + \frac{1}{R_{f2}} (h_3' - h_2') + Q_1(t) + \frac{1}{R_{f3}} (h_3')$$

$$i \rightarrow C_p = A/\rho g$$

$$R \rightarrow \frac{1}{R_f} = \rho \cdot g \cdot R_f$$

$$C \rightarrow L_f = \rho L/A$$

• Analógia Tipo 2:

$$(1): i_1(t) = (C_1 D + 1/R_1) V_1 - (1/R_1) V_2$$

$$(2): 0 = (1/R_1 + C_2 D + 1/R_2) V_2 - 1/R_1 V_1 - 1/R_2 V_3$$

$$(3): 0 = (1/R_2 + 1/L_2 D) V_3 - 1/R_2 V_2 - 1/L_2 D V_4$$

$$(4): \left(\frac{1}{L_2 D} + C_3 D + \frac{1}{R_3} \right) V_4 - \frac{1}{L_2 D} V_3 = 0$$

Analogia Tipo 2:

$$V \rightarrow P = \rho g h$$

$$i \rightarrow Q$$

$$R \rightarrow \bar{R}_f = \rho g R_f$$

$$L \rightarrow L_f = \frac{\rho L}{g}$$

$$C \rightarrow C_f = A / \rho g$$

$$\Rightarrow Q_i(t) = A_1 \ddot{h}_1 + \frac{(h_1' - h_2')}{R_{f1}} \quad (1)$$

$$\Rightarrow 0 = A_2 \ddot{h}_2 + \frac{(h_2' - h_1')}{R_{f1}} + \frac{(h_2' - h_3')}{R_{f2}} \quad (2)$$

$$\Rightarrow 0 = \frac{(h_4 - h_3)}{L_{f2}} + \frac{(h_3' - h_2')}{R_{f2}} \quad (3)$$

$$\Rightarrow 0 = \frac{(h_4 - h_3)}{L_{f2}} + A_3 \ddot{h}_4 + \frac{h_4'}{R_{f3}} \quad (4)$$

②